Agilent
Advanced Power System
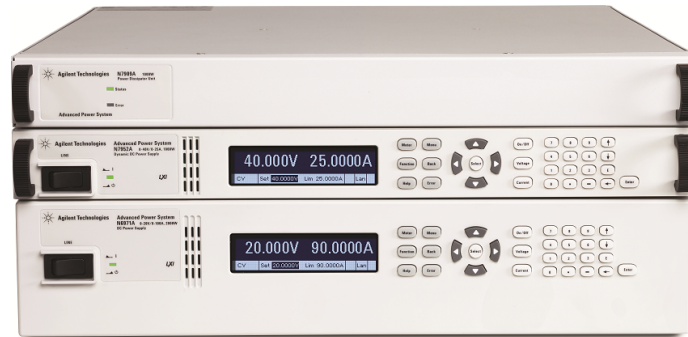# N6900/N7900 Series

Operating and Service Guide

Agilent Technologies

Agilent Advanced Power System
N6900/N7900 Series
Operating and Service Guide

This document includes user, service, and programming information for the Agilent Advanced Power System (APS) Family. If you have feedback on this document, please contact Agilent at www.agilent.com/find/APS-docfeedback.

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Contact Agilent Technologies

You can contact Agilent Technologies for warranty, service, or technical support.

- In the United States: (800) 829-4444

- In Europe: 31 20 547 2111

- In Japan: 0120-421-345

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Legal and Safety Information

Legal Notices

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Legal Notices

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Manual Part Number

N7900-90001

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Software and Documentation Revisions

For the latest firmware revision go to the product page at www.agilent.com/find/APS.

You can download the latest version of this document at www.agilent.com/find/APS-doc . The latest version is also available for mobile devices at www.agilent.com/find/APS-mobilehelp.

This product uses Microsoft Windows CE. Agilent highly recommends that all Windows-based computers connected to Windows CE instruments use current anti-virus software.

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Certification

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This product complies with the WEEE Directive 2002/96/EC) marketing requirement. The affixed product label (see below) indicates that you must not discard this electrical/electronic product in domestic household waste.

Product Category: With reference to the equipment types in the WEEE directive Annex 1, this product is classified as "Monitoring and Control instrumentation" product.

To return unwanted products, contact our local Agilent office, or see www.agilent.com/environment/product for more information.

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If you have questions about your shipment, or if you need information about warranty, service, or technical support, contact Agilent Technologies.

Safety Notices

The following general safety precautions must be observed during all phases of operation of this instrument. Failure to comply with these precautions or with specific warnings or instructions elsewhere in this manual violates safety standards of design, manufacture, and intended use of the instrument. Agilent Technologies assumes no liability of the customer's failure to comply with the requirements.

General

Do not use this product in any manner not specified by the manufacturer. The protective features of this product may be impaired if it is used in a manner not specified in the operation instructions.

Before Applying Power

Verify that all safety precautions are taken. Make all connections to the unit before applying power. Note the instrument's external markings described under "Safety Symbols".

Ground the Instrument

This product is provided with protective earth terminals. To minimize shock hazard, the instrument must be connected to the AC power mains through a grounded power cable, with the ground wire firmly connected to an electrical ground (safety ground) at the power outlet. Any interruption of the protective (grounding) conductor or disconnection of the protective earth terminal will cause a potential shock hazard that could result in personal injury.

Do Not Operate in an Explosive Atmosphere.

Do not operate the instrument in the presence of flammable gases or fumes.

Do Not Remove the Instrument Cover

Only qualified, service-trained personnel who are aware of the hazards involved should remove instrument covers. Always disconnect the power cable and any external circuits before removing the instrument cover.

Fuses

The instrument contains an internal fuse, which is not user accessible.

Do Not Modify the Instrument

Do not install substitute parts or perform any unauthorized modification to the product. Return the product to an Agilent Sales and Service Office for service and repair to ensure that safety features are maintained.

In Case of Damage

Instruments that appear damaged or defective should be made inoperative and secured against unintended operation until they can be repaired by qualified service personnel.

CAUTION

A CAUTION notice denotes a hazard. It calls attention to an operating procedure, practice, or the like that, if not correctly performed or adhered to, could result in damage to the product or loss of important data. Do not proceed beyond a CAUTION notice until the indicated conditions are fully understood and met.

WARNING

A WARNING notice denotes a hazard. It calls attention to an operating procedure, practice, or the like that, if not correctly performed or adhered to, could result in personal injury or death. Do not proceed beyond a WARNING notice until the indicated conditions are fully understood and met.

Safety Symbols

Symbol	Description
Direct current	Direct current
Alternating current	Alternating current
Frame or chassis terminal	Frame or chassis terminal
Standby supply	Standby supply. Unit is not completely disconnected from AC mains when switch is off.
Caution, risk of electric shock	Caution, risk of electric shock
Caution	Caution, refer to accompanying documents
Earth ground terminal	Earth ground terminal
CE	The CE mark is a registered trademark of the European Community.
ETL Intertek	The ETL mark is a registered trademark of Intertek.
N10149	The C-tick mark is a registered trademark of the Spectrum Management Agency of Australia. This signifies compliance with the Australian EMC Framework regulations under the terms of the Radio Communications Act of 1992.
KC	South Korean Class A EMC Declaration This equipment is Class A suitable for professional use and is for use in electromagnetic environments outside of the home.
40	Contains one or more of the 6 hazardous substances above the maximum concentration value (MCV), 40 Year EPUP.
1SM1-A	This text indicates that the instrument is an Industrial Scientific and Medical Group 1 Class A product (CISPER 11, Clause 4).
ICES/NMB-001	This text indicates product compliance with the Canadian Interference- Causing Equipment Standard (ICES-001).

Model Features and Options

Model Features

Feature	Agilent N6900 models		Agilent N7900 dynamic models	
	1 kW	**2 kW**	**1 kW**	**2 kW**
Voltage/Current Ratings	N6950A 9 V/100 A N6951A 20 V/50 A N6952A 40 V/25 A N6953A 60V/16.7A N6954A 80V/12.5A	N6970A 9 V/200 A N6971A 20V/100 A N6972A 40 V/50 A N6973A 60 V/33.4A N6974A 80 V/25 A	N7950A 9 V/100 A N7951A 20 V/50 A N7952A 40 V/25 A N7953A 60V/16.7A N7954A 80V/12.5A	N7970A 9 V/200 A N7971A 20V/100 A N7972A 40 V/50 A N7973A 60 V/33.4A N7974A 80 V/25 A
Voltage and current programming	14-bit precision	14-bit precision	16-bit precision	16-bit precision
Voltage and current measurements	18-bit precision	18-bit precision	18-bit precision	18-bit precision
Programmable output resistance	•	•	•	•
Current sinking up to 10% of rated current[1]	•	•	•	•
Power measurements	•	•	•	•
Amp-Hour and Watt-Hour Measurements	•	•	•	•
Low current measurement range			•	•
Seamless current measurements			•	•
Adjustable sample rate			•	•
Array readback			•	•
External data logging			•	•
Parallel operation	•	•	•	•
Signal routing	•	•	•	•
Output lists			•	•
Arbitrary waveforms			•	•
Disconnect relays with polarity reverse[2]			N7950A[3] N7951A-N7954A	N7970A[3] N7971A-N7974A

[1]Current sinking up to 100% of rated current requires one power dissipator for 1 kW models, and two power dissipators for 2 kW models. 2 kW models with one power dissipator can sink 50% of their rated current.
[2] An AC network is always present across the output terminals.
[3] Polarity reverse relays not included on models N7950A and N7970A.

Accessories/Options

Accessory/ Option Number	Description
N7909A	1 kW power dissipator. 1 unit is required for 1 kW power supplies to sink the rated output power; 2 units are required for 2 kW power supplies to sink the rated output power.
N7908A Option 057	Black Box Recorder board. Installs in a slot on the bottom of unit. When installed, appears as Option 057 in the "About" screen and must be check-marked on the unit label.
N7907A	Rack Ear and Slide Accessory Kit - everything needed for mounting 1 kW models, 2 kW models, and the power dissipator in 19-inch EIA cabinets.
N6700-60012	1U Rack ears only - for 1 kW models and the power dissipator (1.75 in. high)
5063-9212	2U Rack ears only - for 2 kW models (3.5 in. high)
5063-9219	2U Rack ears with handles - for 2 kW models (3.5 in. high)
5003-1128	Rack slides only - for mounting 1 kW models, 2 kW models, and the power dissipator in 19-inch EIA cabinets.
E664AC	Rails only - for mounting 2 kW models in 19 inch EIA cabinets. Because of required airflow, you **cannot** use rails for rack mounting 1 kW models or the power dissipator.
Option UK6	Commercial calibration with test results data.
Option 760	Disconnect relays with polarity reverse. When installed, appears as option 760 in the "About" screen and on the unit label. Included on most N7900 models - see previous table.
Option 761	Disconnect relays - no polarity reverse. When installed, appears as option 761 in the "About" screen and on the unit label. Included on N7950A and N7970A models - see previous table.

Specifications and Characteristics

Introduction

Unless otherwise noted, specifications are warranted over the ambient temperature range of 0 to 40°C after a 30-minute warm-up period. Specifications apply at the output terminals, with the sense terminals connected to the output terminals (local sensing). Accuracy specifications are warranted for one year.

Supplemental characteristics are not warranted but are descriptions of performance determined either by design or by type testing. All supplemental characteristics are typical unless otherwise noted.

Specifications - Agilent N6900 Series

1 kW Specifications	N6950A	N6951A	N6952A	N6953A	N6954A

DC Ratings
  Voltage source:
  Current source:
  Current sink 10% rating:
  Current sink 100% rating:[1]
  Power:[2]
	0 to 9 V
	0 to 100 A
	-10 A
	-100 A
	900 W
		0 to 20 V
		0 to 50 A
		-5 A
		-50 A
		1 kW
			0 to 40 V
			0 to 25 A
			-2.5 A
			-25 A
			1 kW
				0 to 60 V
				0 to 16.7 A
				-1.67 A
				-16.7 A
				1 kW
					0 to 80 V
					0 to 12.5 A
					-1.25 A
					-12.5 A
					1 kW

Output ripple & noise[3]
  CV rms:
  CV peak-to-peak:
	1 mV
	9 mV				

Load regulation
  Voltage:
  Current:
	0.5 mV
	8 mA
		0.75 mV
		3 mA
			1.5 mV
			1 mA
				2 mV
				1 mA
					2 mV
					0.8 mA

1 kW Specifications	N6950A	N6951A	N6952A	N6953A	N6954A

Voltage programming & measurement accuracy[4, 5, 6]
  Lead drop ≤1 V max:
  Lead drop ≤25% of V rating:
	0.03% +1.5 mV
	0.03% +1.9 mV
		0.03% +3 mV
		0.03% +4 mV
			0.03% +6 mV
			0.03% +7.9 mV
				0.03% +9 mV
				0.03% +12 mV
					0.03% +12 mV
					0.03% +16 mV

Current programming & measurement accuracy[4]	0.1% +30 mA	0.1% +15 mA	0.1% +8 mA	0.1% +5 mA	0.1% +4 mA

Transient response[7]
  Recovery Time:
  Settling band:
	100 µs
	150 mV
		100 µs
		150 mV
			100 µs
			100 mV
				100 µs
				150 mV
					100 µs
					200 mV

2 kW Specifications	**N6970A**	**N6971A**	**N6972A**	**N6973A**	**N6974A**

DC Ratings
  Voltage source:
  Current source:
  Current sink 10% rating:
  Current sink 100% rating:[1]
  Power:[2]
	0 to 9 V
	0 to 200 A
	-20 A
	-200 A
	1.8 kW
		0 to 20 V
		0 to 100 A
		-10 A
		-100 A
		2 kW
			0 to 40 V
			0 to 50 A
			-5 A
			-50 A
			2 kW
				0 to 60 V
				0 to 33.3 A
				-3.33 A
				-33.3 A
				2 kW
					0 to 80 V
					0 to 25A
					-2.5 A
					-25 A
					2 kW

Output ripple & noise[3]
  CV rms:
  CV peak-to-peak:
	1 mV
	9 mV (spanning)				

Load regulation
  Voltage:
  Current:
	0.5 mV
	15 mA
		0.75 mV
		6 mA
			1.5 mV
			1.5 mA
				2 mV
				1.5 mA
					2 mV
					1.5 mA

Voltage programming & measurement accuracy[4, 5, 6]
  Lead drop ≤1 V max:
  Lead drop ≤25% of V rating:
	0.03% +1.5 mV
	0.03% +1.9 mV
		0.03% +3 mV
		0.03% +4 mV
			0.03% +6 mV
			0.03% +7.9 mV
				0.03% +9 mV
				0.03% +12 mV
					0.03% +12 mV
					0.03% +16 mV

Current programming & measurement accuracy[4]	0.1%+60 mA	0.1%+30 mA	0.1%+15 mA	0.1%+10 mA	0.1%+8 mA

Transient response[7]
  Recovery Time:
  Settling band:
	100 µs
	150 mV
		100 µs
		150 mV
			100 µs
			100 mV
				100 µs
				150 mV
					100 µs
					200 mV

[1] Current sinking up to 100% of rated current requires one power dissipator for 1 kW models, and two power dissipators for 2 kW models. 2 kW models with one power dissipator can sink 50% of their rated current.
[2] Maximum continuous power available is derated at 1% of rating per degree C from 40°C to 55°C
[3] From 20 Hz to 20 MHz
[4] At 23°C ±5°C after a 30 minute warm-up; measurement NPLC=1; valid for 1 year, see Calibration Interval
[5] With resistance programming enabled, the voltage programming offset component increases by a factor of 2.1
[6] Load lead drop applies to each load lead
[7] Time to recover to within the settling band following a load change from 50% to 100% of full load (10 µs rise time)

Specifications - Agilent N7900 Series

1 kW Specifications	N7950A	N7951A	N7952A	N7953A	N7954A

DC Ratings
  Voltage source:
    Current source:
    Current sink 10% rating:
    Current sink 100% rating:[1]
    Power:[2]
	0 to 9 V
	0 to 100 A
	-10 A
	-100 A
	900 W
		0 to 20 V
		0 to 50 A
		-5 A
		-50 A
		1 kW
			0 to 40 V
			0 to 25 A
			-2.5 A
			-25 A
			1 kW
				0 to 60 V
				0 to 16.7 A
				-1.67 A
				-16.7 A
				1 kW
					0 to 80 V
					0 to 12.5 A
					-1.25 A
					-12.5 A
					1 kW

Output ripple & noise[3]
  CV rms:
  CV peak-to-peak:
	1 mV
	9 mV				

Load regulation
  Voltage:
  Current:
	0.5 mV
	8 mA
		0.75 mV
		3 mA
			1.5 mV
			1 mA
				2 mV
				1 mA
					2 mV
					0.8 mA

Voltage programming &
measurement accuracy[4, 5, 6]
  Lead drop ≤1 V max:
  Lead drop ≤25% of V rating:
	0.03% +1 mV
	0.03% +1.4 mV
		0.03% +2 mV
		0.03% +3 mV
			0.03% +4 mV
			0.03% +5.9mV
				0.03% +6 mV
				0.03% +9 mV
					0.03% +8 mV
					0.03% +12mV

Current programming & measurement accuracy[4]	0.04% +15 mA	0.04% +8 mA	0.04% +4 mA	0.04%+2.5 mA	0.04% +2 mA
Current measurement low range accuracy	0.05% +3 mA	0.05% +1 mA	0.05% +0.6 mA	0.05% +0.3 mA	0.05%+0.25mA

Transient response[7]
  Recovery Time:
  Settling band:
	100 µs
	150 mV
		100 µs
		150 mV
			100 µs
			100 mV
				100 µs
				150 mV
					100 µs
					200 mV

2 kW Specifications	**N7970A**	**N7971A**	**N7972A**	**N7973A**	**N7974A**

DC Ratings
  Voltage source:
    Current source:
    Current sink 10% rating:
    Current sink 100% rating:[1]
    Power:[2]
	0 to 9 V
	0 to 200 A
	-20 A
	-200 A
	1.8 kW
		0 to 20 V
		0 to 100 A
		-10 A
		-100 A
		2 kW
			0 to 40 V
			0 to 50 A
			-5 A
			-50 A
			2 kW
				0 to 60 V
				0 to 33.3 A
				-3.33 A
				-33.3 A
				2 kW
					0 to 80 V
					0 to 25A
					-2.5 A
					-25 A
					2 kW

Output ripple & noise[3]
  CV rms:
  CV peak-to-peak:
	1 mV
	9 mV				

Load regulation
  Voltage:
  Current:
	0.5 mV
	15 mA
		0.75 mV
		6 mA
			1.5 mV
			1.5 mA
				2 mV
				1.5 mA
					2 mV
					1.5 mA

Voltage programming &
measurement accuracy[4, 5, 6]
  Lead drop ≤1 V max:
  Lead drop ≤25% of V rating:
	0.03% +1 mV
	0.03% +1.4 mV
		0.03% +2 mV
		0.03% +3 mV
			0.03% +4 mV
			0.03% +5.9mV
				0.03% +6 mV
				0.03% +9 mV
					0.03% +8 mV
					0.03% +12mV

Current programming & measurement accuracy[4]	0.04% +30 mA	0.04% +15 mA	0.04% +8 mA	0.04% +5 mA	0.04% +4 mA

2 kW Specifications	N7970A	N7971A	N7972A	N7973A	N7974A
Current measurement low range accuracy	0.05% +6 mA	0.05% +2 mA	0.05% +1.2 mA	0.05% +0.6 mA	0.05% +0.5 mA
Transient response[7] Recovery Time: Settling band:	100 µs 150 mV	100 µs 150 mV	100 µs 100 mV	100 µs 150 mV	100 µs 200 mV

[1] Current sinking up to 100% of rated current requires one power dissipator for 1 kW models, and two power dissipators for 2 kW models. 2 kW models with one power dissipator can sink 50% of their rated current.
[2] Maximum continuous power available is derated at 1% of rating per degree C from 40°C to 55°C
[3] From 20 Hz to 20 MHz
[4] At 23°C ±5°C after a 30 minute warm-up; measurement NPLC=1; valid for 1 year, see Calibration Interval
[5] With resistance programming enabled, the voltage programming offset component increases by a factor of 3.15
[6] Load lead drop applies to each load lead
[7] Time to recover to within the settling band following a load change from 50% to 100% of full load (10 µs rise time)

Supplemental Characteristics - Agilent N6900 Series

1 kW Characteristics	N6950A	N6951A	N6952A	N6953A	N6954A
Voltage programming range	0.009 to 9.18 V	0.02 to 20.4 V	0.04 to 40.8 V	0.06 to 61.2 V	0.08 to 81.6 V
Voltage programming resolution	0.84 mV	1.7 mV	3.5 mV	5 mV	6.7 mV
Current programming range - no dissipator	−10.2 to 102 A	−5.1 to 51 A	−2.55 to 25.5 A	−1.7 to 17 A	−1.275 to 12.75 A
Current programming range - with dissipator	−102 to 102 A	−51 to 51 A	−25.5 to 25.5 A	−17 to 17 A	−12.75 to 12.75 A
Current programming resolution	30 mA	15 mA	8 mA	5 mA	4 mA
Current measurement range	-225 to 225 A	-112.5 to 112.5A	-56.2 to 56.2 A	-37.6 to 37.6 A	-28.1 to 28.1 A
Resistance programming range	0 to 0.1 Ω	0 to 0.4 Ω	0 to 1.6 Ω	0 to 3.4 Ω	0 to 6.4 Ω
Resistance programming accuracy[1]	0.12% +1.6 mΩ*A	0.12% +3.2 mΩ*A	0.1% +6.4 mΩ*A	0.1% +8.8 mΩ*A	0.1% +12.8 mΩ*A
Resistance programming resolution	0.8 µΩ	3.4 µΩ	13 µΩ	30 µΩ	54 µΩ
Voltage programming & measurement TempCo[2]	0.0022%+30µV	0.0022%+60µV	0.0022%+120µV	0.0022%+180µV	0.0022%+220µV
Current programming & measurement TempCo[2]	0.0057%+250µA	0.0058%+125µA	0.0058%+60µA	0.0058%+40µA	0.0058%+30µA
Resistance programming TempCo	0.0068%	0.0070%	0.0070%	0.0070%	0.0070%

1 kW Characteristics	N6950A	N6951A	N6952A	N6953A	N6954A
Voltage measurement noise (peak)	2 mV	3.5 mV	7 mV	10 mV	14 mV
Current measurement noise (peak)	45 mA	22 mA	10 mA	6 mA	4 mA
Output current noise CC rms:	15 mA	15 mA	15 mA	15 mA	15 mA
Common mode current CC rms: CC peak-to-peak:	2 mA 10 mA	1 mA 10 mA	1 mA 10 mA	1 mA 10 mA	1.5 mA 10 mA
Voltage up-programming time[3] 10% to 90%: Settling time:[5]	3 ms 10 ms				
Voltage down-programming time[4] 90% to 10%: Settling time:[5]	3 ms 10 ms				
Current up-programming time[6] 10% to 90%:	2.5 ms				
Output-on delay time Voltage priority: Current priority:	12 ms 14 ms				
Line regulation[7] Voltage: Current:	< 10 µV < 10 µA				
2 kW Characteristics	**N6970A**	**N6971A**	**N6972A**	**N6973A**	**N6974A**
Voltage programming range	0.009 to 9.18 V	0.02 to 20.4 V	0.04 to 40.8 V	0.06 to 61.2 V	0.08 to 81.6 V
Voltage programming resolution	0.84 mV	1.7 mV	3.5 mV	5 mV	6.7 mV
Current programming range - no dissipator	-20.4 to 204 A	−10.2 to 102 A	−5.1 to 51 A	−3.4 to 34 A	−2.55 to 25.5 A
Current programming range - with dissipators	−204 to 204 A	−102 to 102 A	−51 to 51 A	−34 to 34 A	−25.5 to 25.5 A
Current programming resolution	60 mA	30 mA	15 mA	10 mA	8 mA
Current measurement range	-450 to 450 A	-225 to 225 A	-112.5 to 112.5A	-74.9 to 74.9 A	-56.2 to 56.2 A

2 kW Characteristics	N6970A	N6971A	N6972A	N6973A	N6974A
Resistance programming range	0 to 0.05 Ω	0 to 0.2 Ω	0 to 0.8 Ω	0 to 1.7 Ω	0 to 3.2 Ω
Resistance programming accuracy[1]	0.12% +1.6 mΩ*A	0.12% +3.2 mΩ*A	0.1% +6.4 mΩ*A	0.1% +8.8 mΩ*A	0.1% +12.8 mΩ*A
Resistance programming resolution	0.4 μΩ	1.7 μΩ	7 μΩ	15 μΩ	27 μΩ
Voltage programming & measurement TempCo[2]	0.0022%+30μV	0.0022%+60μV	0.0022%+120μV	0.0022%+180μV	0.0022%+220μV
Current programming & measurement TempCo[2]	0.0048%+500μA	0.0049%+250μA	0.0049%+120μA	0.0049%+80μA	0.0049%+60μA
Resistance programming TempCo	0.0060%	0.0060%	0.0060%	0.0060%	0.0060%
Voltage measurement noise (peak)	2 mV	3.5 mV	7 mV	10 mV	14 mV
Current measurement noise (peak)	75 mA	45 mA	18 mA	12 mA	7 mA
Output current noise CC rms:	20 mA	20 mA	15 mA	15 mA	15 mA
Common mode current CC rms: CC peak-to-peak:	2 mA 15 mA	1 mA 10 mA	1 mA 10 mA	1 mA 10 mA	2 mA 10 mA
Voltage up-programming time[3] 10% to 90%: Settling time:[5]	3 ms 10 ms				
Voltage down-programming time[4] 90% to 10%: Settling time:[5]	3 ms 10 ms				
Current up-programming time[6] 10% to 90%:	2.5 ms				
Output-on delay time Voltage priority: Current priority:	12 ms 14 ms				
Line regulation[7] Voltage: Current:	< 10 μV < 10 μA				

[1] Resistance programming accuracy varies with output current. For example, for an N7970A unit at 0.1Ω with a 50A transient, accuracy is: (0.1Ω * 0.06%) + (1.6mΩ*A/50A) = 92 µΩ.
[2] Per degree C
[3] With full resistive load and a voltage transition from 0.1 % to 100% of rated output
[4] With no load and a voltage transition from 100 % to 0.1% of rated output
[5] From start of voltage change to within 0.1% of final full scale value
[6] With full resistive load and a current transition from 0.1 % to 100% of rated output
[7] Line regulation is guaranteed by design

Supplemental Characteristics - Agilent N7900 Series

1 kW Characteristics	N7950A	N7951A	N7952A	N7953A	N7954A
Voltage programming range	0.009 to 9.18 V	0.02 to 20.4 V	0.04 to 40.8 V	0.06 to 61.2 V	0.08 to 81.6 V
Voltage programming resolution	0.21 mV	0.42 mV	0.84 mV	1.25 mV	1.68 mV
Current programming range - no dissipator	−10.2 to 102 A	−5.1 to 51 A	−2.55 to 25.5 A	−1.7 to 17 A	−1.275 to 12.75 A
Current programming range - with dissipator	−102 to 102 A	−51 to 51 A	−25.5 to 25.5 A	−17 to 17 A	−12.75 to 12.75 A
Current programming resolution	1.9 mA	0.95 mA	0.47 mA	0.32 mA	0.24 mA

Current measurement range
  High range
  Low range
	-225 to 225 A
	-11 to 11 A
		-112.5 to 112.5A
		-5.5 to 5.5 A
			-56.2 to 56.2 A
			-2.75 to 2.75 A
				-37.6 to 37.6 A
				-1.84 to 1.84 A
					-28.1 to 28.1 A
					-1.37 to 1.37 A

Resistance programming range	0 to 0.1 Ω	0 to 0.4 Ω	0 to 1.6 Ω	0 to 3.4 Ω	0 to 6.4 Ω
Resistance programming accuracy[1]	0.06% +1.6 mΩ*A	0.06% +3.2 mΩ*A	0.06% +6.4 mΩ*A	0.06% +8.8 mΩ*A	0.06% +12.8 mΩ*A
Resistance programming resolution	0.8 µΩ	3.4 µΩ	13 µΩ	30 µΩ	54 µΩ
Voltage programming & measurement TempCo[2]	0.0022%+30µV	0.0022%+60µV	0.0022%+120µV	0.0022%+180µV	0.0022%+220µV
Current programming & measurement TempCo[2]	0.0035%+250µA	0.0035%+125µA	0.0042%+60µA	0.0037%+40µA	0.0036%+30µA
Current measurement low range TempCo[2]	0.0042%+80µA	0.0045%+40µA	0.0050%+20µA	0.0046%+12µA	0.0045%+9µA
Resistance programming TempCo	0.0046%	0.0049%	0.0054%	0.0050%	0.0049%
Voltage measurement noise (peak)	2 mV	3.5 mV	7 mV	10 mV	14 mV

1 kW Characteristics	N7950A	N7951A	N7952A	N7953A	N7954A
Current measurement noise (peak)	45 mA	22 mA	10 mA	6 mA	4 mA
Current measurement low range noise (peak)	30 mA	17 mA	7 mA	4 mA	2 mA
Output current noise CC rms:	15 mA	15 mA	15 mA	15 mA	15 mA
Common mode current CC rms: CC peak-to-peak:	2 mA 10 mA	1 mA 10 mA	1 mA 10 mA	1 mA 10 mA	1.5 mA 10 mA
Voltage up-programming time[3] 10% to 90%: Settling time:[5]	0.5 ms 1 ms				
Voltage down-programming time[4] 90% to 10%: Settling time:[5]	0.35 ms 0.8 ms				
Current up-programming time[6] 10% to 90%:	2.5 ms				
Output-on delay time Voltage priority: with relay on: Current priority: with relay on:	12 ms 38 ms 14 ms 46 ms				
Line regulation[7] Voltage: Current:	< 10 µV < 10 µA				
Voltage programming bandwidth[8] - 3 dB point: - 1 dB point:	2000 Hz 1000 Hz				
Voltage measurement bandwidth - 3 dB point: - 1 dB point:	25 kHz 14 kHz				
Current programming bandwidth[9] - 3 dB point: - 1 dB point:	120 Hz 70 Hz				
Current measurement bandwidth - 3 dB point: - 1 dB point:	25 kHz 14 kHz				

2 kW Characteristics	N7970A	N7971A	N7972A	N7973A	N7974A
Voltage programming range	0.009 to 9.18 V	0.02 to 20.4 V	0.04 to 40.8 V	0.06 to 61.2 V	0.08 to 81.6 V
Voltage programming resolution	0.21 mV	0.42 mV	0.84 mV	1.25 mV	1.68 mV
Current programming range - no dissipator	-20.4 to 204 A	−10.2 to 102 A	−5.1 to 51 A	−3.4 to 34 A	−2.55 to 25.5 A
Current programming range - with dissipators	−204 to 204 A	−102 to 102 A	−51 to 51 A	−34 to 34 A	−25.5 to 25.5 A
Current programming resolution	3.8 mA	1.9 mA	0.95 mA	0.64 mA	0.48 mA

Current measurement range
  High range
  Low range
	-450 to 450 A
	-22 to 22 A
		-225 to 225 A
		-11 to 11 A
			-112.5 to 112.5A
			-5.5 to 5.5 A
				-74.9 to 74.9 A
				-3.67 to 3.67 A
					-56.2 to 56.2 A
					-2.75 to 2.75 A

Resistance programming range	0 to 0.05 Ω	0 to 0.2 Ω	0 to 0.8 Ω	0 to 1.7 Ω	0 to 3.2 Ω
Resistance programming accuracy[1]	0.06% +1.6 mΩ*A	0.06% +3.2 mΩ*A	0.06% +6.4 mΩ*A	0.06% +8.8 mΩ*A	0.06% +12.8 mΩ*A
Resistance programming resolution	0.4 µΩ	1.7 µΩ	7 µΩ	15 µΩ	27 µΩ
Voltage programming & measurement TempCo[2]	0.0022%+30µV	0.0022%+60µV	0.0022%+120µV	0.0022%+180µV	0.0022%+220µV
Current programming & measurement TempCo[2]	0.0029%+500µA	0.0031%+250µA	0.0035%+120µA	0.0032%+80µA	0.0032%+60µA
Current measurement low range TempCo[2]	0.0040%+160µA	0.0041%+80µA	0.0045%+40µA	0.0042%+24µA	0.0041%+18µA
Resistance programming TempCo	0.0043%	0.0045%	0.0049%	0.0046%	0.0045%
Voltage measurement noise (peak)	2 mV	3.5 mV	7 mV	10 mV	14 mV
Current measurement noise (peak)	75 mA	45 mA	18 mA	12 mA	7 mA
Current measurement low range noise (peak)	50 mA	30 mA	12 mA	6 mA	3 mA
Output current noise CC rms:	20 mA	20 mA	15 mA	15 mA	15 mA

Common mode current
  CC rms:
  CC peak-to-peak:
	2 mA
	15 mA
		1 mA
		10 mA
			1 mA
			10 mA
				1 mA
				10 mA
					2 mA
					10 mA

2 kW Characteristics	N7970A	N7971A	N7972A	N7973A	N7974A

Voltage up-programming time[3]
  10% to 90%:
  Settling time:[5]
			0.5 ms
			1 ms		

Voltage down-programming time[4]
  90% to 10%:
  Settling time:[5]
			0.35 ms
			0.8 ms		

Current up-programming time[6] 10% to 90%:			2.5 ms		

Output-on delay time
  Voltage priority:
  with relay on:
  Current priority:
  with relay on:
			12 ms
			38 ms
			14 ms
			46 ms		

Line regulation[7]
  Voltage:
  Current:
			< 10 µV
			< 10 µA		

Voltage programming bandwidth[8]
  - 3 dB point:
  - 1 dB point:
			2000 Hz
			1000 Hz		

Voltage measurement bandwidth
  - 3 dB point:
  - 1 dB point:
			25 kHz
			14 kHz		

Current programming bandwidth[9]
  - 3 dB point:
  - 1 dB point:
			120 Hz
			70 Hz		

Current measurement bandwidth
  - 3 dB point:
  - 1 dB point:
			25 kHz
			14 kHz		

[1] Resistance programming accuracy varies with output current. For example, for an N7970A unit at 0.1Ω with a 50A transient, accuracy is: $(0.1Ω * 0.06\%) + (1.6mΩ*A/50A) = 92$ µΩ.
[2] Per degree C
[3] With full resistive load and a voltage transition from 0.1 % to 100% of rated output
[4] With no load and a voltage transition from 100 % to 0.1% of rated output
[5] From start of voltage change to within 0.1% of final full scale value
[6] With full resistive load and a current transition from 0.1 % to 100% of rated output
[7] Line regulation is guaranteed by design
[8] With High Bandwidth setting, resistive load condition (see Voltage Programming Response)
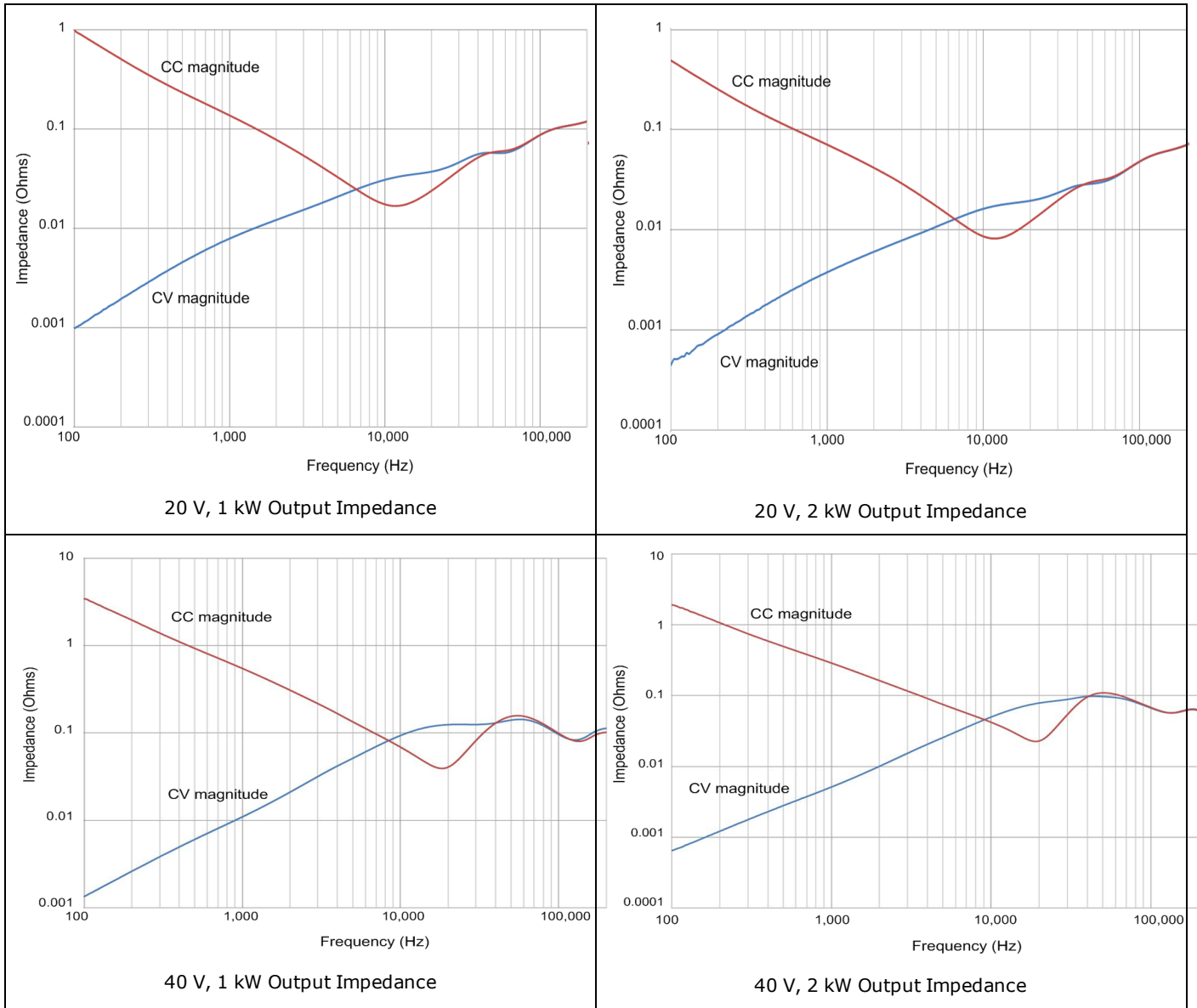[9] With resistive load condition

Common Characteristics

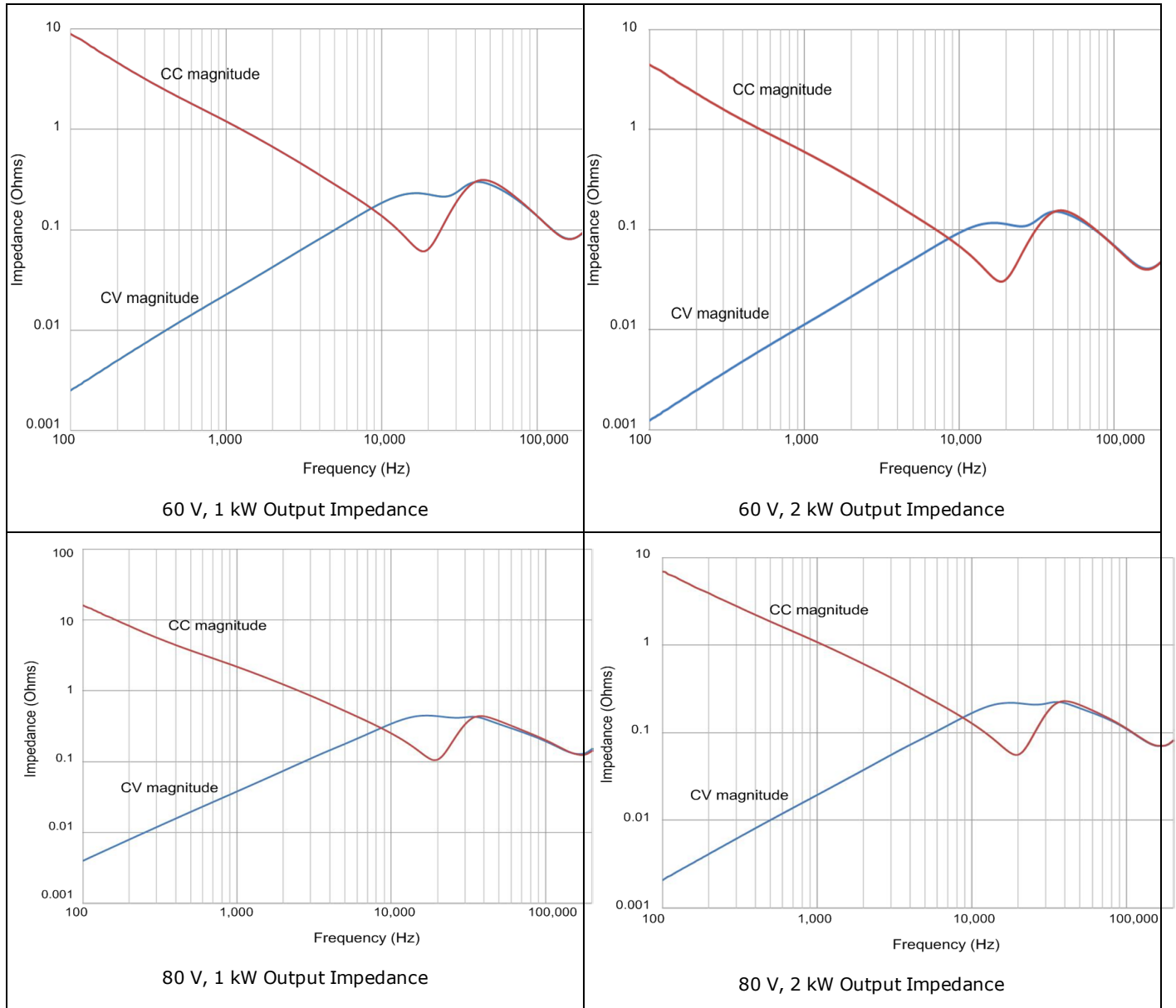| Common Characteristic	All Models
Command Processing Time	≤ 1 ms from receipt of command to start of output change. Applies to simple settings commands over the GPIB interface (see Command Processing Times)
Digital Port Max voltage rating:	+16.5 VDC/- 5 VDC between pins
Pins 1 & 2 as FLT:	Maximum low-level output voltage = 0.5 V @ 4 mA Maximum low-level sink current = 4 mA Typical high-level leakage current = 1 mA @ 16.5 VDC
Pins 1-7 as outputs:	Maximum low-level output voltage = 0.5 V @ 4 mA; 1 V @ 50 mA; 1.75 V @ 100 mA Maximum low-level sink current = 100 mA Typical high-level leakage current = 0.8 mA @ 16.5 VDC
Pins 1-7 as inputs:	Maximum low-level input voltage = 0.8 V Minimum high-level input voltage = 2 V Typical low-level current = 2 mA @ 0 V (internal 2.2k pull-up) Typical high-level leakage current = 0.12 mA @ 16.5 VDC
Pin 8:	Pin 8 is common (internally connected to chassis ground)
Regulatory Compliance EMC:	Complies with European EMC Directive for test and measurement products Complies with Australian standard and carries C-Tick mark This ISM device complies with Canadian ICES-001 Cet appareil ISM est conforme à la norme NMB-001 du Canada
Safety:	Complies with European Low Voltage Directive and carries the CE-marking. Conforms to US and Canadian safety regulations. Declarations of Conformity for this product may be downloaded from the Web. Go to http://regulations.corporate.agilent.com and click on "Declarations of Conformity."
Environmental Operating environment:	Indoor use, installation category II (for AC input), pollution degree 2
Temperature range:	0°C to 55°C (Maximum continuous power available is derated at 1% of rating per degree C from 40°C to 55°C)
Relative humidity:	95% or less (non-condensing)
Altitude:	Up to 2000 meters
Storage temperature:	-30°C to 70°C
Acoustic Noise Declaration	Complies with the requirements of the German Sound Emission Directive from 18 January 1991. Sound Pressure Lp <70 dB(A), At Operator Position, Normal Operation, According to EN 27779 (Type Test).

Output Terminal Isolation Maximum rating:	No output terminal may be more than ±240 VDC from any other terminal or chassis ground.
AC Input Input Ratings:	~ 100–120, 200–240 VAC; 50/60/400 Hz
Power Consumption:	2000 VA for 1 kW units; 3000 VA for 2 kW units
Power Factor:	0.99 @ nominal input and rated power
Fuse:	Internal fuse - not user accessible
	NOTE:AC mains circuits rated at 100-120 VAC cannot supply enough current to power either the 1 kW or the 2 kW models when operated at their full rated output power. When connected to a 100-120 VAC mains, the instrument turns off the output and sets either the CP+ or PF status bit when the output power exceeds 700 W.
Typical Weight	1 kw models: 23 lbs. (10.5 kg.) 2 kw models: 34 lbs. (15.5 kg.) N7909A: 18 lbs. (8.2 kg.)

Output Impedance Graphs

1 kW Models	2 kW Models
 9 V, 1 kW Output Impedance	 9 V, 2 kW Output Impedance

20 V, 1 kW Output Impedance

20 V, 2 kW Output Impedance

40 V, 1 kW Output Impedance

40 V, 2 kW Output Impedance

60 V, 1 kW Output Impedance

60 V, 2 kW Output Impedance

80 V, 1 kW Output Impedance

80 V, 2 kW Output Impedance
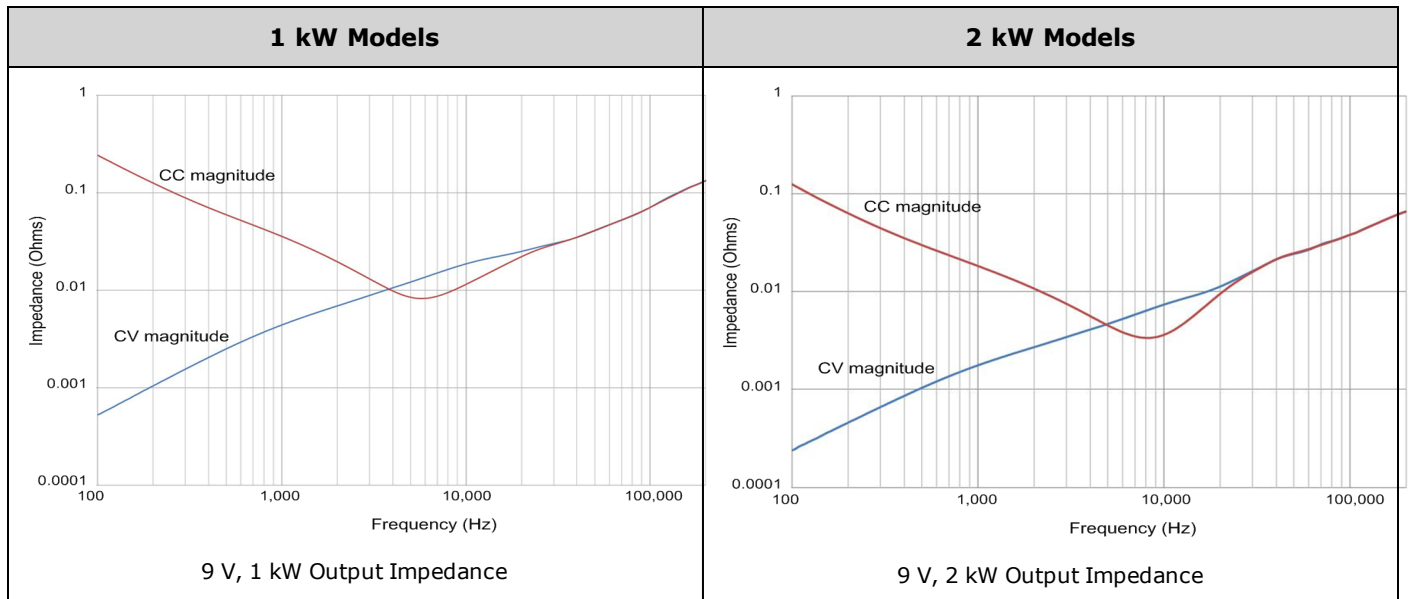
Inductive Load Boundary

The following figures show the boundary limitation for inductive loads and for fast CV/CC mode crossover operation. Operation above the inductive load boundary may result in output instability. The boundary limit represents operating conditions including a 20% current overshoot. Note that increased load resistance allows increased output inductance.

1 kW Inductive Load Boundary

2 kW Inductive Load Boundary

Output Quadrants

Key

Sourcing power

Sinking power up to 10% of rating (without dissipator)

Sinking power up to 100% of rating (with dissipator)
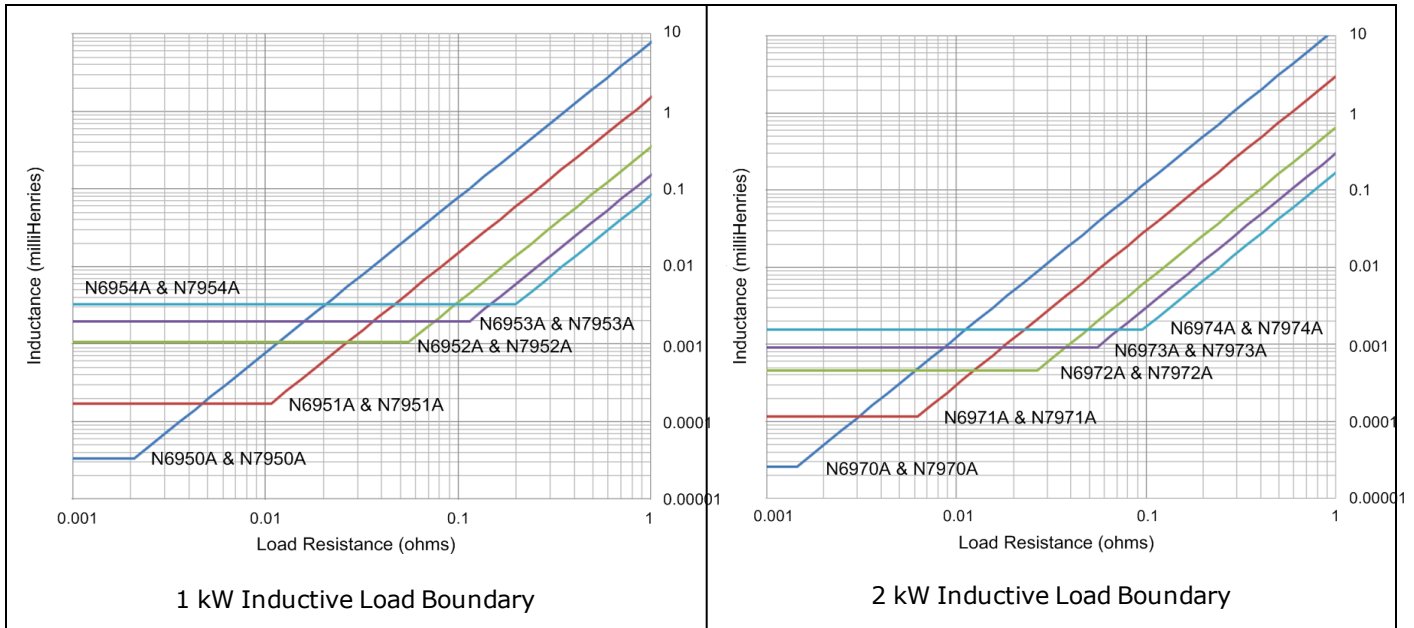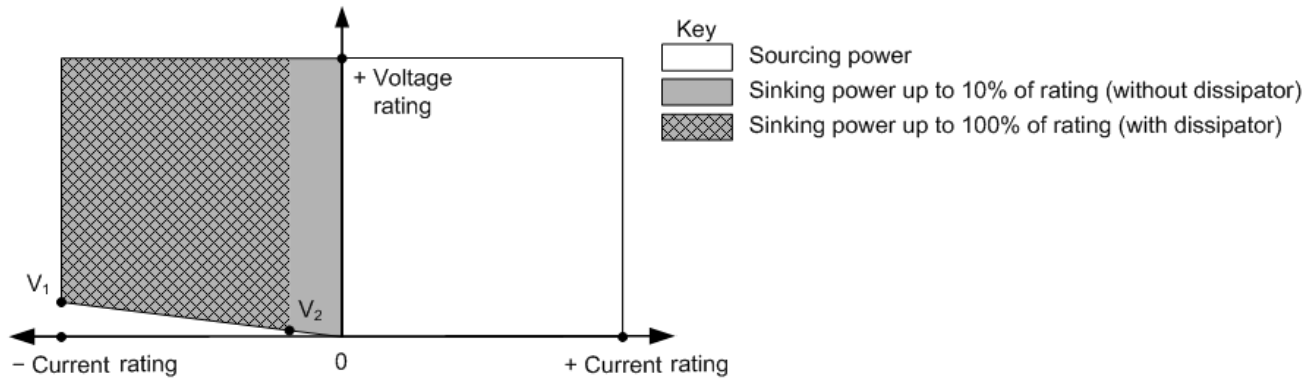
	N6950A/70A N7950A/70A	N6951A/71A N7951A/71A	N6952A/72A N7952A/72A	N6953A/73A N7953A/73A	N6954A/74A N7954A/74A
+ Voltage rating	9 V	20 V	40 V	60 V	80 V
+ Current rating	100 A/200 A	50 A/100 A	25 A/50 A	16.7 A/33.3 A	12.5 A/25 A
- Current rating (with dissipator)	-100 A/-200 A	-50 A/-100 A	-25 A/-50 A	-16.7A/-33.3A	-12.5 A/-25 A
V1	0.68 V	0.525 V	1.9 V	1.47 V	2 V
V2	0.068 V	0.0525 V	0.19 V	0.147 V	0.2 V
Minimum sinking resistance	6.8m Ω/3.4 mΩ	10.5 mΩ/5.2mΩ	76 mΩ/38 mΩ	89 mΩ/45 mΩ	160 mΩ/80 mΩ

Voltage Programming Response

The following graphs show the output voltage programming response characteristic. These graphs apply for small signals only, under resistive load conditions.

N7900 Models
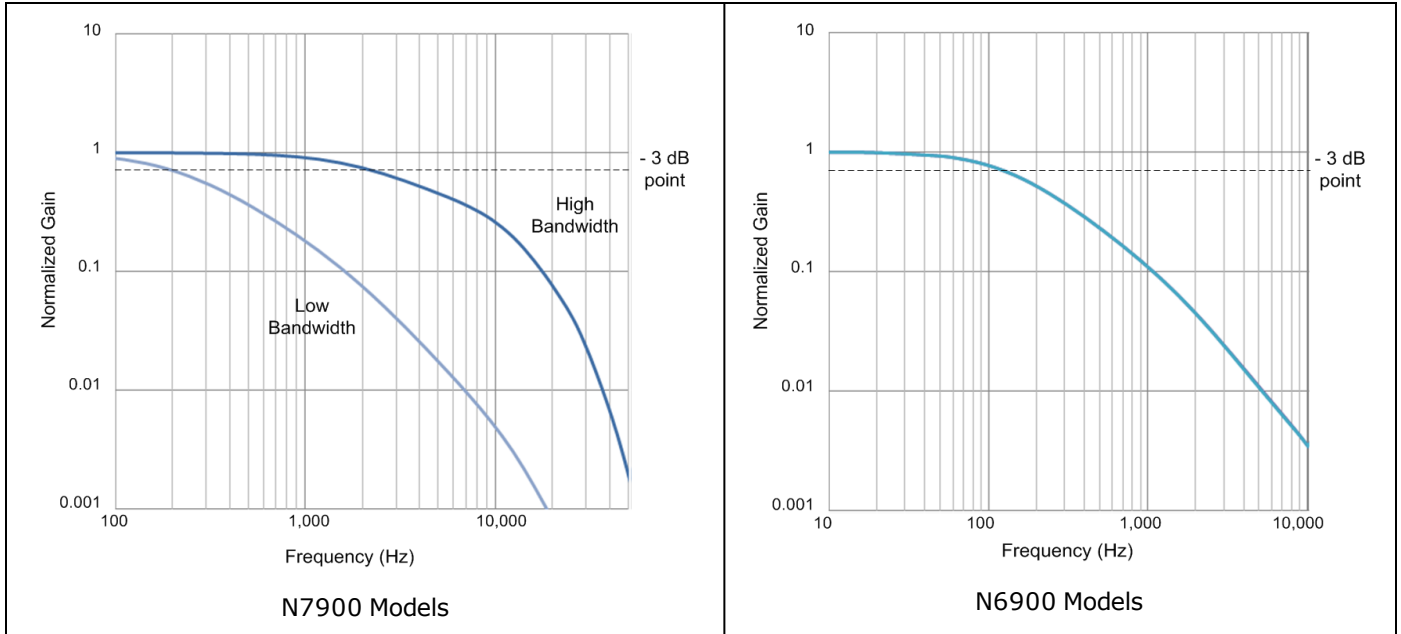
N6900 Models

Output Dynamic Response N7900 models only

The following graph shows the square wave amplitude thresholds versus frequency for each model. Above the indicated amplitude threshold, sustained generation of a square wave may lead to engagement of the excessive dynamic protection (EDP) function, which disables the output. EDP protection may be engaged by programmed voltage changes, lists, Arbs, or load-induced voltage swings.
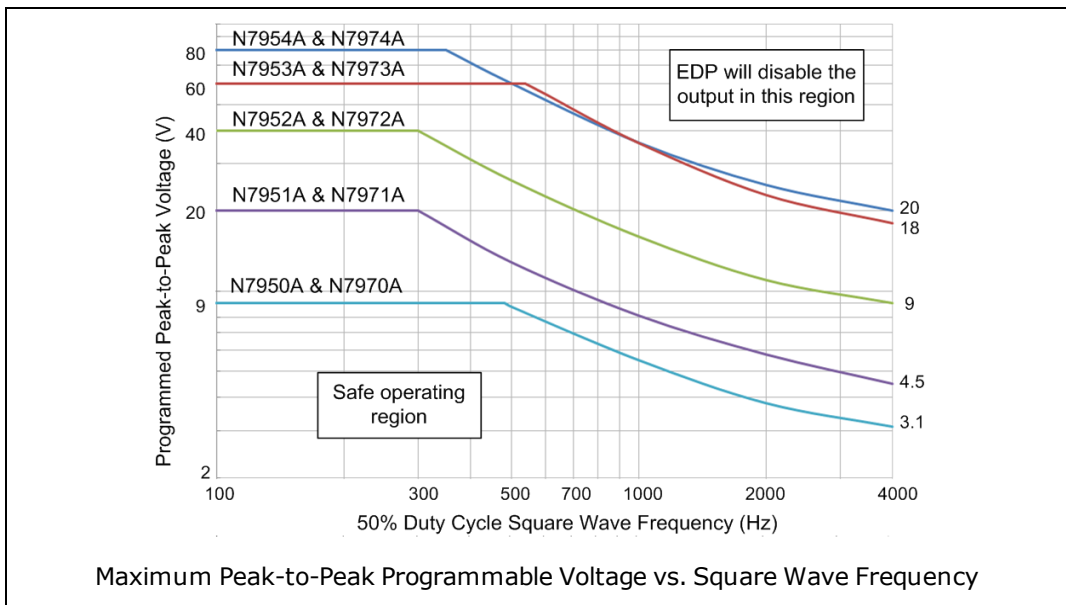
Maximum Peak-to-Peak Programmable Voltage vs. Square Wave Frequency

A-to-D Converter Noise Performance
- with shorter measurement intervals

The following table shows short-term measurement accuracy and resolution with various measurement settings. Measurement accuracy specifications are provided at 1 NPLC of averaging. This table lets you calculate measurement accuracy at shorter averaging intervals. Simply add the percent of noise value in the "Percent of noise added to spec" columns to the fixed accuracy value in the specification table.

For example, to determine the percent of noise to add to the accuracy specification of the voltage measurement of an N7950A when making measurements at 512 microseconds (0.031 NPLC), simply multiply the voltage measurement range (9 V) by the percent of noise added to spec value (0.0016%) = (0.54 millivolts). Then add this number to the fixed accuracy specification (1 mV + 0.54 mV = 1.54 mV).

NPLC @60 Hz	Number of averaged points[1]	Voltage Measurement		Current Measurement		Low Measurement Range[1]	
		Percent of noise added to spec.	Effective Resolution (in bits)	Percent of noise added to spec.	Effective Resolution (in bits)	Percent of noise added to spec.	Effective Resolution (in bits)
1	3255	0	>20	0	>19	0	>16
0.6	1953	0.00001%	19.9	0.00026%	18.6	0.002%	15.6
0.1	325	0.00076%	17.0	0.0019%	15.7	0.015%	12.7
0.06	195	0.0011%	16.5	0.0027%	15.2	0.022%	12.2
0.031	100	0.0016%	15.9	0.0041%	14.6	0.033%	11.6
0.010	33	0.0031%	15.0	0.0078%	13.6	0.063%	10.6
0.006	20	0.0041%	14.6	0.010%	13.3	0.082%	10.3
0.003	10	0.006%	14.0	0.015%	12.7	0.120%	9.7
0.0003	1	0.02%	12.3	0.049%	11.0	0.390%	8.0

[1] This parameter is programmable only on N7900 models.

Dimension Diagrams

All dimensions are in millimeters.

5

503

535

425.6

27

44.5
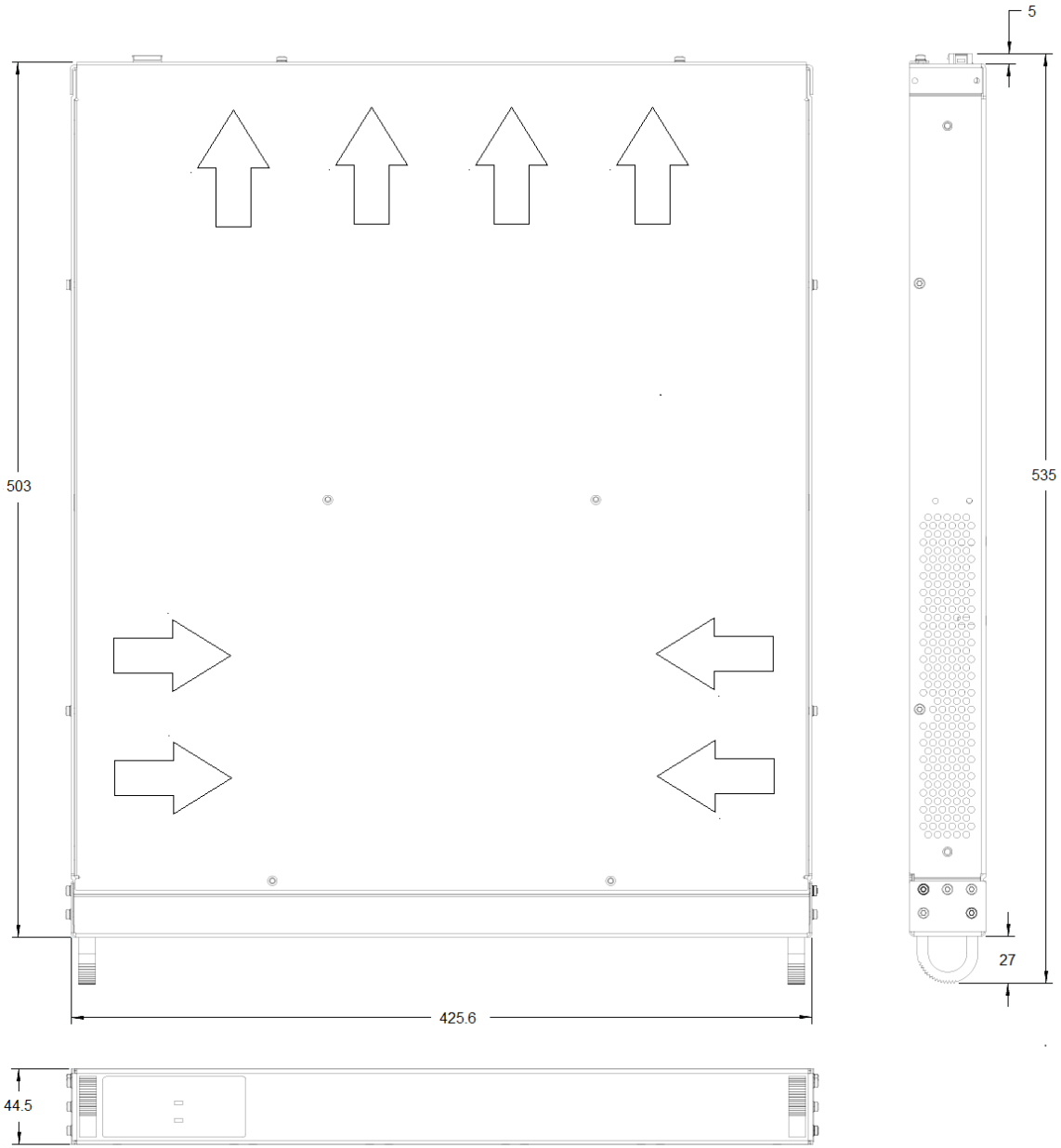
Power Dissipator Unit
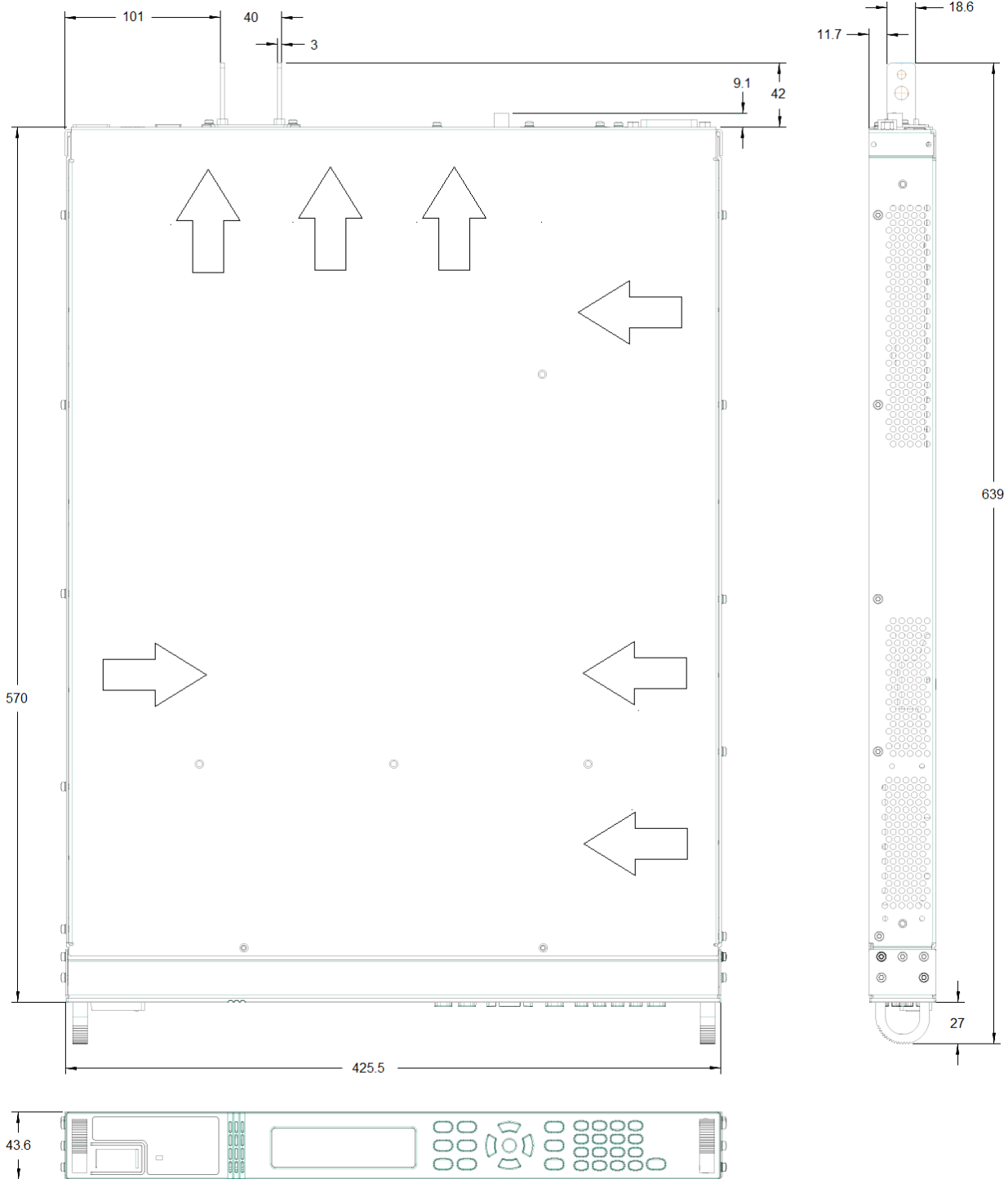
1 kW Models
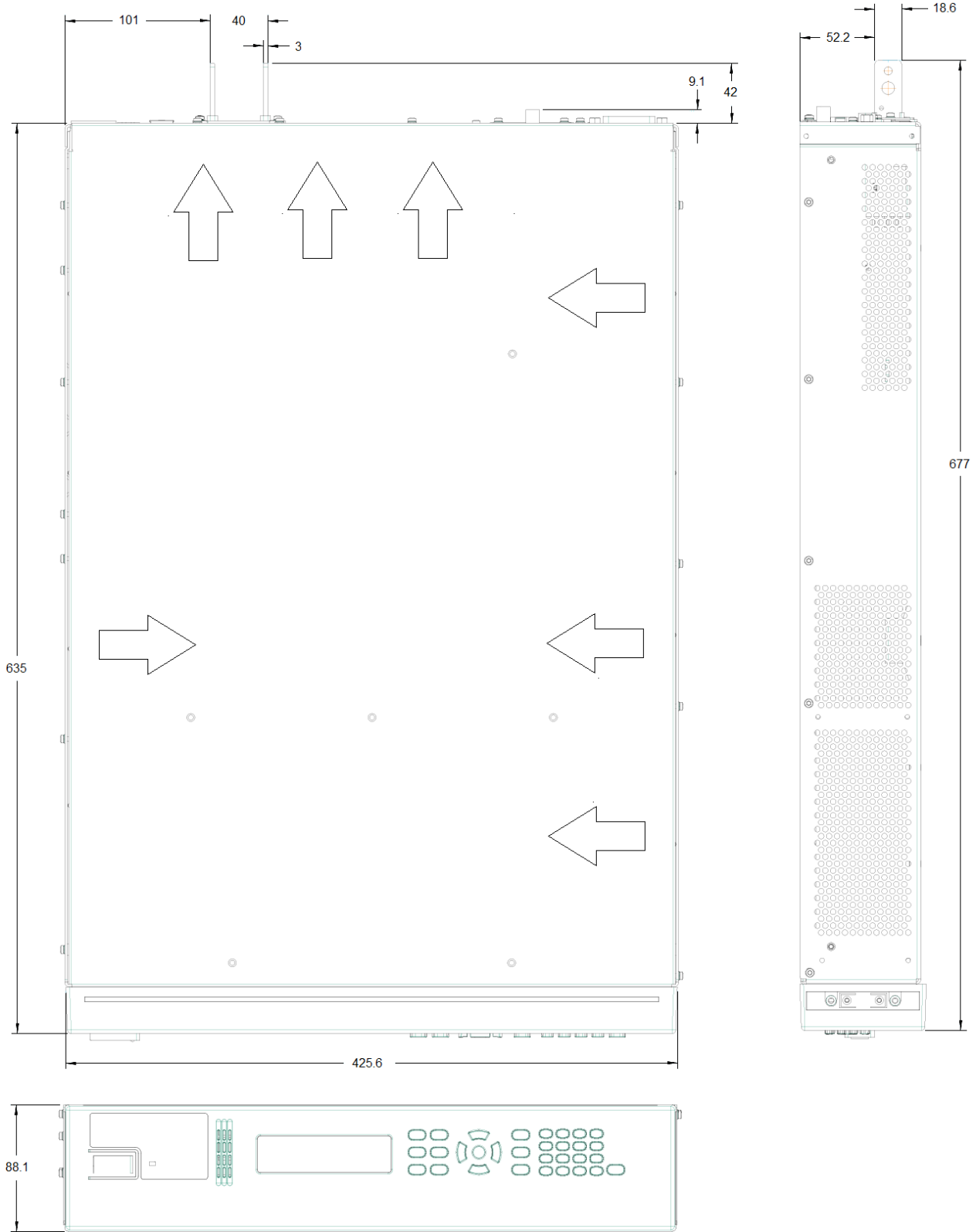
2 kW Models

Operating Information

Introduction to the Instrument

Installing the Instrument

Getting Started

Using the Advanced Power System

Using the Power Assistant Software

Introduction to the Instrument

Advanced Power System at a Glance

Front Panel at a Glance

Front Panel Display at a Glance

Front Panel Keys at a Glance

Rear Panel at a Glance

Power Dissipator at a Glance

The Advanced Power System (APS) includes 1U and 2U rack-mountable DC power supplies and power dissipators with performance and features that are optimized for automated test systems.

The APS models are available in power levels of 1 kW and 2 kW. Voltage levels range from 9 V to 80 V. Current levels range from 12.5 A to 200 A.

The output and system features are described as follows. Not all output features are available on every power supply. The Models and Options section describes the features that apply only to specific models.

Output features

- Full programming capability is provided for the entire range of output voltage and current

- Output can operate in voltage priority or current priority mode

- High-speed up and down output programming

- Output resistance programming

- Turn-on/turn-off delays allow output on/off sequencing across multiple units

- Current sharing capability for paralleled outputs

- Protection capability includes over-voltage, over-current, over-temperature, and open sense lead detection

- Two-quadrant operation provides current sourcing and sinking capability

- 10% rated current-sink capability standard; 100% rated current-sink capability with N7909A power dissipators

- Output disconnect relays on N7900 models (Polarity reverse relays not included on models N7950A and N7970A)
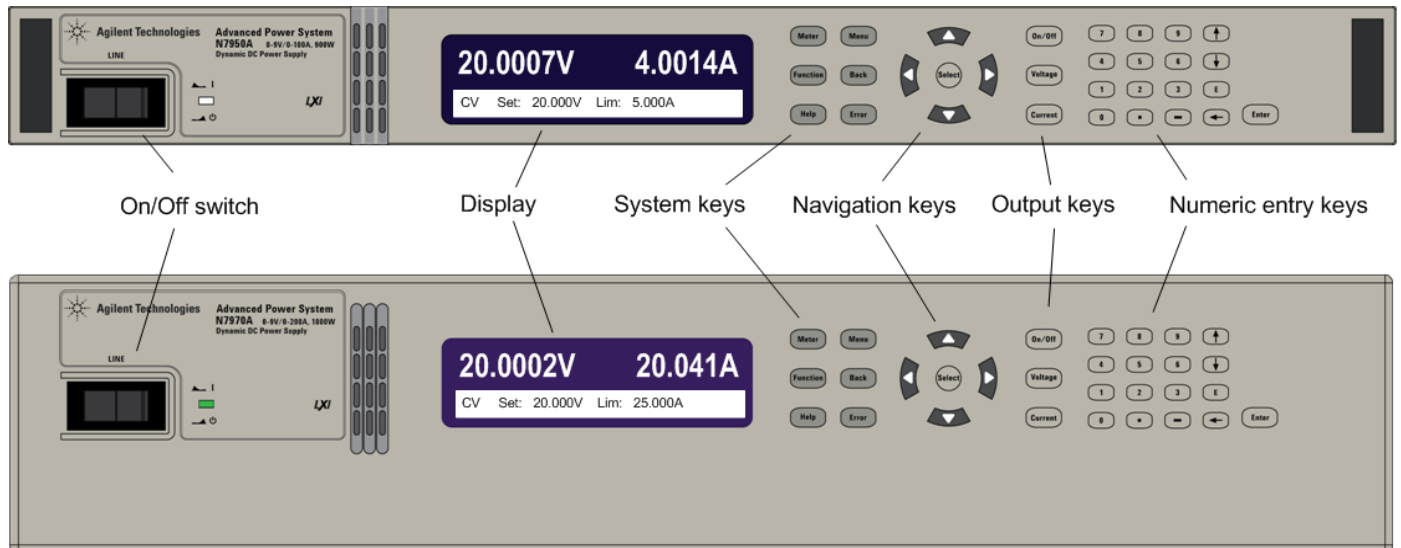
Measurement features

- 5.12 μs sample rate

- Real-time power measurements

- Amp-Hour and Watt-Hour Measurements

- Seamless current measurements across ranges on N7900 models

- Digitized measurement capability on N7900 models

- Continuous "external" data logging on N7900 models

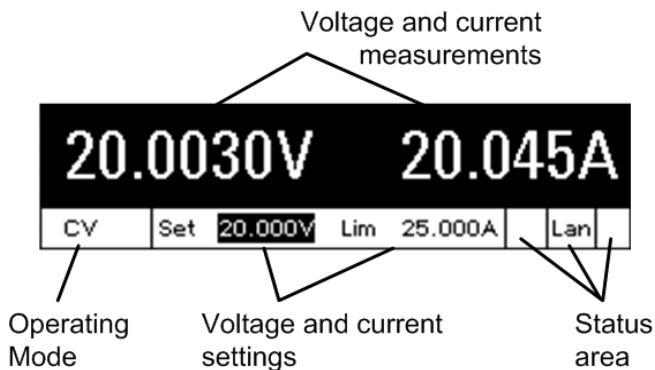- Continuous "Black Box" data recording available as an installable accessory

System features

- Save and recall up to 10 instrument states in non-volatile memory

- Customized signal routing capability

- GPIB (IEEE-488), LAN, and USB remote programming interfaces are built in

- Front panel menu setup for GPIB and LAN parameters

- LXI Core 2011 compliant, including a built-in Web server

- SCPI (Standard Commands for Programmable Instruments) compatibility

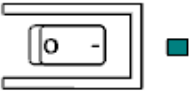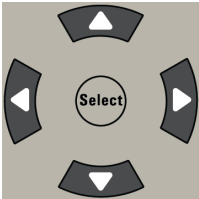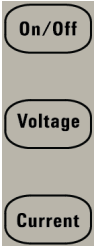## Front Panel at a Glance

Front Panel Display at a Glance

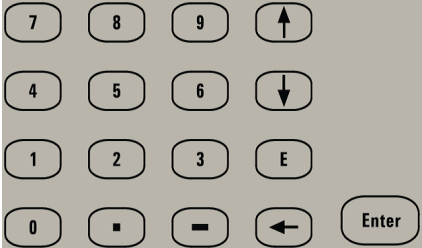|	
Voltage and current measurements	Displays the actual output voltage and current
Operating mode	Indicates one of the following: OFF = the output is off CV = the output is in constant voltage mode CC = the output is in constant current mode CP+ = the output is disabled by the positive power limit CP− = the output is disabled by the negative power limit VL+ = the output is in positive voltage limit mode CL+/− = the output is in positive or negative current limit mode OV = the output is disabled by the over-voltage protection OV− = the output is disabled by the negative over-voltage protection OC = the output is disabled by the over-current protection OT = the over-temperature protection has tripped PF = the output is disabled by a power-fail condition SF = a sense lead fault has been detected P = the instrument has been paralleled with another instrument Inh = the output is disabled by an external inhibit signal Unr = the output is unregulated Prot = the output is disabled by a protection condition on another unit Edp = the output is disabled by excessive output dynamics protection UProt = a user-defined protection signal has disabled the output IPK+/− = the output is in positive or negative peak current limit CSF = a current sharing fault has occurred
Voltage and current settings	Displays the programmed voltage and current. These settings may not match the measured output voltage or current. For example, in constant voltage operation, if the output current setting (limit) may be set to 1 A, but the actual (measured) output current must be less than 1 A for the output to remain in constant voltage mode. If the Current limit is reached, the output will no longer be operating in constant voltage mode, but will be in current limit mode. In this case, the actual output voltage will now be less than the output voltage setting.
Status area	Indicates the following remote interface activity: Err = an error has occurred (press Error key to display error message) Lan = the LAN is connected and has been configured IO = there is activity on one of the remote interfaces

Front Panel Keys at a Glance

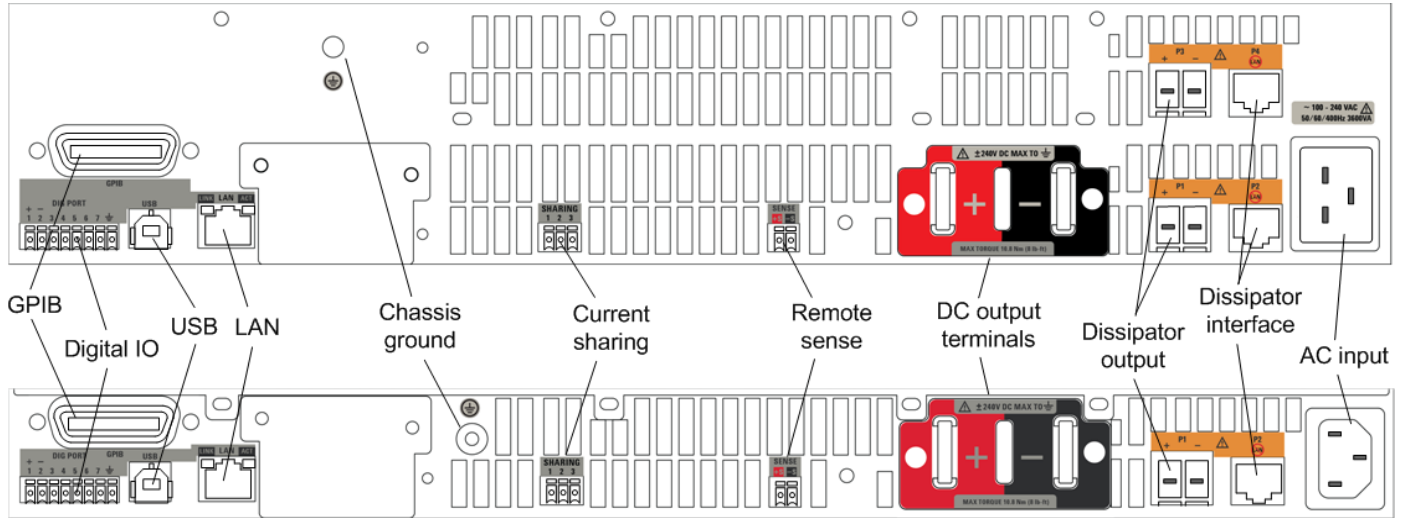The following table lists the main parts of the front panel, generally from left to right:

	The On/Off switch turns the unit on or off. The indicator next to the On/Off switch shows the display status. **Green** indicates normal operation. **Yellow** indicates that the display is in screen saver mode. It is also on during the boot-up process. Press any key to exit screen saver mode.

Meter Menu Function Back Help Error	The System keys access the following front panel meter and command menus: Meter returns the display to metering mode. Menu accesses the command menu. Function key is reserved for future use. Back backs out of a menu without activating any changes. Help accesses information about the displayed menu control. Error displays any error messages in the error queue.
▲ ◄ Select ► ▼	The navigation keys do the following: The Arrow keys move around in the command menus. They also select alpha characters in alpha-numeric entry fields. The Select key lets you make a selection in the command menus. It also lets you enter edit mode for editing the numeric parameters.
On/Off Voltage Current	The Output keys do the following: On/Off controls the output. Voltage lets you change the voltage setting. Current lets you change the current setting.
7 8 9 ↑ 4 5 6 ↓ 1 2 3 E 0 . − ← Enter	The Numeric entry keys do the following: The 0 through 9 keys enter numbers. The (.) key is the decimal point. The – key is used to enter a minus sign. The up/down arrow keys increment or decrement voltage or current settings. They also select letters in alphabetic entry fields. The E key enters an exponent. Add the value to the right of the E. The Backspace key deletes digits as it backspaces over them. The Enter key enters a value. If you exit a field without pressing the Enter key, the value is ignored.

NOTE   Press the Help key to get context sensitive help.

Rear Panel at a Glance

The following table lists the main parts of the rear panel, generally from left to right:

GPIB	The GPIB interface connector
Digital IO	The digital IO pins
USB	The USB interface connector
LAN	The LAN interface connector
Chassis ground	The chassis ground terminal. Provides an earth ground
Current sharing	The current sharing connector
Remote sense	The remote sense terminals
DC output	The positive and negative output terminals
P1 Dissipator output	Power connections to the N7909A. 1 kW power supplies require one power dissipator. 2 kW power supplies require two power dissipators to sink the rated output power.
P2 Dissipator interface	Power dissipator interface. One interface required per dissipator. Only connect the supplied CAT6A cable to the P2 interface.
AC input	The AC lint input

WARNING   **For protection from electrical shock, the power cord ground must not be defeated. If only a two-contact electrical outlet is available, connect the instrument's chassis ground screw (see above) to a good earth ground.**

Power Dissipator at a Glance

Status LED   Error LED   Current input   Interface
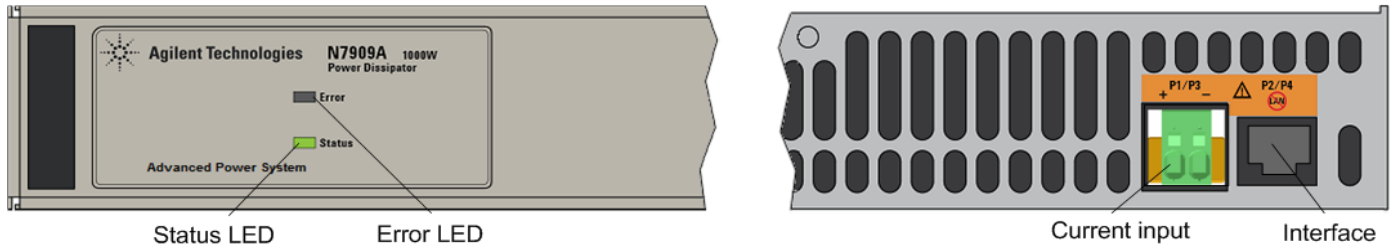
The following table lists the main parts of the front and rear panels:

Status LED	Green - the N7909A has been recognized by the power supply and is fully operational. Yellow - power is available, but no communication established with the power supply.
Error LED	Red - a fault has occurred. This can occur because a cable has been disconnected or because of a hardware failure. The LED will flash in case of a thermal overload.
P1/P3 Current input	The power connections to the power supply. 1 kW power supplies require one power dissipator. 2 kW power supplies require two power dissipators to sink the rated output power.
P2/P4 Interface	The N7909A interface. One interface connection is required for each power dissipator. Only connect the supplied CAT6A cable to the P2 interface.

Front Panel Menu Reference

This is an overview of the front-panel menus.

Press the **Menu** key to access the front panel menus.

For a brief tutorial on how to navigate the front panel menu, refer to Use the front panel menu.

Menu Reference

1st Menu Level	2nd Level	3rd Level	Description
Output	Voltage		Programs output voltage settings
	Current		Programs output current settings
	Mode		Programs output priority mode
	Sequence		Displays sequence commands
		Delay	Programs output on/off delay
		Couple	Configures output state coupling
	Advanced		Displays Advanced commands
		Slew	Programs output current or voltage slew rates
		Polarity	Programs output polarity ⬤ N7900 models only
		Resistance	Programs output resistance
		Bandwidth	Programs output voltage bandwidth
		CurrSharing	Enables/disables output current sharing
Measure	Range		Selects voltage and current measurement ranges
	Sweep		Configures measurement sampling and NPLC ⬤ N7900 models only
	NPLC		Number of power line cycles ⬤ N6900 models only
	Window		Selects Rectangular or Hanning window type ⬤ N7900 models only
	Control		Initiates, triggers, and aborts acquisitions; displays trig state
	AhWh		Measures or resets amp-hours and watt hours
	Temp		Displays ambient temperature and over-temperature margin

1st Menu Level	2nd Level	3rd Level	Description
Transient	Mode		Selects voltage and current transient modes
	Step		Configures voltage or current steps and trigger signals
	List		Displays List commands N7900 models only
		Pace	Specifies Dwell or Trigger paced list
		Repeat	Specifies number of list repetitions, or continuous list
		Terminate	Specifies list termination conditions
		Config	Configures individual list step settings
		Reset	Aborts the list and resets all list settings
	Arb		Displays Arb commands N7900 models only
		Repeat	Specifies number of Arb repetitions, or continuous Arb
		Terminate	Specifies Arb termination conditions
		Config	Configures individual Arb settings
	TrigSource		Specifies the transient and CD Arb trigger source
	Control		Initiates, triggers, and aborts transients; displays trig state
Protect	OVP		Configures over-voltage protection settings
	OCP		Configures over-current protection settings
	Inhibit		Configures inhibit input mode settings
	WDog		Configures output watchdog protections settings
	SFD		Enables/disables sense fault detection
	Clear		Clears protection conditions and displays output status
States	Reset		Resets all instrument settings to the reset (*RST) state
	SaveRecall		Saves and recalls instrument settings
	PowerOn		Selects the power-on instrument state

1st Menu Level	2nd Level	3rd & 4th Levels	Description
System	IO		Displays IO commands
		LAN	Displays LAN commands
		Settings	View the currently active network settings
		Modify	Modify the network configuration (IP, Name, DNS, WINS, mDNS, Services)
		Apply	Applies the configuration changes and restarts unit
		Cancel	Cancels the configuration changes
		Reset	Performs an LXI LCI reset of LAN settings and restarts
		Defaults	Resets the network to the as-shipped defaults and restarts
		USB	Displays USB identification string
		GPIB	Display or change the GPIB address
		DigPort	Displays DigPort commands
		Pins	Configures the individual digital port pins
		Data	Reads/writes data to the digital port
	BBR		Displays Black Box Recorder commands
		Status	Displays the BBR status
		Period	Configures the BBR logging period
		Snapshot	Takes a snapshot of the BBR data
	Signal		Displays signal commands
		Define	Defines the individual signal expressions
		Couple	Configures the output on/output couple source
		Protect	Configures the user-protection function
		Status	Configures the user-status source
		Threshold	Configures the signal threshold comparators

				Description
Preferences				Displays Preferences commands
	Clock			Sets the real-time clock for the Black Box Recorder
	Display			Configures the screen saver and start-up meter view
	LineFreq			Sets the line frequency preferences
	Lock			Locks the front panel keys with a password
	Relay			Sets the output relay preferences N7900 models only
Admin				Displays Admin commands
	Login			Enter a password to access the Admin functions
	Cal			Displays calibration commands
		Vprog		Calibrates voltage programming
		Curr		Calibrates current programming and measurement
		Misc		Calibrates CMRR, CurrTC, CurrSharing, and ResBout
		Count		View the calibration count
		Date		Saves the calibration date
		Save		Saves the calibration data
	IO			Enables/disables the LAN, USB, and GPIB
	Sanitize			Performs NISPOM secure erase of all user data
	Update			Password protected firmware update
	Password			Changes the admin password
About				Displays model, options, serial number, and firmware

Installing the Instrument

Before Installation or Use

Single Unit Connections

Parallel Connections

Series Connections

Power Dissipator Connections

Interface Connections

Rack Mounting

Black Box Recorder

Before Installation or Use

Inspect the Unit

When you receive your APS unit, inspect it for any obvious damage that may have occurred during shipment. If there is damage, notify the shipping carrier and nearest Agilent Sales and Support Office immediately. Refer to www.agilent.com/find/assist.

Until you have checked out the unit, save the shipping carton and packing materials in case the unit has to be returned.

Check for Items Supplied

Before getting started, check the following list and verify that you have received these items. If anything is missing, please contact your nearest Agilent Sales and Support Office.

N6900/N7900 Items	Description	Part Number
Power Cord	A power cord suitable for your location	Call the Agilent Sales and Support Office
Product Reference CD	Includes software and documentation	Agilent N7900-13601
Automation-Ready CD	Contains Agilent IO Libraries Suite	Agilent E2094N
Digital connector plug	8-pin connector for the digital port	Agilent 1253-6408; Phoenix Contact 1840421
Sharing connector plug	3-pin connector for the sharing port	Agilent 0360-3038; Phoenix Contact 1840379
Sense cable	2-pin + and - sense wire cable	Agilent 5190-4501 Plug only: Agilent 1253-8485; Phoenix Contact 1952267
Safety cover	Safety cover for output bus bars	Agilent 5003-1126
Calibration certificate	Calibration certificate referenced to serial number	N/A
N7909A Items	**Description**	**Part Number**
Installation sheet	Contains installation information	N7909-90001
Dissipator power cable plugs	2 connector plugs for fabricated cable	Agilent 0360-3050; Phoenix Contact 1718481
Dissipator interface cable	1 m cable (CAT6A) for interface connections	Agilent 8121-2314

Review Safety Information

This power supply is a Safety Class 1 instrument, which means it has a protective earth terminal. That terminal must be connected to earth ground through a power source equipped with an earth ground. Refer to the Safety Summary page for general safety information. Before installation or operation, check the power supply and review this guide for safety warnings and instructions. Safety warnings for specific procedures are located at appropriate places throughout this guide.

Observe Environmental Conditions

WARNING   **Do not operate the instrument in the presence of flammable gases or fumes.**

The environmental conditions of the power supply are documented under Specifications. Basically, the unit should only be operated indoors in a controlled environment. Do not operate the unit in areas where the ambient temperature exceeds +55 degrees Celsius. This applies for rack-mounting as well as for bench use.

Provide Adequate Air Flow

CAUTION   Do not block the air intake at the sides of the instrument or the exhaust at the rear of the instrument.

The dimensions of your power supply as well as an outline diagram are given under Specifications. Fans cool the power supply by drawing air through the sides and exhausting it out the back. The unit must be installed in a location that allows sufficient space of at least 2 inches (51 mm) at the sides and back of the unit for adequate air circulation.

Single Unit Connections

Line Cord Connection

Output Connections

Single Load Connections

Multiple Load Connections

Remote Sense Connections

Additional Load Considerations

Line Cord Connection

| WARNING | **FIRE HAZARD Use only the power cord that was supplied with your instrument. Using other types of power cords may cause overheating of the power cord, resulting in fire.** |

SHOCK HAZARD The power cord provides a chassis ground through a third conductor. Be certain that your power outlet is of the three-conductor type with the correct pin connected to earth ground.

Connect the power cord that was supplied with your unit to the AC mains connector on the rear of the unit. If the wrong power cord was shipped with your unit, contact your nearest Agilent Sales and Support Office.

The AC input on the back of your unit is a universal AC input. It accepts nominal line voltages in the range of 100 VAC to 240 VAC. The frequency can be 50 Hz, 60 Hz, or 400 Hz.

| NOTE | The detachable power cord may be used as an emergency disconnecting device. Removing the power cord will disconnect AC input power to the unit. Ensure that the power cord is accessible. |

Operation With AC Mains Circuits Rated Below 180 VAC

AC mains circuits rated at 100-120 VAC cannot supply enough current to power either the 1 kW or the 2 kW models when operated at their full rated output power. When connected to a 100-120 VAC mains, the instrument turns off the output and sets either the CP+ or PF status bit when the output power exceeds 700 W.

Sense Connections

A sense cable is shipped along with your instrument. Install the sense cable between the sense connector to the output terminals. Insert the plug into the sense connector and attach the spade connectors to the screws provided on the output terminals.
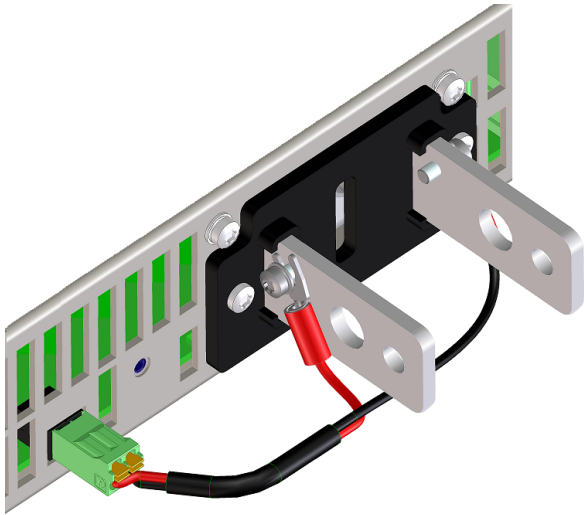
| CAUTION | Observe polarity when installing the sense cable. |

If the sense cable is not installed prior to instrument turn-on or becomes disconnected, the instrument responds with a sense fault (SF) status indication on the front panel. The unit will continue to operate, but the voltage at the output terminals will be approximately 1% higher than the programmed value. Once the sense cable is connected, instrument status and operation returns to normal.

Output Connections

| WARNING | **SHOCK HAZARD Turn off AC power before making rear panel connections.** |

The following factors should be considered when wiring the load to the power supply:

- Load wire current carrying capacity
- Load wire insulation rating (must be equivalent to the maximum output voltage)
- Load wire voltage drop
- Load wire noise and impedance effect

Wire Size

| WARNING | **FIRE HAZARD To satisfy safety requirements, load wires must be large enough not to overheat when carrying the maximum short circuit current of the power supply. If there is more than one load, then any pair of load wires must be capable of safely carrying the full-rated current of the supply. Paralleled load wires may be required for larger-ampacity power supplies.** |

The following table lists the characteristics of AWG (American Wire Gauge) copper wire.

AWG	Equivalent mm^2	Nearest Metric size	Ampacity (Note1)	Resistance (Note2)
18	0.823	1.0 mm^2	14	6.385
16	1.31	1.5 mm^2	18	4.016
14	2.08	2.5 mm^2	25	2.526
12	3.31	4 mm^2	30	1.589
10	5.26	6 mm^2	40	0.9994
8	8.37	10 mm^2	60	0.6285
6	13.30	16 mm^2	80	0.3953
4	21.15	25 mm^2	105	0.2486
2	33.62	35 mm^2	140	0.1564
1/0	53.48	70 mm^2	195	0.0983
2/0	67.43	70 mm^2	225	0.0779
3/0	84.95	95 mm^2	260	0.0618

Note 1. Ampacity is based on 26-30 °C ambient temperature with the conductor rated at 60 °C. Ampacity decreases at higher temperatures.
Note 2. Resistance is in ohms/1000 feet, at 20 °C wire temperature.

Along with conductor temperature, you must also consider voltage drop when selecting wire sizes. The power supply will tolerate a voltage drop of 1 V per lead while maintaining the specified output programming and measurement accuracy (see N6900 and N7900 specifications). Voltage drops of up to 25% of the rated output voltage per lead will be tolerated with only slightly reduced output programming and measurement accuracy. Of course, any voltage drop in the load leads reduces the maximum voltage available at the load. The load lead drop must be subtracted from the rated voltage of the power supply to determine the maximum voltage available at the load.
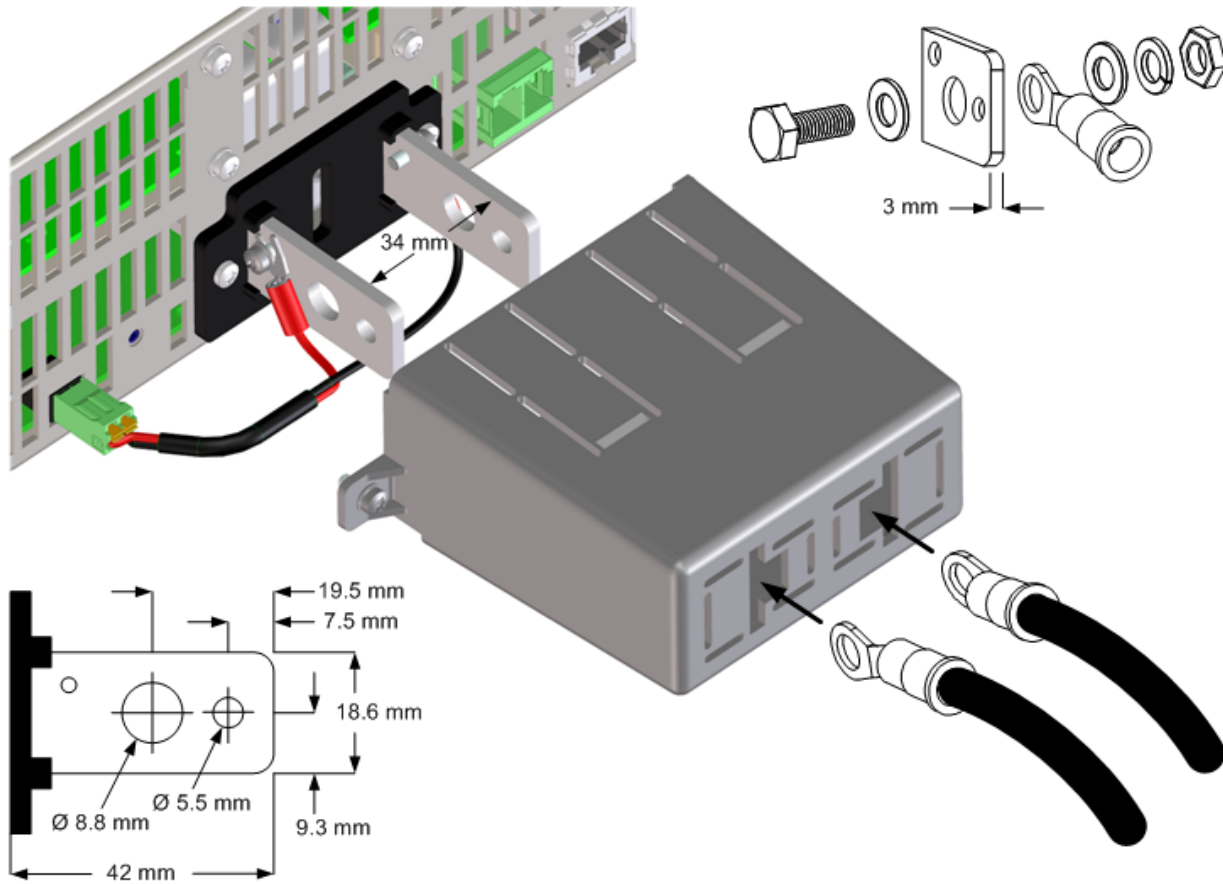
Single Load Connections

CAUTION   Tightening torque cannot exceed 10.8 Nm (8 lb-ft).

1. As shown in the following figure, terminate all load wires with wire terminal lugs securely attached. DO NOT use unterminated wires for load connections at the power supply.

2. Route the wires through the safety cover before attaching them to the bus bars. Knockouts are provided on for larger diameter wires. The figure illustrates the recommended hardware for connecting wires to the bus bars. You must provide all cabling and mounting hardware. Ensure that the wire-mounting hardware does not short the output terminals.

3. Attach the wire terminals to the inside of the bus bars to ensure enough space for installing the shield. Twist or bundle the load wires to reduce lead inductance and noise pickup. The goal is to always minimize the loop area or physical space between the + and - output leads from the power supply to the load.

4. Attach the safety cover to the rear panel. Note that heavy wiring cables must have some form of strain relief to prevent bending the safety cover or bus bars.

Multiple Load Connections

If you are using local sensing and are connecting multiple loads to one output, connect each load to the output terminals using separate connecting wires as shown in the following figure. This minimizes mutual coupling effects and takes full advantage of the power supply's low output impedance. Keep each pair of wires as short as possible and twist or bundle them to reduce lead inductance and noise pickup. The goal is to always minimize the loop area or physical space between the + and - output leads from the power supply to the load.

If load considerations require the use of distribution terminals that are located away from the power supply, twist or bundle the wires from the output terminals to the remote distribution terminals. Connect each load to the distribution terminals separately. Remote voltage sensing is recommended under these circumstances. Sense either at the remote distribution terminals or, if one load is more sensitive than the others, directly at the critical load.
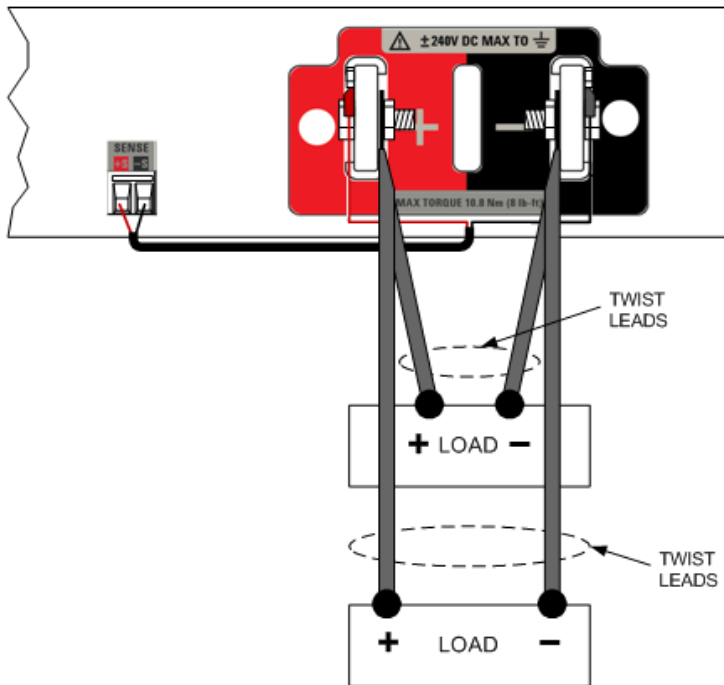
Remote Sense Connections

Remote sensing improves the voltage regulation at the load by monitoring the voltage there instead of at the output terminals. This allows the power supply to automatically compensate for the voltage drop in the load leads. Remote sensing is especially useful for CV operation with load impedances that vary or have significant lead resistance. It has no effect during CC operation. Because sensing is independent of other power supply functions, remote sensing can be used regardless of how the power supply is programmed.
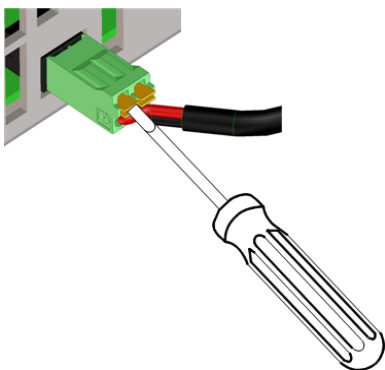
Connect the unit for remote sensing by first removing the sense cable between sense and load terminals.

| NOTE | Push in the orange release tabs with a small flat-blade screwdriver to release and insert the sense wires. |

Keep sense wire size between AWG 16 (1.5 mm^2) maximum and AWG 24 (0.2 mm^2) minimum.

Strip wire insulation back 10 mm.

Make your connections as shown in the following figure. Connect the load to the output terminals using separate connecting wires. Keep the wire-pair as short as possible and twist or bundle it to reduce lead inductance and noise pickup. Keep load leads under 14.7 meters (50 feet) per lead because of inductance effects.

Connect the sense leads as close to the load as possible. Do NOT bundle the sense wire-pair together with the load leads; keep the load wires and sense wires separate. Sense wiring can be of a lighter gauge than the load wiring. The sense leads can carry up to 1 mA of current without degrading the current measurement. Note however, that any voltage drop in the sense leads can degrade the output voltage regulation. Try to keep the sense lead resistance less than about 0.5 Ω per lead (this requires 20 AWG or heavier for a 50 foot length).
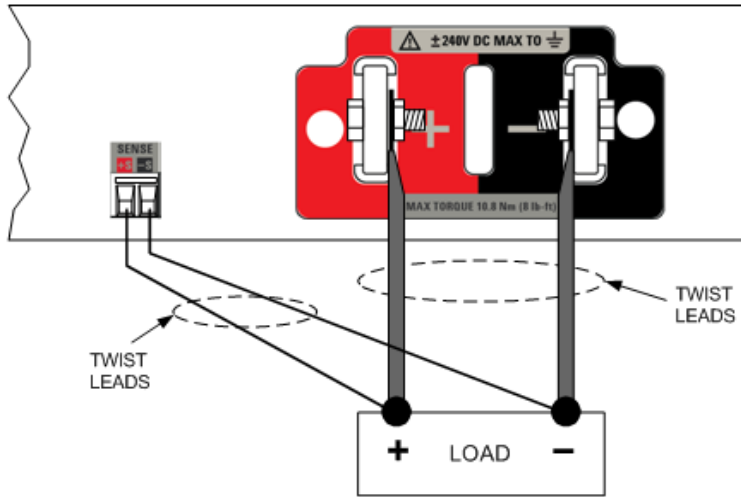
Open/Shorted/Reverse Sense Lead Detection

The sense leads are part of the output's feedback path. Connect them in such a way so that they do not inadvertently become open circuited. When an open sense lead is detected prior to output turn-on or while the output is on, the instrument responds with a sense fault (SF) status indication on the front panel. The response time is about 50 microseconds. You can use the Advanced Signal Routing capability to turn this fault into an output protection feature. Otherwise, the power supply returns to local sensing mode, with the voltage at the output terminals approximately 1% higher than the programmed value. Once the sense wires are reconnected, instrument status and operation returns to normal.

You can disable this feature if it creates objectionable disruptions at the DUT or if the lead configuration or load dynamics cause the system to falsely trip.

Front Panel	SCPI Command
Select **Protect\SFD** Check Enable sense fault detection to enable; uncheck to disable. Then press **Select**.	To enable/disable sense fault detection: SENS:FAUL:STAT ON|OFF

Shorted sense leads are detected by the over-voltage protection function. This function is not programmable and results in the output being disabled due to an over-voltage fault (OV).

Reversed sense leads are detected by the negative over-voltage protection function. This function is not programmable and results in the output being disabled due to a negative over-voltage fault (OV-).

NOTE   It is very important to make sure the sense wires are connected properly. This is because the over-voltage protection cannot detect sense lead mis-wiring without enabling the output, thereby briefly subjecting the load to unintended voltages.

Over-voltage Protection

Over-voltage protection (OVP) provides a configurable over-voltage protection based on sense lead voltage. Having the OVP circuit monitor the sense lead voltage rather than the output terminal voltage allows for more precise voltage monitoring directly at the load. Since incorrect sense wiring could defeat this feature, there is also a backup local OVP function. Refer to Programming Output Protection for further information.

The backup local OVP function tracks the programmed OVP setting and trips if the voltage at the + and - output terminals rises more than 1V + 10% of the unit's voltage rating above the programmed OVP setting.

Output Noise

Any noise picked up on the sense leads will appear at the output terminals and may adversely affect CV load regulation. Twist the sense leads or use a ribbon cable to minimize the pickup of external noise. In extremely noisy environments it may be necessary to shield the sense leads. Ground the shield at the power supply end only; do not use the shield as one of the sensing conductors.

The noise specifications documented under Specifications apply at the output terminals when using local sensing. However, voltage transients may be produced at the load by noise induced in the leads or by load current transients acting on the inductance and resistance of the load lead. If it is desirable to keep voltage transient levels to a minimum, place an aluminum or tantalum capacitor, with an approximate value of 10 microfarad per foot (30.5 cm) of load lead, right across the load.

Additional Load Considerations

Response Time With External Capacitor

When programming with an external capacitor, voltage response time may be longer than that for purely resistive loads. Use the following formula to estimate the additional up-programming response time:

$$\text{Response Time} = \frac{\text{(added output capacitor)} \times \text{(change in Vout)}}{\text{(current limit setting)} - \text{(load current)}}$$

Note that programming into an external output capacitor may cause the power supply to briefly enter constant current or constant power operating mode, which adds additional response time. By setting the proper voltage slew rate when using an external capacitor, it may be possible to prevent mode crossover into constant current.

Positive and Negative Voltages

Either positive or negative voltages with respect to ground can be obtained from the output by grounding (or "commoning") one of the output terminals. Always use two wires to connect the load to the output regardless of where or how the system is grounded. The power supply can be operated with any output terminal ± 240 VDC including output voltage from ground.

NOTE   The APS models are optimized for grounding the negative output terminal. Grounding the positive terminal may result in increased current measurement noise and a reduction in current measurement accuracy.

Parallel Connections

Parallel Description

Sharing Cable Fabrication

Load, Sense, and Sharing Connections

Parallel Description

Connecting power supplies in parallel provides a greater current capability than can be obtained from a single unit. The use of current sharing is highly recommended (for further information refer to Current Sharing Operation). Note that units can be operated in parallel without using the current sharing function, but the output current will not be shared equally and constant voltage mode operation may not be maintained on all units.

CAUTION	**To Prevent Possible Equipment Damage:**

- Connect no more than five units **of identical voltage ratings** in parallel.

- Always connect the **negative** output terminals of all current-sharing units together to prevent damaging the Sharing bus.

Current sharing considerations:

- The **Sharing** terminals must be connected for current sharing operation as shown in the figure under Load, Sense, and Sharing Connections. If the Sharing cable is disconnected, the paralleled units will still operate, but will not share current or maintain constant voltage mode operation.

- Turn the outputs on and off together for clean output on/off operation. It is recommended to use the digital I/O pins to couple the output turn-on/turn-off transitions between the units as described under Output Sequence Control.

- Do not use local sensing if there can be a voltage drop greater than 0.5% of the voltage rating of the units as measured from the local sense points of any unit to the local sense points of any other paralleled unit. Use remote sensing as shown under Load, Sense, and Sharing Connections.

Sharing Cable Fabrication

A connector plug is supplied with each unit, but the cable itself must be fabricated. You must provide the cable wiring. The following figure illustrates the cable assembly. Note that pin 1 is not used. Briefly:

- Keep wire size around AWG 20 or 22 (0.5 mm^2).

- Strip wire insulation back 7 mm.

- Insert the wires into the connector and tighten the screw terminal.

- Twist or bundle the wires to reduce noise. Shielding is not required.

- Connect pins 2 together; connect pins 3 together.

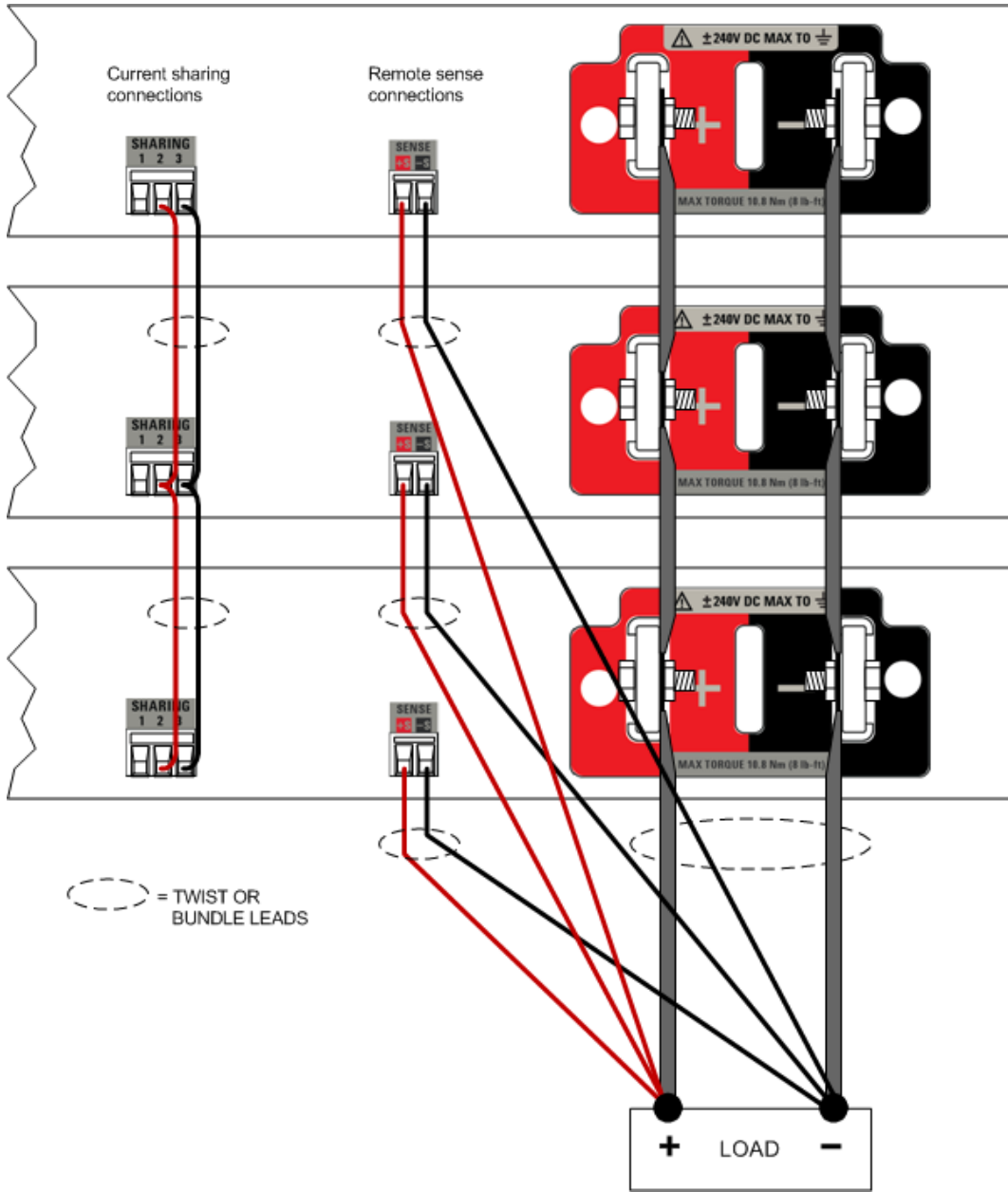Agilent N6900/N7900 Series Operating and Service Guide

Load, Sense, and Sharing Connections

The following figure shows how to connect three units in parallel. Note the following recommendations:

- Install the paralleled units relatively close to each other in a stacked configuration.

- Bus bars can be used instead of cables to parallel the output terminals in a stacked configuration. Place the bus bars on the inside of the output terminals.

- Keep the wiring from the power supplies to the load as short as possible and twist or bundle the leads to reduce lead inductance and noise pickup. The goal is to always minimize the loop area or physical space between the + and - output leads from the power supply to the load.

- If the units cannot be located close together, a symmetrical arrangement of separate load-wire pairs of equal length connecting to a common load point is highly recommended. This provides the best possible dynamic response.

- Connect the sense leads of each paralleled unit directly to the load.

Although the following figure shows the recommended use of remote sensing, local sensing may be used if absolutely necessary. However, with local sensing, the sharing circuits will work properly only if the voltage drop measured *between* the local sense points of any unit to the local sense points of any other paralleled unit is less than 0.5% of the maximum voltage rating of the units.

Current sharing connections

Remote sense connections

= TWIST OR BUNDLE LEADS

SHARING 1 2 3

SENSE

± 240V DC MAX TO

MAX TORQUE 10.8 Nm (8 lb-ft)

LOAD

Series Connections

Series Description

Load, Sense, and Diode Connections

Series Diode Considerations

Capacitance Limits

Series Description

Connecting power supplies in series provides a greater voltage capability than can be obtained from a single unit. Note the following important considerations:

- If your device under test does not have any energy sourcing ability such as a battery, power supply, or large energy storage device, the power supplies can be connected and operated in series. Observe all applicable warnings and cautions (see below).

- If your device under test includes a small capacitance, it is may be acceptable to connect power supplies in series in most cases. Refer to the Capacitance Limits table at the end of this section for detailed information.

- Always use series connections **with a series protection diode** when devices such as large capacitors, power supplies, batteries, or any other energy sources that may force current back into the power supply are connected to the output. This diode protects the units from damage due to reverse current as described under Series Diode Considerations. If using the series diode is not acceptable in your application, please contact Agilent Technologies to speak to a power product support engineer for assistance.

The following warnings and cautions must be followed in all cases:

| **WARNING** | **SHOCK HAZARD Floating voltages must not exceed 240 VDC. No output terminal may be more than 240 VDC from chassis ground.** |

CAUTION **To Prevent Possible Equipment Damage:**

- Only connect units of **identical voltage *and* current ratings** in series.

- Lock the output relays closed on N7900 models. Output relays are not rated to switch voltages higher than the individual instrument rating.

- Always turn the AC power on and off together. Never leave any units powered on while the others are off.

- Always turn the outputs on and off together. It is recommended to use the digital I/O pins to couple the output turn-on/turn-off transitions between the units as described under Output Sequence Control.

- Always program identical voltage settings on all units, and synchronize the voltage up and down programming across units.

- Set the positive current limit to identical values on all series-connected units.

- Set the negative current limit to its **most negative** value, thus allowing each instrument maximum capability to protect itself and balance the voltages.

- Couple the output protection systems of the series-connected units as described under Fault/Inhibit System Protection. This prevents uneven voltage sharing between units if one or more shut down due to a fault condition.

- If the current Sharing cables are connected, do not enable current sharing under any circumstances or the power supply may be damaged. Refer to Enable Current Sharing to disable. To protect the unit in case the current sharing function is accidentally enabled, you should physically disconnect the current sharing cable from the back of the unit.

- Do not use the N7909A power dissipator when connecting power supplies in series. Series connections are not allowed if the power supplies are being used to sink current.

Load, Sense, and Diode Connections

The following figure shows how to connect three units in series. Note the following recommendations:

- To guarantee protection from reverse currents in all cases, it is recommended to always connect a series diode in line with your load as shown.

- Install the units relatively close to each other in a stacked configuration.

- Keep the wiring from the power supplies to the load as short as possible and twist or bundle the leads to reduce lead inductance and noise pickup. The goal is to always minimize the loop area or physical space between the + and - output leads from the power supply to the load.

- If the series diode is being used, connect the sense leads as shown below. Without the diode, connect the +s lead directly to the load.
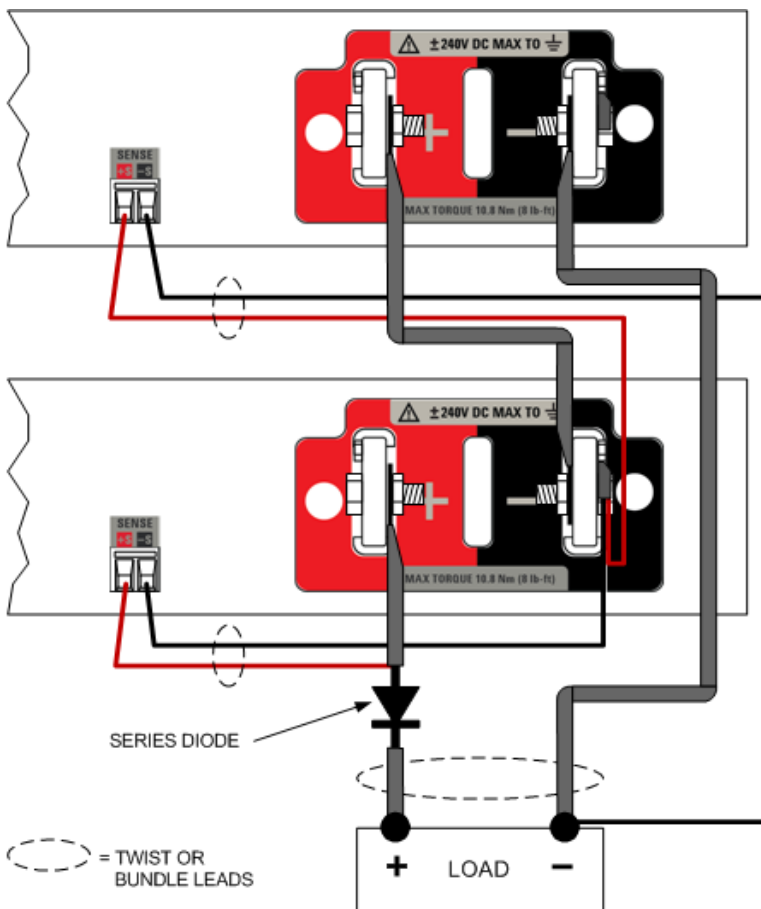
Series Diode Considerations

The series diode protects the power supplies by isolating the potentially harmful external energy source from the power supply outputs, thereby completely eliminating the risk of instrument damage due to reverse currents. The use of the protection diode will not allow current-sinking operation. The power supplies will not be able to down-program the voltage at the load, nor can they act as a load.

The series diode needs to have a reverse voltage rating of at least the sum of the voltage ratings of all the series-connected units. Allow an appropriate margin for voltage overshoots and for the maximum current rating of the series-connected units.

As shown in the figure, the + sense lead of the end unit must be connected to the anode (the power supply side) of the diode, and not to the cathode (the load side) to protect the sense leads from possible damage. Note that this will degrade the voltage regulation and programming accuracy at the load.

To improve programming accuracy, use a DMM to measure the voltage at the load and programmatically compensate for the voltage drop across the diode by adjusting the output voltage of the power supplies. The diode drop will vary depending on output current and temperature.

| NOTE | If using the series diode is not acceptable in your application, please contact Agilent Technologies to speak to a power product support engineer for assistance. |

Capacitance Limits

The following table describes the maximum load capacitance that can be tolerated in a series configuration. If you suspect that your load capacitance exceeds these values, you must install the series diode as previously described.

1 kW Models in series	Maximum load capacitance with 2 units in series	2 kW Models in series	Maximum load capacitance with 2 units in series
N6950A/N7950A	381 µF	N6970A/N7970A	763 µF
N6951A/N7951A	94 µF	N6971A/N7971A	188 µF
N6952A/N7952A	23 µF	N6972A/N7972A	46 µF
N6953A/N7953A	11 µF	N6973A/N7973A	22 µF
N6954A/N7954A	6 µF	N6974A/N7974A	12µF

Power Dissipator Connections

The N7909A Power Dissipator

The N7909A power dissipator is required to provide 100% of the rated current-sink capability of the APS models. For further information about current sinking, refer to Current Sinking Operation.

The dimensions of your power dissipator as well as an outline diagram are given under Specifications. Fans cools the power dissipator by drawing air through the sides and exhausting it out the back. Do not block the air intake at the sides of the instrument or the exhaust at the rear of the instrument. Additional installation requirements are as follows:

- Only install the power dissipator in a location that allows sufficient space of at least 50 mm (2 inches) at the sides and back of the unit for adequate air circulation.

- The power dissipator may be located anywhere near the power supply (above, below, or adjacent), as long as the power dissipator is physically located within 1 meter of the power supply.

- Turn off the power supply before connecting any power dissipator units. The power dissipator is discovered at power-on and is automatically enabled.

- Use only the supplied CAT6A cable for the interface connections. Snap the cable into the **P2** connectors. When installing a second power dissipator on 2 kW units, connect the second CAT6A cable into the **P4** connector on the power supply. Do not use other LAN cables as they will not work properly. The supplied CAT6A cable is shielded and uses the shield as a conductor.

  CAUTION   Never plug the CAT6A cable into the LAN connector, or 01the unit will be damaged.

- Use the fabricated power cable for the power (P1) connections (see below). Snap the cable into the **P1** connectors. When installing a second power dissipator on 2 kW units, connect the second power cable into the **P3** connector on the power supply.

Power Cable Fabrication

Two end-connectors are included with the power dissipator. You must provide the cable wiring. The following illustration provides assembly details. Briefly:

- Keep wire length to one meter or less, or the power supply will not meet its published specifications.
- Keep wire size between AWG 10 (6 mm^2) maximum and AWG 14 (2.5 mm^2) minimum. Wires must carry currents of up to 15 A.
- Strip wire insulation back 15 mm.
- Push the wire straight into the oval opening (1). Observe polarity.
- Twist or bundle the wires to reduce noise.

- To release the wire, insert a small screwdriver into the square release-tab opening (2).

- To release the connector from the unit, push both orange release tabs in together (3) and pull back on the plug.
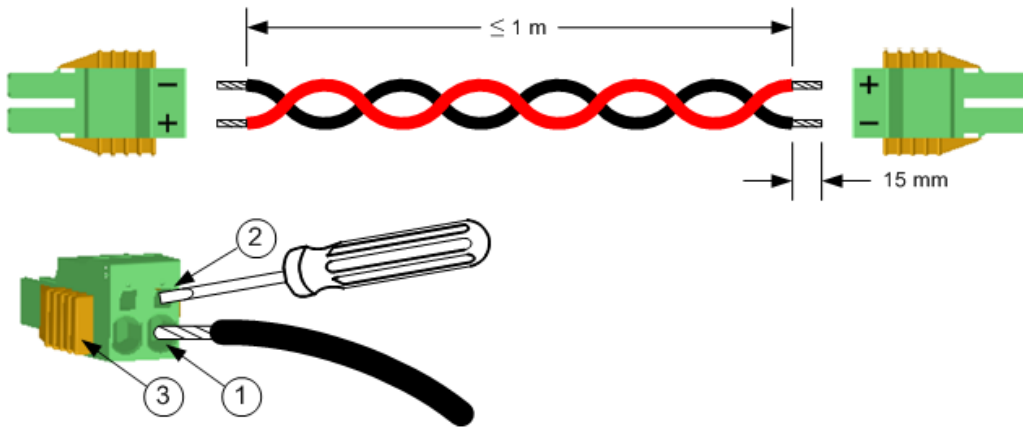
Power Dissipator Connections - 1 kW Units
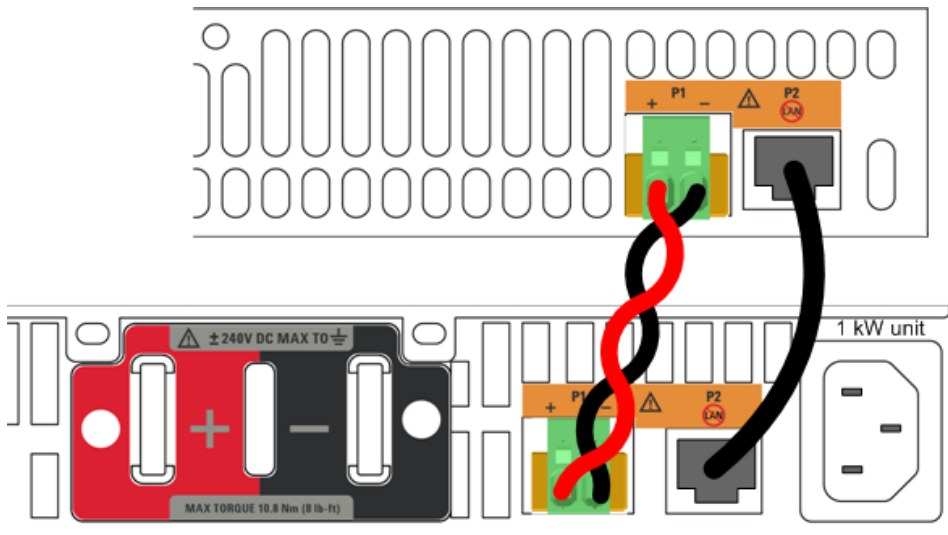
Power Dissipator Connections - 2 kW Units

NOTE If you are using only one power dissipator with your 2 kW power supply, it does not matter if you are connecting to the upper or lower connectors. In this case, you will only be able to dissipate up to 1 kW of output power.
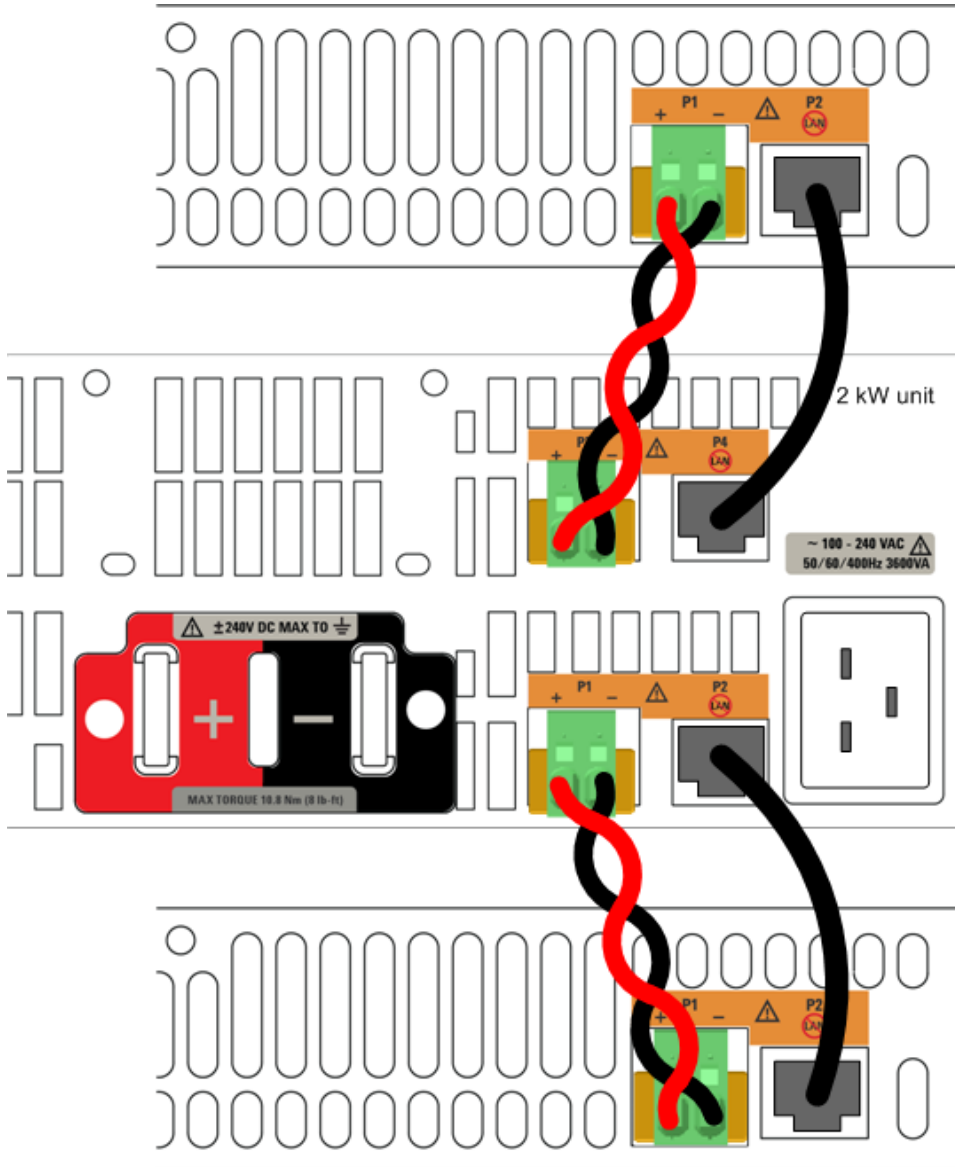
Interface Connections

GPIB Connections

USB Connections

LAN Connections - site and private

Digital Port Connections

This section describes how to connect to the various communication interfaces on your APS. For further information about configuring the remote interfaces, refer to Remote Interface Configuration.

If you have not already done so, install the Agilent IO Libraries Suite from the Automation-Ready CD that is shipped with your instrument.

| NOTE | For detailed information about interface connections, refer to the Agilent Technologies USB/LAN/GPIB Interfaces Connectivity Guide, located on the Automation-Ready CD. |

GPIB Connections

The following figure illustrates a typical GPIB interface system.
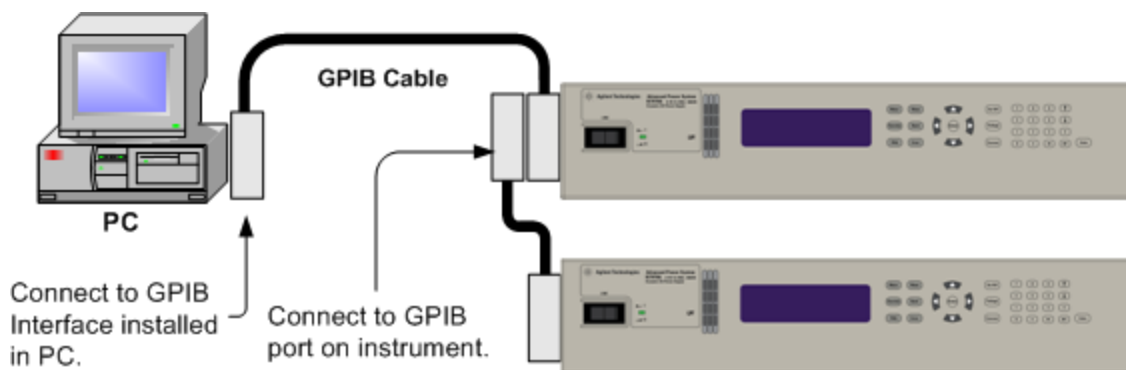
1. Connect your instrument to the GPIB interface card using a GPIB interface cable.

2. Use the Connection Expert utility of the Agilent IO Libraries Suite to configure the GPIB card's parameters.

3. You can now use Interactive IO within the Connection Expert to communicate with your instrument, or you can program your instrument using the various programming environments.

USB Connections

The following figure illustrates a typical USB interface system.
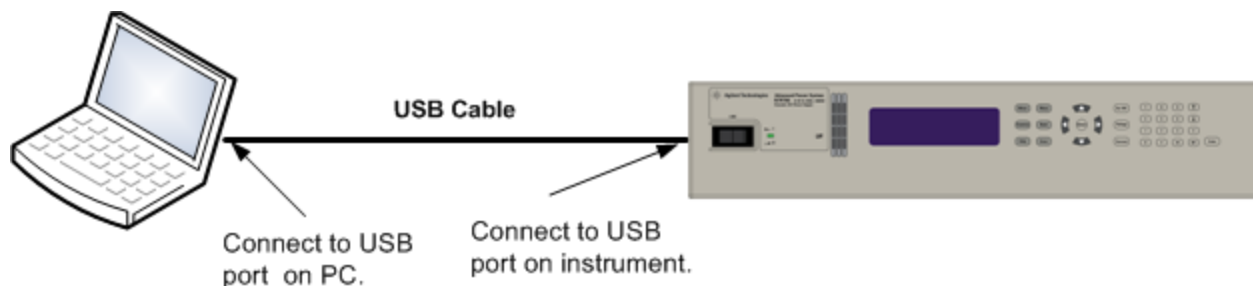
1. Connect your instrument to the USB port on your computer.

2. With the Connection Expert utility of the Agilent IO Libraries Suite running, the computer will automatically recognize the instrument. This may take several seconds. When the instrument is recognized, your computer will display the VISA alias, IDN string, and VISA address. This information is located in the USB folder.

3. You can now use Interactive IO within the Connection Expert to communicate with your instrument, or you can program your instrument using the various programming environments.

LAN Connections - site and private

A site LAN is a local area network in which LAN-enabled instruments and computers are connected to the network through routers, hubs, and/or switches. They are typically large, centrally-managed networks with services such as DHCP and DNS servers. The following figure illustrates a typical site LAN system.
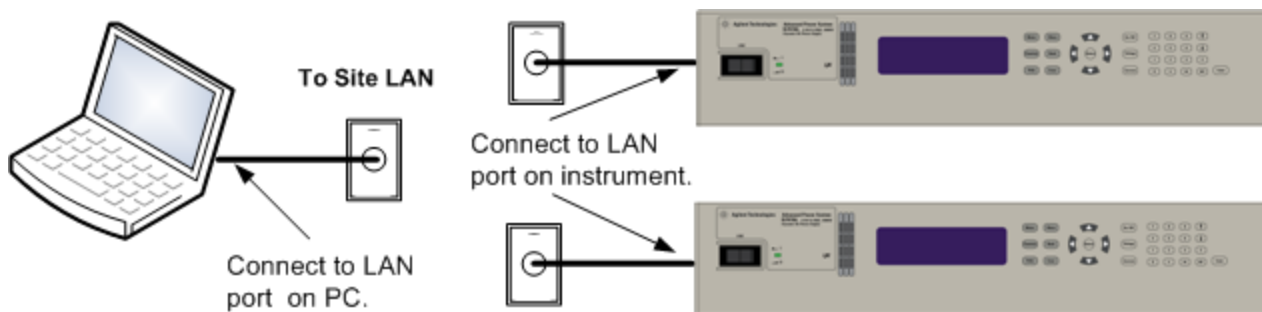
A private LAN is a network in which LAN-enabled instruments and computers are directly connected, and not connected to a site LAN. They are typically small, with no centrally-managed resources. The following figure illustrates a typical private LAN system.
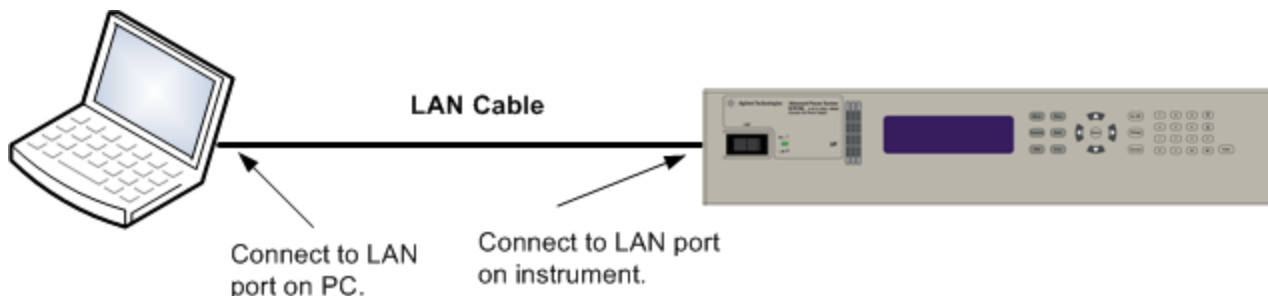
1. Connect the instrument to the site LAN or to your computer using a LAN cable. The as-shipped instrument LAN settings are configured to automatically obtain an IP address from the network using a DHCP server (DHCP is set On). The DHCP server will register the instrument's hostname with the dynamic DNS server. The hostname as well as the IP address can then be used to communicate with the instrument. If you are using a private LAN, you can leave all LAN settings as they are. Most Agilent products and most computers will automatically choose an IP address using auto-IP if a DHCP server is not present. Each assigns itself an IP address from the block 169.254.nnn. The front panel **Lan** indicator will come on when the LAN port has been configured.

2. Use the Connection Expert utility of the Agilent IO Libraries Suite to add the APS models and verify a connection. To add the instrument, you can request the Connection Expert to discover the instrument. If the instrument cannot be found, add the instrument using the instrument's hostname or IP address.

3. You can now use Interactive IO within the Connection Expert to communicate with your instrument, or you can program your instrument using the various programming environments. You can also use the Web browser on your computer to communicate with the instrument as described under Using the Web Interface.

Digital Port Connections

| NOTE | It is good engineering practice to twist and shield all signal wires to and from the digital connector. If shielded wire is used, connect only one end of the shield to chassis ground to prevent ground loops. |

An 8-pin connector and a quick-disconnect connector plug are provided for accessing the digital port functions. Disconnect the connector plug to make your wire connections. The connector plug accepts wires sizes from AWG 14 (1.5 mm^2) to AWG 28 (0.14 mm^2). Wire sizes smaller than AWG 24 (0.25 mm^2) are not recommended. Strip wire insulation back 7 mm.

1. Insert wires

2. Tighten screws

3. Fault/Inhibit configurable pins (observe INH polarity)

4. Output Couple configurable pins

5. Digital IO-configurable or Expression-configurable pins

6. Signal common
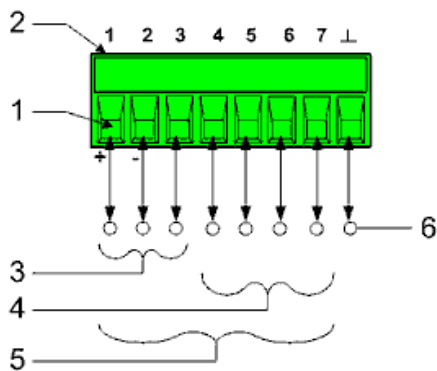
Information on using the digital port is found under Programming the Digital Port. The electrical characteristics are described under Common Characteristics.

Rack Mounting

This section contains information for installing an N7907A Rack Mount Kit. This rack mount kit allows the 1 kW and 2 kW power supplies as well as the power dissipator to be mounted in a 19-inch EIA rack cabinet.

Before getting started, check the following list and verify that you have received these items. If anything is missing, please contact your nearest Agilent Sales and Support Office.

Items Supplied	Agilent Part number
2 pair – Slide rails	5003-1128
2 – 1U rack ears for 1kW units or power dissipator units	5002-2816
2 – 2U rack ears for 2kW units	5063-9212
8 – Clip-nuts for attaching to rack frame (10-32)	0590-0804
4 – Fixed slide attachment screws (10-32 x 0.5)	2680-0104
4 – Movable slide attachment screws (M4 x 12 mm)	0515-1013
6 – Front ear attachment screws (M3 x 8 mm)	0515-0372
4 – Front dress screws (10-32 x 0.625)	0570-1577

Installing the Instrument

CAUTION   Do not block the air intake at the sides of the instrument or the exhaust at the rear of the instrument.

You cannot use standard support rails for rack mounting your instrument as they would block the airflow needed for cooling.

Tools required: Phillips driver, T22 Torx driver, T10 Torx driver.

1. Install eight clip-nuts on the rack frame where your instrument will be located. As shown in the illustration, install three on each front corner; and one on each rear corner.

2. Separate the pieces of each slide rail pair and install the stationary part of each slide to the two clip nuts on the sides of the instrument rack using the four fixed slide rail screws provided.

3. Install the movable part of each slide to the sides of the instrument using the four movable slide rail screws provided. Use location (3a) for the 1 kW units; location (3b) for the 2 kW units, and location (3c) for the power dissipator unit.

4. Install the front panel ears to the instrument using the six front ear screws provided.

5. Slide the instrument into the rack.

6. Attach the front ears to the instrument rack using the four front dress screws provided.
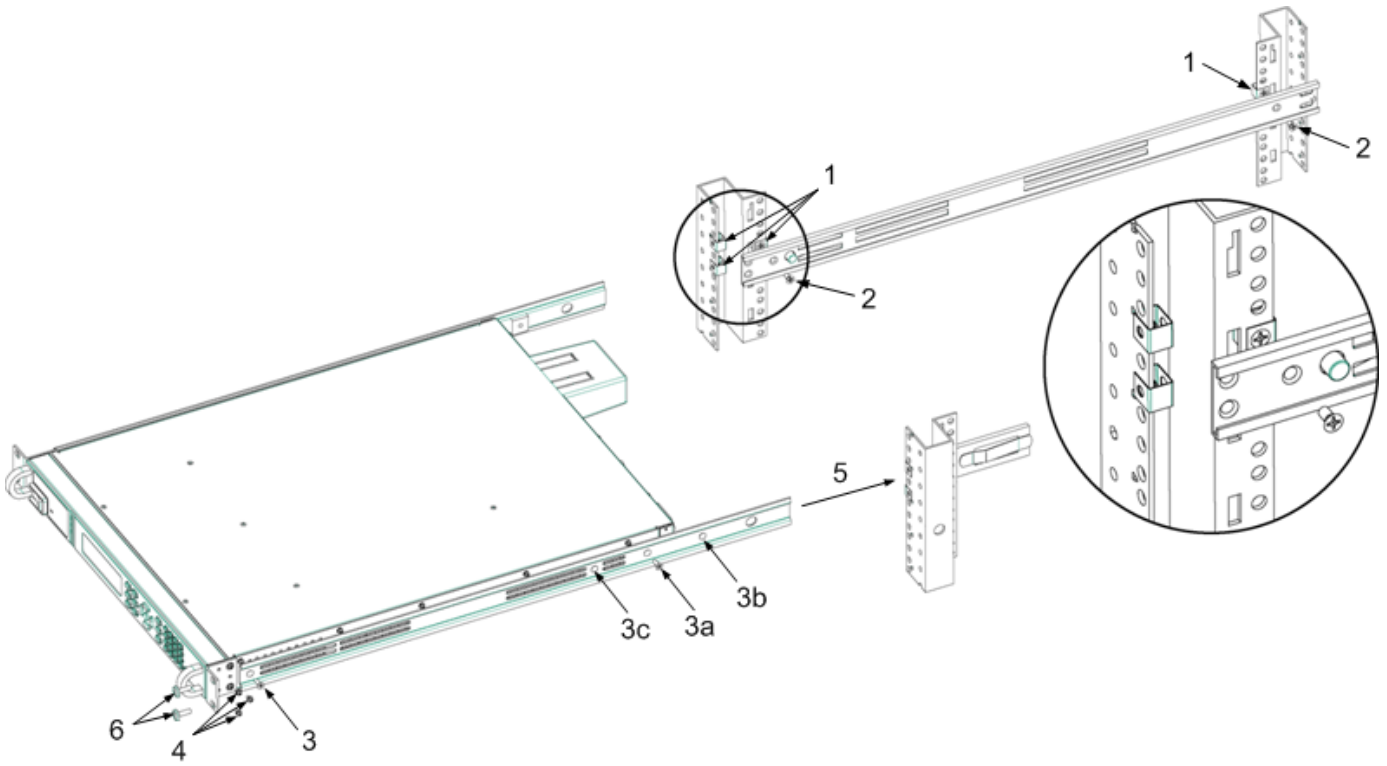
Rack Mounting

Black Box Recorder

The N7908A Black Box Recorder accessory board installs in the Black Box Recorder located on the bottom of the chassis. Refer to Black Box Data Recording for information about using the Black Box Recorder.

Installing the Instrument

CAUTION	Turn off the instrument, remove the power cord, and turn the unit over. Observe all precautions for handling electrostatic discharge sensitive devices when installing the BBR board.

1. Remove the access cover by loosening the two screws.

2. Position the BBR board with the connector facing down and snap it into the unit.

3. Replace the access cover and tighten the screws..

4. Check the box labeled [ ] Option 057 on top of the unit to indicate the option is installed.

Getting Started

Turn the Unit On

Set the Output Voltage

Set the Output Current

Set Over-voltage Protection

Enable the Output

Use Built-in Help System

Turn the Unit On

Verify that the line cord is connected and plugged in.

Turn the unit on with the front panel power switch. The front panel display will light up after a few seconds. A power-on self-test occurs automatically when you turn the unit on. This test assures you that the power supply is operational.

NOTE   It may take about 30 seconds or so for the power supply to initialize before it is ready for use.

If the instrument does not turn on, verify that the power cord is firmly connected (power-line voltage is automatically sensed at power-on). Also make sure that the instrument is connected to an energized power source. If the LED next to the power switch is off, there is no AC power connected. If the LED is amber, the instrument is in standby mode with AC power connected, and if it is green, the instrument is on.

If a self-test error occurs, a message is displayed on the front panel. If the message "Drive failed" appears, refer to Black Box Data Recording. For other self-test errors, see Service and Maintenance for instructions on returning the instrument for service.

Set the Output Voltage

Method 1

Use the left and right navigation keys to navigate to the setting that you wish to change.
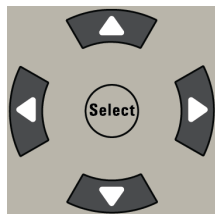
In the following display, the voltage setting is selected. Enter a value using the numeric keypad. Then press **Select**.

You can also use the numeric arrow keys to adjust the value up or down. Values become effective when the output is turned on.

In voltage priority mode, the unit will maintain the output voltage at its programmed setting. In current priority mode, the unit will limit the output voltage when it reaches the specified voltage limit value. Refer to Set the Output Mode for more information.

Method 2

Use the **Voltage** key to select the voltage entry field. In the display below, the voltage setting is selected. Enter the desired setting using the numeric keypad. Then press **Enter**.

If you make a mistake, either use the backspace key to delete the number, press Back to back out of the menu, or press Meter to return to meter mode.

Set the Output Current

Method 1

Use the left and right navigation keys to navigate to the setting that you wish to change.
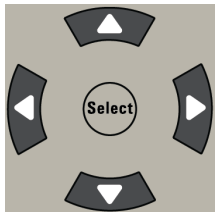
In the display below, the current setting is selected. Use the up and down navigation keys to toggle between the + and - limit entries. Enter a value using the numeric keypad. Then press **Select**.
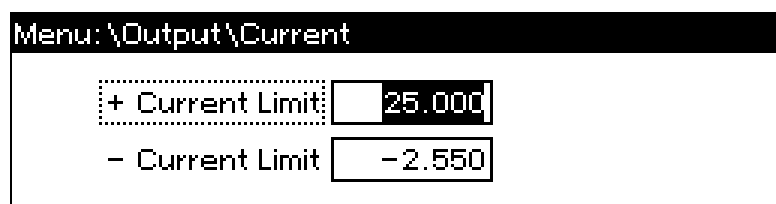
You can also use the numeric arrow keys to adjust the value up or down. You can set both positive and negative current values. Values become effective when the output is turned on.

In current priority mode, the unit will maintain the output current at its programmed setting. In voltage priority mode, the unit will limit the output current when it reaches the specified current limit value. Refer to Set the Output Mode for more information.

Method 2

Use the **Current** key to select the current entry field. In the display below, the current setting is selected. Enter the desired setting using the numeric keypad. Then press **Enter**.

```
Menu: \Output\Current

   + Current Limit     25.000

   – Current Limit     –2.550
```

If you make a mistake, either use the backspace key to delete the number, press Back to back out of the menu, or press Meter to return to meter mode.

Set Over-voltage Protection

Use the front panel menu.

The front panel command menu lets you access most of the instrument's functions. The actual function controls are located at the lowest menu level. Briefly:

- Press the **Menu** key to access the command menu.

- Press the left and right (**<**, **>**) navigation keys to move across the menu commands.

- Press the center **Select** key to select a command and move down to the next level in the menu.

- Press the **Help** key at the lowest menu level to display help information about the function controls.

- To exit the command menu press the **Meter** key to immediately return to meter mode, or press the **Menu** key to return to the top level.

For a map of the front panel menu commands, refer to Front Panel Menu Reference.

Menu example - accessing over-voltage protection.

Press the **Menu** key to access the front panel command menu. The first line identifies the menu path. When the menu is first accessed, the menu is at the top or root, and the path is empty. The second line indicates the commands that are available at the present menu level. In this case, the top-level menu commands are shown, with the Output command highlighted. The third line indicates which commands are available under the Output command. If there are no lower level commands, a brief description of the highlighted command is displayed.

```
Menu:\
Output Measure Transient Protect States System
Voltage, Current, Mode, Sequence, Advanced
```

Press the right arrow navigation key **>** to traverse the menu until the Protect command is highlighted. Press the **Select** key to access the Protect commands.

```
Menu:\
Output Measure Transient Protect States System
OVP, OCP, Inhibit, WDog, SFD, Clear
```

Since the OVP command is already highlighted, press the Select key to access the OVP dialog.

```
Menu:\Protect
OVP OCP Inhibit WDog SFD Clear
Overvoltage protection settings.
```

Note that the OVP setting for this model is set to 24 V. You can change the OVP setting using the numeric entry keys and pressing **Enter** and **Select**. Press the **Meter** key to return to meter view.

```
Menu:\Protect\OVP


        OVP Level   24.00
```

Enable the Output

Use the **On/Off** key to enable the output. If a load is connected to the output, the front panel display will indicate that it is drawing current. Otherwise, the current reading will be zero. The status indicator shows the output's status. In this case, "CV" indicates the output is in constant voltage mode.

```
15.0030V   20.045A
CV   Set  15.000V  Lim  25.000A    Lan
```

For a description of the status indicators, refer to Front Panel Display at a Glance.

Use Built-in Help System

View the list of help topics.

Press the **Help** key to view the list of available help topics. To scroll through the list, press the up and down navigation arrows.

Press **Meter** or **Back** to exit Help.

View the help information for displayed messages.

Whenever a limit is exceeded or any other invalid configuration is found, the instrument will display a message, including Error code information.

Press **Meter** or **Back** to exit Help.

Remote Interface Configuration

USB Configuration

GPIB Configuration

LAN Configuration

Modifying the LAN Settings

Using the Web Interface

Using Telnet

Using Sockets

Interface Lockout

Introduction

This instrument supports remote interface communication over three interfaces: GPIB, USB, and LAN. All three interfaces are "live" at power up. To use the interfaces, you must first install the Agilent IO Libraries software located on the Agilent Automation-Ready CD provided with your instrument. Then connect your instrument to your PC.

The front panel **IO** indicator comes on whenever there is activity on the remote interfaces. The front panel **Lan** indicator comes on when the LAN port is connected and configured.

This instrument provides Ethernet connection monitoring. With Ethernet connection monitoring, the instrument's LAN port is continually monitored, and automatically reconfigured when the instrument is unplugged for a minimum of 20 seconds and then reconnected to a network

USB Configuration

There are no configurable USB parameters. You can retrieve the USB connect string using the front panel menu:

Front Panel	SCPI Command
Select **System\IO\USB** The dialog displays the USB connect string.	Not available

GPIB Configuration

Each device on the GPIB (IEEE-488) interface must have a unique whole number address between 0 and 30. The instrument ships with the address set to 5. Your computer's GPIB interface card address must not conflict with any instrument on the interface bus. This setting is non-volatile; it will not be changed by power cycling or *RST. Use the front panel menu to change the GPIB address:

Front Panel	SCPI Command
Select **System\IO\GPIB**. Use the numeric keys to enter a new value from 0 to 30. Then press **Enter**.	Not available

LAN Configuration

The following sections describe the primary LAN configuration functions on the front-panel menus. Note that there are no SCPI commands to configure the LAN parameters. All LAN configuration must be done from the front panel.

| **NOTE** | After changing the LAN settings, you must Save the changes. Select: **System\IO\LAN\Apply**. Selecting Save cycles power to the instrument and activates the settings. LAN settings are non-volatile, they will not be changed by power cycling or *RST. If you do not want to save your changes select: **System\IO\LAN\Cancel**. Selecting Cancel cancels all changes. |

When shipped, DHCP is on, which may enable communication over LAN. The letters DHCP stands for Dynamic Host Configuration Protocol, a protocol for assigning dynamic IP addresses to devices on a network. With dynamic addressing, a device can have a different IP address every time it connects to the network.

Viewing Active Settings

To view the currently active LAN settings:

Front Panel	SCPI Command
Select **System\IO\LAN\Settings** Displays the active LAN settings. Use the up and down arrow key to scroll through the list.	Not available

The currently active settings for the IP Address, Subnet Mask, and Default Gateway may be different from the front panel configuration menu settings - depending on the configuration of the network. If the settings are different, it is because the network has automatically assigned its own settings

Resetting the LAN

You can perform an LXI LCI reset if the LAN settings. This resets DHCP, DNS server address configuration, mDNS state, mDNS service name and web password. These settings are optimized for connecting your instrument to a site network. They should also work well for other network configurations.

You can also reset the LAN to the as-shipped settings. This returns **ALL** LAN settings to the as-shipped values and restarts networking. All default LAN settings are listed under Non-volatile Settings.

Front Panel	SCPI Command
Select **System\IO\LAN\Reset** Select **System\IO\LAN\Defaults** Select Reset. Selecting Reset activates the selected LAN settings and restarts networking.	Not available

Modifying the LAN Settings

IP Address

Select IP to configure the addressing of the instrument. Press the **Menu** key, then select **System\IO\LAN\Config\IP**. The configurable parameters include:

Front Panel	SCPI Command
Select **System\IO\LAN\Modify\IP** Select Auto or Manual. See below for a full description.	Not available

- **Auto** - automatically configures the addressing of the instrument. When selected, the instrument will first try to obtain an IP address from a DHCP server. If a DHCP server is found, the DHCP server will assign an IP address, Subnet Mask, and Default Gateway to the instrument. If a DHCP server is unavailable, the instrument will try to obtain an IP address using AutoIP. AutoIP automatically assigns an IP address, Subnet Mask, and Default Gateway addresses on networks that do not have a DHCP server.

- **Manual** - allows you to manually configure the addressing of the instrument by entering values in the following three fields. These fields only appear when Manual is selected.

- **IP Address** - This value is the Internet Protocol (IP) address of the instrument. An IP address is required for all IP and TCP/IP communications with the instrument. An IP Address consists of 4 decimal numbers separated by periods. Each decimal number ranges from 0 through 255 with no leading zeros (for example, 169.254.2.20).

- **Subnet Mask** - This value is used to enable the instrument to determine if a client IP address is on the same local subnet. The same numbering notation applies as for the IP Address. When a client IP address is on a different subnet, all packets must be sent to the Default Gateway.

- **DEF Gateway** - This value is the IP Address of the default gateway that allows the instrument to communicate with systems that are not on the local subnet, as determined by the subnet mask setting. The same numbering notation applies as for the IP Address. A value of 0.0.0.0 indicates that no default gateway is defined.

Dot-notation addresses ("nnn.nnn.nnn.nnn" where "nnn" is a byte value from 0 to 255) must be expressed with care, as most PC web software interprets byte values with leading zeros as octal (base 8) numbers. For example, "192.168.020.011" is actually equivalent to decimal "192.168.16.9" because ".020" is interpreted as "16" expressed in octal, and ".011" as "9". To avoid confusion, use only decimal values from 0 to 255, with no leading zeros.

Host Name

A hostname is the host portion of the domain name, which is translated into an IP address. To configure the hostname of the instrument:

Front Panel	SCPI Command
Select **System\IO\LAN\Modify\Name**	Not available

You can enter any value from the numeric keypad. For additional characters, use the up/down navigation keys to enter an alpha character by scrolling through the selection list that appears when you press the keys. Use the left/right navigation keys to traverse the text field. Use the backspace key to delete a value. Press Enter when you are finished.	

Host Name - This field registers the supplied name with the selected naming service. If the field is left blank, no name is registered. A hostname may contain upper and lower case letters, numbers and dashes (-). The maximum length is 15 characters.

Each instrument is shipped with a default hostname with the format: A-modelnumber-serialnumber, where modelnumber is the unit's 6-character model number (e.g. N6950A), and serialnumber is the last five characters of the 10-character serial number located on the label on the top of the unit (e.g. 45678 if the serial number is MY12345678).

DNS Server and WINS Server

DNS is an internet service that translates domain names into IP addresses. It is also needed for the instrument to find and display its hostname assigned by the network. Normally, DHCP discovers the DNS address information; you only need to change this if DHCP is unused or not functional.

WINS configures the Windows service of the instrument. This is similar to the DNS service that translates domain names into IP addresses.

To manually configure the DNS and WINS services:

Front Panel	SCPI Command
Select **System\IO\LAN\Modify\DNS** or Select **System\IO\LAN\Modify\WINS** Select Primary Address or Secondary Address. See below for a full description.	Not available

- **Primary Address** - This field enters the primary address of the server. Contact your LAN administrator for server details. The same numbering notation applies as for the IP Address. A value of 0.0.0.0 indicates that no default server is defined.

- **Secondary Address** - This field enters the secondary address of the server. Contact your LAN administrator for server details. The same numbering notation applies as for the IP Address. A value of 0.0.0.0 indicates that no default server is defined.

Dot-notation addresses ("nnn.nnn.nnn.nnn" where "nnn" is a byte value from 0 to 255) must be expressed with care, as most PC web software interprets byte values with leading zeros as octal (base 8) numbers. For example, "192.168.020.011" is actually equivalent to decimal "192.168.16.9" because ".020" is interpreted as "16" expressed in octal, and ".011" as "9". To avoid confusion, use only decimal values from 0 to 255, with no leading zeros.

mDNS Service Name

The mDNS service name is registered with the selected naming service. To configure the mDNS service name of the instrument:

Front Panel	SCPI Command
Select **System\IO\LAN\Modify\mDNS** You can enter any value from the numeric keypad. For additional characters, use the up/down navigation keys to enter an alpha character by scrolling through the selection list that appears when you press the keys. Use the left/right navigation keys to traverse the text field. Use the backspace key to delete a value. Press Enter when you are finished.	Not available

● **mDNS Service Name** - This field registers the service name with the selected naming service. If the field is left blank, no name is registered. A service name may contain upper and lower case letters, numbers and dashes(-).

● Each instrument is shipped with a default service name with the format: Agilent-modelnumber-description-serialnumber, where modelnumber is the unit's 6-character model number (e.g. N6950A), description is the description, and serialnumber is the 10-character serial number located on the label on the top of the unit (e.g. MY12345678).

Services

This selects the LAN services to enable or disable.

Front Panel	SCPI Command
Select **System\IO\LAN\Modify\Services** Check or uncheck the services that you wish to enable or disable.	Not available

● The configurable services include: VXI-11, Telnet, Web control, Sockets, and mDNS.

● You must enable Web control if you wish to remotely control your instrument using its built-in Web interface.

Using the Web Interface

Your APS has a built-in Web interface that lets you control it directly from the Web browser on your computer. With the Web interface, you can access the front panel control functions including the LAN configuration parameters. Up to six simultaneous connections are allowed. With additional connections, performance will be reduced.

NOTE	The built-in Web interface only operates over the LAN. It requires Internet Explorer 7+. You also need the Java Plug-in version 7+. This is included in the Java Runtime Environment.

The Web interface is enabled when shipped. To launch the Web interface:

1. Open the Web browser on your computer.

2. Enter the instrument's hostname or IP address into the browser's Address field. The following home page will appear.

3. Click on the Browser Web Control button in the navigation bar on the left to begin controlling your instrument.

4. For additional help about any of the pages, click on the Help with this Page button.
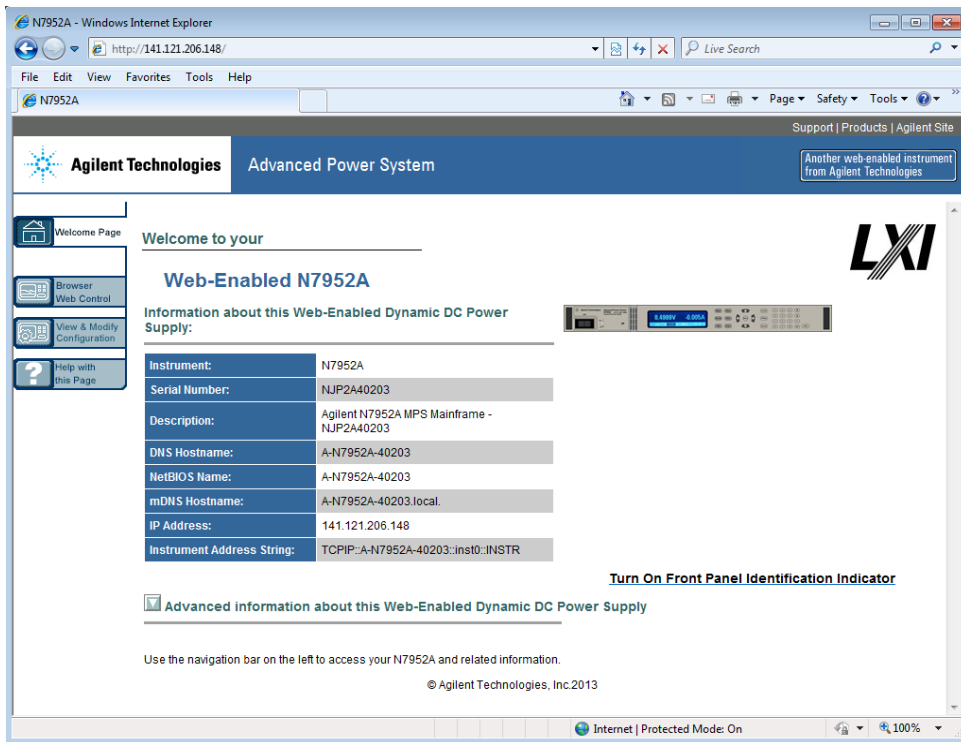
If desired, you can control access to the Web interface using password protection. As shipped, no password is set. To set a password, click on the View & Modify Configuration button. Refer to the on-line help for additional information about setting a password.

Using Telnet

In an MS-DOS Command Prompt box type: telnet hostname 5024 where hostname is the APS hostname or IP address, and 5024 is the instrument's telnet port.

You should get a Telnet session box with a title indicating that you are connected to the power supply. Type the SCPI commands at the prompt.

Using Sockets

NOTE   Power supplies allow any combination of up to six simultaneous data socket, control socket, and telnet connections to be made.

Agilent instruments have standardized on using port 5025 for SCPI socket services. A data socket on this port can be used to send and receive ASCII/SCPI commands, queries, and query responses. All commands must be terminated with a newline for the message to be parsed. All query responses will also be terminated with a newline.

The socket programming interface also allows a control socket connection. The control socket can be used by a client to send device clear and to receive service requests. Unlike the data socket, which uses a fixed port number, the port number for a control socket varies and must be obtained by sending the following SCPI query to the data socket: SYSTem:COMMunicate:TCPip:CONTrol?

After the port number is obtained, a control socket connection can be opened. As with the data socket, all commands to the control socket must be terminated with a newline, and all query responses returned on the control socket will be terminated with a newline.

To send a device clear, send the string "DCL" to the control socket. When the power system has finished performing the device clear it echoes the string "DCL" back to the control socket.

Service requests are enabled for control sockets using the Service Request Enable register. Once service requests have been enabled, the client program listens on the control connection. When SRQ goes true the instrument will send the string "SRQ +nn" to the client. The "nn" is the status byte value, which the client can use to determine the source of the service request.

Interface Lockout

The USB interface, LAN interface, and the Web server are enabled when shipped. To enable or disable the interfaces from the front panel:

Front Panel	SCPI Command
Select **System\Admin\IO** Enable or disable the interfaces by checking or unchecking the following items: Enable LAN, Enable GPIB, and Enable USB Press Select.	Not available

If you cannot access the Admin menu, it may be password protected.

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Programming Output Transients

Sequencing the Output

Making Measurements

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Programming the Output

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> **NOTE**   When the APS is first turned on, it may take about 30 seconds or so to initialize the instrument before it is ready for use.

Set the Output Priority Mode

You can select either Voltage priority or Current priority mode.

Voltage priority mode is used when you want the output voltage to remain constant. The output voltage will remain at its programmed setting as long as the load current remains within the positive or negative current limit setting.

Current priority mode is used when you want the output current to remain constant. The output current will remain at its programmed setting as long as the load voltage remains within the voltage limit setting.

Refer to [Priority Mode Operation](#) for more information.

Front Panel	SCPI Command
Select **Output\Mode**. Select either Voltage priority or Current priority. Then press **Select**.	To specify current or voltage priority mode: FUNC CURR|VOLT

> **NOTE**   When switching between Voltage priority and Current priority mode, the output is turned off and the output settings revert to their Power-on or RST values.

Set the Output Voltage

When the unit is in voltage priority mode, the output voltage remains at its programmed setting as long as the load current remains within its programmed positive or negative limit.

Front Panel	SCPI Command
Press the **Voltage** key. Enter a value and press Select.	To set the output voltage to 40 volts: VOLT 40

When the unit is in current priority mode, you can specify a voltage limit which limits the output voltage at the specified value. The output current will remain at its programmed setting as long as the load voltage remains within the voltage limit setting.

Front Panel	SCPI Command
Press the **Voltage** key. Specify a + Voltage limit. Then press **Select**.	To set the voltage limit: VOLT:LIM 42

Set the Output Current

When the unit is in voltage priority mode, you can specify a positive and negative current limit, which limits the output current at the specified value. In voltage priority mode, the output voltage remains at its programmed setting as long as the load current remains within its programmed positive or negative limit.

Front Panel	SCPI Command
Press the **Current** key. Specify a positive or negative Current limit. Then press **Select**.	To set the positive current limit: CURR:LIM 12 To set the negative current limit: CURR:LIM:NEG -3

When the unit is in current priority mode, you can specify a positive or negative output current level, which will be maintained as long as the output voltage remains within its programmed limit.

Front Panel	SCPI Command
Press the **Current** key. Enter a positive or negative value. Then press **Select**.	To set the output current to +5 amperes: CURR 5 To set the output current to −5 amperes: CURR −5

Set the Slew Rate

The voltage slew rate determines the rate at which the voltage changes to a new programmed setting. This applies to both voltage settings in voltage priority mode, and voltage limit settings in current priority mode. When set to MAXimum, INFinity, or to a very large value, the slew rate will be limited by the analog performance of the output circuit. This setting can used to prevent crossover into current limit while up- and down-programming capacitive loads. Use the following equation to calculate the maximum slew rate limit to ensure smooth and linear up- and down-programming performance.

Max slew rate (V/s) = (Current limit setting (A) – Load current (A))/(Load capacitance (F))

The current slew rate determines the rate at which the current changes to a new programmed setting. This applies to both current settings in current priority mode, and current limit settings in voltage priority mode. When set to MAXimum, INFinity, or to a very large value, the slew rate will be limited by the analog performance of the output circuit.

Front Panel	SCPI Command
Select **Output\Advanced\Slew** Then select Voltage or Current Enter the voltage or current slew rate in the Slew Rate field. Check Max slew rate to program the fastest slew rate.	To set the voltage slew rate to 5 V/s VOLT:SLEW 5 To set the current slew rate to 1 A/s CURR:SLEW 1 To set the fastest slew rate: VOLT:SLEW MAX

Set the Output Bandwidth

Voltage bandwidth modes to allow you to optimize output response time with capacitive loads.

High1 bandwidth mode provides maximum up-programming speed as well as the fastest transient response settling time. This mode is optimized for use with resistive loads; however capacitive loads up to the limits outlined in the table below can be used when using load leads shorter than 3 meters (10 feet). Exceeding these limits can lead to voltage programming overshoots and transient response instability.

Low bandwidth mode is optimized for use with large capacitive loads up to the limits shown in the table below, along with load leads longer than 3 meters (10 feet). In this mode the up- and down-programming speed and voltage control-loop bandwidth are limited to prevent voltage programming overshoots and improve transient response stability. Low mode provides the best stability and overshoot minimization over all load configurations.

NOTE	Connecting very low ESR capacitors larger than the High mode limit with load leads shorter than 3 m (10 ft.) is not recommended in either bandwidth range. This load configuration can lead to voltage programming overshoots.

1 kW Models	High limit	Low limit	2 kW Models	High limit	Low limit
N6950A/N7950A	0 to 3800 µF	0 to 190,000 µF	N6970A/N7970A	0 to 7600 µF	0 to 380,000µF
N6951A/N7951A	0 to 1000 µF	0 to 50,000 µF	N6971A/N7971A	0 to 2000 µF	0 to 100,000 µF
N6952A/N7952A	0 to 240 µF	0 to 12,000 µF	N6972A/N7972A	0 to 480 µF	0 to 24,000 µF
N6953A/N7953A	0 to 100 µF	0 to 5600 µF	N6973A/N7973A	0 to 200 µF	0 to 11,200 µF
N6954A/N7954A	0 to 60 µF	0 to 3000 µF	N6974A/N7974A	0 to 120 µF	0 to 6000 µF

Front Panel	SCPI Command
Select **Output\Advanced\Bandwidth**. Select either High1 or Low. Then press **Select**.	To select the high bandwidth: VOLT:BWID HIGH1 To select the low bandwidth: VOLT:BWID LOW

Set the Output Resistance

Output resistance programming is mainly used in battery testing applications and only applies in Voltage Priority mode. It is used to emulate the internal resistance of a non-ideal voltage source such as a battery. Values are programmed in ohms. Model-specific resistance programming ranges are as follows:

1 kW Models	Range	2 kW Models	Range
N6950A/N7950A	0 to 0.1 Ω	N6970A/N7970A	0 to 0.05 Ω
N6951A/N7951A	0 to 0.4 Ω	N6971A/N7971A	0 to 0.2 Ω
N6952A/N7952A	0 to 1.6 Ω	N6972A/N7972A	0 to 0.8 Ω
N6953A/N7953A	0 to 3.4 Ω	N6973A/N7973A	0 to 1.7 Ω
N6954A/N7954A	0 to 6.4 Ω	N6974A/N7974A	0 to 12.8 Ω

Front Panel	SCPI Command
Select **Output\Advanced\Resistance**. Specify an Output Resistance value. Then check the **Enable** box. Then press **Select**.	To enable output resistance: RES: ON To select a resistance of 0.5 ohms: RES: 0.5

Enable the Output

Because of internal circuit start-up procedures and any installed relay options, OUTPut ON may take tens of milliseconds to complete its function. OUTPut OFF delays may also be in effect. For more information regarding output turn-on and turn-off delays, refer to Output Sequence Control.

Front Panel	SCPI Command
Press the **On/Off** key.	OUTP ON|OFF

> **NOTE** In addition to the front panel and SCPI Output On and Output Off commands, you can also use OnCouple, OffCouple, and expression signals to enable and disable the output. Refer to Sequencing the Output for more information.

Configure the Output Relays (N7900 models only)

Double-pole, double-throw relays are provided to disconnect both the output and sense terminals. A polarity reversal function is also provided.

The normal operating mode of the relay is to open and close as the output is turned on or off. The relays are only opened or closed when the output is at a safe state (zero voltage; zero current). You can lock the relays so that they are always closed. This can circumvent any additional relay turn on/turn off delays present in the N7900 models.

Front Panel	SCPI Command
Select **System\Preferences\Relay**. Select **Lock Closed** to leave the relays closed at all times, and press **Select**.	To leave the relays closed: OUTP:REL:LOCK ON

You can also reverse the polarity of the output and sense terminals. Note that this command briefly turns the output off while the output and sense terminal polarities are switched. Also note that you can enable or disable the function of the polarity reversal to prevent accidental use.

Front Panel	SCPI Command
Select **Output\Advanced\Pol**. Check the **Reverse** box. Then press **Select**. Uncheck the **Reverse** box to return the polarity to normal. To enable polarity reversal, select **System/Preferences/Relay** then check **Enable Polarity Reverse**. Then press **Select**. Uncheck the **Enable Polarity Reverse** box to lock out polarity reversal.	To switch the output and sense terminal polarities of the output: OUTP:REL:POL REV To return the polarities back to normal: OUTP:REL:POL NORM To lock out polarity reversal: OUTP:REL:POL ENAB OFF

NOTE   Although the plus and minus rails of the output power mesh are physically disconnected from the output terminals, an AC filter network is still connected to the plus and minus sense and output terminals as shown in the figure below. This AC network is required to meet EMI regulations.

AC Filter Network		Model	C1	C2	R1
		N7950A	10 μF	0.3 μF	0.15 Ω
		N7951A	3.3 μF	0.2 μF	0.25 Ω
		N7952A	2.2 μF	0.1 μF	0.3 Ω
		N7953A	1 μF	0.047 μF	0.5 Ω
		N7954A	0.47 μF	0.047 μF	0.5 Ω
		N7970A	20 μF	0.6 μF	0.075 Ω
		N7971A	6.6 μF	0.4 μF	0.125 Ω
		N7972A	4.4 μF	0.2 μF	0.15 Ω
		N7973A	2 μF	0.94 μF	0.25 Ω
		N7974A	0.94 μF	0.94 μF	0.25 Ω

Programming Output Protection

Set the Over-Voltage Protection

Set the Over-Current Protection

Output Watchdog Timer

User-Defined Protection

Clear Output Protection Functions

Introduction

The APS models have many protection functions. These functions disable the output to protect the device under test as well as the power supply. A front panel status indicator will turn on when a protection function has been set. Most protection functions are latching, which means that they must be cleared once they have been set.

Of the following protection functions, the OV, OC, PROT, INH, and UProt are user-programmable.

OV	Over-voltage protection is a hardware OVP whose trip level is a user-programmable value. Over-voltage protection also occurs automatically if the remote sense leads are shorted. OV protection is always enabled.
OV-	Negative over-voltage protection detects if the remote sense leads are reversed. At instrument turn-on, it also detects if voltages more negative than -2V are present at the output terminals. OV- protection is not programmable and is always enabled.
OC	Over-current protection is a user-programmable function that can be enabled or disabled. When enabled, the output will be disabled when the output reaches the current limit setting.
CP+	Positive over-power compares the output power against a built-in threshold. A CP+ protection occurs when the threshold is exceeded. CP+ protection is always enabled.
CP-	Negative over-power compares the internally dissipated power against a built-in threshold. A CP- protection occurs when the threshold is exceeded. CP- protection is always enabled.
OT	Over-temperature protection monitors the internal temperature of the power supply and disables the output if the temperature exceeds the pre-defined limit (see OUTPut:PROTection:TEMPerature:MARGin?). Note that sensor information from any connected power dissipator is combined with the information from the power supply into a single indicator. OT protection is always enabled.
PF	Power-fail indicates that a power fail condition on the AC mains has occurred and has disabled the output. PF protection is always enabled.
EDP	Excessive dynamic protection disables the output in the event of excessive large repetitive voltage swings caused by programmed voltage changes, lists, Arbs, or load-induced voltage swings (see Output Dynamic Response). If unchecked, these voltage swings could result in premature failure of components in the instrument. EDP protection is always enabled.

Prot	Prot indicates that the output is disabled because the programmed output watchdog timer has expired.
INH	The Inhibit input (pin 3) on the rear panel digital connector can be programmed to act as an external shutdown signal. Refer to Inhibit Input for further information.
UProt	A User-defined protection condition has disabled the output.

Set the Over-Voltage Protection

The over-voltage protection will turn the output off if the output voltage reaches the programmed over-voltage limit. The OVP circuit monitors the voltage at the + and – sense terminals. Note that an OVP shutdown will automatically occur if the + and – sense leads are accidentally shorted to each other.

Front Panel	SCPI Command
Select **Protect\OVP** Enter a value in the OVP level box. Then press **Select**.	To set the OVP level to 50 volts: VOLT:PROT 50

Set the Over-Current Protection

Enable OCP

When over-current protection is enabled, the power supply turns off the output if the output current reaches the current limit setting and transitions from constant voltage (CV) to current limit (CL+ or CL-) mode.

Front Panel	SCPI Command
Select **Protect\OCP** Check **Enable OCP**. Then press **Select**.	To enable OCP: CURR:PROT:STAT ON

Delay OCP

You can specify an OCP delay to prevent momentary output settings, load, and status changes from tripping the over-current protection. In most cases these momentary conditions would not be considered an over-current protection fault, and having an OCP condition disable the output when they occur would be a nuisance. Specifying an OCP delay lets the OCP circuit ignore these momentary changes during the specified delay period. Once the OCP delay time has expired and the over-current condition persists, the output will shut down.

The following selections are available to start the over-current delay timer:

Settings Change this starts the over-current delay whenever a command changes the output settings. It includes changes made by the transient system so that the timer is started at each list step and at each Arb output change. It also includes voltage and current slew changes, so that the timer is restarted throughout the entire slew time.

Current Limit starts the over-current delay timer by any transition of the output into current limit mode.

The delay can be programmed from 0 to 0.255 seconds. You can specify if the OCP delay timer is started by any transition of the output into CC mode, or only at the end of a settings change in voltage, current, or output state.

Front Panel	SCPI Command
Select **Protect\OCP** Enter a delay value. Then press **Select**. By default, the delay timer will be started by an output settings change. Check "Start delay on CC" to start the delay timer by ANY output transition into CL mode.	To specify a 10 millisecond delay: CURR:PROT:DEL 0.01 To start the delay timer by an output settings change: CURR:PROT:DEL:STAR SCH To start the delay timer by ANY output transition into CL mode: CURR:PROT:DEL:STAR CCTR

Factors that influence how long the output settings or load change may last include: difference between old output value and new output value, the current limit setting, and the load capacitance in CV mode or load inductance in CC mode. The delay required must be determined empirically; the output programming-response time characteristics may be used as guidelines.

Also note that the time it takes the output to go into CL mode varies - depending on the magnitude of the over-current condition compared to the current limit setting. For example, if the over-current is only slightly greater than the current limit setting, it may take several tens of milliseconds for the output to set the CC status bit. If the over-current is significantly greater than the current limit setting, it may only take a few hundred microseconds or less for the output to set the CL status bit. To determine when the output will shut down, you must add the time it takes for the CL status bit to the over-current protection delay time. If the over-current persists beyond the sum of these two time intervals, the output will shut down.

Output Watchdog Timer

When enabled, the output watchdog timer causes the output to go into protection mode if there is no SCPI I/O activity on the remote interfaces (USB, LAN, GPIB) within the user-specified time period. Note that the watchdog timer function is NOT reset by activity on the front panel – the output will still shut down after the time period has elapsed.

After the time period has expired, the output will be disabled, but the programmed output state is not changed. The Prot bit in the status questionable register as well as the Prot indicator on the front panel will be set. A watchdog protect can be cleared as described under Clear Output Protection Functions below.

The watchdog delay can be programmed from 1 to 3600 seconds in 1-second increments. To enable the watchdog timer and specify a delay value, proceed as follows:

Front Panel	SCPI Command
Select **Protect\WDog** Check Enable Watchdog to enable the watchdog timer. Enter a value in the Watchdog Delay box. Then press **Select**.	To enable the output watchdog timer: OUTP:PROT:WDOG ON To set the output watchdog timer to 120 seconds: OUTP:PROT:WDOG:DEL 120

User-Defined Protection

User-defined protection lets you expand the built-in protection capabilities of the APS to include additional output behavior and status conditions. This is accomplished by programming a user-defined signal expression and routing it to the protection circuit of the unit. See Using Expression Signal Routing. When the expression is true, it responds with a latching user-defined protect (UProt), and disables the output. To enable User-defined protection:

Front Panel	SCPI Command
Select **System\Signal\Protect** Check Enable to enable user protection. Select the expression from the Source dropdown list. Then press **Select**.	Enable user-protection: OUTP:PROT:USER:STAT ON Select an expression from 1 to 8: OUTP:PROT:USER:SOUR EXPR<1-8>

Clear Output Protection Functions

If an over-voltage, over-current, over-temperature, power-fail condition, power-limit condition, protection condition, or inhibit signal occurs, the output is disabled. The appropriate operating status indicator on the front panel will be on. To clear the protection function and restore normal operation, first remove that condition that caused the protection fault. Then, clear the protection function as follows:

Front Panel	SCPI Command
Select **Protect\Clear** Select Clear.	To clear a protection fault: OUTP:PROT:CLE

Programming Output Transients

Common Actions for All Transients

Programming a Step Transient

Programming a List Transient

Programming an Arbitrary Waveform

Output Transients

An output transient is defined as a triggered action that causes a change in output voltage or current. The three available transient types are: step, list, and arbitrary waveforms.

An output step is a one-time event that steps the output voltage or current up or down in response to a trigger.

A list describes a precisely timed, complex sequence of output steps or changes.

An arbitrary waveform generator (Arb) allows the output to generate complex user-defined voltage or current waveforms of up to 65,535 data points.

Common Actions for All Transients

- Enable the output transient function
- Program the transient parameters
- Select the trigger source
- Initiate the transient system
- Trigger the transient

The following figure illustrates the transient trigger process. This applies to all transient types. The arrows on the right are specific to List transients. For an overview of the trigger system, refer to Trigger Overview.
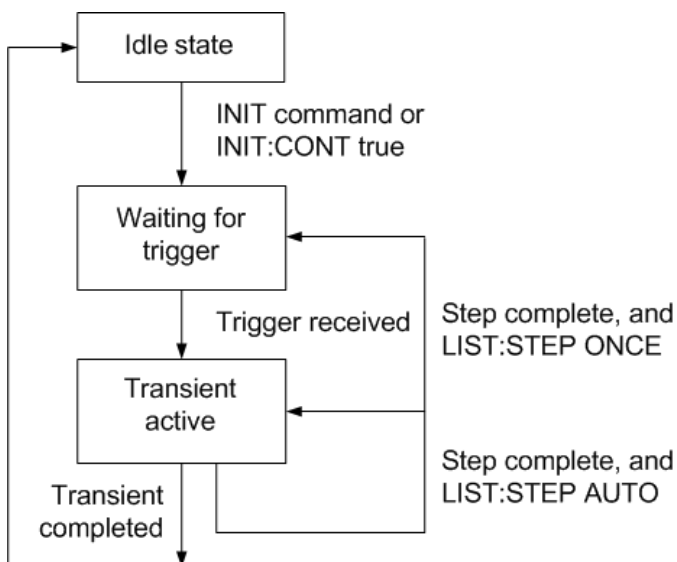
Enable the output transient function

First, you must enable the output to respond to transient triggers. Unless an output transient function enabled, nothing will happen even if you have programmed the transient parameters and generated a transient trigger.

Front Panel	SCPI Command
Select **Transient\Mode**. If you are operating in voltage priority mode select Voltage mode. If you are operating in current priority mode select Current mode. In the dropdown list, select Step, List or Arb transients. Then press **Select**.	To enable the transient function, use: VOLT:MODE STEP VOLT:MODE LIST VOLT:MODE:ARB or CURR:MODE STEP CURR:MODE:LIST CURR:MODE:ARB

NOTE   In Step mode, the triggered value becomes the immediate value when the trigger is received. In Fixed mode, trigger signals are ignored; the immediate values remain in effect when a trigger is received.

Program the transient parameters

For example, set the triggered voltage level if you are programming a voltage step:

Front Panel	SCPI Command
Select **Transient\Step**. Select the Trig Voltage box to set the voltage. Enter a value and press Select.	To set a voltage step level of 15 V use: VOLT:TRIG 15

Select the trigger source

NOTE   A TRIGger:TRANsient[:IMMediate] command over the bus will always generate an immediate transient trigger, regardless of the selected trigger source.

Unless you are using the front panel menu or a TRIGger:TRANsient[:IMMediate] command to trigger the transient, select a trigger source from the following:

Trigger Source	Description
Bus	Selects GPIB device trigger, *TRG, or <GET> (Group Execute Trigger).
EXPRession <1-8>	Selects one of eight user-defined expressions. See Defining Signal Expressions.
External	Selects ANY pin that has been configured as a Trigger Input on the digital control port.

Immediate	Triggers the transient as soon as it is INITiated.
Pin<1-7>	Selects a specific pin<n> that is configured as a Trigger Input on the digital control port.

Use the following commands to select a trigger source:

Front Panel	SCPI Command
Select **Transient\TrigSource**. To select immediate triggers, select Imm. To select Bus triggers, select Bus. To select digital pin 5 as the trigger, select Pin 5, or EXT. To select expression1 as the trigger, select Expr1.	To select Bus triggers: TRIG:TRAN:SOUR BUS To select digital pin 5 as the trigger: TRIG:TRAN:SOUR PIN5 To select expression1 as the trigger: TRIG:TRAN:SOUR EXPR1

Initiate the transient system

When the unit is turned on, the trigger system is in the idle state. In this state, the trigger system is disabled, ignoring all triggers. The INITiate commands enable the trigger system to receive triggers.

Front Panel	SCPI Command
Select **Transient\Control**. Scroll to Initiate. Then press **Select**.	To initiate the transient trigger system: INIT:TRAN

It takes a few milliseconds for the instrument to be ready to receive a trigger signal after receiving the INITiate:TRANsient command. If a trigger occurs before the trigger system is ready for it, the trigger will be ignored. You can test the WTG_tran bit in the operation status register to know when the instrument is ready to receive a trigger after being initiated.

Front Panel	SCPI Command
Select **Transient\Control**. The Trig state field indicates "Initiated".	To query the WTG_tran bit (bit 4): STAT:OPER:COND?

If a bit value of 16 is returned in the query, the WTG_tran bit is true, and the instrument is ready to receive the trigger signal. Refer to Status Overview

NOTE   Unless INITiate:CONTinuous:TRANsient is programmed, the instrument executes one transient each time a trigger signal is received. Thus, it will be necessary to initiate the trigger system each time another triggered transient is desired.

Trigger the transient

The trigger system is waiting for a trigger signal in the initiated state. You can immediately trigger the transient as follows:

Front Panel	SCPI Command
Select **Transient\Control**. Select Trigger to generate an immediate trigger signal regardless of the trigger source setting.	To generate a transient trigger: TRIG:TRAN Alternatively, if the trigger source is BUS, you can also program a *TRG or an IEEE-488 <get> command.

As previously discussed, a trigger can also be generated by a digital pin, or a user-defined expression. If any of these systems are configured as the trigger source, the instrument will wait indefinitely for the trigger signal. If the trigger does not occur, you must manually return the trigger system to the idle state. The following commands return the trigger system to the idle state:

Front Panel	SCPI Command
Select **Transient\Control**. Then select the Abort control.	ABOR:TRAN

When a trigger is received, the triggered functions are set to their programmed transient values. When the triggered actions are completed, the trigger system returns to the idle state.

You can test the TRAN-active bit in the Operation Status register to know when the transient trigger system has returned to the idle state.

Front Panel	SCPI Command
Select **Transient\Control**. The Trig state field indicates "Idle".	To query the TRAN-active bit (bit 6): STAT:OPER:COND?

If a bit value of 64 is returned in the query, the TRAN-active bit is true, and the transient action is NOT complete. When the TRAN-active bit is false, the transient action is complete. Refer to Status Tutorial for more information.

Programming a Step Transient

Program the Step Levels

Use the following commands to program the triggered output step level. The output will go to this level when the trigger is received. In the front panel menu, you can only program the step level based on the priority mode that you are operating in - voltage or current priority.

Front Panel	SCPI Command
Select **Transient\Step**. Select the Trig Voltage box to set the voltage. Select the Trig Current box to set the current. Enter a value and press Select.	To set a voltage step level of 15 V use: VOLT:TRIG 15 To set a current step level of 1 A use: CURR:TRIG 1

Generate a Trigger Out Signal

The output step can generate a trigger signal that can be routed to a pin on the digital port that has been configured as a trigger output (TOUT). Use the following commands to generate a trigger signal when the step occurs:

Front Panel	SCPI Command
Select **Transient\Step**. Check Enable Trigger Output. Then press **Select**.	To program the Step function to generate a trigger signal, use: STEP:TOUT ON

Programming a List Transient (N7900 models only)

- Program the list values

- Program the dwell values

- Specify the list pacing

- Specify any trigger signals that the list should generate

- Specify how many times you want the list to repeat

- Specify how you want the list to end

Lists let you generate complex sequences of output changes with rapid, precise timing, which may be synchronized with internal or external signals. In contrast to an output step, which is a one-time output change, an output list is a sequence of output changes. Lists can contain up to 512 individually programmed steps, and can be programmed to repeat themselves. Only the parameters associated with one of the priority modes, either voltage or current priority, may be list controlled.

The voltage and current lists are paced by a separate dwell list that defines the duration or dwell of each step. Each of the up to 512 steps can have a unique dwell time associated with it, which specifies the time in seconds that the list will remain at that step before moving on to the next step.

Lists can also be trigger-paced, in which the list advances one step for each trigger received. This is useful if you need an output list to closely follow triggered events. With a trigger-paced list, triggers that are received during the dwell period are ignored. You can set the list dwell time to zero ensure that no triggers are lost.

Lists can also generate trigger signals at specified steps. This is accomplished by two additional lists: a beginning-of-step (BOST) and an end-of-step (EOST) list. These lists define which steps will generate a trigger signal and if the trigger occurs at the beginning or end of the step. These trigger signals can be used to synchronize other events with the list.

All lists (voltage, current, dwell, BOST, EOST) must be set to the same number of steps, otherwise an error occurs when the list is run. For convenience, a list may be programmed with only one step or value. In this case, a single-step list is treated as if it had the same number of steps as the other lists, with all values being equal to the one value.

> **NOTE**   List data is not saved as part of a saved instrument state.

Program the list values

Example 1 If you are programming a voltage pulse or pulse train, set the amplitude and width of the pulse. To generate a pulse with an amplitude of 15 V and a pulse width of 1 second, use:

Front Panel	SCPI Command
Select **Transient\List\Config**. Select List Step 0 (the pulse) and enter a voltage value of 15. Press Select. Select List Step 1 (the off time) and enter a voltage value of 0. Press Select.	To program the amplitude for step 0 (the pulse) and step 1 (the off time): LIST:VOLT 15,0

Example 2 If you are programming an arbitrary voltage list, specify the values for the list. The order in which the values are entered determines the order in which the values will be output. To generate the voltage list shown in the figure, a list may include the following values: 9, 0, 6, 0, 3, 0:
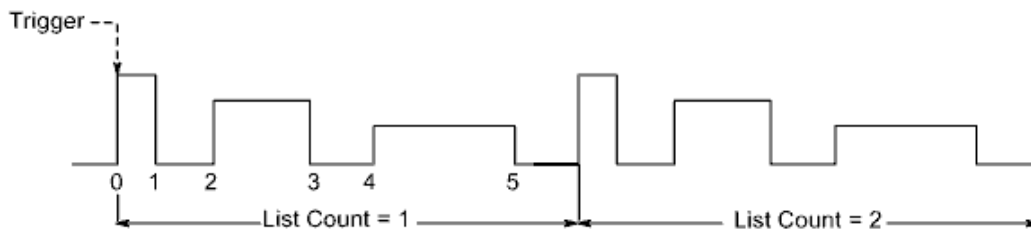
Front Panel	SCPI Command
Select **Transient\List\Config**. Select the List Step number and enter a voltage value. Press Select. Repeat this for each step. Use the up/down arrows to select the next step.	To program a voltage list of 5 steps: LIST:VOLT 9,0,6,0,3,0

Program the dwell values

Example 1 If you are programming a voltage pulse, set the dwell time of the pulse width. Also specify the dwell of the off time. This is necessary if you are generating a pulse train, since the off time determines the time between pulses. To generate a pulse with a pulse width of 1 second and an off time of 2 seconds, use:

Front Panel	SCPI Command
Select **Transient\List\Config**. Select List Step 0 (the pulse) and enter a dwell value of 1. Press Select.	To program the dwell for step 0 (the pulse) and step 1 (the off time): LIST:DWEL 1,2

Select List Step 1 (the off time) and enter a dwell value of 2. Press Select.	

You have now configured a single pulse. If you wish to generate a pulse train, simply specify the number of pulse repetitions as described under "Specify How Many Times the List Repeats".

Example 2 If you are programming an arbitrary voltage list, specify the values for the list. The dwell values determine the time interval, in seconds, that the output remains at each step in the list before it advances to the next step. To specify the six dwell intervals in the figure, a list may include the following values: 2, 3, 5, 3, 7, 3:

Front Panel	SCPI Command
Select **Transient\List\Config**. Select the List Step number and enter a dwell value. Press Select. Repeat this for each step. Use the up/down arrows to select the next step.	To program a dwell of 5 values, use: LIST:DWEL 2,3,5,3,7,3

NOTE   The number of dwell steps must equal the number of voltage steps. If a dwell list has only one value, that value will be applied to all steps in the list.

Specify the list pacing

You can specify if the list will be dwell or trigger-paced. The default selection is dwell-paced.

In a dwell paced list, each step is assigned a dwell time. The dwell time determines the time that the output remains at the step. As each dwell time elapses, the next step is immediately output.

In a trigger-paced list, the list advances one step for each trigger received. You can also a dwell period if you want to ignore triggers during the dwell time, or guarantee a minimum dwell time between triggered list steps.

Front Panel	SCPI Command
Select **Transient\List\Pace**. Select either **Dwell paced** or **Trigger paced**. Then press **Select**.	To set the list pacing to dwell-paced: LIST:STEP AUTO To set the list pacing to trigger-paced: LIST:STEP ONCE

Specify any trigger signals that the list should generate

You can generate trigger signals that can be routed to other destinations. See Using Expression Signal Routing. For example you can use trigger signals to trigger actions on any external equipment connected to the digital port. The following figure gives an example of generating four trigger signals on the arbitrary list of Example 2.

Front Panel	SCPI Command
Select **Transient\List\Config**. Select the List Step number 4. To generate a trigger, enter a 1 in the Tout Begin Step field. Select the List Step numbers 0, 2, and 4. To generate a trigger, enter a 1 in the Tout End Step field. If zeroes are entered in the fields, no trigger is generated for the step.	To program a trigger at the beginning of step 4: LIST:TOUT:BOST 0,0,0,0,1,0 To program a trigger at the end of step 0, 2, and 4: LIST:TOUT:EOST 1,0,1,0,1,0

Specify how many times you want the list to repeat

You can specify how many times you want the list (or pulse) to repeat. At reset, the list count is set to 1 repetition. Sending the INFinity parameter in the SCPI command makes the list repeat indefinitely.

Front Panel	SCPI Command
Select **Transient\List\Repeat**. Enter the number of list repetitions (2) and press Select.	To program the list to repeat twice: LIST:COUN 2

Specify how you want the list to end

Specify the output state after the list has completed. There are two choices: the output returns to the value that was in effect before the list started, or the output remains at the value of the last list step.

Front Panel	SCPI Command
Select **Transient\List\Terminate**. Select either Return to Start, or Stop at Last Step and press Select.	To return the output to the pre-list state: LIST:TERM:LAST OFF To keep the output at the end list state: LIST:TERM:LAST ON

Programming an Arbitrary Waveform [N7900 models only]

- Specify the Arb type and dwell
- Configure the Arb
- Specify how many times you want the Arb to repeat
- Specify how you want the Arb to end

| NOTE | Certain output amplitude and frequency combinations can exceed the instrument's dynamic response capability and cause the output to shut down, especially under no-load conditions. Refer to Output Dynamic Response for more information. |

The output of the Agilent N7900 models can be modulated by the instrument's built-in arbitrary waveform generator. This allows the output to generate complex user-defined voltage or current waveforms. The following are key features of the constant-dwell arbitrary waveform generator:

- Generate voltage or current arbitrary waveforms.
- Arbs can contain up to 65,535 data points.
- A single dwell value applies to every point in the arbitrary waveform (constant-dwell).
- Only the Arb that corresponds to the active priority mode, either voltage or current priority, may be generated.

Specify the Arb type and dwell

To specify the Arb type and dwell:

Front Panel	SCPI Command
Select **Transient\Arb\Config**. In the dropdown list, pick either a voltage or a current Arb. Then press **Select**. Enter a dwell value in the Dwell field. Then press **Select**.	To specify a voltage or current Arb: ARB:FUNC:TYPE VOLT ARB:FUNC:TYPE CURR To specify a dwell time of 1 millisecond: ARB:VOLT:CDW:DWEL 0.001 ARB:CURR:CDW:DWEL 0.001

Configure the Arb

Note that you can only *view* Arb point data from the front panel. You cannot *program* Arb data from the front panel. You must use the SCPI ARB:CURRent:CDWell or ARB:VOLTage:CDWell commands to program the Arb data.

Front Panel	SCPI Command
Select **Transient\Arb\Config**. If Arb points have been imported or programmed using the SCPI command, the Points field displays the number of points in the Arb.	To program 10 points in a current Arb: ARB:CURR:CDW 1,2,2,3,4,4,3,2,2,1 To query the number of Arb points: ARB:CURR:CDW:POIN?

View the amplitude of any Arb point by entering the point number in the Point # field. The Level field displays the amplitude.	To query the Arb point values: ARB:CURR:CDW?

Specify how many times you want the Arb to repeat

Depending on your application, specify how many times you want the Arb to repeat. Sending the INFinity parameter in the SCPI command makes the Arb repeat indefinitely. At reset, the Arb count is set to 1.

Front Panel	SCPI Command
Select **Transient\Arb\Repeat**. Enter the number of list repetitions (2) and press Select.	To program the Arb to repeat twice: ARB:COUN 2

Specify how you want the Arb to end

Specify the output state after the Arb has completed. There are two choices: the output returns to the state it was in before the Arb started, or the output remains at the values of the last Arb point.

Front Panel	SCPI Command
Select **Transient\Arb\Terminate**. Select either Return to Start, or Stop at Last Step and press Select.	To return the output to the pre-Arb state: ARB:TERM:LAST OFF To keep the output at the Arb end point: ARB:TERM:LAST ON

Sequencing the Output

This section describes how you can synchronize output turn-on and turn-off sequences on single and multiple units.

Turn-On/Turn-Off Behavior

Turn-On/Turn-Off Delays

Enabling/Disabling the Output

Sequencing Multiple Units

Turn-On Turn-Off Behavior

The following figure illustrates the output turn-on and output turn-off sequence followed by a description of the individual components.
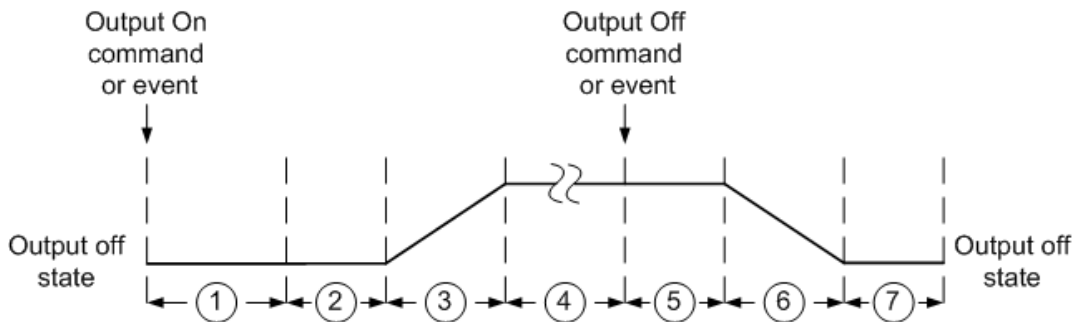
Sequence Description

1. Upon the receipt of an Output On command, the power supply waits for the duration of the user-programmed turn-on delay (which is zero by default).

2. In Voltage Priority mode the power supply programs the output to the minimum voltage setting during the internal delay time, which is 12 milliseconds for N6900 models and 38 milliseconds for N7900 models due to output relay closure. In Current Priority mode the power supply ensures that there is zero output current flow during the internal delay time, which is 14 milliseconds for N6900 models and 46 milliseconds for N7900 models due to output relay closure.

3. The output is programmed to the output setting while following the slew rate and compliance limit.

4. The output reaches the programmed setting.

5. Upon the receipt of an Output Off command, the power supply waits for the duration of the user-programmed turn-off delay (which is zero by default).

6. In Voltage Priority mode the power supply down-programs the output to the minimum voltage setting. In Current Priority mode the power supply down-programs the output current to zero. In both cases the slew rate setting (if programmed) is followed. If a slow slew rate has not been programmed, the power supply may wait up to 250 milliseconds (but only as long as necessary) for the output to down-program before proceeding to the next step.

7. For N6900 models, the output stage is turned off immediately. For N7900 models there is an additional 18 millisecond wait for the output relays to open before the output stage is turned off.

> **NOTE**   To circumvent the relay turn on/off delays in the N7900 models a non-volatile OUTPut:RELay:LOCK command can be sent, after which the delays will mirror those seen in the N6900 models.

Turn-On/Turn-Off Delays

All power supplies exhibit a maximum delay offset that applies from the time that a command to turn on the output is received until the output actually turns on. Specifying a common delay offset will serves as a reference point for any user-programmed turn-on delays. This user-defined offset also makes it possible to connect multiple power supplies together and program accurate turn-on sequences across multiple outputs. The user-programmed turn-on delay will then be added to the common user-defined reference point.

There is no need to specify a common delay offset when outputs turn off. Outputs start executing their turn-off delays as soon as an Output Off command is received.

The maximum delay offset is shown in the following table.

Models	Voltage Priority	Current Priority
N6900 models or locked relays	12 milliseconds	14 milliseconds
N7900 models	38 milliseconds	46 milliseconds

Enabling/Disabling the Output

In addition to the front panel and SCPI Output On and Output Off commands, you can also use OnCouple, OffCouple, and expression signals to enable and disable the output. These signals provide an additional level of control when sequencing the output on individual and multiple units.

The following figure illustrates the programming path when using the OnCouple, OffCouple, and expression signals to control the output.
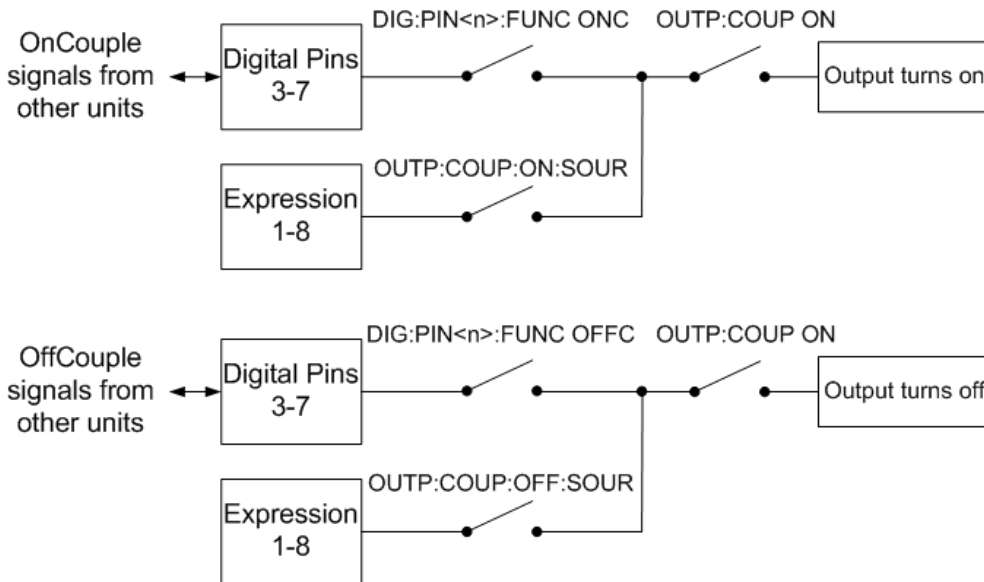
As shown in the figure, you can configure digital ports pins 3 through 7 to provide the OnCouple and OffCouple signals that enable or disable the output. The output is enabled or disabled when the corresponding signal is true. Refer to Output Couple Control for more information on configuring the digital port pins.

User-defined expression signals can also be used to enable or disable the output. User-defined expressions can combine a wide variety of status signals and output level conditions to create an expression signal that, when true, will enable or disable the output. Refer to Defining Signal Expressions and Signal Expression Targets for more information.

Lastly, you must enable output sequencing to use OnCouple, OffCouple, and expression signals to enable or disable the output. Refer to Enable Output Sequencing below.

Sequencing Multiple Units

To sequence the output turn-on sequence for multiple units:

1. Connect and configure the digital connector pins of all units.

2. Enable the sequence function on each unit.

3. Specify the user-programmed turn-on delay for each unit.

4. This step is required if you have power supplies with **different** minimum delay offsets (see above). Specify a common delay offset for all of the sequenced units. The common delay offset must be larger or equal to the largest maximum delay offset. When the common delay offset completes, the user-programmed turn-on delays will start.

Connect and Configure the Digital Connector Pins

The digital connector pins of the sequenced units must be connected together and configured. Refer to Output Couple Control for more information.

Enable Output Sequencing

Output turn-on sequencing must be enabled on each unit that will participate in output turn-on synchronization.

Front Panel	SCPI Command
Select **Output\Sequence\Couple**. Check Enable to enable sequencing. Uncheck to disable.	To enable, send: OUTP:COUP ON To disable, send: OUTP:COUP OFF

Specify the Turn-On and Turn-Off Delays for each Unit

Turn-on delays can be specified for all coupled units. Any delay sequence can be implemented. There are no restrictions on what the sequence is or what unit comes up first.

Front Panel	SCPI Command
Select **Output\Sequence\Couple**. Specify the Turn-on delay in seconds. Repeat for each additional unit.	Program a turn-on delay: OUTP:DEL:RISE .02 Repeat for each instrument.

Turn-off delays can also be specified for all coupled units. Any delay sequence can be implemented. There are no restrictions on what the sequence is or what unit comes up first.

Front Panel	SCPI Command
Select **Output\Sequence\Couple**. Specify the Turn-off delay in seconds. Repeat for each additional unit.	Program a turn-off delay: OUTP:DEL:FALL .01 Repeat for each instrument.

NOTE There is no need to specify a delay offset when outputs turn off. Outputs start executing their turn-off delays as soon as an Output Off command is received.

Specify the Common Delay Offset

The following figures illustrate how the common delay offset can be used to synchronize the user-programmed turn-on delays when sequencing power supplies with different minimum delay offsets.

In the first figure, the actual start of the output turn on occurs at 22 ms, 58 ms, and 76 ms because the minimum delay offsets are added to the user-programmed turn on delay.
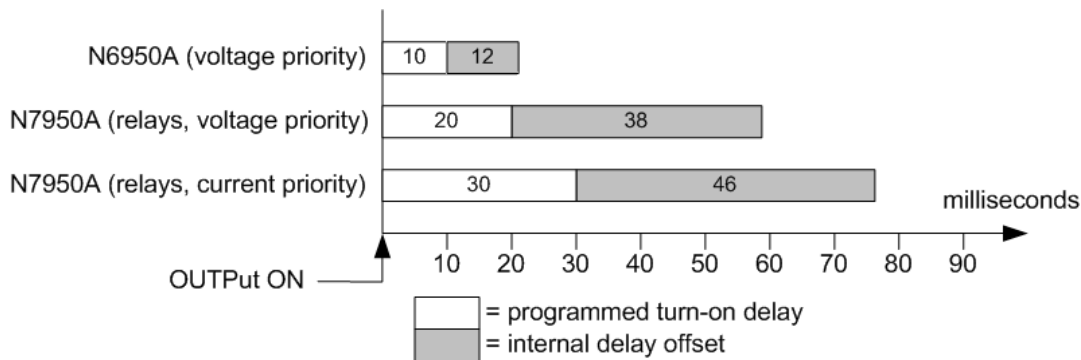
In the second figure, although you cannot eliminate the minimum delay offset, you can specify a common delay offset to accurately synchronize the user-programmed turn on delays with each other. In this example that actual start of the output turn-on occurs at 60 ms, 70 ms, and 80 ms respectively. You will always need to account for the common delay offset.
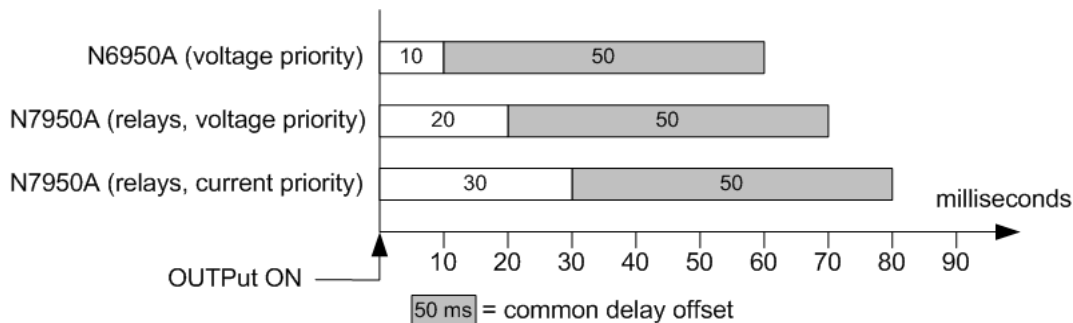
The common delay offset assures that the user-programmed turn-on delays will be synchronized to start at the completion of the common delay offset. Query the delay offset of each unit and use the slowest delay as the common delay offset.

Front Panel	SCPI Command
Select **Output\Sequence\Couple**. The Max delay offset for this frame field displays the delay offset of the unit. Enter the delay offset value of the slowest unit in the Delay offset field in milliseconds. Then press **Select**.	To query the delay offset of the slowest unit: OUTP:COUP:MAX:DOFF? Use the delay offset of the slowest unit to specify the common delay offset OUTP:COUP:DOFF .051

Making Measurements

Average Measurements

The APS models have a fully integrated voltmeter and ammeter to measure the actual voltage and current that is being supplied to the load.

Whenever the power supply is on, the front panel automatically measures output voltage and current by acquiring a number of measurements over the specified number of power line cycles, and averaging the samples. The default number of power line cycles is 1 cycle. At 1 cycle, the number of samples (or points) is 3255 @60 Hz and 3906 @50 Hz. The default sample interval is 5.12 microseconds.

Use the following commands to make a measurement:

Front Panel	SCPI Command
Select the **Meter** key. Repeatedly press the key to cycle through the following measurement functions: Voltage, Current Voltage, Power Voltage, Current, Power If dashes are displayed, the front panel measurement is interrupted because a remote interface measurement is taking place.	To measure average (DC) output voltage, current, or power: MEAS:VOLT? MEAS:CURR? MEAS:POW? To return measurement data from the previously acquired array: FETC:VOLT? FETC:CURR? FETC:POW?

Number of Power Line Cycles (NPLC)

You can set the measurement time in number of power line cycles (NPLC). Using an integer number of power line cycles can reduce measurement noise from line frequency sources.

Front Panel	SCPI Command
Select **Measure\NPLC** N6900 models only Select **Measure\Sweep** N7900 models only Enter the number of power line cycles in the NPLC field. Then press **Select**.	To set the number of power line cycles to 10 use: SENS:SWE:NPLC 10

> **NOTE** The AC line frequency is detected automatically for the SENSe:SWEep:NPLC command.

Measurement Windowing

Windowing is a signal conditioning process that reduces the error in average measurements made in the presence of periodic signals and noise. Two window functions are available: Rectangular and Hanning. At power-on, the measurement window is Rectangular.

The Rectangular window calculates average measurements without any signal conditioning. However, in the presence of periodic signals such AC line ripple, a Rectangular window can introduce errors when calculating average measurements. This can occur when a non-integral number of cycles of data has been acquired due to the last partial cycle of acquired data.

One way of dealing with AC line ripple is to use a Hanning window. The Hanning window applies a cos4 weighting function to the data when calculating average measurements. This attenuates the AC noise in the measurement window. The best attenuation is achieved when at least three or more waveform cycles are in the measurement.

Front Panel	SCPI Command
Select **Measure\Window**. Then select either **Rectangular** or **Hanning**. Then press **Select**.	To set the sense window to Hanning use: SENS:WIND HANN

Seamless Current Measurement Ranging N7900 models only

Agilent N7900 models have two current measurement ranges, a high and a low range (see specifications).A seamless current ranging function ensures that no data is lost due to range switching. Seamless ranging is enabled by default. The commands to enable seamless current measurement ranging are:

Front Panel	SCPI Command
Select **Measure\Range**. Select Auto to enable seamless measurement ranging. Then press **Select**.	To enable seamless measurement ranging: SENS:CURR:RANG:AUTO ON

You can also manually select the lower (or high) current measurement range. The lower current measurement range provides greater measurement accuracy, provided that the measurement does not exceed the range. If the measurement exceeds the range, an "Overload" error will occur. Use the following commands to select the low current measurement range.

Front Panel	SCPI Command
Select **Measure\Range**. Select the low (or high) measurement range from the current dropdown menu. Then press **Select**.	To set the 2.5 A range: SENS:CURR:RANG 2.5 Program any value up to the highest rating of the range.

Amp-Hour and Watt-Hour Measurements

Amp-hour and watt-hour measurements are available on all APS models. These measurements are made independently of other measurements.

The amp-hour and watt-hour measurements are created by accumulating full range current and power measurements at approximately 200k samples/second. The accumulators can hold enough data for at least 100,000 hours.

The approximate limit of accumulated charge is $\pm(900,000,000 \bullet I_{RATING})$ in Coulombs or $\pm(250,000 \bullet I_{RATING})$ in Amp-hours.

The approximate limit of accumulated energy is $\pm(1,100,000,000 \bullet P_{RATING})$ in Joules or $\pm(310,000 \bullet P_{RATING})$ in Watt-hours.

I_{RATING} is the current rating of the unit. P_{RATING} is the power rating of the unit (either 1 kW or 2 kW).

Front Panel	SCPI Command
Select **Measure\Window\AHWH**. Displays the accumulated Amp-hours and Watt-hours. Select Reset to return the measurements to zero.	To return the Amp-hours: FETC:AHO? To return the Watt-hours: FETC:WHO? To reset Amp-hours and Watt-hours: SENS:AHO:RES SENS:WHO:RES

Temperature Measurements

You can return the ambient temperature measured at he air inlet on the right side of the unit.

You can also return the difference in temperature between the internal temperature sensors and their over-temperature trip levels. The remaining temperature margin of the sensor that is closest to tripping the over-temperature protection is reported.

Temperature measurements are returned in degrees C.

Front Panel	SCPI Command
Select **Measure\Window\Temp**. Displays the ambient temperature and over-temperature margin in degrees C.	To return the ambient temperature: SYST:TEMP:AMB? To return the over-temperature margin: OUTP:PROT:TEMP:MARG?

Digitized Measurements `N7900 models only`

In addition to the average voltage, current, and power measurements, which are available from both the front panel and via SCPI commands, digitized measurements can also be returned. Digitized measurements differ from average measurements because you can select the type of measurement returned and fine tune the quality of the measurement.

Measurement Types

The following digitized measurements are available. These can only be measured using the corresponding SCPI command.

ACDC is a calculation that returns the total RMS measurement (AC + DC).

HIGH level is a calculation that generates a histogram of the waveform using 16 bins between the maximum and minimum data points. The bin containing the most data points above the 50% point is the high bin. The average of all the data points in the high bin is returned as the High level. If no high bin contains more than 1.25% of the total number of acquired points, then the maximum data point is returned.

LOW level is a calculation that generates a histogram of the waveform using 16 bins between the maximum and minimum data points. The bin containing the most data points below the 50% point is the low bin. The average of all the data points in the low bin is returned as the Low level. If no low bin contains more than 1.25% of the total number of acquired points, then the minimum data point is returned.

MAX is the maximum value of the digitized measurement.

MIN is the minimum value of the digitized measurement.

Array queries are also available to return ALL values in the voltage and current measurement buffer. No averaging is applied, only raw data is returned from the buffer.

Front Panel Menu	SCPI Command
Not available	To measure RMS voltage & current: MEAS:VOLT:ACDC? MEAS:CURR:ACDC? To measure the high level of a pulse: MEAS:VOLT:HIGH? MEAS:CURR:HIGH? To measure the low level of a pulse: MEAS:VOLT:LOW? MEAS:CURR:LOW? To measure the maximum value: MEAS:VOLT:MAX? MEAS:CURR:MAX? To measure the minimum value: MEAS:VOLT:MIN? MEAS:CURR:MIN?

	To take a measurement and return array data: MEAS:ARR:VOLT? MEAS:ARR:CURR? MEAS:ARR:POW?

Measurement Quality

The following figure illustrates the relationship between measurement samples (or points), and the time interval between samples in a typical measurement. You can fine tune the measurement by specifying the number of points in the measurement acquisition as well as the time interval between points.
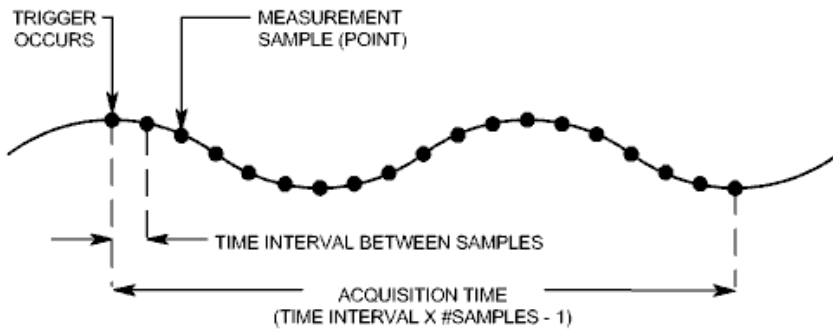
You can configure the measurement acquisition as follows:

Front Panel	SCPI Command
Select **Measure\Sweep**. Enter the number of points. Then press **Select**. Enter the time interval. Then press **Select**.	To set the time interval to 60µs with 4096 samples, use: SENS:SWE:TINT 60E-6 SENS:SWE:POIN 4096

The maximum number of sample points that are available for all measurements is 512 K points (K = 1024).

Time interval values can range from 5.12 microseconds to 40,000 seconds for both voltage and current measurements. Values above 5.12 microseconds are rounded to the nearest 5.12 microsecond increment. Values above 10.24 microseconds are rounded to the nearest 10.24 microsecond increment. Values above 20.48 microseconds are rounded to the nearest 20.48 microsecond increment.

Note that Agilent N7900 models also support the NPLC (number of power line cycles) command to configure measurement tint and points as previously discussed. The NPLC command automatically increases the number of points to maintain the shortest possible time interval. If the maximum number of points for that time interval is reached, it increases the time interval.

Measurement Triggering N7900 models only

- Capture pre-trigger data, if desired

- Select the trigger source

- Initiate the acquisition system

- Trigger the measurement

- Fetch the measurement

- Multiple trigger events per measurement

Use the acquisition trigger system to synchronize the digitized measurements with a trigger signal from a number of trigger sources. Then use FETCh commands to return voltage or current information from the acquired data.

The following figure illustrates the measurement acquisition process. This process applies to both measurement triggers and external data logging. For an overview of the trigger system, refer to Trigger Overview.
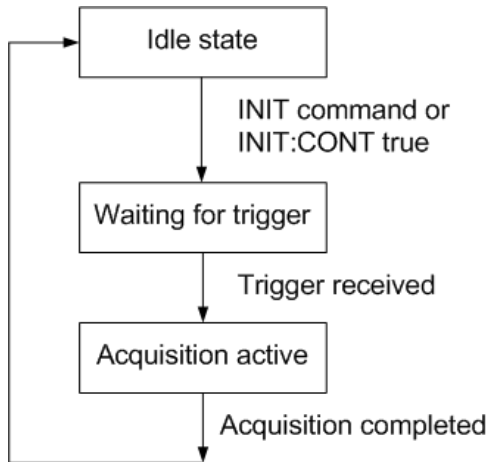
Capture pre-trigger data, if desired

The measurement system lets you capture data before, after, or at the trigger signal. As shown in the following figure, you can move the block of data being read into the acquisition buffer with reference to the trigger. This allows pre- or post-trigger data sampling.
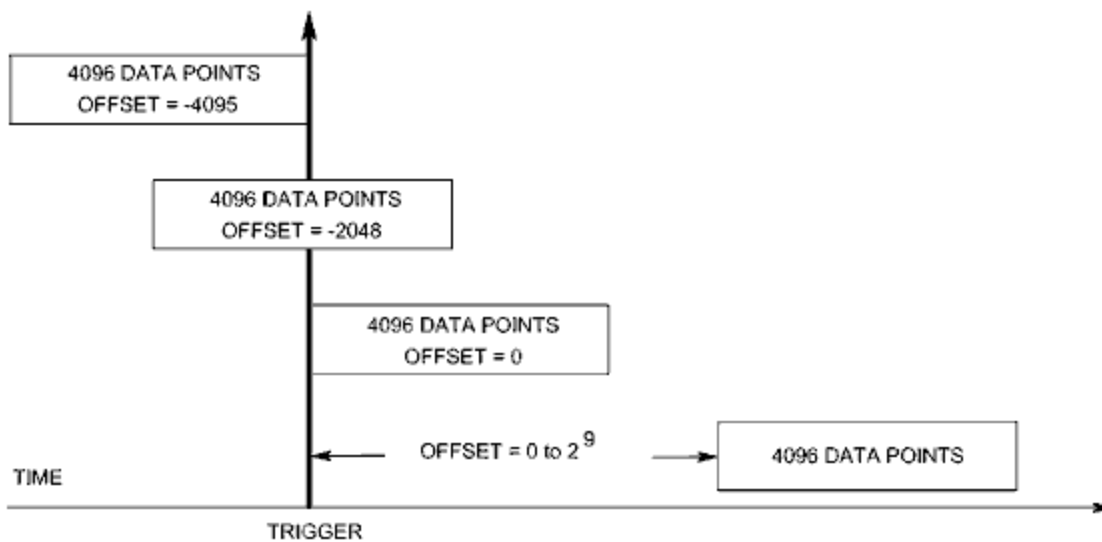
To offset the beginning of the acquisition buffer relative to the acquisition trigger:

Front Panel	SCPI Command
Select **Measure\Sweep**. Enter an Offset value. Then press **Select**.	To offset the measurement by 100 points use: SENS:SWE:OFFS:POIN 100

When the value is 0, all measurement samples are taken after the trigger. Positive values represent the delay after the trigger occurs but before the samples are acquired. This can be used to exclude measurement samples that occur during the delay time. (Delay time = offset x sample period). Negative values represent data samples taken prior to the trigger. This lets you acquire measurement samples prior to the trigger.

Select the trigger source

NOTE	A TRIGger:ACQuire[:IMMediate] command over the bus will always generate an immediate measurement trigger, regardless of the selected trigger source.

Unless you are using TRIGger:ACQuire[:IMMediate], select a trigger source from the following:

Trigger Source	Description
Bus	Selects GPIB device trigger, *TRG, or <GET> (Group Execute Trigger).
Current	Selects an output current level.
Expression<1-8>	Selects one of eight user-defined expressions. See Using Expression Signal Routing.
External	Selects ANY pin that has been configured as a Trigger Input on the digital control port.
Pin<1-7>	Selects a specific pin<n> that is configured as a Trigger Input on the digital control port.
Transient	Selects the unit's transient system. You must also set up the transient system to generate a trigger out signal. See Programming Output Transients.
Voltage	Selects an output voltage level.

Use the following commands to select a trigger source:

Front Panel	SCPI Command
Not available	To select Bus triggers: TRIG:TRAN:SOUR BUS To select digital pin 5 as the trigger: TRIG:ACQ:SOUR PIN5 To select a voltage or current level: TRIG:ACQ:SOUR VOLT TRIG:ACQ:SOUR CURR

	To select an output transient as trigger: TRIG:ACQ:SOUR TRAN
	To select expression1 as the trigger: TRIG:ACQ:SOUR EXPR1

Initiate the acquisition system

When the unit is turned on, the trigger system is in the idle state. In this state, the trigger system is disabled, ignoring all triggers. The INITiate commands enable the trigger system to receive triggers.

Front Panel Menu	SCPI Command
Not available	To initiate the measurement trigger system: INIT:ACQ

It takes a few milliseconds for the instrument to be ready to receive a trigger signal after receiving the INITiate:ACQuire command. If a trigger occurs before the trigger system is ready for it, the trigger will be ignored. You can test the WTG_ meas bit in the operation status register to know when the instrument is ready to receive a trigger after being initiated.

Front Panel	SCPI Command
Select **Measure\Control**. The Trig state field indicates "Initiated".	To query the WTG_meas bit (bit 3): STAT:OPER:COND?

If bit 3 is set in the query response, the WTG_meas bit is true, and the instrument is ready to receive the trigger signal. Refer to Status Tutorial for more information.

> **NOTE** The instrument executes one measurement acquisition each time a bus, external, pin, transient, or expression trigger command is received. Thus, it will be necessary to initiate the trigger system each time a triggered measurement is desired.

Trigger the Measurement

The trigger system is waiting for a trigger signal in the initiated state. You can immediately trigger the measurement as follows:

Front Panel Menu	SCPI Command
Not available	To generate a measurement trigger: TRIG:ACQ Alternatively, if the trigger source is BUS, you can also program a *TRG or an IEEE-488 <get> command.

As previously discussed, a trigger can also be generated by an output transient, a digital pin, and output voltage or current level, or a user-defined expression. If any of these systems are configured as the trigger source, the instrument will wait indefinitely for the trigger signal. If the trigger does not occur, you must manually return the trigger system to the idle state. The following commands return the trigger system to the idle state:

Front Panel	SCPI Command
Select **Measure\Control**. Then select the Abort control.	ABOR:ACQ

Fetch the measurement

After a trigger is received and the measurement completes, the trigger system will return to the idle state.

Once the measurement completes, FETCh queries can retrieve the most recent measurement data without initiating a new measurement or altering the data in the measurement buffer.

Front Panel Menu	SCPI Command
Not available	To return RMS voltage & current: FETC:VOLT:ACDC? FETC:CURR:ACDC? To return the high level of a pulse: FETC:VOLT:HIGH? FETC:CURR:HIGH? To return the low level of a pulse: FETC:VOLT:LOW? FETC:CURR:LOW? To return the maximum value: FETC:VOLT:MAX? FETC:CURR:MAX? To return the minimum value: FETC:VOLT:MIN? FETC:CURR:MIN? To return array data: FETC:ARR:VOLT? FETC:ARR:CURR? FETC:ARR:POW?

If a FETCh query is sent before the measurement is finished, the response will be delayed until the measurement trigger occurs and the acquisition completes. You can test the MEAS_active bit in the operation status register to know when the measurement trigger system has returned to the idle state.

Front Panel	SCPI Command
Select **Measure\Control**. The Trig state field indicates "Idle".	To query the MEAS_active bit (bit 5): STAT:OPER:COND?

If bit 5 is set in the query response, the MEAS_active bit is true, and the measurement is NOT complete. When the MEAS_active bit is false, you can retrieve the measurement. Refer to Status Tutorial for more information.

Multiple trigger events per measurement

The N7900 models can capture other triggers that occur during the acquisition, return the number and position of those triggers, and calculate DC values based on a subset of the data surrounding those triggers. The basic concept is that a single long acquisition may contain several events of interest, and that these events are marked by locations where additional triggers occurred. The locations of these events are described as an index into the acquisition's store of acquired data. Indices range from 0 to 1 less than the number of acquired readings (see SENse:SWEep:POINts).

You can query and return the indices where additional triggers occurred during the measurement. The number of indices returned matches the number of triggers that occurred.

Front Panel Menu	SCPI Command
Not available	To query how many (if any) additional triggers occurred: TRIG:ACQ:IND:COUN? To return the indices where the triggers occurred: TRIG:ACQ:IND?

You can also return the actual measurement data that was captured after any of the aforementioned trigger indices.

Front Panel Menu	SCPI Command
Not available	To return DC voltage or current calculated after the trigger indices: FETC:VOLT? [*<start_index>*, *<points>*] FETC:CURR? [*<start_index>*, *<points>*] To return instantaneous voltage or current data after the trigger indices: FETC:ARR:VOLT? [*<start_index>*, *<points>*] FETC:ARR:CURR? [*<start_index>*, *<points>*]

Using Expression Signal Routing

This section describes how expressions can be used to program signal routing. You can also use the Power Assistant software to program signal routing. For an overview of how the expression signals are mapped into the trigger system, refer to Trigger Overview.

Signal Routing Overview

Defining Signal Expressions

Configuring Threshold Comparators

Specifying Signal Expression Targets

Expression Constraints

Expression Examples

Signal Routing Overview

You can configure up to eight flexible, general purpose signal routing expressions. These signal expressions can be used to drive digital port pins, trigger measurements and transients, change output state, generate user-defined protection and user-defined status signals. Expressions are built using a large selection of signal inputs along with Boolean operators and programmable delays.

The following figure describes the signal routing paths:
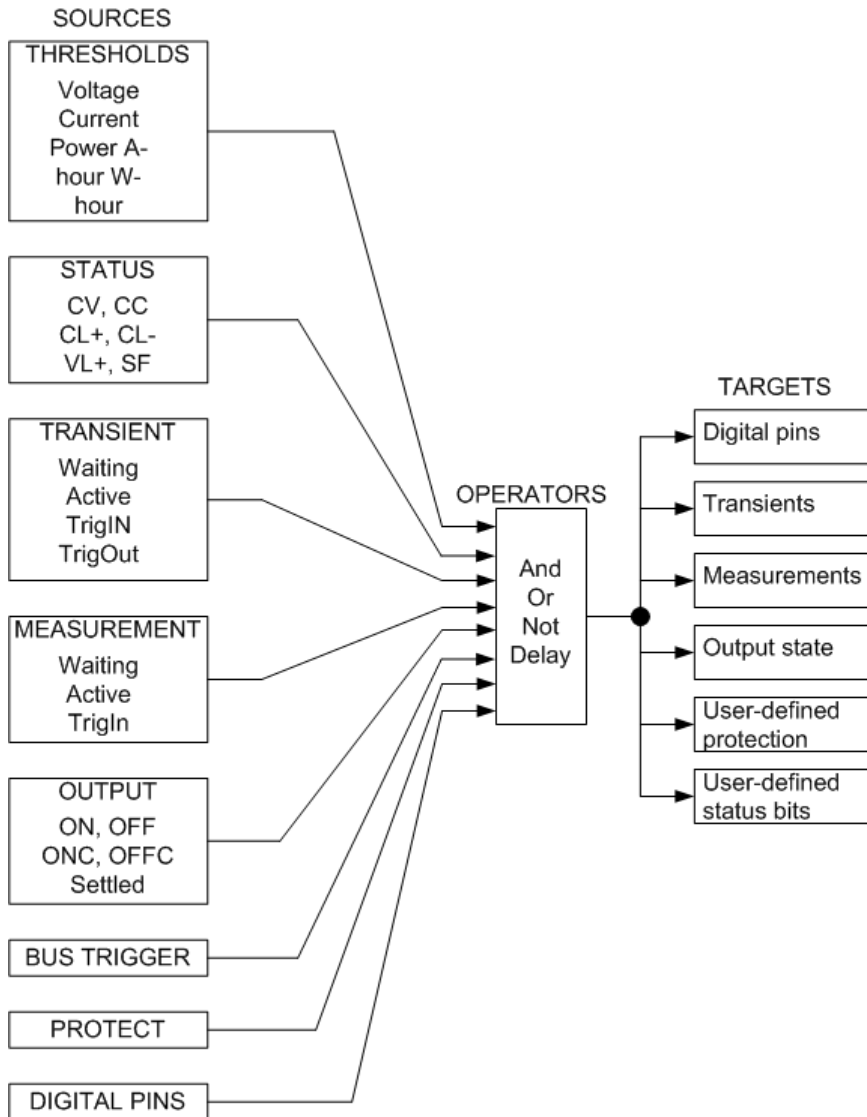
Defining Signal Expressions

Use the following command to define signal expressions:

Front Panel	SCPI Command
Select **System\Signal\Define**. Select an expression number (1 to 8) in the dropdown list. Existing expressions will be displayed in the text field. Enter the expression using the available input names and operators in the text field (see below).	To define signal expression number 1: SYST:SIGN:DEF EXPR1,"expression" Define the "expression" using the available input parameters and operators. See Examples.

You can enter any value from the numeric keypad. For additional characters, use the up/down navigation keys to enter an alpha character by scrolling through the selection list that appears when you press the keys. Use the left/right navigation keys to traverse the text field. Use the backspace key to delete a value. Press Enter when you are finished.

See Examples.

Expressions must be enclosed in quotes ("") inside SCPI commands. Expressions are case-insensitive. You can enter alpha characters as all caps , all lowercase, or mixed case. Spaces must be included on either side of the Boolean operators And, Or , and Not. Spaces are not required around parentheses.

The following table describes the available signal sources. The Type column describes the signal; an event generates a pulse; a state generates a level.

Signal Source	Type	Description
Thr<1-4>	state	Output of the SENSe:THReshold<1|2|3|4> comparators
WtgAcqTrig	event	Waiting for acquisition trigger
WtgTranTrig	event	Waiting for transient trigger
AcqActive	state	Acquisition is initiated or in progress
TranActive	state	Transient is initiated or in progress
AcqTrigIn	event	The trigger that causes the acquisition
TranTrigIn	event	The trigger that causes the transient
TranTrigOut	event	Triggers generated by a list or step
BusTrig	event	A received bus trigger, either *TRG or GET
DigPin<1-7>	state	A digital port pin
OutpOn	state	The output state is ON
OutpOff	state	The output state is OFF
OnC	event	Pulses true when the output is starting to turn on
OffC	event	Pulses true when the output is starting to turn off
OutpSettled	state	The output is settled (not transitioning from a setting change)
CV	state	The output is regulating in CV mode

CC	state	The output is regulating in CC mode
CL+	state	The output is in positive current limit
CL-	state	The output is in negative current limit
VL+	state	The output is in positive voltage limit
Prot	state	The output is disabled by an active protection function
OpenSense	state	The open sense status

The following Boolean operations (And, Or, Not), parentheses for grouping, and programmable delays can be applied to expression inputs.

Operator/Operation	Description
And, Or, Not	Boolean operations
()	Parentheses for grouping and nesting sub-expressions
Delay <sub-expression>, < time>,[<deglitch>]	Delays the signal described by expression and/or suppresses positive pulses narrower than the deglitch time parameter. Delays range from 0 to 167 seconds with these ranges: 0 to 0.02097 s with 1.28 us resolution 0.02097 to 0.167 s with 10.24 us resolution 0.167 to 1.677 s with 102.4 us resolution 1.677 to 16.776 s with 1.024 ms resolution 16.776 to 167.761 s with 10.24 ms resolution. Deglitch range is 0 to 85 seconds with 20 ns resolution. To program a deglitch value without programming a delay, simply enter zero as the delay time.

Configuring Threshold Comparators

The APS models have four built-in level comparators that can generate an output signal based on the comparison of two input signals. These comparators can be set to measure one of five different parameters types and generate a signal based on whether the measured parameter is greater than or less than the specified level:

VOLTage level - the measured voltage level.

CURRent level - the measured current level.

POWer level - the measured power level.

AHOur level - the measured amp-hour level.

WHOur level - the measured watt-hour level.

The following commands define a comparison of the measured voltage to a pre-defined level of 10 V for comparator #1:

Front Panel	SCPI Command
Select **System\Signal\Threshold**. Select the voltage comparator (1 - 4) from the Threshold dropdown list. Select one of 5 comparison parameters in the Function dropdown list (e.g. Voltage). Specify a threshold level in the Level field. Define the comparator output to be true when the measured level is either greater or less than the specified level. Select > or < in the Operation dropdown.	To specify a voltage comparison for comparator 1: SENS:THR1:FUNC VOLT To specify a voltage threshold of 10 V: SENS:THR1:VOLT:LEV 10 Define the comparator output to be true when the measured level is greater than (GT) 10 V: SENS:THR1:FUNC GT

Specifying Signal Expression Targets

Signal expressions can be used to control digital port pins, specify trigger sources, control the OnCouple/OffCouple signals, create user-defined protection functions, and generate user-defined status signals.

Digital Port Pins

To control digital port pins using expressions (see Programming the Digital Port):

Front Panel	SCPI Command
Select **System\IO\DigPort\Pins**. Select a pin in the Pin field. In the Function field, select the expression that will control the pin.	To control a digital pins: DIG<1-7>:FUNC EXPR<1-8>

Trigger Sources

To set output transient and measurement trigger sources using expressions (see Programming Transients and Making Measurements):

Front Panel	SCPI Command
Select **Transient\TrigSource**. Select the expression that will trigger the transient from Transient trigger source dropdown list. Select the expression that will trigger the Arb from the CD Arb trigger source dropdown list. Measurement trigger sources cannot be selected from the front panel.	To trigger transients using expressions: TRIG:TRAN:SOUR EXPR<1-8> To trigger Arbs using expressions: TRIG:ARB:SOUR EXPR<1-8> To trigger measurements using expressions: TRIG:ACQ:SOUR EXPR<1-8>

OnCouple/OffCouple Signals

To control the instrument's output state (on or off) using expressions:

Front Panel	SCPI Command
Select **System\Signal\Couple**. Select the expression that will turn the output on from the On couple source dropdown list. Select the expression that will turn the output off from the Off couple source dropdown list.	To turn the output on using expressions: OUTP:COUP:ON:SOUR EXPR<1-8> To turn the output off using expressions: OUTP:COUP:OFF:SOUR EXPR<1-8>

User-Defined Protection

To set the user-defined protection source using expressions (see Programming Output Protection):

Front Panel	SCPI Command
Select **System\Signal\Protect**. Select the expression that will set the user-defined protection from the Source dropdown list. Then check Enable.	To set user-defined protection: OUTP:PROT:USER:SOUR EXPR<1-8> To enable user-protection: OUTP:PROT:USER:STAT ON

User-Defined Status Events

To set the user-defined status bits using expressions (see Status Overview):

Front Panel	SCPI Command
Select **System\Signal\Status**. Select the expression that will control the User1 status bit from the User1 status source dropdown list. Select the expression that will control the User2 status bit from the User2 status source dropdown list.	To set user-defined status bits: STAT:OPER:USER<1,2>:SOUR EXPR<1-8>

Expression Constraints

There is a limit to the total number of expressions and delays that can be programmed.

- A maximum of 8 expressions may be created (EXPR<1-8>).

- A maximum of 11 **different** inputs can be used across all expressions.

- A maximum of eight delays can be used across all expressions.

- Delays cannot be nested.

- Combining delays with other operators reduces the number of available expressions. Each **additional** input or sub-expression that is combined with a delay using AND or OR, reduces the number of remaining available expressions by one.

In the following expression, because the delay is ORed with another input, the maximum number of remaining available expressions is six.

Front Panel	SCPI Command
Select **System\Signal\Define**. Select Expression 1 in the dropdown list. Enter "Delay(CV,1) Or CC" in the text field.	Program the signal expression. SYST:SIGN:DEF EXPR1, "Delay(CV,1) Or CC"

In the following expression, because the delay is ORed with two inputs, the maximum number of remaining available expressions is five.

Front Panel	SCPI Command
Select **System\Signal\Define**. Select Expression 1 in the dropdown list. Enter "Delay(CV,1) Or CC Or DigPin1" in the text field.	Program the signal expression. SYST:SIGN:DEF EXPR1, "Delay(CV,1) Or CC Or DigPin1"

In the following expression, because the delay is ORed with one sub-expression, the maximum number of remaining available expressions is six.

Front Panel	SCPI Command
Select **System\Signal\Define**. Select Expression 1 in the dropdown list. Enter "Delay(CV,1) Or (CC And DigPin1)" in the text field.	Program the signal expression. SYST:SIGN:DEF EXPR1, "Delay(CV,1) Or (CC And DigPin1)"

To put it another way, if the above three expressions (Examples 5-7) were all created, you would have only one more expression available for use.

Expression Examples

Example 1 Create a digital signal on pin1 of the digital port that is true whenever the output is in positive or negative current limit:

Front Panel	SCPI Command
Select **System\Signal\Define**. Select Expression 1 in the dropdown list.t. Enter "CL+ Or CL-" in the text field.	Program the signal expression. SYST:SIGN:DEF EXPR1, "CL+ Or CL-" Program the digital pin. DIG:PIN1:FUNC EXPR1

You can enter any value from the numeric keypad. For additional characters, use the up/down navigation keys to enter an alpha character by scrolling through the selection list that appears when you press the keys. Use the left/right navigation keys to traverse the text field. Use the backspace key to delete a value. Press Enter when you are finished. Select **System\IO\DigPort\Pins**. Select pin 1 in the Pin field. In the Function field, select Expr 1.	

Example 2 Create a trigger source that will trigger an output transient (step or list) whenever the output current is between 2.1 A and 2.7 A:

Front Panel	SCPI Command
Select **System\Signal\Threshold**. Select voltage comparator 1 (Threshold 1) from the dropdown list. Select Current from the Function list. Enter 2.1 in the Level field. Select > from the Operation list. Select voltage comparator 2 (Threshold 2) from the dropdown list. Select Voltage from the Function list. Enter 2.7 in the Level field. Select < from the Operation list. Select **System\Signal\Define**. Select Expression 2 in the dropdown list. Enter "THR1 And THR2" in the text field. You can enter any value from the numeric keypad. For additional characters, use the up/down navigation keys to enter an alpha character by scrolling through the selection list that appears when you press the keys. Use the left/right navigation keys to traverse the text field. Use the backspace key to delete a value. Press Enter when you are finished. Select **Transient\TrigSource**. Select Expr2 from the Transient trigger source list.	Program the threshold comparators. (GT = greater than; LT = less than) SENS:THR1:FUNC CURR SENS:THR2:FUNC CURR SENS:THR1:CURR 2.1 SENS:THR2:CURR 2.7 SENS:THR1:OPER GT SENS:THR2:OPER LT Program the signal expression. SYST:SIGN:DEF EXPR2, "THR1 And THR2" Program the output trigger source. TRIG:TRAN:SOUR EXPR2

Example 3 Create a custom protection that will disable the output if the output voltage moves outside the window between 23.5 V and 24.5 V:

Front Panel	SCPI Command
Select **System\Signal\Threshold**. Select voltage comparator 3 (Threshold 3) from the dropdown list. Select Voltage from the Function list. Enter 23.5 in the Level field. Select < from the Operation list. Select voltage comparator 4 (Threshold 4) from the dropdown list. Select Voltage from the Function list. Enter 24.5 A in the Level field. Select > from the Operation list. Select **System\Signal\Define**. Select Expression 3 in the dropdown list. Enter "THR3 Or THR4" in the text field. You can enter any value from the numeric keypad. For additional characters, use the up/down navigation keys to enter an alpha character by scrolling through the selection list that appears when you press the keys. Use the left/right navigation keys to traverse the text field. Use the backspace key to delete a value. Press Enter when you are finished. Select **System\Signal\Protect** Select Expr3 from the dropdown list. Then select Enable.	Program the threshold comparators. (GT = greater than; LT = less than) SENS:THR3:FUNC VOLT SENS:THR4:FUNC VOLT SENS:THR3:VOLT 23.5 SENS:THR4:VOLT 24.5 SENS:THR3:OPER LT SENS:THR4:OPER GT Program the signal expression. SYST:SIGN:DEF EXPR3, "THR3 Or THR4" Program the output protection state. OUTP:PROT:USER:SOUR EXPR3 OUTP:PROT:USER:STAT ON

Example 4 Create a trigger source that triggers a measurement 50 milliseconds after the output has settled..

Front Panel	SCPI Command
Select **System\Signal\Define**. Select Expression 4 in the dropdown list. Enter "Delay(OutpSettled, 0.05)" in the text field. You can enter any value from the numeric keypad. For additional characters, use the up/down navigation keys to enter an alpha character by scrolling through the selection list that appears when you press the keys. Use the left/right navigation keys to traverse the text field. Use the backspace key to delete a value. Press Enter when you are finished.	Program the signal expression. SYST:SIGN:DEF EXPR4, "Delay(OutpSettled,0.05)" Program the measurement trigger source. TRIG:ACQ:SOUR EXPR4

Programming the Digital Port

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Digital Control Port

A Digital Control Port consisting of seven I/O pins is provided to access various control functions. Each pin is user-configurable. The following control functions are available for the I/O pins. See SCPI Programming Reference for details on the SCPI commands to program the Digital Port.

The following table describes the possible pin configuration for the digital port functions. For a complete description of the electrical characteristics of the digital control port, refer to the Specifications section.

Function	Description
DIO	General-purpose ground-referenced digital input/output function. The output can be set with [SOURce:]DIGital:OUTPut:DATA.
DINput	Digital input-only mode. The digital output data of the pin is ignored.
EXPRession <1-8>	A user-defined expression drives the pin.
FAULt	Applies only to pin 1. Pin 1 functions as an isolated fault output. The fault signal is true when any output is in a protected state. Pin 2 serves as the isolated common for pin 1. When pin 1 is set to the FAULt function, the instrument ignores any commands to program pin 2. Queries of pin 2 will return FAULt. If pin 1 is changed from FAULt to another function, pin 2 is set to DINPut.
INHibit	Applies only to pin 3. When pin 3 is configured as an inhibit input; a true signal at the pin will disable the output.
ONCouple	Applies only to pins 4-7. The ONCouple pin synchronizes the output On state between instruments. Only one pin can be configured as an ONCouple. The pin functions as both an input and an output.
OFFCouple	Applies only to pins 4-7. The OFFCouple pin synchronizes the output Off state between instruments. Only one pin can be configured as an OFFCouple. The pin functions as both an input and an output.

TINput	A trigger input pin can be selected as the source for measurement and transient trigger signals. See TRIGger:ACQuire:SOURce and TRIGger:TRANsient:SOURce
TOUTput	A trigger output pin will generate output triggers from any subsystem that has been configured to output trigger signals.
Common	Applies only to pin 8. Connected to ground.

In addition to the configurable pin functions, the signal polarity (Positive or Negative) for each pin is also configurable. For level signals, POSitive indicates a voltage high at the pin. NEGative indicates a voltage low at the pin. For edge signals, POSitive means a rising edge and NEGative means a falling edge.

Bi-Directional Digital I/O

Each of the seven pins can be configured as general purpose bi-directional digital inputs and outputs. The polarity of the pins can also be configured. Pin 8 is the signal common for the digital I/O pins. Data is programmed according to the following bit assignments:

Pin	7	6	5	4	3	2	1
Bit Weight	6 (msb)	5	4	3	2	1	0 (lsb)

The digital I/O pin can be used to control both relay circuits as well as digital interface circuits. The following figure illustrates typical relay circuits as well as digital interface circuit connections using the digital I/O functions
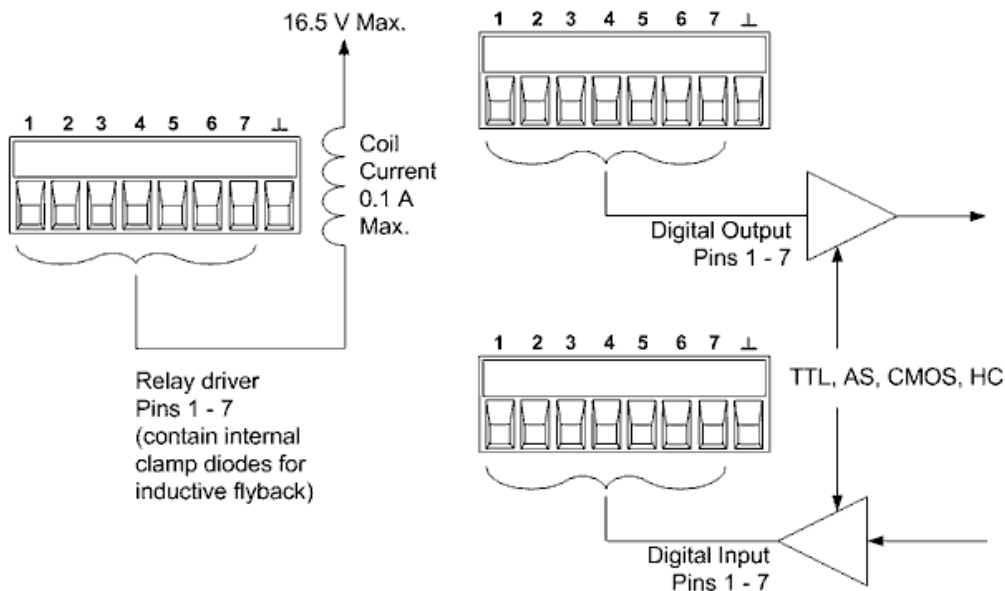
To configure the pins for digital I/O:

Front Panel	SCPI Command
Select **System\IO\DigPort\Pins**. Select a pin in the Pin field.	To select the pin function: DIG:PIN<1-7>:FUNC DIO

In the Function field, select Dig IO.	To select pin polarity: DIG:PIN<1-7>:POL POS
In the Polarity field, select either Positive or Negative.	To configure pins 1 through 7 as "0000111": DIG:OUTP:DATA 7
To send data to the pins, select **System\IO\DigPort\Data**.	
Select the Data Out field and enter the binary word.	

Digital Input

Each of the seven pins can be configured as digital input only. The polarity of the pins can also be configured. Pin 8 is the signal common for the digital input pins. The pin status reflects the true condition of the external signal that is applied to the pin. The pin state is not affected by the setting of DIGital:OUTPut:DATA. To configure the pins for digital input only:

Front Panel	SCPI Command
Select **System\IO\DigPort\Pins**.	To select the pin function: DIG:PIN<1-7>:FUNC DINP
Select a pin in the Pin field.	
In the Function field, select **Dig In**.	To select pin polarity: DIG:PIN<1-7>:POL POS
In the Polarity field, select either Positive or Negative.	To read the data on the pins: DIG:INP:DATA?
To read the data from the pins, select **System\IO\DigPort\Data**.	
The input data is displayed as a binary number in the Data In field.	

Expression<1-8>

NOTE   Refer to Using Expression Signal Routing for a complete description of the instrument's signal routing capability.

Each of the seven pins can be configured to have one of eight user-defined expressions drive the pin. The polarity of the pins can also be configured. Pin 8 is the signal common for the expression pins. To configure the pins for expressions:

Front Panel	SCPI Command
Select **System\IO\DigPort\Pins**.	To select the pin function: DIG:PIN<1-7>:FUNC EXPR1
Select a pin in the Pin field.	
In the Function field, select one of the 8 EXPRession functions.	To select pin polarity: DIG:PIN<1-7>:POL POS
In the Polarity field, select either Positive or Negative.	

External Trigger I/O

Each of the seven pins can be configured as trigger inputs or trigger outputs. The polarity of the pins can also be configured. When you program trigger polarity, POSitive means a rising edge and NEGative means a falling edge. Pin 8 is the signal common for the trigger pins. For an overview of the trigger system, refer to Trigger Overview.

When configured as a trigger input, you can apply either a negative-going or a positive-going pulse to the designated trigger input pin. The trigger latency is 5 microseconds. The minimum pulse width is 4 microseconds for positive-going signals, and 10 microseconds for negative-going signals. The pin's polarity setting determines which edge generates a trigger-in event.

When configured as a trigger output, the designated trigger pin will generate a 10 microsecond-wide pulse when a Trigger Out occurs. Depending on the polarity setting, it can be either positive-going (rising edge) or negative-going (falling-edge) when referenced to common.

Front Panel	SCPI Command
Select **System\IO\DigPort\Pins**. Select a pin in the Pin field. In the Function field, select either the Trig In or Trig Out function. In the Polarity field, select either Positive or Negative.	To select the trigger output function for pin 1: DIG:PIN1:FUNC TOUT To select the trigger input function for pin 2: DIG:PIN2:FUNC TINP To select the pin polarity: DIG:PIN1:POL POS DIG:PIN2:POL POS

Fault Output

Pins 1 and 2 can be configured as a fault-output pair. The Fault Output function enables a fault condition to generate a protection fault signal on the digital port. Refer to Programming Output Protection for a list of protection signals.

Both pins 1 and 2 are dedicated to this function. Pin 1 is the Fault output; pin 2 is the common for pin 1. This provides for an optically-isolated output. The polarity of pin 1 can also be configured. When the pin polarity is POSitive, a fault condition causes the isolated output to conduct. Note that the Fault output signal remains latched until the fault condition is removed and the protection circuit is cleared. as explained under Clearing Protection Functions.

NOTE   Pin 2's selected function is ignored. Pin 2 should be connected to the ground of the external circuit.

Front Panel	SCPI Command
Select **System\IO\DigPort\Pins**. Select pin 1, then Function, then Fault Out. In the Polarity field, select either Positive or Negative.	To configure the Fault function: DIG:PIN1:FUNC FAUL To select the pin polarity: DIG:PIN1:POL POS

Inhibit Input

Pin 3 can be configured as a remote inhibit input. The Inhibit Input function lets an external input signal control the output state of instrument. The input is level triggered. The signal latency is 5 microseconds. Pin 8 is the common for pin 3.

The following non-volatile inhibit input modes can be programmed:

LATChing - causes a logic-true transition on the Inhibit input to disable the output. The output will remain disabled after the inhibit signal is received.

LIVE - allows the enabled output to follow the state of the Inhibit input. When the Inhibit input is true, the output is disabled. When the Inhibit input is false, the output is re-enabled.

OFF - The Inhibit input is ignored.

To configure the Inhibit Input function:

Front Panel	SCPI Command
Select **System\IO\DigPort\Pins**. Select pin 3, then Function, then Inhibit In. In the Polarity field, select either Positive or Negative. Select **Protect\Inhibit**. Select either Latching or Live. To disable the Inhibit signal, select Off.	To select the Inhibit function: DIG:PIN3:FUNC INH To select the pin polarity: DIG:PIN3:POL POS To set Inhibit mode to Latching: OUTP:INH:MODE LATC To set Inhibit mode to Live: OUTP:INH:MODE LIVE To disable the Inhibit signal: OUTP:INH:MODE OFF

Fault/Inhibit System Protection

As shown in the following figure, when the Fault outputs and Inhibit inputs of several instruments are daisy-chained, an internal fault condition in one of the units will disable all outputs without intervention by either the controller or external circuitry. Note that when using the Fault/Inhibit signals in this manner, both signals must be set to the same polarity.

Also, as shown in the figure, you can also connect the Inhibit input to a manual switch or external control signal that will short the Inhibit pin to common whenever it is necessary to disable all outputs. **Negative** polarity must be programmed for all pins in this case. You can also use the Fault output to drive an external relay circuit or signal other devices whenever a protection fault occurs.
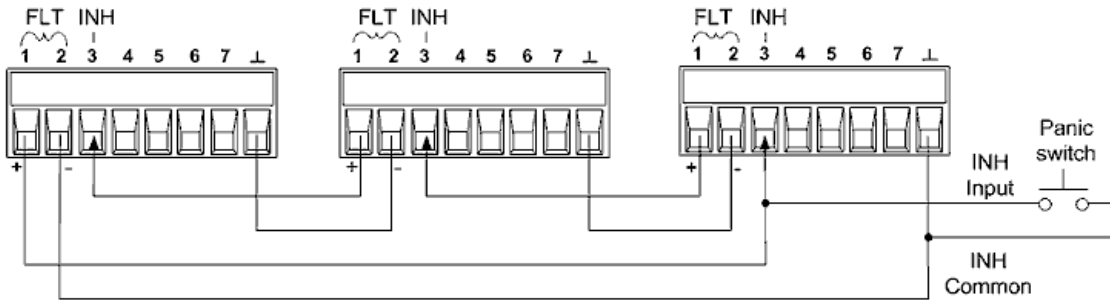
Clearing a System Protection Fault

To restore all instruments to a normal operating condition when a fault condition occurs in a daisy-chained system protection configuration, two fault conditions must be removed:

1. The initial protection fault or external Inhibit signal.

2. The subsequent daisy-chained fault signal (which is sourced by the Inhibit signal).

> **NOTE** Even when the initial fault condition or external signal is removed, the Inhibit fault signal is still active and will continue to shut down the outputs of all the units.

To clear the daisy-chained fault signal if the operating mode of the Inhibit input is Live, simply clear the output protection on any ONE unit as explained in chapter 4. If the operating mode of the Inhibit input is Latched, turn off the Inhibit input on ALL units individually. To re-enable the chain, re-program the Inhibit input on each unit to Latched mode.

Output Couple Control

This function lets you connect multiple instruments together and synchronize the output on/off sequence across all units. Each unit that will be sequenced must also be "coupled" to the other units.

1. Couple the output on each unit as described under Sequencing the Output.

2. Set the delay offset of each individual unit to match the longest delay offset of the group.

3. Connect and configure the digital connector pins of the sequenced units as shown below.

Only pins 4 through 7 can be configured as "coupled" pins. The designated pins will function as both an input and an output, with a negative transition on one pin providing the sequence signal to the other pins. The polarity of the pins is not programmable; it is set to NEGative.
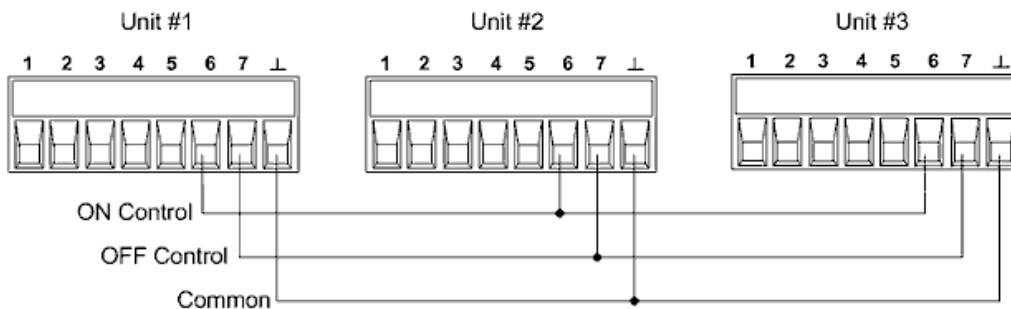
In this example, pin 6 is configured as the output On control. Pin 7 is configured as the output Off control. The ground or Common pins are connected together.

Front Panel	SCPI Command
Select **System\IO\DigPort\Pins**. Select pin 6, then Function, then ONCouple. Select **Pins**., select pin7, then Function, then OFFCouple. Repeat these steps for units #2 and #3	To set pin 6 of unit 1 as the ON control: DIG:PIN6:FUNC ONC To configure pin 7 of unit 1 as the OFF control: DIG:PIN7:FUNC OFFC Repeat these commands for units 2 and 3.

Once configured and enabled, turning the output on or off on any coupled unit will cause all coupled units to turn on or off according to their user-programmed delays.

External Data Logging (Elog) [N7900 models only]

Select the Measurement Function and Range

Specify the Integration Period

Select the Elog Trigger Source

Initiate and Trigger the Elog

Periodically Retrieve the Data

Terminate the Elog

External Data Logging

| NOTE | The external data logging function can only be programmed using SCPI commands.

The Agilent N7900 models have an "external" data logging function (Elog) that lets you continuously log voltage and current measurements independently of other measurement functions. Data logging is external to the instrument because it can only be implemented using SCPI commands. Voltage and current measurement data is temporarily stored in a FIFO (first-in, first-out) buffer located in the instrument. However, this buffer is only large enough to hold about 20 seconds of accumulated measurements. This means that you must periodically empty the internal buffer to an external storage device; otherwise the data in the buffer will be overwritten.

The following table details the various data logging functions.

Function	Description
Data Storage	Buffers measurements for about 20 seconds and requires that the computer periodically reads measurements to prevent the internal buffer from overflowing. The computer needs to provide the external data storage.
Measurement Functions	Both output voltage and output current can be logged.
Integration Period	Minimum integration period is 102.4 microseconds for one parameter with data format set to REAL. During the specified integration period, the samples are averaged, and min and max values are tracked.
Data viewing	No front panel view or control. Data is collected and viewed externally.

Note that the Elog function uses the acquire trigger process to make the measurements.

Select the Measurement Function and Range

The following commands select a measurement function:

Front Panel	SCPI Command
Not available	To enable voltage or current measurements: SENS:ELOG:FUNC:VOLT ON SENS:ELOG:FUNC:CURR ON

	To enable min/max measurements: SENS:ELOG:FUNC:VOLT:MINM ON SENS:ELOG:FUNC:CURR:MINM ON

Agilent N7900 models have two current measurement ranges, a high and a low range (see specifications). A seamless current ranging function ensures that no data is lost due to range switching. Seamless ranging is enabled by default. The commands to enable seamless current measurement ranging are:

Front Panel	SCPI Command
Not available	To enable seamless elog autoranging: SENS:ELOG:CURR:RANG:AUTO ON

Specify the Integration Period

The integration period can be set from a minimum of 102.4 microseconds to a maximum of 60 seconds.

Front Panel	SCPI Command
Not available	To set an integration period of 600 microseconds: SENS:ELOG:PER 0.0006

During the integration period, Elog samples are averaged, and the minimum and maximum values are tracked. At the end of each integration period the average, minimum, and maximum values are added to the internal FIFO buffer.

Although the absolute minimum integration period is 102.4 microseconds, the actual minimum depends on the number of measurements that are being logged. The formula is 102.4_microseconds X #_of_measurements. For example:

102.4 microseconds: 1 measurement (voltage or current)
204.8 microseconds: 2 measurements (voltage and current)
409.6 microseconds: 4 measurements (voltage+min+max+current)

If the specified integration period is at or near the minimum logging intervals, the data format must be specified as binary. If the REAL format is not specified, the data will be in ASCII format and the minimum logging intervals will typically be up to five times longer than what can be achieved with binary format.

Front Panel	SCPI Command
Not available	To set the data format to REAL: FORM[:DATA] REAL

Select the Elog Trigger Source

The TRIGger:ELOG command generates an immediate trigger regardless of the trigger source. Unless you are using this command, select a trigger source from the following:

Trigger Source	Description
Bus	Selects GPIB device trigger, *TRG, or <GET> (Group Execute Trigger).

External	Selects ANY pin that has been configured as a Trigger Input on the digital control port.
Immediate	Triggers the transient as soon as it is INITiated.
Pin<1-7>	Selects a specific pin<n> that is configured as a Trigger Input on the digital control port.

Use the following commands to select one of the available trigger sources:

Front Panel	SCPI Command
Not available	To select Bus triggers: TRIG:TRAN:SOUR BUS To select digital pin 5 as the trigger: TRIG:ACQ:SOUR PIN5 To select expression1 as the trigger: TRIG:ACQ:SOUR EXPR1

Initiate and Trigger the Elog

When the power supply is turned on, the trigger system is in the Idle state. In this state, the trigger system is disabled, ignoring all triggers. The INITiate command enables the measurement system to receive triggers. To initiate and trigger the Elog:

Front Panel	SCPI Command
Not available	To initiate the Elog: INIT:ELOG To trigger the Elog: TRIG:ELOG Alternatively, if the trigger source is BUS, you can also program a *TRG or an IEEE-488 <get> command.

When triggered, the Elog starts placing data in the internal measurement buffer. Because the buffer is only large enough to hold 20 seconds of accumulated measurement your PC application must periodically retrieve (or fetch) the data from this buffer.

Periodically Retrieve the Data

Each FETCh command returns number of requested records of the data in the buffer and removes them, making room available for more data. The Elog continues until it is aborted.

An Elog record is one set of voltage and current readings for one time interval. The exact format of a record depends on which functions have been enabled for Elog sensing. If all functions are enabled, then one record will contain the following data in the specified order:

Current average
Current minimum
Current maximum
Voltage average
Voltage minimum
Voltage maximum

Front Panel	SCPI Command
Not available	To retrieve a maximum of 1000 records: FETC:ELOG? 1000

ASCII data (the default format) is returned as comma-separated ASCII numeric data sets of average/min/max values terminated by a newline. REAL data is returned as a definite length block, with the byte order specified by the FORMat:BORDer command.

Terminate the Elog

Front Panel	SCPI Command
Not available	To abort the Elog: ABOR:ELOG

Black Box Data Recording

Black Box Recorder

Logged Data

BBR Status

BBR Period

BBR Length

Snapshot Operation

Snapshot Event Tags

BBR Clock Setup

BBR Alignment

Black Box Recorder

The N7908A Black Box Recorder is a user-installable option that performs continuous background logging of output voltage, current, power, and system status to its own dedicated mass storage device.

> **NOTE**   You must use the Power Assistant software to view the BBR data after a snapshot operation. You cannot view BBR data on the front panel or view the data using SCPI commands.

The following list describes the key attributes of the BBR function:

- The BBR drive is discovered at power-on and is automatically enabled. If the BBR is not present or working, a self-test error is generated and logging is disabled. Refer to BBR Status.

- Logging starts automatically when the unit is turned on and does not interfere with any source or measurement functions of the unit. Logging is done to a circular queue of approximately 380 MB.

- Two available logging rates are: one record every 10 ms, or one record every 100 ms. The 10 ms rate saves 24 hours of data before the queue overwrites. The 100 ms rate saves 10 days of data before the queue overwrites.

- Logging never stops while the unit is on except when the logging rate or the real-time clock settings are changed. In these cases, logging is paused and restarted. Logging also stops when a Power-fail protection occurs. In this case logging only resumes after output protection is cleared by the user when AC power returns.

- Logged data is preserved after a power cycle. A time-stamped event is logged each time power is turned on.

Logged Data

The following output measurements are automatically logged per data record:

Average voltage	Average current	Average power
Maximum voltage	Maximum current	Maximum power
Minimum voltage	Minimum current	Minimum power

Status bits and events are also logged into the BBR. Refer to Questionable Status Group for status definitions. You can select the status items using the Power Assistant software.

BBR Status

To check the status of the Black Box Recorder:

Front Panel	SCPI Command
Select **System\BBR\Status** A message displays the BBR status.	SYST:BBR:STAT? Returns true if the BBR is logging.

When the BBR drive has been removed from an instrument, the status message indicates: "BBR is enabled but drive was not detected. If removed, disable to stop error messages". To disable subsequent self-test errors and remove the BBR accessory from the instrument's option list, press the Disable button that appears on the display. The status message will then indicate "BBR is not installed".

BBR Period

To specify the logging period:

Front Panel	SCPI Command
Select **System\BBR\Period** Select either 10 ms or 100 ms.	SENS:BBR:PER 0.1 Specifies a period of 100 ms.

BBR Length

To return the length of the BBR data:

Front Panel	SCPI Command
Select **System\BBR\Snapshot** The length of the BBR data in hours is displayed in the Logged Data field.	SYST:BBR:TIME? Returns length of the BBR data in seconds.

Snapshot Operation

- It is good practice to verify the system date and time before retrieving Black Box data. Refer to BBR Clock Setup.

- You can retrieve logged data by requesting a "snapshot" either from the front panel or using SCPI commands. Snapshot operation can take up to 1 minute. You cannot request another snapshot while one is already in progress. On the front panel, the snapshot time is specified in hours and percent of hours. In SCPI, the time is specified in seconds.

- The snapshot always uploads from the most recent data entry on back.

- Snapshot copies the specified data into separate data and event files.

- Snapshot files can be retrieved and viewed on a PC using the Power Assistant software.

To make a snapshot of the recorded data:

Front Panel	SCPI Command
Select **System\BBR\Snapshot** Enter a time period in the Snapshot field. For example, 1.5 would be one and a half hours. Select Enter. Then select Snapshot. The Status field displays the percent completion of the snapshot operation.	SYST:BBR:SNAP 5400 Specify the time period in seconds. For example, 5,400 seconds specifies a time period of one and a half hours. To return the percent snapshot completion, use: SYST:BBR:SNAP:STAT?

Snapshot Event Tags

The BBR has a separate event log that is synchronized with data log. You can add user-defined event tags to the BBR data. This can only be accomplished via SCPI commands, and not from the front panel.

- The BBR event file log has room for 100,000 event strings.

- The maximum length of the event string is 53 characters.

- Events that are older than the oldest BBR data are deleted.

- Data logging is not paused for an event log.

The event is logged as soon as the event command is received. To add an event to the event log:

Front Panel	SCPI Command
Not available	SYST:BBR:EVEN "Starting Test ABC at 10:05:02" Places the quoted text into the event log.

BBR Clock Setup

The real-time clock is used to time-stamp the BBR, which is its only function. When shipped, the real-time clock is set to Greenwich mean time. To set the clock:

Front Panel	SCPI Command
Select **System\Preferences\Display\Clock**. Enter the date in the Month, Day and Year fields. Enter the time in the Hour, Minute, and Second fields. Press Select to set the date and time.	To set the date: SYSTem:DATE To set the time: SYSTem:TIME

NOTE   There will be a slight gap/discontinuity of less than 1 second in the BBR record when the clock is set.

BBR Alignment

If the BBR option is installed, it is recommended that you align the real-time clock in the power supply with the clock on your computer/controller before you perform any critical activity or test. This will remove any error due to long term clock drifting.

Clock Drift

The real-time clock's time base has a tolerance of ±100 ppm. This causes the time base to steadily drift in relation to a perfect time reference. The following table illustrates this effect on long term BBR measurements. Note that drift times apply to both 10 ms and 100 ms logging rates.

Logging Time	Drift
1 hour	±0.36 seconds
1 day	±8.64 seconds
10 days (requires 100 ms logging rate)	±86.4 seconds

BBR Alignment Methods

Method 1 - Set the real-time clock using the front panel or SCPI command as described above under Real Time Clock Setup. Note that there is no automated way to synchronize the RTC to NIST, TIME.GOV, or other internet clock sources. There is no external clock input to set the real-time clock. Once the real time clock has been set on multiple units, mis-alignment of the BBR records between units will be minimized.

Method 2 - Send a text message (event tag) into the BBR record using the SCPI SYSTem:BBR:EVENt "message" command. With this command, you can write a text record into the BBR log to mark a particular time in the record. For example, you can send the following text message into the event log "Starting Test ABC at 10:05:02". Each BBR record is logged every 10 ms (or 100 ms), so the message alignment should be within 1-2 records or 10-20 ms of the logged data, depending on how fast you can read and send the time to the instrument. By sending this event tag to several units, you can create a common event tag to align all BBR records.

Method 3 - Send a digital pulse into a digital input pin on the rear of the power supply (see Digital Input). This digital pulse will be detected and can be setup to trigger a user-defined status bit. See Using Expression Signal Routing. All status bits, including the user-defined status bit, are recorded in the BBR log. This will locate the pulse to within 10 ms, as the BBR is logged every 10 ms (or 100 ms). By sending this pulse into several units, you can create a common event tag to align all BBR records. Of course, you can combine these last two methods and also tag the digital pulse with a text message in the log to record the meaning of that particular pulse.

Current Sharing Operation

[Program the Output Voltage and Current](#)

[Enable the Current Sharing Function](#)

[Specification Effects](#)

[Current Sharing Effects](#)

Introduction

> **CAUTION**   **Equipment Damage** For parallel operation, only connect power supplies that have the same voltage rating.

Current sharing is an analog control function that fine-tunes the output voltage up to about 0.5% of the unit's voltage rating, so that multiple units may be paralleled when operating in voltage or current priority mode. In this way, models having the same voltage rating can share current equally among participating units.

The current sharing setup consists of paralleling the output terminals and connecting the Sharing cable as described under [Parallel Connections](#). The Sharing cable provides the analog signal that allows units of the same voltage rating to share current equally. You must also program the output voltage and current and enable the sharing function as described in this section. The following list details the current sharing operation:

- Connect no more than five units **of identical voltage ratings** in parallel.

- If any paralleled units are turned on or off while current sharing, the load current will automatically be shared among the remaining active units, provided that the required load current is within the current capability of the remaining units.

- Units of mixed power (1 kW and 2 kW) with the same voltage rating can participate in current sharing. This lets you take advantage of the higher current capability of the 2 kW units.

- The current sharing function can be turned on or off from the front panel as explained under [Enable the Current Sharing Function](#). This action opens the sharing relay, which disconnects the sharing bus. This lets you configure the output leads for parallel or non-parallel operation with the current sharing cable installed.

- To determine the total load current, you must sum the output current readings of the individual paralleled units.

Program the Output Voltage and Current

Refer to [Set the Output Voltage](#) and [Set the Output Current](#) for details.

In voltage priority mode:

- Program the output voltage setting of each participating unit to the same value.

- Set the current limit of each participating unit according to the following equations. This will allow all units to share current until the total current limit point is reached, which is the sum total of all the individual current limits.

For each 1kW unit: $I_{CL\_1kW} = I_{CL\_TOTAL} / (N_T + N_{2kW})^*$
For each 2kW unit: $I_{CL\_2kW} = 2(I_{CL\_TOTAL}) / (N_T + N_{2kW})$

where:

I_{CL_1kW} is the current limit setting of the 1kW unit

I_{CL_2kW} is the current limit setting of the 2kW unit

I_{CL_TOTAL} is the sum total of all individual current limits

N_T is the total number of paralleled units of any rating

N_{2kW} is the total number of paralleled 2 kW units

*If there are no 2kW units used, then $N_{2kW}= 0$.

Note that in a mixed power configuration, you must set the current limit of the 2 kW units to twice the value of the 1 kW units. This is because in a mixed power configuration, each 2kW unit will contribute twice as much current as each 1kW unit.

When the current limit setting of any paralleled unit is reached, the output current of that unit will limit at its specified setting.

In current priority mode:

- Set the voltage limit of each participating unit to the same value.

- Program the current setting of each participating unit according to the equations above if current sharing is desired. The total output current will be the sum of all the individual current settings.

Note that in current priority mode, the sharing configuration will balance the currents only if all of the units are operating in voltage limit mode, with the CV status annunciator on.

Enable the Current Sharing Function

When current sharing is enabled, the front panel status indicator displays a "P", indicating that the sharing function has been enabled and the sharing relay has closed to connect the instrument to the Sharing bus.

Front Panel	SCPI Command
Select **Output\Advanced\CurrSharing** Check Enable current sharing to enable. Uncheck to disable. Then press **Select**.	To enable or disable current sharing: CURR:SHAR ON|OFF

> **NOTE** When the output is disabled, the sharing relay automatically opens and disconnects the unit from the Sharing bus.

Specification Effects

The design of the APS has been optimized for parallel operation. Therefore, the effect of paralleled units on the specifications has been kept to a minimum.

When units are paralleled, there is no degradation of any specification other than the load regulation specification. All other specifications, including output noise, programming accuracy, readback accuracy, and transient response are unaffected by paralleled operation. For example, the transient response specification for a paralleled combination is the same as the transient response for an individual unit.

Load Regulation Effect

With two or more units are paralleled with current sharing enabled, there will be a small additional voltage regulation effect. The worst case additional voltage regulation effect is as follows:

$$\Delta V_{OUT(WORST\_CASE)} = 0.003\% (V_{RATING})$$

To determine the total output voltage regulation effect for a specific unit, you must add the worst-case value from the following table to the CV load regulation specification for each paralleled unit.

These are the worst-case values for each unit based on its voltage rating.

V_{RATED}	$\Delta V_{OUT(WORST\_CASE)}$
9 V	0.27 mV
20 V	0.60 mV
40 V	1.20 mV
60 V	1.80 mV
80 V	2.40 mV

Example: You have two 80 V units connected in parallel. The load regulation effect due to current sharing is 2.4 mV from the table above. The CV load regulation specification is 2 mV. Therefore, the total output voltage regulation effect is 2 mV + 2.4 mV, or 4.4 mV.

Current Sharing Effects

This section describes the current sharing effects of the paralleled units. These only affect the operation of the paralleled units when operating near the current limit setting in voltage priority mode, operating near the voltage limit setting in current priority mode, or when using the low current measurement range.

In an ideal current sharing configuration, the total load current would be shared equally among all paralleled power supplies. For example, if you have three 1kW units connected in parallel and the load draws 75 A, each 1kW unit would contribute *exactly* 25 A to the total load current requirement.

However, due to internal offset and gain differences among the paralleled units, there will be slight differences in the current being shared by the individual units. Normally this does not affect the operation of the units or the total current being drawn by the load in any way. However, because of these slight sharing differences, the output current of an individual unit may bump up against the current limit setting before the other units do. This will result in a current sharing fault (CSF), which means that one of the units is no longer sharing current equally. The units will continue to source current until the current limit setting of all units is reached. If the load current attempts to increase above the sum of the individual current limits, the paralleled units will be in constant current mode, with the output current being regulated rather than the output voltage.

Another way that current sharing deviation can affect operation is when using the low current measurement range on N7900 models. Current sharing deviations are greater as a percentage of output current when operating at low current levels than when operating at high current levels. Thus, when operating at less than 10 % of the output current rating, the current sharing offset errors between paralleled units may be large enough to cause an unexpected "Out of Range" measurement error on the low current range. It is therefore recommended to leave the measurement range setting on Auto.

Note that when current sharing, the algebraic sum of the contributed currents of the paralleled units will always equal the total current drawn by the load. To determine the total load current, you must sum the output current readings of the individual paralleled units.

If you need to determine what the worst case current deviation among paralleled units is, refer to the Current Sharing Tutorial.

Current Sinking Operation

Power Dissipator Operation

Querying the Power Dissipator

Current Sinking

Current sinking, also referred to as down-programming, is the ability to pull current into the positive terminal of the DC power supply. For example, the power supply pulls or sinks current into the positive terminal whenever a lower output voltage is programmed. This is necessary because stored energy from the power supply's output capacitor and external capacitance from the load including the wiring must be discharged to lower the voltage at the output terminals.

The ability to rapidly transition from a higher to a lower constant voltage level greatly improves the power supply's output response time. This is the most commonly used function of the built in down-programmer, which is automatic and completely transparent to the user.

When operated as a stand-alone unit, the DC power supply can continuously sink up to 10% of its rated current for an indefinite time. This is adequate for rapidly down-programming the majority of loads connected to the output.

With the addition of Agilent N7909A Power Dissipator Units, the DC power supply can sink up to 100% of it rated current. This allows for the possibility of sinking the power supply's full rated output current for an indefinite time. This capability is useful with large capacitive loads, or with battery charging/discharging applications.

Note that this two-quadrant sourcing and sinking capability of the DC power supply allows for seamless transitions between sourcing and sinking current without changing the power supply's output characteristics or introducing any disruptive behavior. The following controls are provided to fully utilize the two-quadrant output capability of the supply.

Current Limit control in voltage priority mode

When operating in voltage priority mode, you can program a negative or positive current limit. This will limit any current overshoots that may occur during rapid down-programming or up-programming.

Current setting control in current priority mode

When operating in current priority mode, you can program the output current to seamlessly cross the zero point when transitioning from positive to negative or negative to positive. Additionally, when operating in the negative current quadrant, you can program a negative current setting that will hold the sink current at the specified value. This is useful, for example, for discharging a battery at a constant current rate.

If your application requires precise control of the source and sink currents, current slew controls are available to specify a current slew rate when sourcing and sinking current.

Power Dissipator Operation

Power supply models rated at 1 kW, require one Agilent N7909A power dissipator to sink 100% of their rated current. Power supply models rated at 2 kW, require two Agilent N7909A power dissipators to sink 100% of their rated current. 2 kW models connected to one power dissipator can sink 50% of their rated output current. Refer to Connections-Power Dissipator for installation information.

- Each N7909A unit has a total power dissipating capacity of 1 kW.

- Current sinking requires a minimum operating voltage as shown in the output quadrant characteristic.

- The N7909A does not have an On/Off switch. It turns on and off with the power supply. An LED on the unit will indicate that the unit is connected and operational. See Power Dissipator at a Glance for information about the front panel LEDs. The power dissipator must be connected **before** the power supply is tuned on, or it will not be recognized and does nothing. If the power dissipator is connected but not working, the power supply indicates a self-test error.

- The only operating difference for the power supply when the power dissipator is connected is that the sink current capability is increased from 10% to 100% of the rated current, and the negative power protection limit (CP-) is also increased.

- If the N7909A is disconnected during operation, the power supply indicates that a self-test error has occurred and reduces the sink current capability to 10% of the rated current. The negative power protection limit (CP-) is also reduced, which may cause the unit to go into a CP- protection mode.

- The cables connecting the N7909A to the power supply cannot be longer than 1 meter. This limits the distance that the N7909A can be located away from the power supply.

- The temperature sensor information from the power dissipator is combined with the temperature sensor information from the power supply. The minimum difference between the internal temperature sensors and the over-temperature trip level is reported by the OUTPut:PROTection:TEMPerature:MARGin? query.

Querying the Power Dissipator

Other than looking at the front panel LED of the power dissipator, the only way to know if the unit is connected and operating correctly is to query the negative current limit of the power supply.

Front Panel	SCPI Command
Not available	To query the negative current limit: CURR:LIM:NEG? MIN Note that the MIN parameter returns the most-negative current value.

If the negative current limit query returns a value that equals 10% of the rated current of the power supply, the power dissipator is not recognized by the power supply. Turn the power supply off, make sure that the power dissipator is properly connected, and turn the power supply on again.

For 1 kW models, if the negative current limit query returns a value that equals 100% of the rated current of the power supply, the power dissipator is connected and recognized.

For 2 kW models, if the negative current limit query returns a value that equals 100% of rated current of the power supply, both power dissipators are connected and recognized. If the value equals 50% of the rated current, only one power dissipator is connected and recognized.

System-Related Operations

Though not directly related to output programming, the following functions also control instrument operation.

Instrument Identification

Instrument State Storage

Front Panel Display

Front Panel Lock-Out

Password Protection

Instrument Identification

You can query the model number, serial number, options, and firmware revision. SCPI commands return information with the *IDN? and *OPT? queries.

Front Panel	SCPI Command
Select **System\About\Frame**.	To return manufacturer, model number, serial number, and firmware revision: *IDN? To return the installed options: *OPT?

Instrument State Storage

The power supply has ten storage locations in non-volatile memory to store instrument states. The locations are numbered 0 through 9. Any state previously stored in the same location will be overwritten.

Front Panel	SCPI Command
Select **States\SaveRecall**. In the SaveRecall field, enter a location from 0 to 9. Then press **Select**. Select Save to save the state to Recall to recall a state.	To save a state in location 1: *SAV 1 To recall a state from location 1: *RCL 1

Specifying a power-on state

When shipped, the power supply is configured to automatically recall the reset (*RST) settings at power-on. However, you can configure the power supply to use the settings you have stored in memory location 0 at power-on.

Front Panel	SCPI Command
Select **States\PowerOn**. Select Recall State 0. Then press **Select**.	OUTP:PON:STAT RCL0

Front Panel Display

The power supply has a front panel screen saver that significantly increases the life of the LCD display by turning it off during periods of inactivity. The delay can be set from 30 to 999 minutes in 1 minute increments. As shipped, the screen saver comes on one hour after activity on the front panel or interface has ceased.

When the screen saver is active, the front panel display turns off, and the LED next to the Line switch changes from green to amber. To restore the front panel display, simply press one of the front panel keys. The first action of the key turns the display on. Subsequently, the key will revert to its normal function.

If the Wake on I/O function is selected, the display is restored whenever there is activity on the remote interface. This also resets the timer on the screen saver. As shipped, Wake on I/O is active.

Front Panel	SCPI Command
Select **System\Preferences\Display\Saver** Enable or disable the screen saver by checking or unchecking the Screen Saver checkbox. Then press **Select**. Enter a value in minutes in the Saver Delay field to specify the time when the screen saver will activate. Check Wake on I/O to activate the display with I/O bus activity.	Not available

Specifying the power-on view

Note that you can specify which measurement functions are displayed at turn-on.

Front Panel	SCPI Command
Select **System\Preferences\Display\View**. From the dropdown menu select: Voltage,Current; Voltage,Power; or Volt,Curr,Power. Then press **Select**.	To select a turn-on meter view: DISP:VIEW METER_VI DISP:VIEW METER_VP DISP:VIEW METER_VIP

Front Panel Lock-Out

You can lock the front panel keys to prevent unwanted control of the instrument from the front panel. This is the most secure way of locking the front panel keys because you need a password to unlock the front panel. This parameter is saved in non-volatile memory. Therefore, the front panel remains locked even after AC power is cycled.

Front Panel	SCPI Command
Select **System\Preferences\Lock** In the dialog box, enter the password to unlock the front panel. Then select Lock.	Not available

The menu to unlock the front panel appears every time a key is pressed. Enter the password to unlock the front panel.	

NOTE   If the password is lost, the SYSTem:PASSword:FPANel:RESet command can reset the front panel lockout password. Refer to Calibration Switches for more information.

The SYSTem:COMMunicate:RLSTate RWLock command can also lock and unlock the front panel. This command is completely independent of the front panel lockout function. If you use this command to lock the front panel, the front panel will be unlocked when AC power is cycled.

Password Protection

You can password-protect all functions located in the Admin menu. These include: instrument calibration, interface access, non-volatile memory reset, firmware update, password updates.

As shipped, the Admin menu password is 0 (zero). This means that you do not have to enter a password to access the Admin menu. Simply select **System\Admin\Login** and press Enter. To password-protect the Admin menu:

Front Panel	SCPI Command
Select **System\Admin\Password** The password must be numeric, and up to 15 digits long. Press Select Log out of the Admin menu to activate the password. You can now only enter the Admin menu by providing the right password. Enter the password in the Password field.	Enter calibration mode using the original password CAL:STAT ON, <password> To change the password: CAL:PASS <password> To exit calibration mode and activate the password: CAL:STAT OFF

If the password is lost, access can be restored by setting an internal switch to reset the password to 0. If the message "Locked out by internal switch setting" or "Calibration is inhibited by switch setting" appears, the internal switch is set to prevent the password from being changed. Refer to Calibration Switches for more information.

Priority Mode Tutorial

Voltage Priority

Current Priority

Voltage Priority

In voltage priority mode the output is controlled by a constant-voltage feedback loop, which maintains the output voltage at its programmed setting as long as the load current remains within the positive or negative current limit settings. Voltage priority mode is best suited for use with resistive or high impedance loads, and loads that are sensitive to voltage overshoots. Do not use voltage priority mode with low-impedance sources such as batteries, power supplies, or large charged capacitors.

In voltage priority mode, the output voltage should be programmed to the desired value. A positive and negative current limit value should also be set. The current limit should always be set to a value that is greater than the actual output current requirement of the external load. The following figure shows the voltage priority operating locus of the output. The area in the white quadrants shows the output as a source (sourcing power). The area in the shaded quadrants shows the output as a load (sinking power).
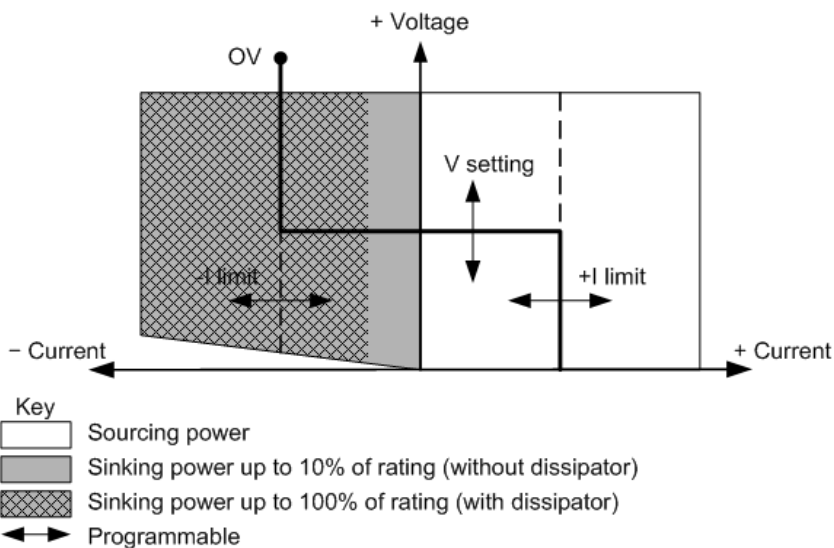
The heavy solid line illustrates the locus of possible operating points as a function of the output load. As shown by the horizontal portion of the line, the output voltage remains regulated at its programmed setting as long as the load current remains within the positive or negative current limit setting. A CV (constant voltage) status flag indicates that the output voltage is being regulated and the output current is within its limit settings.

When the output current reaches either the positive or negative current limit, the unit no longer operates in constant voltage mode and the output voltage is no longer held constant. Instead, the power supply will now regulate the output current at its current limit setting. Either a LIM+ (positive current limit), or LIM− (negative current limit) status flag is set to indicate that a current limit has been reached. These conditions are annunciated by CL+ or CL- on the front panel.

As shown by the vertical portions of the load line, the output voltage may continue to increase in the positive direction or decrease in the negative direction as current is forced into or pulled out of the unit. When the output voltage exceeds the over-voltage protection setting, the output will shut down, the output relays will open, and the OV status bit will be set.

Current Priority

In current priority mode the output is controlled by a bi-polar constant current feedback loop, which maintains the output source or sink current at its programmed setting. The output current will remain at its programmed setting as long as the load voltage remains within the voltage limit setting. Current priority mode is best suited for use with batteries, power supplies, large charged capacitors, and loads that are sensitive to current overshoots. It minimizes current overshoots during programming, turn-on, and turn-off transitions and seamlessly transitions between positive and negative currents.

In current priority mode, the output current should be programmed to the desired positive or negative value. A positive voltage limit value should also be set. The voltage limit should always be set to a value that is greater than the actual output voltage requirement of the external load. The following figure shows the current priority operating locus of the output. The area in the white quadrants shows the output as a source (sourcing power). The area in the shaded quadrants shows the output as a load (sinking power).
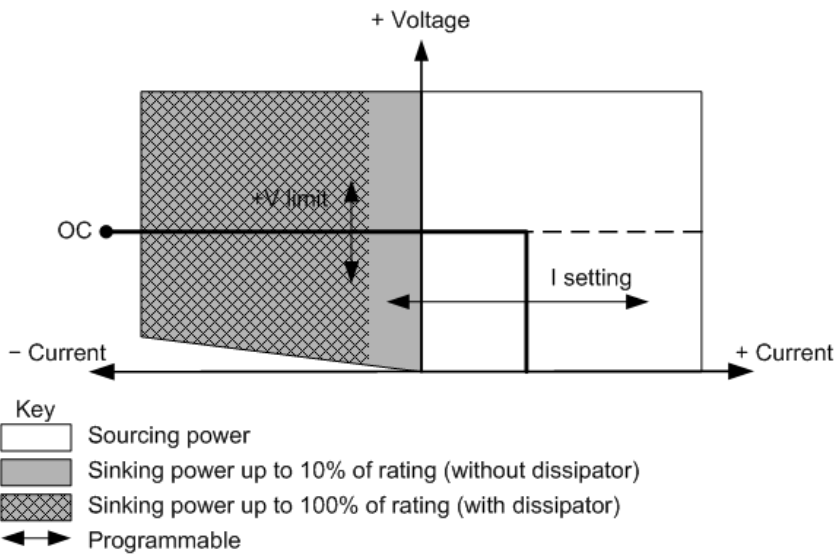
The heavy solid line illustrates the locus of possible operating points as a function of the output load. As shown by the vertical portion of the line, the output current remains regulated at its programmed setting as long as the output voltage remains within its limit setting. A CC (constant current) status flag indicates that the output current is being regulated and the output voltage is within its limit settings.

If the output voltage reaches the voltage limit, the unit no longer operates in constant current mode and the output current is no longer held constant. Instead, the power supply will now regulate the output voltage at its voltage limit setting. A LIM+ (positive voltage limit) status flag is set to indicate that the voltage limit has been reached. This condition is annunciated by VL+ on the front panel.

As shown by the horizontal portion of the load line, when the unit is sinking power, the output current may continue to increase in the negative direction as more current is forced into the unit. This can happen when the load is a power source such as a battery, and its output voltage is higher than the voltage limit setting of the power supply. Once the current exceeds the built-in negative over-current limit, the output will shut down, the output relays will open, and the OC status bits will be set. In such a case, it is important to set the voltage limit properly in order prevent this protection shutdown.

Current Sharing Tutorial

Current Sharing Calculations

Sharing Deviation for Units of Equal Power (either 1 kW or 2 kW)

Sharing Deviation for Units of Mixed Power (1 kW paralleled with 2 kW)

This section describes how to calculate the current sharing effects of paralleled units of equal and mixed power. These only affect the operation of the paralleled units when operating near the current limit setting in voltage priority mode, operating near the voltage limit setting in current priority mode, or when using the low current measurement range. For a description of the current sharing operation, refer to Current Sharing.

Current Sharing Calculations

In an ideal current sharing configuration, the total load current would be shared equally among all paralleled power supplies.

$$I_{OUT(1kW\_IDEAL)} = I_{LOAD\_TOTAL} / (N_T + N_{2kW})$$
$$I_{OUT(2kW\_IDEAL)} = 2(I_{LOAD\_TOTAL}) / (N_T + N_{2kW})$$

where:

I_{LOAD_TOTAL} is the total load current

N_T is the total number of paralleled units of any rating

N_{2kW} is the total number of paralleled 2 kW units

The difference between the ideal output current and the actual output current for a single contributing paralleled unit can be expressed in the form of a gain error, G and offset error, K as shown.

$$\Delta I_{OUT(WORST\_CASE)} = \pm G(I_{OUT(IDEAL)}) \pm K(I_{RATING})$$

where:

G is the gain error

K is the offset error

In a 1 kW configuration, the I_{RATING} is the rated current for the 1 kW unit

In a 2 kW configuration, the I_{RATING} is the rated current for the 2 kW unit

In a mixed power configuration, the I_{RATING} is the rated current for the 2 kW unit

The following sections describe how to calculate the worst-case deviation from the ideal current for each contributing paralleled unit.

Sharing Deviation for Units of Equal Power (either 1 kW or 2 kW)

The following table gives the Gain and Offset values for paralleled units of equal power:

Paralleled Units (N$_T$)	Gain Error % (G)	Offset Error % (K)	Gain and Offset Equations
2	0.200	0.6	
3	0.267	1.2	G = 0.4%((N$_T$ − 1)/N$_T$)
4	0.300	1.8	K = 0.6%(N$_T$ − 1)
5	0.320	2.4	

Example (60 A load current) You have three 1 kW, 40 V, 25 A units connected in parallel drawing a total load current of 60 A. Using the gain and offset values from the above table (G=0.267%; K=1.2%), the worst-case deviation from the ideal current sharing contribution of 20 A for an individual unit would be as follows:

$$\Delta I_{OUT(WORST\_CASE)} = \pm G(I_{OUT(IDEAL)}) \pm K(I_{RATING})$$
$$\Delta I_{OUT(WORST\_CASE)} = \pm 0.267\%(20A) \pm 1.2\%(25A)$$
$$\Delta I_{OUT(WORST\_CASE)} = \pm 0.353A$$

Note that the percent of deviation from the ideal becomes greater for smaller output currents, because the offset error predominates. This holds true all the way down to zero current. If, in the above example, the paralleled units were drawing no current (0 A) , the worst case deviation would still be:

$$\Delta I_{OUT(WORST\_CASE)} = \pm 0.267\%(0A) \pm 1.2\%(25A)$$
$$\Delta I_{OUT(WORST\_CASE)} = \pm 0.3A$$

Sharing Deviation for Units of Mixed Power (1 kW paralleled with 2 kW)

Note that calculating the current deviation in this procedure is a little more complicated than the previous one, because the 1 kW and the 2 kW units each contribute a *different* amount of current toward the total load current. Ideally, the 2 kW units contribute twice as much current as the participating 1 kW units.

The following table gives the Gain and Offset values for up to five paralleled units of mixed power:

Paralleled Units (N$_T$)	Gain Error % (G)	Offset Error % (K)	Gain and Offset Equations
2	0.267	0.40	
3	0.320	1.08	G = 0.8%((N$_T$ − 1)/(1 + 2(N$_T$ − 1)))
4	0.343	1.71	K = 1.2%(N$_T$((N$_T$ − 1.5)/(2N$_T$ − 1)))
5	0.356	2.33	

Example (300 A load current) You have three 9V units connected in parallel. Two of the units are 1kW units with a rated current of 100A. The other is a 2kW unit with a rated current of 200A. The load draws 300A of current.

You must first calculate the ideal output current contribution for the 1 kW and the 2 kW units. The ideal current contribution for the 1 kW unit is calculated as follows:

$$I_{OUT(1KW\_IDEAL)} = I_{LOAD\_TOTAL} / (N_T + N_{2kW})$$
$$I_{OUT(1KW\_IDEAL)} = 300A / (3+1)$$
$$I_{OUT(1KW\_IDEAL)} = 75A$$

The ideal current contribution for a 2 kW unit is calculated as follows:

$$I_{OUT(2KW\_IDEAL)} = 2(I_{LOAD\_TOTAL}) / (N_T + N_{2kW})$$
$$I_{OUT(2KW\_IDEAL)} = 2(300A) / (3+1)$$
$$I_{OUT(2KW\_IDEAL)} = 150A$$

where $N_T = 3$, $N_{1KW} = 2$, and $N_{2kW} = 1$

Note that the total ideal current equals the total load current: 2(75A) + 150A = 300A

You can now use the gain and offset values for three paralleled units of mixed power (G=0.320%; K=1.08%) to determine the worst-case deviation from the ideal current for each 1 kW unit. Note that for a mixed power configuration, the equations use I_{2kW_RATING} for both the 1kW and the 2kW calculations.

$$\Delta I_{OUT(1KW\_WORST\_CASE)} = \pm G(I_{OUT(1KW\_IDEAL)}) \pm K(I_{2kW\_RATING})$$
$$\Delta I_{OUT(1KW\_WORST\_CASE)} = \pm 0.32\%(75A) \pm 1.08\%(200A)$$
$$\Delta I_{OUT(1KW\_WORST\_CASE)} = \pm 2.4A$$

Repeat the above step for the 2 kW unit.

$$\Delta I_{OUT(2KW\_WORST\_CASE)} = \pm G(I_{OUT(2KW\_IDEAL)}) \pm K(I_{2kW\_RATING})$$
$$\Delta I_{OUT(2KW\_WORST\_CASE)} = \pm 0.32\%(150A) \pm 1.08\%(200A)$$
$$\Delta I_{OUT(2KW\_WORST\_CASE)} = \pm 2.64A$$

Using the Power Assistant Software

This section explains how to use the Agilent N7906A Power Assistant software.

Using the Meter View

Black Box Data Recording

Configuring Signal Routing

Installing and Running the Software

Requirements:

- Agilent N6900/N7900 Series Advanced Power System

- Windows 8 (32-bit and 64-bit)
  Windows 7 SP1 (32-bit and 64-bit)
  Windows XP SP3 (32-bit)

- Agilent IO Libraries Suite (version 16.3 or later)

- Microsoft .NET Framework 4 (standalone installer)

NOTE	The Agilent Connection Expert does not have to be running for you to use the Power Assistant software, but it must be installed on your computer. However, before you run the Power Assistant for the first time, you must use the Agilent Connection Expert to connect to establish a connection to your instrument.

The Power Assistant software is available on the CD ROM that was shipped with your instrument. It is also available on the Agilent web at www.agilent.com/find/N7906A. To install and run the software:

1. Download the file AdvancedPSSoftware_Setup.exe and run it on your computer. This will install the Power Assistant software.

2. Connect your instrument to your computer and run the Agilent Connection Expert. Make sure that a connection to your instrument is established.

3. Select the **Agilent N7906** icon to run the Power Assistant software application.

Using the Meter View

The Meter tab displays the front panel of the instrument that you are connected to. You can control the instrument from this window much that same way that you use the actual front panel of the instrument. Select one of the other tabs (Black Box or Trigger) to access the remaining applications.
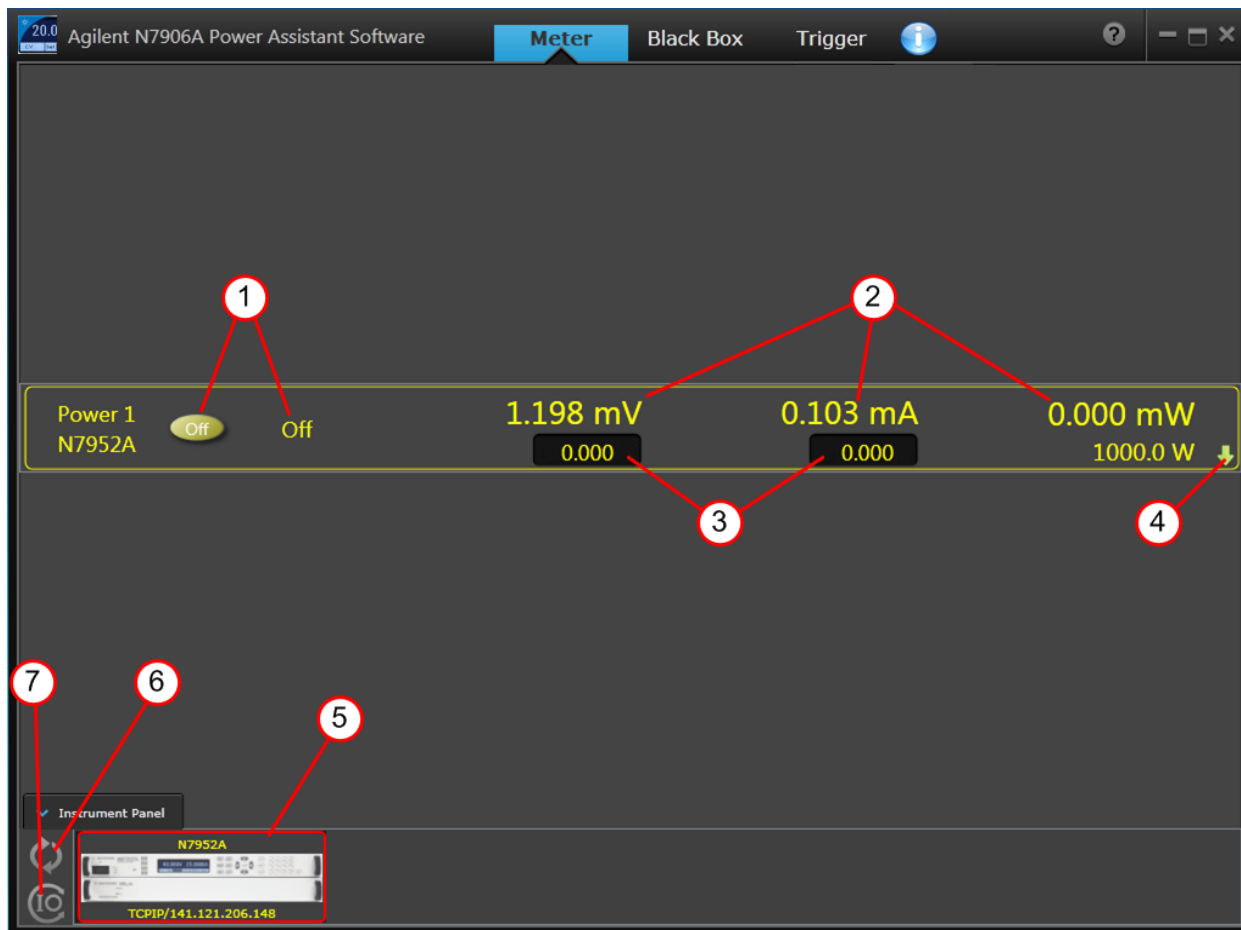
Note the following controls:

1. Turns the output on or off

2. Displays the measured output values

3. Displays the output settings

4. Expands the front panel controls (see below)

5. Displays the instrument that is being controlled

6. Click to refresh the instrument list

7. Click to launch the Agilent Connection Expert

When you expand the front panel controls, the following additional controls appear. These access the same controls that are available from the actual front panel of the instrument.

Configuring Signal Routing

This section explains how to use the Power Assistant to configure signal routing.

Routing Signals

Downloading the Routing

Saving the Routing File

Viewing the SCPI Commands

More Examples

Routing Signals

Select the **Trigger** tab on top of the Power Assistant window. To get started configuring signal routing:

1. Select a signal source from the Source list on the left panel. For example click the Status icon to place it onto the work area. Select CL+ from the Status dropdown list.

2. Select a signal target from the Target list on the right panel. For example click the Digital icon to place it onto the work area. Select Pin 1 and Positive polarity from the Digital dropdown list.

3. Move the Status and Digital icons together until a dotted yellow line appears. Continue moving the icons until the dotted line becomes solid.

As shown below, you have now routed the CL+ status signal to Pin 1 on the digital connector. Any time a CL+ (positive current limit) occurs, the signal is routed to digital connector pin 1.
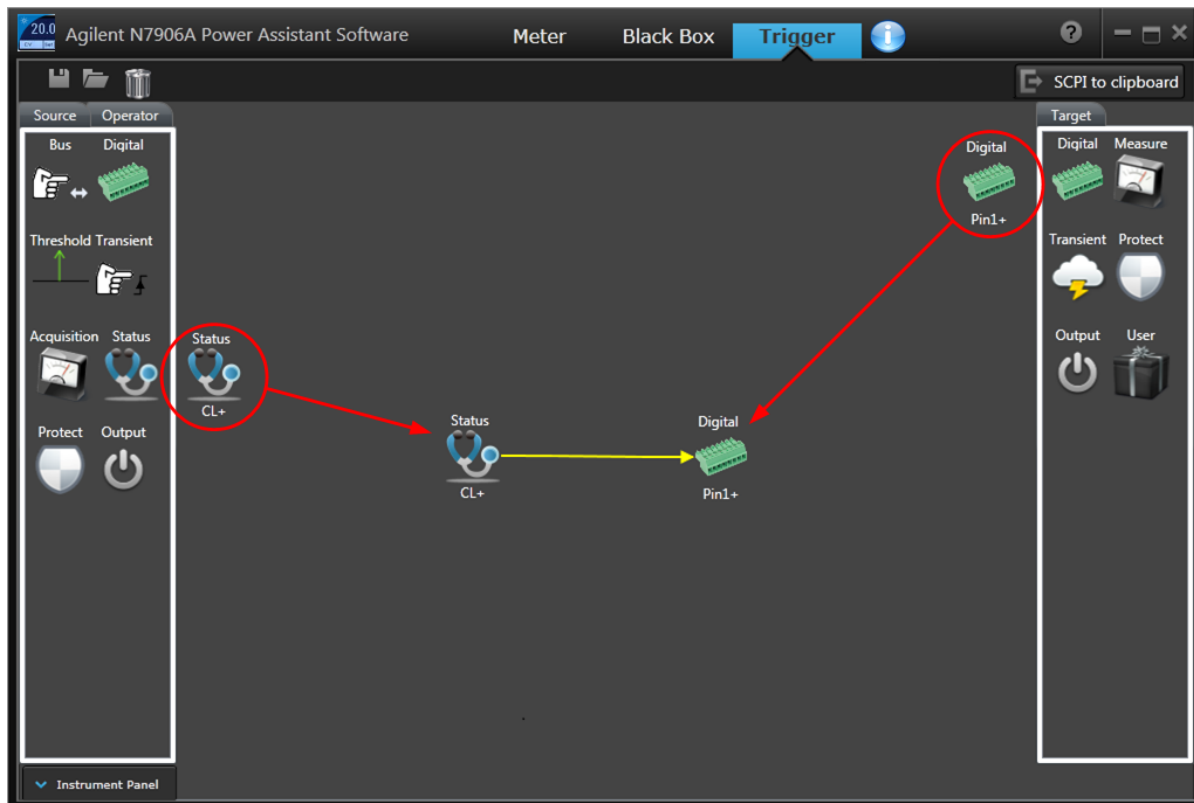
Downloading the Routing

When you have completed the signal routing, you must download it to the instrument.

- Click **Instrument Panel** if the instrument to which you are connected, does not appear in the window.

- Click on the instrument to select it. Click the green down arrow to download the routing to the instrument (see below).

- If you have a routing already downloaded that you wish to edit, click the green up arrow to upload the routing to the Power Assistant.
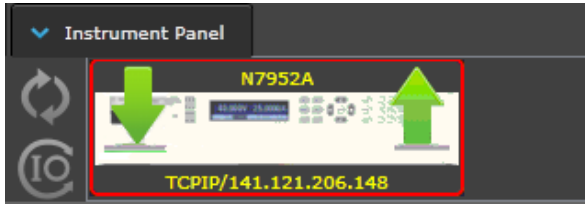
Saving the Routing File

You can save and retrieve routing files on your computer.

- Click the **Disc** icon on top of the window to save the file. The default file location is C:\Program Files\Agilent\PowerAssistant. Rename the file, as the default filename is overwritten each time a new file is saved.

- Click the **Folder** icon to open any saved files with the Power Assistant.

Viewing the SCPI Commands

If you wish to view the source code for the expression you have created, select **SCPI to Clipboard** to copy the equivalent SCPI commands to your computer's clip board.
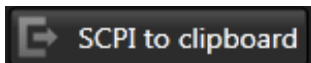
Then paste the file into Notepad or any other text editor.

The following figure shows the equivalent SCPI commands from the above example copied to Notepad.
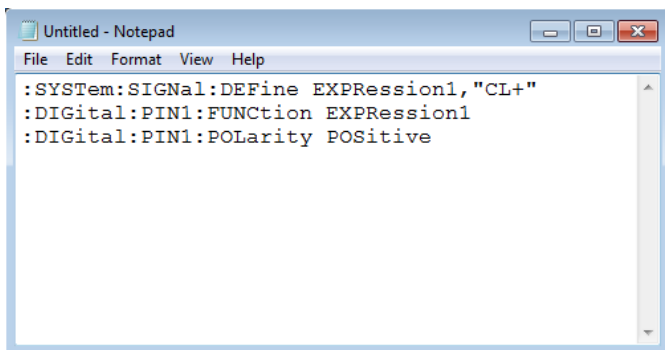
More Examples

The following examples illustrate some simple signal routings.

Example 1 Create a digital signal on pin1 of the digital port that is true whenever the output is in positive or negative current limit:

1. Select the Status icon from the Source list to place it onto the work area. Select CL- from the Status dropdown list.

2. Select another Status icon from the Source list to place it onto the work area. Select CL+ from the Status dropdown list.

3. Select the OR operator from the Operator list to place it onto the work area.

4. Move the CL- and CL+ icons toward the inputs of the Operator icon until the solid yellow connection lines appear.

5. Select the Digital icon from the Target list to place it onto the work area. Select Pin 1 and Positive polarity from the Digital dropdown list.

6. Move the Pin1 icon toward the output of the Operator icon until the solid yellow connection line appears.
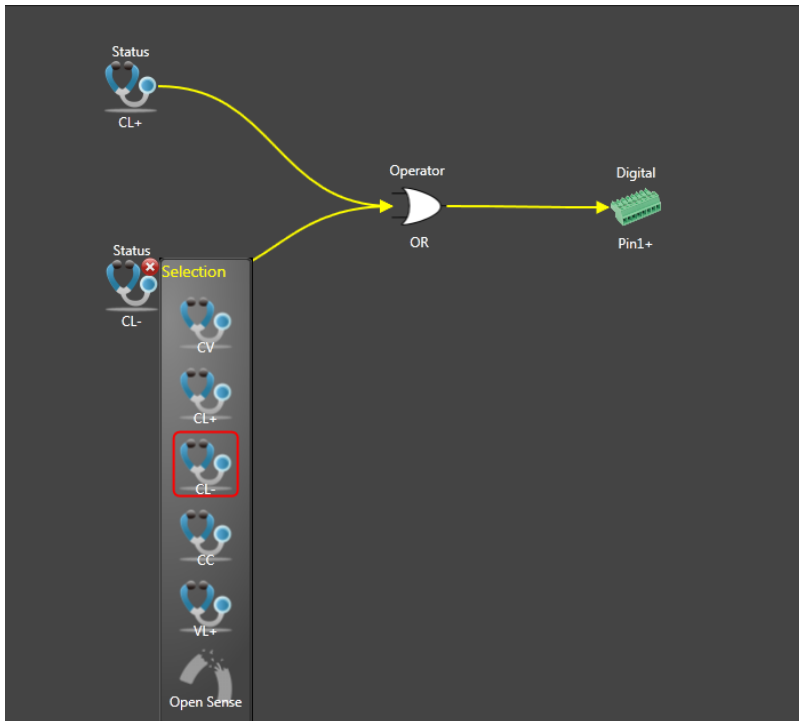
Example 2 Create a trigger source that will trigger an output transient (step or list) whenever the output current is between 2.1 A and 2.7 A.

1. Select the Threshold icon from the Source list to place it onto the work area. Select Current, > direction, and enter a 2.1 level in the Level dropdown list.

2. Select another Threshold icon from the Source list to place it onto the work area. Select Current, < direction, and enter a 2.7 level in the Level dropdown list.

3. Select the AND operator from the Operator list to place it onto the work area.

4. Move the Threshold icons toward the inputs of the Operator icon until the solid yellow connection lines appear.

5. Select the Transient icon from the Target list to place it onto the work area. Select Trigger from the Transient dropdown list.

6. Move the Transient icon toward the output of the Operator icon until the solid yellow connection line appears.
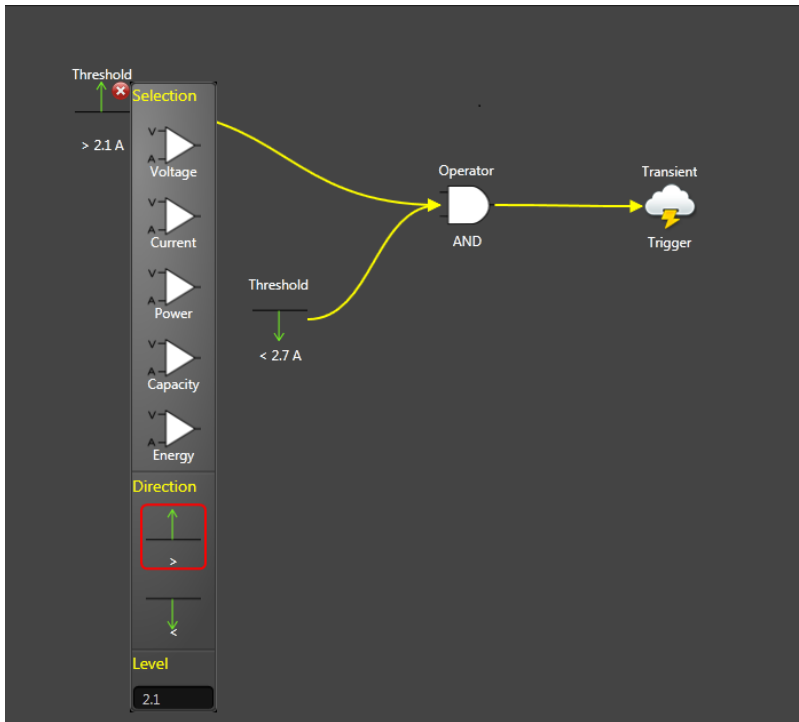
Example 3 Create a custom protection that will disable the output if the output voltage moves outside the window between 23.5 V and 24.5 V.

1. Select the Threshold icon from the Source list to place it onto the work area. Select Voltage, > direction, and enter a 24.5 level in the Level dropdown list.

2. Select another Threshold icon from the Source list to place it onto the work area. Select Voltage, < direction, and enter a 23.5 level in the Level dropdown list.

3. Select the OR operator from the Operator list to place it onto the work area.

4. Move the Threshold icons toward the inputs of the Operator icon until the solid yellow connection lines appear.

5. Select the Protect icon from the Target list to place it onto the work area.

6. Move the Protect icon toward the output of the Operator icon until the solid yellow connection line appears.
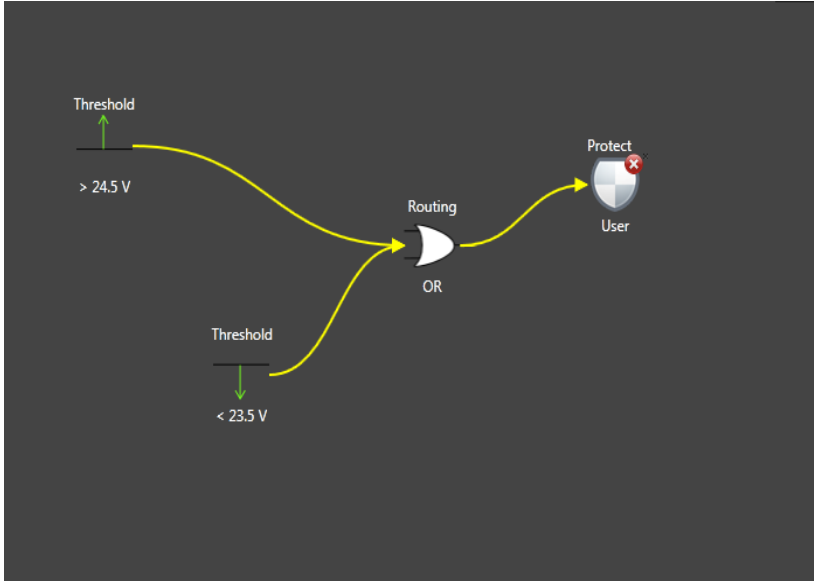
Example 4 Create a trigger source that triggers a measurement 50 milliseconds after the output has settled.

1. Select the Output icon from the Source list to place it onto the work area. Select Settled from the Output dropdown list.

2. Select the Delay operator from the Operator list to place it onto the work area. Enter a 0.05 second delay time in the Time field of the dropdown list.

3. Move the Output icon toward the input of the Operator icon until the yellow connection line appears.

4. Select the Measure icon from the Target list to place it onto the work area.

5. Move the Measure icon toward the output of the Operator icon until the solid yellow connection line appears.

Black Box Data Recording

Black Box Data Recording

This section explains how to use the Power Assistant to retrieve and view data from the Black Box Recorder.

Making a Snapshot

Retrieving the Snapshot

Viewing the Snapshot

Configuring the Display

Viewing the Snapshot

Exporting the Snapshot Data

Saving the Snapshot File

Making a Snapshot

| NOTE | It is good practice to verify the system date and time before retrieving Black Box data. Refer to BBR Clock Setup. |

You can retrieve logged data by requesting a "snapshot" either from the front panel or using SCPI commands. Refer to Snapshot Operation. The snapshot always uploads from the most recent data entry on back.

Once you have created the snapshot, you can retrieve and view the snapshot data with the Power Assistant.

Retrieving the Snapshot

Select the **Black Box** tab on top of the Power Assistant window.

- Click **Instrument Panel** if the instrument to which you are connected, does not appear in the window.

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Black Box Data Recording

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Making a Snapshot

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Making a Snapshot

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- Click **Instrument Panel** if the instrument to which you are connected, does not appear in the window.

- Click on the instrument to select it. Click the green up arrow to upload the snapshot to the instrument (see below). A progress bar lets you know that the file is uploading.

- Once the file has finished uploading, the data will appear in the display.

Viewing the Snapshot

The Black Box tab displays the snapshot data file that you retrieved from the instrument. The snapshot always uploads from the most recent data entry on back. The following figure illustrates a sample snapshot file:

Note the following areas of interest:

1. The area on top of the display indicates the total time period of the snapshot

2. The yellow line is the output voltage.

3. The green line is the output current.

4. The green portion of the window displays the status states.

5. The vertical red lines indicate when power was cycled on or off.

6. The pale blue dots on the timeline indicate where a user-defined message was placed into the log (see Viewing Snapshot Events).

Configuring the Display

Not all of the snapshot data can be displayed on the window at the same time. You can decide which data you wish to view.

- Click **Configuration** to configure the snapshot view.

- Click the items that you wish to appear on the display. Scroll down to view all of the items in the list. In the following example, six items are selected. This matches what is shown in the previous figure.
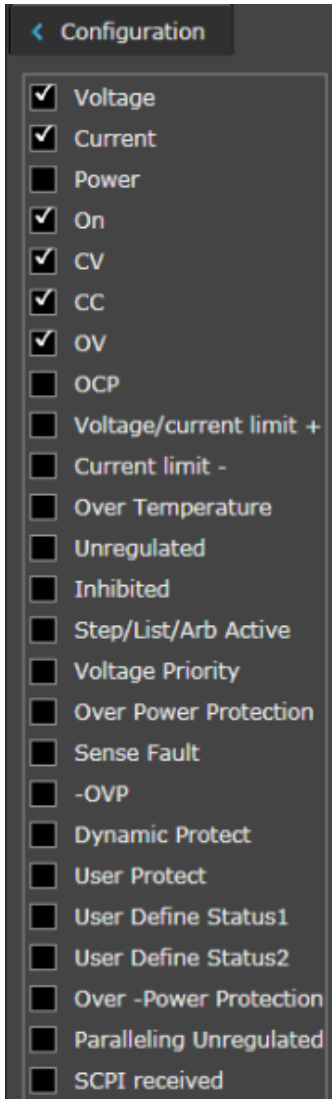
Viewing Snapshot Events

Click on the pale blue dots on the timeline to view the user defined message that was placed into the BBR log . Refer to Snapshot Event Tags for information on how to place event messages into the BBR.
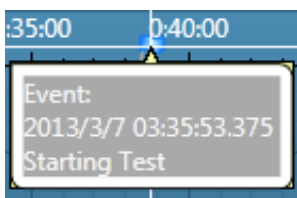
Exporting the Snapshot Data

You can export the snapshot data to an Excel or CSV file. Select **Export** to export the snapshot data.
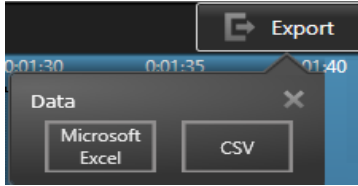
Select Microsoft Excel to export the data to Excel.

Select CSV to save the data in .csv format. The default file location is C:\Program Files\Agilent\PowerAssistant.

Saving the Snapshot File

You can save and retrieve snapshot files on your computer.

- Click the **Disc** icon on top of the window to save the file. The default file location is C:\Program Files\Agilent\PowerAssistant. Rename the file, as the default filename is overwritten each time a new file is saved.

- Click the **Folder** icon to open any saved files with the Power Assistant.

SCPI Programming Reference

Introduction to the SCPI Language

Commands by Subsystem

Command Quick Reference

Reset State (*RST)

SCPI Error Messages

Compatibility Commands

Related Information

IO Libraries and Instrument Drivers

The Agilent IO Libraries Suite software is provided on the Agilent Automation Ready CD-ROM provided with your instrument. Installation instructions are provided on the CD-ROM.

You can also download the Agilent IO Libraries Suite software, along with IVI-COM and LabVIEW drivers from the Agilent Developer Network at www.agilent.com/find/adn.

Advanced Power System Documentation

This document is provided on a Product Reference CD that is shipped with your instrument. You can also download this document at ww.agilent.com/find/APS-doc.

For detailed information about interface connections, refer to the Agilent Technologies USB/LAN/GPIB Interfaces Connectivity Guide, located on the Automation-Ready CD. Or you can download the guide from the Web at www.agilent.com/find/connectivity.

Web Interface

The APS provides a Web interface that is built into the instrument. You can use this interface over LAN for remote access and control of the instrument via a Web browser. See Using the Web Interface for details.

Example Programs

There are several example programs on the product page Web site at ww.agilent.com/find/APS. These are application-focused programs that demonstrate different programming environments.

Introduction to the SCPI Language

Keywords

Queries

Command Separators and Terminators

Syntax Conventions

Parameter Types

Device Clear

Typical Command Processing Times

Introduction

This instrument complies with the rules and conventions of the present SCPI version (see SYSTem:VERSion?).

SCPI (Standard Commands for Programmable Instruments) is an ASCII-based instrument command language designed for test and measurement instruments. SCPI has two types of commands, common and subsystem.

IEEE-488.2 Common Commands

The IEEE-488.2 standard defines a set of common commands that perform functions such as reset, self-test, and status operations. Common commands always begin with an asterisk (*****), are three characters in length, and may include one or more parameters. The command keyword is separated from the first parameter by a blank space. Use a semicolon (**;**) to separate multiple commands as shown below:

Subsystem Commands

Subsystem commands perform specific instrument functions. They are comprised of alphabetically arranged commands that extend one or more levels below the root in a hierarchical structure, also known as a *tree system*. In this structure, associated commands are grouped together under a common node or root, thus forming *subsystems*. A portion of the OUTPut subsystem is shown below to illustrate the tree system. Note that some [optional] commands have been included for clarity.

```
OUTPut
      [:STATe] OFF|0|ON|1
      :DELay
            :FALL <value>|MIN|MAX
            :RISE <value>|MIN|MAX
      :INHibit
            :MODE LATChing|LIVE|OFF
```

Keywords

Keywords, also referred to as headers, are instructions recognized by the instrument. Common commands are also keywords.

OUTPut is the root keyword, DELay is a second-level keyword, FALL and RISE are third-level keywords. Colons (**:**) separate the keyword levels.

The command syntax shows most commands (and some parameters) as a mixture of upper- and lower-case letters. The upper-case letters indicate the abbreviated spelling for the command. For shorter program lines, you can send the abbreviated form. For better program readability, you can send the long form.

In the above examples, OUTP and OUTPUT are both acceptable forms. You can use upper- or lower-case letters. Therefore, OUTPUT, outp, and Outp are all acceptable. Other forms such as OUT, are not valid and will generate an error.

Queries

Following a keyword with a question mark (**?**) turns it into a query (Example: VOLTage?, VOLTage:TRIGgered?). If a query contains parameters, place the query indicator at the end of the last keyword, before the parameters. Insert a space between the query indicator and the first parameter.

You can query the programmed value of most parameters. For example, you can query the previously set OUTPut:DELay:FALL time by sending:

```
OUTPut:DELay:FALL?
```

You can also query the minimum or maximum allowable fall time as follows:

```
OUTPut:DELay:FALL? MIN
OUTPut:DELay:FALL? MAX
```

You must read back all the results of a query before sending another command to the instrument. Otherwise, a *Query Interrupted* error will occur and the unreturned data will be lost.

Command Separators and Terminators

Separators

Colons (**:**) separate keyword levels. Blank spaces must be used to separate command parameters from their corresponding keyword. If a command requires more than one parameter, use a comma to separate adjacent parameters. In the following example, the optional *startindex* and *points* parameters must be separated with a comma. Note the space between CURRent? and the first parameter.

```
FETCh:CURRent? [<start_index>, <points>]
```

Semicolons (**;**) separate commands within the same subsystem. This lets you send several subsystem commands within the same message string. For example, sending the following command string:

```
OUTPut:STATe ON;DELay:RISE 1;FALL 2
```

is the same as sending the following commands:

```
OUTPut ON
OUTPut:DELay:RISE 1
OUTPut:DELay;FALL 2
```

Note that the semicolon follows the implied path of the hierarchical tree structure. In the above example, the optional :STATe keyword must follow the OUTput keyword to place the command parser at the second level in the hierarchy. This allows the use of the DELay keyword after the semicolon, since DELay is a second-level keyword. Next, the command parser is placed at the third level in the hierarchy by the :RISE keyword. This allows the use of the FALL keyword after the second semicolon, since FALL is a third-level keyword.

You can also combine commands of different subsystems within the same message string. In this case, you must use a colon to return the command parser to the root level in order to access another subsystem. For example, you could clear the output protection and check the status of the Operation Condition register in one message by using a root specifier as follows:

```
OUTPut:PROTection:CLEar;:STATus:OPERation :CONDition?
```

Note the use of the colon *after* the semicolon in order to return the command parser to the root.

Terminators

A command string sent to the instrument must terminate with a new line (<NL>) character. The IEEE-488 EOI (End-Or-Identify) message is interpreted as a <NL> character and can be used to terminate a command string in place of an <NL>. A carriage return followed by a new line (<CR><NL>) is also accepted. Command string termination will always reset the current SCPI command path to the root level.

Syntax Conventions

- Triangle brackets (**< >**) indicate that you must specify a value for the enclosed parameter. For example, in the OUTPut:DELay syntax statements shown above, the <*value*> parameter is enclosed in triangle brackets. The brackets are not sent with the command string. You must specify a value for the parameter (Example: "OUTP:DEL:FALL 0.1") unless you select another option shown in the syntax (Example: "OUTP:DEL:FALL MIN").

- A vertical bar (**|**) separates multiple parameter choices for a given command string. For example, LATChing|LIVE|OFF in the OUTPut:INHibit command indicates that you can specify "LATChing", "LIVE", or "OFF". The bar is not sent with the command string.

- Square brackets (**[ ]**) enclose some syntax elements - nodes and parameters for example. This indicates that the element is optional and can be omitted. The brackets are not sent with the command string. In the case of an optional parameter, if you do not specify a value for an optional parameter the instrument will ignore the parameter. In the FETCh:CURRent? example above, the optional <startindex> and <points> parameters let you return array data starting at startindex and containing the specified number of data points. If these parameters are not specified, the query returns all of the array data.

- Braces (**{ }**) indicate parameters that may be repeated zero or more times. It is used especially for showing lists. The notation <value>{,<value>} shows that the first value must be entered, while additional values may be omitted or may be entered one or more times.

Parameter Types

The SCPI language defines several data formats to be used in commands and queries.

Numeric Parameters

Commands that require numeric parameters will accept all commonly used decimal representations of numbers including optional signs, decimal points, and scientific notation. If a command accepts only certain specific values, the instrument will automatically round the input numeric parameters to the accepted values. The following command requires a numeric parameter for the voltage value:

```
[SOURce:]VOLTage 50V|MIN|MAX
```

Note that special values for numeric parameters such as MINimum, MAXimum, and INFinity are also accepted. Instead of selecting a specific value for the voltage parameter, you can substitute MIN to set the voltage to its minimum allowable value, MAX to set it to its maximum allowable value.

You can also send engineering unit suffixes with numeric parameters (e.g., V for volts, A for amperes, W for Watts). All parameters values are in base units.

Discrete Parameters

Discrete parameters are used to program settings that have a limited number of values (like IMMediate, EXTernal, or BUS). They may have a short form and a long form just like command keywords. You can use upper- or lower-case letters. Query responses will always return the short form in all upper-case letters. The following command requires a discrete parameter for the display settings:

```
DISPlay:VIEW METER_VI|METER_VP|METER VIP
```

Boolean Parameters

Boolean parameters represent a single binary condition that is either true or false. For a false condition, the instrument will accept "OFF" or "0". For a true condition, the instrument will accept "ON" or "1". When you query a Boolean setting, the instrument will always return "0" or "1". The following command requires a Boolean parameter:

```
DISPlay OFF|0|ON|1
```

ASCII String Parameters

String parameters can contain virtually any set of ASCII characters. A string must begin and end with matching quotes; either with a single quote or a double quote. You can include the quote delimiter as part of the string by typing it twice without any characters in between. The following command uses a string parameter:

```
CALibrate:DATE "12/12/12"
```

Arbitrary Block Program or Response Data

Definite-length block data <Block> allows any type of device-dependent data to be programmed or returned as a series of 8-bit binary data bytes. This is particularly useful for transferring large quantities of data or 8-bit extended ASCII codes.

Device Clear

Device Clear is an IEEE-488 low-level bus message that you can use to return the instrument to a responsive state. Different programming languages and IEEE-488 interface cards provide access to this capability through their own unique commands. The status registers, the error queue, and all configuration states are left unchanged when a Device Clear message is received.

Device Clear performs the following actions:

- If a measurement is in progress, it is aborted.

- The instrument returns to the trigger idle state.

- The instrument's input and output buffers are cleared.

- The instrument is prepared to accept a new command string.

  | NOTE | The ABORt command is the recommended method to terminate an instrument operation.

Typical Command Processing Times

The following table documents some typical, average command processing times for several types of setting commands and response queries. This can help you determine the impact of some commonly used SCPI commands on total test time. All times are in milliseconds.

Setting commands like VOLT <n> only account for the IO latency + command processing, not the time for the action to complete (like the output voltage to finish changing or output state completing turn on).

Query command times apply from when the command was sent to the instrument until the response is received.

Setting Commands	GPIB	LAN
Set the output voltage: VOLT <n>	0.5 ms	2.5 ms
Set the unit to the reset state: *RST	10.5 ms	11.5 ms
Query Commands		
Return the voltage setting: VOLT?	1.3 ms	5 ms
Return the output setting: OUT?	1 ms	5.5 ms
Return 10 point measurement: MEAS:VOLT?	6 ms	9.5 ms
Return 10 point fetch: FETC:VOLT?	1.5	5 ms
Return 1 NPLC measurement: MEAS:VOLT?	28 ms	32.5 ms
Return 1 NPLC fetch: FETC:VOLT?	5.5 ms	10 ms
Return 25 k point measurement: MEAS:VOLT?	180 ms	182 ms
Return 25 k point fetch: FETC:VOLT?	32.5 ms	36.7 ms
Return 25 k point ASCII array fetch: FETC:ARR:VOLT?	9267 ms	5818 ms
Return 25 k point binary array fetch: FETC:ARR:VOLT?	558 ms	537 ms

Commands by Subsystem

ABORt

CALibrate

DISPlay

FETCh

FORMat

HCOPy

IEEE-488 Common

INITiate

LXI

MEASure

OUTPut

SENSe

[SOURce:]

    ARB

    CURRent

    DIGital

    FUNCtion

    LIST

    POWer

    RESistance

    STEP

    VOLTage

STATus

SYSTem

TRIGger

Status Tutorial

Trigger Tutorial

ABORt Subsystem

Abort commands cancel any triggered actions and returns the trigger system back to the Idle state. Abort commands are also executed with the *RST command.

ABORt:ACQuire
ABORt:ELOG `N7900 models only`
ABORt:TRANsient

ABORt:ACQuire - Cancels any triggered measurements. It also resets the WTG-meas and MEAS-active bits in the Operation Status registers.

ABORt:ELOG - Stops external data logging. It also resets the WTG-meas and MEAS-active bits in the Operation Status registers.

ABORt:TRAN - Cancels any triggered actions. It also resets the WTG-tran and TRAN-active bits in the Operation Status registers. Note that this command does not turn off continuous triggers if INITiate:CONTinuous:TRANsient ON has been programmed. In this case, the trigger system will automatically re-initiate.

Parameter	Typical Return
(none)	(none)
Aborts the triggered measurement: ABOR:ACQ	

ARB Subsystem N7900 models only

ARB commands program the constant-dwell arbitrary waveforms. Constant-dwell waveforms can have up to 65,535 points assigned to them, with the same dwell time for each point.

[SOURce:]

   ARB

      :COUNt *<value>*|INFinity   Specifies the number of times the Arb repeats.

      :CURRent

         :CDWell

            [:LEVel] *<value>*{,*<value>*}|*<Block>* Specifies the level of each point in the Arb.

               :DWELl *<value>*   Specifies the dwell time of each point in the Arb.

               :POINts?   Returns the number of points in the Arb.

      :FUNCtion

         :TYPE CURRent|VOLTage   Specifies either a voltage or current Arb.

      :TERMinate

         :LAST 0|OFF|1|ON   Selects the output setting after the Arb ends.

      :VOLTage

         :CDWell

            [:LEVel] *<value>*{,*<value>*}|*<Block>* Specifies the level of each point in the Arb.

               :DWELl *<value>*   Specifies the dwell time of each point in the Arb.

               :POINts?   Returns the number of points in the Arb.

[SOURce:]ARB:COUNt *<value>*|MIN|MAX|INFinity
[SOURce:]ARB:COUNt? [MIN|MAX]

Specifies the number of times the Arb repeats. Use the INFinity parameter to repeat the Arb continuously.

Parameter	Typical Return
1 – 256, *RST 1	<count>
Programs a repeat count of 10: ARB:COUN 10	

[SOURce:]ARB:CURRent:CDWell[:LEVel] *<value>*{,*<value>*}|*<Block>*
[SOURce:]ARB:CURRent:CDWell[:LEVel]?
[SOURce:]ARB:VOLTage:CDWell[:LEVel] *<value>*{,*<value>*}|*<Block>*
[SOURce:]ARB:VOLTage:CDWell[:LEVel]?

Specifies the level of each point in the Arb. Values are specified in either amperes or volts. The minimum and maximum values depend on the ratings of the unit.

Current and voltage Arbs share settings, so setting the current Arb resets the voltage Arb level to its default value and vice versa. For better performance, the list can be sent as single precision floating point values in definite length arbitrary block format instead of an ASCII list. The response format is dependent on the return format ASCII or REAL.

Parameter	Typical Return
-10.2% to 102% of current rating or 0 to 102% of voltage rating	<value> [,<value>] or <Block>
With power dissipator: up to -102% to 102% of current rating	
Programs a constant dwell Arb of 5 voltage points: ARB:VOLT:CDW 5,4,3,2,1	

[SOURce:]ARB:CURRent:CDWell:DWELl *<value>*
[SOURce:]ARB:CURRent:CDWell:DWELl?
[SOURce:]ARB:VOLTage:CDWell:DWELl *<value>*
[SOURce:]ARB:VOLTage:CDWell:DWELl?

Specifies the dwell time of each point in the Arb. Values are in seconds and are rounded to the nearest 10.24-microsecond increment.

Current and voltage Arbs share settings, so setting this parameter for a current Arb changes the voltage dwell value and vice versa.

Parameter	Typical Return
0.00001024 – 0.30, *RST 0.001	<dwell value>
Programs a constant dwell time of 0.2 seconds: ARB:CURR:CDW:DWEL 0.2	

[SOURce:]ARB:CURRent:CDWell:POINts?
[SOURce:]ARB:VOLTage:CDWell:POINts?

Returns the number of points in the Arb.

Parameter	Typical Return
(none)	<points>
Returns the number of current points in the Arb: ARB:CURR:CDW:POIN?	

[SOURce:]ARB:FUNCtion:TYPE CURRent|VOLTage
[SOURce:]ARB:FUNCtion:TYPE?

Specifies either a voltage or current Arb. Only one type of Arb may be output at a time. The selection must match the priority mode.

Parameter	Typical Return
CURRent|VOLTage, *RST VOLTage	VOLT or CURR

Parameter	Typical Return
Specifies a voltage Arb: ARB:FUNC:TYPE VOLT	

[SOURce:]ARB:TERMinate:LAST 0|OFF|1|ON
[SOURce:]ARB:TERMinate:LAST?

Selects the output setting after the Arb ends. When ON (1), the output voltage or current remains at the last Arb value. The last Arb voltage or current value becomes the IMMediate value when the ARB completes. When OFF (0), and also when the Arb is aborted, the output returns to the settings that were in effect before the Arb started.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
Terminate with the output at the last Arb value: ARB:TERM:LAST ON	

CALibrate Subsystem

Calibrate commands calibrate the instrument.

| NOTE | Read the calibration section before calibrating. Improper calibration can reduce accuracy and reliability. |

CALibrate

:COUNt?	Returns the number of times the unit has been calibrated.
:CURRent	
:LEVel *<value>*	Calibrates the current programming and measurement.
:MEASure *<value>*	Calibrates the low range current measurement.
:SHARing	Calibrates the Imon signal for paralleled units.
:TC	Calibrates the temperature coefficient.
:DATA *<value>*	Enters the calibration value read by the external meter.
:DATE *<"date">*	Enters the calibration date in nonvolatile memory.
:LEVel P1|P2|P3	Advances to the next level in the calibration.
:PASSword *<value>*	Sets a numeric password to prevent unauthorized calibration.
:RESistance	
:BOUT	Calibrates the bottom out resistance.
:SAVE	Saves the calibration constants in non-volatile memory.
:STATe 0|OFF|1|ON	Enables or disables calibration mode.
:VOLTage	
:LEVel *<value>*	Calibrates the voltage programming and measurement.
:CMRR	Calibrates the voltage common mode rejection ratio.

CALibrate:COUNt?

Returns the number of times the unit has been calibrated. The count is incremented whenever the calibration (and date) is saved, the administration password is changed or reset, or the firmware is updated.

Parameter	Typical Return
(none)	<count>
Return the calibration count: CAL:COUN?	

CALibrate:CURRent:LEVel *<value>*

Calibrates the current programming and measurement. The value selects the range to calibrate.

Parameter	Typical Return
The maximum current of the output range being calibrated.	(none)
Calibrates the current of the 10 A range: CAL:CURR:LEV 10	

CALibrate:CURRent:MEASure *<value>*

Calibrates the low range current measurement. The value selects the range to calibrate.

Parameter	Typical Return
The maximum current of the measurement range being calibrated.	(none)
Calibrates the current of the 10 A measurement range: CAL:CURR:MEAS 10	

CALibrate:CURRent:SHARing

Calibrates the Imon signal for paralleled units.

Parameter	Typical Return
(none)	(none)
Calibrates the current sharing: CAL:CURR:SHAR	

CALibrate:CURRent:TC

Calibrates the temperature coefficient.

Parameter	Typical Return
(none)	(none)
Calibrates the temperature coefficient: CAL:CURR:TC	

CALibrate:DATA *<value>*

Enters the calibration value read by the external meter. You must first select a calibration level for the value being entered. Data values are expressed in base units - either volts or amperes, depending on which function is being calibrated.

Parameter	Typical Return
Numeric value	(none)
Specify calibration value 0.0237: CAL:DATA 2.37E-2	

CALibrate:DATE *<"date">*
CALibrate:DATE?

Enters the calibration date in nonvolatile memory. Enter any ASCII string up to 15 characters. The query returns the date.

Parameter	Typical Return
<"date"> String program data. Enclose string parameters in single or double quotes.	<last cal date>
Enters the calibration date: CAL:DATE "12/12/12"	

CALibrate:LEVel P1|P2|P3
CALibrate:LEVel?

Advances to the next level in the calibration. P1 is the first level; P2 is the second; P3 is the third.

Parameter	Typical Return
P1|P2|P3	(none)
Selects the first calibration point: CAL:LEV P1	

- Some calibration sequences may require some settling time after sending CAL:LEV but before reading the data from the DVM and sending CAL:DATA.

CALibrate:PASSword *<password>*

Sets a numeric password to prevent unauthorized calibration. This is the same as the Admin password.

Parameter	Typical Return
<password> A numeric value of up to 15 digits	(none)
Set a new password to a value of 1234: CAL:PASS 1234	

- If the password is set to 0, password protection is removed and the ability to enter calibration mode is unrestricted. The as-shipped setting is 0 (zero).

- To change the password: unsecure calibration memory with old code, then set the new code.

- If you forget your password, refer to Calibration Switches.

- This setting is non-volatile; it will not be changed by power cycling or *RST.

CALibrate:RESistance:BOUT

Calibrates the bottom out resistance.

Parameter	Typical Return
(none)	(none)
Calibrates the bottom out resistance: CAL:RES:BOUT	

CALibrate:SAVE

Saves the calibration constants in non-volatile memory. Do this at the end of the calibration to avoid losing changes.

Parameter	Typical Return
(none)	(none)
Store calibration constants into non-volatile memory: CAL:SAVE	

CALibrate:STATe 0|OFF|1|ON [,<password>]
CALibrate:STATe?

Enables or disables calibration mode. Calibration mode must be enabled for the instrument to accept any calibration commands. The first parameter specifies the state. The second optional parameter is the password.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
<password> a numeric value up to 15 digits	(none)
Disable calibration: CAL:STAT OFF Enable calibration: CAL:STAT ON [,value]	

<password> is required if it has been set to a non-zero value.

CALibrate:VOLTage:LEVel <value>

Calibrates the voltage programming and measurement. The value selects the range to calibrate.

Parameter	Typical Return
The maximum voltage of the output range being calibrated.	(none)
Calibrates the voltage of the 20 V range: CAL:VOLT:LEV 20	

CALibrate:VOLTage:CMRR

Calibrates the voltage common mode rejection ratio.

Parameter	Typical Return
(none)	(none)
Calibrates the common mode rejection ratio: CAL:VOLT:CMRR	

CURRent Subsystem

Current commands program the output current of the instrument.

[SOURce:]
   CURRent
     [:LEVel]
       [:IMMediate]

[:AMPLitude] *<value>*	Sets the output current when in current priority mode
:TRIGgered	
[:AMPLitude] *<value>*	Sets the triggered output current
:LIMit	
[:POSitive]	
[:IMMediate]	
[:AMPLitude] *<value>*	Sets the current limit when in voltage priority mode.
:NEGative	
[:IMMediate]	
[:AMPLitude] *<value>*	Sets the current limit when in voltage priority mode.
:MODE FIXed|STEP|LIST|ARB	Sets the transient mode.
:PROTection	
:DELay	
[:TIME] *<value>*	Sets the over-current protection delay.
:STARt SCHange|CCTRans	Specifies what starts the over-current protection delay timer.
:STATe 0|OFF|1|ON	Enables or disables the over-current protection.
:SHARing	
[:STATe] 0|OFF|1|ON	Enables or disables current sharing on paralleled units.
:SLEW	
[:IMMediate] *<value>*|INFinity	Sets the current slew rate.
:MAXimum 0|OFF|1|ON	Enables or disables the maximum slew rate override.

[SOURce:]CURRent[:LEVel][:IMMediate][:AMPLitude] *<value>*|MIN|MAX
[SOURce:]CURRent[:LEVel][:IMMediate][:AMPLitude]? [MIN|MAX]
[SOURce:]CURRent[:LEVel]:TRIGgered[:AMPLitude] *<value>*|MIN|MAX
[SOURce:]CURRent[:LEVel]:TRIGgered[:AMPLitude]? [MIN|MAX]

Sets the immediate or triggered current level when the output is operating in current priority mode. The triggered level is a stored value that is transferred to the output when an output Step is triggered. Units are in amperes. The maximum value depends on the current rating of the unit. The minimum value is the most negative value.

Parameter	Typical Return
-10.2% to 102% of rating, *RST 0 With power dissipator: up to -102% to 102% of rating	<current level>
Sets the positive current limit to 2 A: `CURR:LIM 2`	

[SOURce:]CURRent:LIMit[:POSitive][:IMMediate][:AMPLitude] *<value>*|MIN|MAX
[SOURce:]CURRent:LIMit[:POSitive][:IMMediate][:AMPLitude]? [MIN|MAX][SOURce:]
CURRent:LIMit:NEGative[:IMMediate][:AMPLitude] *<value>*|MIN|MAX
[SOURce:]CURRent:LIMit:NEGative[:IMMediate][:AMPLitude]? [MIN|MAX]

Sets the current limit when in voltage priority mode. Units are in amperes. The maximum value depends on the current rating of the unit. The minimum value is the most negative value.

Parameter	Typical Return
Positive: 0 to 102% of rating, *RST 1.02% of rating Negative: -10.2% of rating to 0, *RST -10.2% of rating Negative with power dissipator: up to -102% of rating to 0	<+current limit> <−current limit>
Sets the positive current limit to 2 A: CURR:LIM 2 Sets the negative current limit to -2 A: CURR:LIM:NEG -2	

[SOURce:]CURRent:MODE FIXed|STEP|LIST|ARB
[SOURce:]CURRent:MODE?

Sets the transient mode. This determines what happens to the output current when the transient system is initiated and triggered.

FIXed keeps the output current at its immediate value.

STEP steps the output to the triggered level when a trigger occurs.

LIST causes the output to follow the list values when a trigger occurs.

ARB causes the output to follow the arbitrary waveform values when a trigger occurs.

Parameter	Typical Return
FIXed|STEP|LIST|ARB, *RST FIXed	FIX, STEP, LIST, or ARB
Sets the current mode to Step: CURR:MODE STEP	

[SOURce:]CURRent:PROTection:DELay[:TIME] *<value>*|MIN|MAX
[SOURce:]CURRent:PROTection:DELay[:TIME]? [MIN|MAX]

Sets the over-current protection delay. The over-current protection function will not be triggered during the delay time. After the delay time has expired, the over-current protection function will be active. This prevents momentary changes in output status from triggering the over-current protection function. Values up to 255 milliseconds can be programmed, with a resolution of 1 millisecond.

Parameter	Typical Return
0 – 0.255, *RST 0.020 s	<delay value>
Sets the protection delay to 0.2 seconds: CURR:PROT:DEL 0.2	

- The operation of over-current protection is affected by the setting of the current protection delay start event, which is specified by CURRent:PROTection:DELay:STARt.

[SOURce:]CURRent:PROTection:DELay:STARt SCHange|CCTRans
[SOURce:]CURRent:PROTection:DELay:STARt?

Specifies what starts the over-current protection delay timer. **SCHange** starts the over-current delay whenever a command changes the output settings. **CCTRans** starts the over-current delay timer by any transition of the output into current limit mode.

Parameter	Typical Return
SCHange|CCTRans, *RST SCHange	SCH or CCTR
Selects the CCTRans as the current protection delay mode: CURR:PROT:DEL:STAR CCTR	

[SOURce:]CURRent:PROTection:STATe 0|OFF|1|ON
[SOURce:]CURRent:PROTection:STATe?

Enables or disables the over-current protection. If the over-current protection function is enabled and the output goes into current limit, the output is disabled and the Questionable Condition status register OCP bit is set.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
Enable the current protection state: CURR:PROT:STAT ON	

- An over-current condition can be cleared with OUTPut:PROTection:CLEar after the cause of the condition is removed.

[SOURce:]CURRent:SHARing[:STATe] 0|OFF|1|ON
[SOURce:]CURRent:SHARing[:STATe]?

Enables or disables current sharing on paralleled units. This command must be sent to each unit that is paralleled. When enabled, the load current is shared equally among the paralleled outputs. The rear panel **Share** terminals must be connected; otherwise an error will occur.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
To enable current sharing: CURR:SHAR ON	

[SOURce:]CURRent:SLEW[:IMMediate] *<value>*|MIN|MAX|INFinity
[SOURce:]CURRent:SLEW[:IMMediate]? [MIN|MAX]

Sets the current slew rate. The slew rate is set in amps per second and affects all programmed current changes, including those due to the output state turning on or off. The slew rate can be set to any value between 0 and 9.9E+37. For very large values, the slew rate will be limited by the analog performance of the output circuit. The keywords MAX or INFinity set the slew rate to maximum.

Parameter	Typical Return
0 – 9.9E+37, *RST MAX	<max value>
Sets the output slew rate to 1 A per second: CURR:SLEW 1	

- The query returns the value that was sent, unless the value is less than the minimum slew rate, in which case the minimum value is returned. The resolution of the slew setting is also the minimum value, which can be queried using CURRent:SLEW? MIN. The exact value varies slightly according to calibration.

[SOURce:]CURRent:SLEW:MAXimum 0|OFF|1|ON
[SOURce:]CURRent:SLEW:MAXimum?

Enables or disables the maximum slew rate override. When enabled, the slew rate is set to its maximum value. When disabled, the slew rate is set to the immediate value set by the [SOURce:]CURRent:SLEW command. Use [SOURce:]CURRent:SLEW? MAX to query the maximum slew rate that was set.

Parameter	Typical Return
0|OFF|1|ON, *RST ON	0 or 1
Enable the maximum slew rate: CURR:SLEW:MAX ON	

- The [SOURce:]CURRent:SLEW:MAX command is coupled to the [SOURce:]CURRent:SLEW command. If [SOURce:]CURRent:SLEW sets the rate to MAX or INFinity, [SOURce:]CURRent:SLEW:MAX is enabled. If the slew rate is set to any other value, [SOURce:]CURRent:SLEW:MAX is disabled.

DIGital Subsystem

Digital commands program the digital control port on the rear panel of the instrument.

[SOURce:]

    DIGital

       :INPut

          :DATA?   Reads the state of the digital control port.

       :OUTput

          :DATA *<value>*   Sets the state of the digital control port.

       :PIN<1-7>

          :FUNCtion   Sets the function of the pins. DIO |DINPut |EXPRession<1-8> |FAULt |INHibit |ONCouple
<function> |OFFCouple |TOUTput |TINPut

          :POLarity   Sets the polarity of the pins.
POSitive|NEGative

       :TOUTput

          :BUS

             [:ENABle]   Enables or disables BUS triggers on digital port pins.
0|OFF|1|ON

[SOURce:]DIGital:INPut:DATA?

Reads the state of the digital control port. Returns the binary-weighted value of the state of pins 1 through 7 in bits 0 through 6 respectively.

Parameter	Typical Return
(none)	<bit value>
Reads the state of the digital control port: DIG:INP:DATA?	

[SOURce:]DIGital:OUTPut:DATA *<value>*
[SOURce:]DIGital:OUTPut:DATA?

Sets the state of the digital control port. This only affects the pins whose function has been set to Digital IO operation. The port has seven signal pins and a digital ground pin. In the binary-weighted value that is written to the port, the pins are controlled according to the following bit assignments:

Pin	1	2	3	4	5	6	7
Bit number	0	1	2	3	4	5	6
Decimal value	1	2	4	8	16	32	64

Bit values corresponding to digital port pins that are not configured as DIO are ignored.

Parameter	Typical Return
0 – 127, *RST 0	<bit value>
Programs pins 1, 3, and 5 on: DIG:OUTP:DATA?	

[SOURce:]DIGital:PIN<1-7>:FUNCtion *<function>*
[SOURce:]DIGital:PIN<1-7>:FUNCtion?

Sets the function of the pins. The functions are saved in non-volatile memory.

DIO	General-purpose ground-referenced digital input/output function.
DINput	Digital input-only mode.
EXPRession <1-8>	A user-defined expression drives the pin.
FAULt	Pin 1 functions as an isolated fault output. Pin 2 is common for pin 1
INHibit	Pin 3 functions as an inhibit input.
ONCouple	Pins 4 -7 synchronize the output On state.
OFFCouple	Pins 4 -7 synchronize the output Off state.
TINput	A trigger input function.
TOUTput	A trigger output function

Parameter	Typical Return
DIO | DINPut | EXPRession<1-8> | FAULt | INHibit | ONCouple | OFFCouple TINput | TOUTput	DIO, DIN, EXPR<n>, FAUL, INH, ONC, OFFC, TIN, or TOUT
Sets pin 1 to FAULt mode: DIG:PIN1:FUNC FAUL	

[SOURce:]DIGital:PIN<1-7>:POLarity POSitive\|NEGative
[SOURce:]DIGital:PIN<1-7>:POLarity?

Sets the polarity of the pins. **POSitive** means a logical true signal is a voltage high at the pin. For trigger inputs and outputs, POSitive means a rising edge. **NEGative** means a logical true signal is a voltage low at the pin. For trigger inputs and outputs, NEGative means a falling edge. The pin polarities are saved in non-volatile memory.

Parameter	Typical Return
POSitive|NEGative	POS or NEG
Sets pin 1 to POSitive polarity: DIG:PIN1:POL POS	

[SOURce:]DIGital:TOUTput:BUS[:ENABle] 0|OFF|1|ON
[SOURce:]DIGital:TOUTput:BUS[:ENABle]?

Enables or disables BUS triggers on digital port pins. This allows a BUS trigger to be sent to any digital port pin that has been configured as a trigger output. A trigger out pulse is generated when the state is on and a bus trigger is received. A BUS trigger is generated using the *TRG command.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
Enable BUS triggered signals on the digital pins: CURR:TOUT:BUS ON	

- The query returns 0 (OFF) if the trigger signal will NOT be generated with a BUS trigger command, and 1(ON) if a trigger signal will be generated with a BUS trigger command.

DISPlay Subsystem

Display commands control the front panel display.

DISPlay[:WINDow][:STATe] 0|OFF|1|ON
DISPlay[:WINDow][:STATe]?

Turns the front panel display on or off.

Parameter	Typical Return
0|OFF|1|ON, *RST ON	0 or 1
Turns the front panel display off: DISP OFF	

DISPlay[:WINDow]:VIEW METER_VI|METER_VP|METER_VIP
DISPlay[:WINDow]:VIEW?

Selects the parameters to display on the front panel. **METER_VI** displays output voltage and current. **METER_VP** displays output voltage and power. **METER_VIP** displays output voltage, current, and power.

Parameter	Typical Return
METER_VI|METER_VP|METER_VIP, *RST METER_VI	METER_VI, METER_VP, or METER_VIP
To display voltage and power: DISP:VIEW METER_VP	

FETCh Subsystem

Fetch commands return measurement data that has been previously acquired. FETCh queries do not generate new measurements, but allow additional measurement calculations from the same acquired data. The data is valid until the next MEASure or INITiate command occurs.

```
FETCh
   [:SCALar]
      :CURRent
         [:DC]? [<start_index>, <points>]  Returns the averaged measurement.
         :ACDC?                            Returns the RMS measurement (AC + DC).
         :HIGH?                            Returns the High level of a pulse waveform.
         :LOW?                             Returns the Low level of a pulse waveform.
         :MAXimum?
         :MINimum?                         Returns the maximum or minimum value.
      :POWer
         [:DC]? [<start_index>, <points>]  Returns the averaged measurement.
      :VOLTage
         [:DC]? [<start_index>, <points>]  Returns the averaged measurement.
         :ACDC?                            Returns the RMS measurement (AC + DC).
         :HIGH?                            Returns the High level of a pulse waveform.
         :LOW?                             Returns the Low level of a pulse waveform.
         :MAXimum?
         :MINimum?                         Returns the maximum or minimum value.
   :AHOur? [IGNORE_OVLD]                   Returns the accumulated amp-hours.
   :ARRAY
      :CURRent
         [:DC]? [<start_index>, <points>]  Returns the instantaneous measurement.
      :POWer
         [:DC]? [<start_index>, <points>]  Returns the instantaneous measurement.
      :VOLTage
         [:DC]? [<start_index>, <points>]  Returns the instantaneous measurement.
   :ELOG? <maxrecords>                     Returns the most recent external datalog records.
   :WHOur? [IGNORE_OVLD]                   Returns the accumulated watt-hours.
```

FETCh[:SCALar]:CURRent[:DC]? [<start_index>, <points>]
FETCh[:SCALar]:POWer[:DC]? [<start_index>, <points>]
FETCh[:SCALar]:VOLTage[:DC]? [<start_index>, <points>]

Returns the averaged measurement. Values returned are either in amperes, volts, or watts.

The optional parameters specify a subset starting at <startindex> and of length <points>. **N7900 models only**

Parameter	Typical Return
[<startindex>] the start index [<points>] the number of points	<DC value>
Returns the measured DC current FETC:CURR?	

FETCh[:SCALar]:CURRent:ACDC?
FETCh[:SCALar]:VOLTage:ACDC?

Returns the RMS measurement (AC + DC). Values returned are either in amperes, or volts.

Parameter	Typical Return
(none)	<ACDC value>
Returns the measured RMS voltage FETC:VOLT:ACDC?	

FETCh[:SCALar]:CURRent:HIGH?
FETCh[:SCALar]:VOLTage:HIGH?

Returns the High level of a pulse waveform. Values returned are either in amperes, or volts. See Measurement Types.

Parameter	Typical Return
(none)	<HIGH value>
Returns the measured high level current FETC:CURR:HIGH?	

FETCh[:SCALar]:CURRent:LOW?
FETCh[:SCALar]:VOLTage:LOW?

Returns the Low level of a pulse waveform. Values returned are either in amperes, or volts. See Measurement Types.

Parameter	Typical Return
(none)	<LOW value>
Returns the measured low level voltage FETC:VOLT:LOW?	

FETCh[:SCALar]:CURRent:MAXimum?
FETCh[:SCALar]:VOLTage:MAXimum?
FETCh[:SCALar]:CURRent:MINimum?
FETCh[:SCALar]:VOLTage:MINimum?

Returns the maximum or minimum value. Values returned are either in amperes, or volts.

Parameter	Typical Return
(none)	<MIN value> <MAX value>
Returns the measured maximum current FETC:CURR:MAX? Returns the measured minimum voltage FETC:VOLT:MIN?	

FETCh:AHOur? [IGNORE_OVLD]
FETCh:WHOur? [IGNORE_OVLD]

FETCh:AHOur? - Returns the accumulated amp-hours.

FETCh:WHOur? - Returns the accumulated watt-hours.

See Amp-Hour and Watt-Hour Measurements for details.

If any measurement sample was overrange, the query returns SCPI Not a Number (9.91E37). If the optional IGNORE_OVLD parameter is sent, the accumulated measurement will be returned even if some samples were outside of the measurement range.

Parameter	Typical Return
IGNORE_OVLD ignore overload measurements	<amp-hours> <watt-hours>
Returns the amp-hour measurement FETC:AHO?	

FETCh:ARRay:CURRent[:DC]? [<start_index>, <points>] N7900 models only
FETCh:ARRay:VOLTage[:DC]? [<start_index>, <points>] N7900 models only
FETCh:ARRay:POWer[:DC]? [<start_index>, <points>] N7900 models only

Returns the instantaneous measurement. Values returned are either in amperes, volts, or watts.

The optional parameters specify a subset starting at <startindex> and of length <points>.

The return format depends on the settings of the FORMat:BORDer and FORMat[:DATA] commands. When the data format is set to ASCII, returned values are comma separated. When the data format is set to REAL, data is returned as single precision floating point values in definite length arbitrary block response format.

Parameter	Typical Return
[<startindex>] the start index [<points>] the number of points	<value> [,<value>] or <Block>
Returns the measured current array FETC:ARR:CURR?	

FETCh:ELOG? *<maxrecords>* `N7900 models only`

Returns the most recent external datalog records. Data must be read from the buffer periodically to avoid the buffer overflowing. Whenever data is read using FETCh:ELOG? then that buffer space is made available in the instrument for storing more acquired data.

Maxrecords is the maximum number of records of datalog data that the controller will return.

The return format depends on the settings of the FORMat:BORDer and FORMat[:DATA] commands. When the data format is set to ASCII, returned values are comma separated. When the data format is set to REAL, data is returned as single precision floating point values in definite length arbitrary block response format.

Parameter	Typical Return
[<maxrecords>] the number of records returned (1 to 16,384)	<value> [,<value>] or <Block>
Returns 100 data records FETC:ELOG? 100	

FORMat Subsystem

FORMat commands specify the format for transferring measurement data.

FORMat[:DATA] ASCII|REAL
FORMat[:DATA]?

Specifies the format of the returned data. This is used by queries that can return a block of data. **ASCII** returns data as ASCII bytes in numeric format as appropriate. The numbers are separated by commas. **REAL** returns data in a definite length block as IEEE single precision floating point values. In this case the 4 bytes of each value can be returned in either big-endian or little-endian byte order, determined by the FORMat:BORDer setting.

Parameter	Typical Return
ASCII|REAL, *RST ASCII	ASCII or REAL
Sets the data format to ASCII: FORMat ASCII	

- The data format is used by a small sub set of queries that can return large quantities of data.

FORMat:BORDer NORMal|SWAPped
FORMat:BORDer?

Specifies how binary data is transferred. This only applies when the FORMat:DATA is set to REAL. **NORMal** transfers data in normal order. The most significant byte is returned first, and the least significant byte is returned last (big-endian). **SWAPped** transfers data in swapped-byte order. The least significant byte is returned first, and the most significant byte is returned last (little-endian).

Parameter	Typical Return
NORMal|SWAPped, *RST NORMal	NORM or SWAP
Sets the data transfer to Swapped: FORM:BORD SWAP	

- The byte order is used when fetching real data from SCPI measurements.

FUNCtion Command

[SOURce:]FUNCtion CURRent|VOLTage
[SOURce:]FUNCtion?

Sets the output regulation - voltage priority or current priority. In voltage priority mode the output is controlled by a constant voltage feedback loop, which maintains the output voltage at its programmed setting. In current priority mode the output is controlled by a constant current feedback loop, which maintains the output current at its positive or negative programmed setting.

Parameter	Typical Return
CURRent|VOLTage, *RST VOLTage	CURR or VOLT
Sets the output regulation to current priority: FUNC CURR	

HCOPy Subsystem

HCOPy commands return the display image.

HCOPy:SDUMp:DATA? [BMP|GIF|PNG]

Returns an image of the front panel display. The format may be specified by the optional parameter. If no format is specified, the format is determined by HCOPy:SDUMp:DATA:FORMat.

The response is an indefinite length binary block of the form: #0<data-bytes>NL^END. #0 indicates the response is an indefinite length. The end of the block is a newline with EOI asserted.

Parameter	Typical Return
[BMP|GIF|PNG]	<Block>
Returns the image in GIF format: HCOP:SDUM:DATA? GIF	

HCOPy:SDUMp:DATA:FORMat BMP|GIF|PNG
HCOPy:SDUMp:DATA:FORMat?

Specifies the format for front panel images returned.

Parameter	Typical Return
BMP|GIF|PNG, *RST PNG	BMP, GIF, or PNG
Specify GIF as the image format: HCOP:SDUM:DATA:FORM GIF	

IEEE-488 Common Commands

IEEE-488 Common commands generally control overall instrument functions, such as reset, status, and synchronization. All common commands consist of a three-letter mnemonic preceded by an asterisk: *RST *IDN? *SRE 8.

*CLS	Clear status command.
*ESE *<value>*	Event status enable command and query.
*ESR?	Event status event query.
*IDN?	Identification Query.
*OPC	Sets the OPC (operation complete) bit in the standard event register.
*OPC?	Returns a 1 to the output buffer when all pending operations complete.
*OPT?	Returns a string identifying any installed options.
*RCL *<value>*	Recalls a saved instrument state.
*RST	Resets the instrument to pre-defined values that are either typical or safe.
*SAV *<value>*	Saves the instrument state to one of ten non-volatile memory locations.
*SRE *<value>*	Service request enable command and query.
*STB?	Status byte query.
*TRG	Trigger command.
*TST?	Self-test query.
*WAI	Pauses additional command processing until all pending operations are complete.

*CLS

Clear status command. Clear Status Command. Clears the event registers in all register groups. Also clears the status byte and error queue. If *CLS immediately follows a program message terminator (<NL>), then the output queue and the MAV bit are also cleared. Refer to Status Tutorial for more information.

Parameter	Typical Return
(none)	(none)
Clear event registers, status byte, and error queue: *CLS	

*ESE *<value>*
*ESE?

Event status enable command and query. Sets the value in the enable register for the Standard Event Status group. Each set bit of the register enables a corresponding event. All enabled events are logically ORed into the ESB bit of the status byte. The query reads the enable register. Refer to Status Tutorial for more information.

Parameter	Typical Return
A decimal value corresponding to the binary-weighted sum of the register's bits.	<bit value>
Enable bits 3 and 4 in the enable register: *ESE 48	

- For example, to enable bit 2 (decimal value = 4), bit 4 (decimal value = 16), the corresponding decimal value would be 20 (4 + 16).

- The value returned is the binary-weighted sum of all bits set in the register.

- Any or all conditions can be reported to the ESB bit through the enable register. To set the enable register mask, write a decimal value to the register using *ESE.

- *CLS does not clear the enable register, but does clear the event register.

*ESR?

Event status event query. Reads and clears the event register for the Standard Event Status group. The event register is a read-only register, which latches all standard events. Refer to Status Tutorial for more information.

Parameter	Typical Return
(none)	<bit value>
Read event status enable register: *ESR?	

- The value returned is the binary-weighted sum of all bits set in the register.

- Any or all conditions can be reported to the ESB bit through the enable register. To set the enable register mask, write a decimal value to the register using *ESE.

- Once a bit is set, it remains set until cleared by this query or *CLS.

*IDN?

Identification Query. Returns instrument's identification string, which contains four comma-separated fields. The first field is the manufacturer's name, the second field is the instrument model number, the third field is the serial number, and the fourth field is the firmware revision.

Parameter	Typical Return
(none)	Agilent Technologies,N7915A,MY12345678,A.01.01
Return the instrument's identification string: *IDN?	

Agilent Technologies	Manufacturer
N69xxA or **N79xxA**	Model number
MYxxxxxxxx	Serial number
X.xx.xx	Revision level of firmware

*OPC

Sets the OPC (operation complete) bit in the standard event register. This occurs at the completion of the pending operation. Refer to Status Tutorial for more information.

Parameter	Typical Return
(none)	(none)
Set the Operation Complete bit: OPC?	

- The purpose of this command is to synchronize your application with the instrument.

- Used in conjunction with initiated acquisitions, initiated transients, output state changes, and output to settling time to provide a way to poll or interrupt the computer when these pending operations complete.

- Other commands may be executed before the operation complete bit is set.

- The difference between *OPC and *OPC? is that *OPC? returns "1" to the output buffer when the current operation completes.

*OPC?

Returns a 1 to the output buffer when all pending operations complete. The response is delayed until all pending operations complete.

Parameter	Typical Return
(none)	1
Return a 1 when commands complete: OPC?	

- The purpose of this command is to synchronize your application with the instrument.

- Other commands cannot be executed until this command completes.

*OPT?

Returns a string identifying any installed options. A 0 (zero) indicates no options are installed.

Parameter	Typical Return
(none)	OPT 760
Returns installed options *OPT?	

*RCL <0-9>

Recalls a saved instrument state. This restores the instrument to a state that was previously stored in locations 0 through 9 with the *SAV command. All instrument states are recalled except: (1) trigger systems are set to the Idle state, (2) calibration is disabled, (3) all list settings are set to their *RST values, and (4) non-volatile settings are not affected.

Parameter	Typical Return
0 - 9	(none)
Recall state from location 1: *RCL 1	

- Location 0 is automatically recalled at power turn-on when the Output Power-On state is set to RCL 0.

- Stored instrument states are not affected by *RST.

*RST

Resets the instrument to pre-defined values that are either typical or safe. These settings are described in Reset State.

Parameter	Typical Return
(none)	(none)
Reset the instrument: *RST	

- *RST forces the ABORt commands. This cancels any measurement or transient actions presently in process. It resets the WTG-meas, MEAS-active, WTG-tran, and TRAN-active bits in the Operation Status registers.

*SAV <0-9>

Saves the instrument state to one of ten non-volatile memory locations.

Parameter	Typical Return
0 - 9	(none)
Save state to location 1: *SAV 1	

- If a particular state is desired at power-on, it should be stored in location 0. Location 0 is automatically recalled at power turn-on when the Output Power-On state is set to RCL 0.

- List data and the calibration state is NOT saved as part of the *SAV operation.

- Data saved in non-volatile memory, described under Non-Volatile Settings, is not affected by the *SAV command.

- When shipped, locations 0 through 9 are empty.

*SRE *<value>*
*SRE?

Service request enable command and query. This sets the value of the Service Request Enable register. This determines which bits from the Status Byte Register are summed to set the Master Status Summary (MSS) bit and the Request for Service (RQS) summary bit. A 1 in any Service Request Enable register bit position enables the corresponding Status Byte register bit. All such enabled bits are then logically OR-ed to cause the MSS bit of the Status Byte register to be set. Refer to Status Tutorial for more information.

Parameter	Typical Return
A decimal value corresponding to the binary-weighted sum of the register's bits.	<bit value>
Enable bit 3 and bit 4 in the enable register: *SRE 24	

- When a serial poll is conducted in response to SRQ, the RQS bit is cleared, but the MSS bit is not. When *SRE is cleared (by programming it with 0), the power supply cannot generate an SRQ to the controller.

*STB?

Status byte query. Reads the Status Byte Register, which contains the status summary bits and the Output Queue MAV bit. The Status Byte is a read-only register and the bits are not cleared when it is read. Refer to Status Tutorial for more information.

Parameter	Typical Return
(none)	<bit value>
Read status byte (bits 3 and 5 set): *STB?	

*TRG

Trigger command. Generates a trigger when the trigger subsystem has BUS selected as its source. The command has the same effect as the Group Execute Trigger (<GET>) command.

Parameter	Typical Return
(none)	(none)
Generates an immediate trigger: *TRG	

*TST?

Self-test query. Performs a instrument self-test. If self-test fails, one or more error messages will provide additional information. Use SYSTem:ERRor? to read error queue. See SCPI Error Messages for more information.

Parameter	Typical Return
(none)	0 (pass) or +1 (failed)
Perform self-test: *TST?	

- The power-on self-test is the same self-test performed by *TST.

- *TST? also forces an *RST command.

*WAI

Pauses additional command processing until all pending operations are complete. See OPC for more information.

Parameter	Typical Return
(none)	(none)
Wait until all pending operations complete. *WAI	

- *WAI can only be aborted by sending the instrument a Device Clear command.

INITiate Subsystem

Initiate commands initialize the trigger system. This moves the trigger system from the "idle" state to the "wait-for-trigger" state; which enables the instrument to receive triggers. An event on the selected trigger source causes the trigger to occur.

INITiate[:IMMediate]:ACQuire
INITiate[:IMMediate]:ELOG
INITiate[:IMMediate]:TRANsient

INITiate:ACQuire - Initiates the measurement trigger system.

INITiate:ELOG - Initiates external data logging.

INITiate:TRANsient - Initiates the transient trigger system.

Parameter	Typical Return
(none)	(none)
Initiate the measurement-trigger system: INIT:ACQ	

- It takes a few milliseconds for the instrument to be ready to receive a trigger signal after receiving the INITiate command.

- If a trigger occurs before the trigger system is ready for it, the trigger will be ignored. Check the WTG_meas bit in the operation status register to know when the instrument is ready.

- Use ABORt commands to return the instrument to Idle.

INITiate:CONTinuous:TRANsient 0|OFF|1|ON
INITiate:CONTinuous:TRANsient?

Continuously initiates the transient trigger system. This allows multiple triggers to generate multiple output transients.

Parameter	Typical Return
0|OFF|1|ON, *RST ON	0 or 1
Continually initiates the output trigger system: INIT:CONT:TRAN ON	

- With initiate continuous disabled, the output trigger system must be initiated for each trigger using the INITiate:TRANsient command.

- ABORt:TRANsient does not turn off continuous triggers if INITiate:CONTinuous:TRANsient ON has been programmed. In this case, the trigger system will automatically re-initiate.

LIST Subsystem [N7900 models only]

List commands program an output sequence of multiple voltage or current settings. A comma-delimited list of up to 512 steps may be programmed. Note that these commands only apply in the presently active priority mode, either voltage priority or current priority.

[SOURce:]
    LIST
        :COUNt *<value>*|INFinity   Sets the list repeat count.
        :CURRent
           [:LEVel] *<value>*{,*<value>*}   Specifies the setting for each list step.
           :POINts?   Returns the number of list points.
        :DWELl *<value>*{,*<value>*}   Specifies the dwell time for each list step.
           :POINts?   Returns the number of list points.
        :STEP ONCE|AUTO   Specifies how the list responds to triggers.
        :TERMinate
           :LAST 0|OFF|1|ON   Determines the output value when the list terminates.
        :TOUTput
           :BOSTep
               [:DATA] *<Bool>*{,*<Bool>*}   Generates a trigger out at the Beginning Of STep
               :POINts?   Returns the number of list points.
           :EOSTep
               [:DATA] *<Bool>*{,*<Bool>*}   Generates a trigger out at the End Of STep
               :POINts?   Returns the number of list points.
        :VOLTage
           [:LEVel] *<value>*{,*<value>*}   Specifies the setting for each list step.
           :POINts?   Returns the number of list points.

[SOURce:]LIST:COUNt *<value>*|MIN|MAX|INFinity
[SOURce:]LIST:COUNt? [MIN|MAX]

Sets the list repeat count. This sets the number of times that a list is executed before it completes. The count range is 1 through 4096. Infinity runs the list continuously.

Parameter	Typical Return
1 – 4096, *RST 1	<count>
Sets the list count to 10: LIST:COUN 10	

[SOURce:]LIST:CURRent[:LEVel] *<value>{,<value>}*
[SOURce:]LIST:CURRent[:LEVel]?
[SOURce:]LIST:VOLTage[:LEVel] *<value>,{<value*
[SOURce:]LIST:VOLTage[:LEVel]?

Specifies the setting for each list step. Values are specified in either amperes or volts.

Parameter	Typical Return
Voltage: 0 to 102% of rating Current: -10.2% to 102% of rating Current with power dissipator: up to -102% to 102% of rating	<list value 1>, <list value 2>, <list value 3>
Programs a current list. The list contains 3 steps:LIST:CURR 3,2,1 Programs a voltage list. The list contains 3 steps:LIST:VOLT 20,10,5	

[SOURce:]LIST:DWELl *<value>{,<value>}*
[SOURce:]LIST:DWELl?

Specifies the dwell time for each list step. Dwell time is the time that the output will remain at a specific step. Dwell times can be programmed from 0 through 262.144 seconds with the following resolution:

Range in seconds	Resolution
0 - 0.262144	1 microsecond
0.262144 - 2.62144	10 microseconds
2.62144 - 26.2144	100 microseconds
26.2144 - 262.144	1 millisecond

Parameter	Typical Return
0 – 262.144	<list value 1>, <list value 2>, <list value 3>
Programs a dwell list. The list contains 3 steps: LIST:DWEL 0.2,0.8,1.6	

[SOURce:]LIST:CURRent:POINts?
[SOURce:]LIST:DWELl:POINts?
[SOURce:]LIST:VOLTage:POINts?
[SOURce:]LIST:TOUTput:BOSTep:POINts?
[SOURce:]LIST:TOUTput:EOSTep:POINts?

Returns the number of list points. Points are the same as steps. The queries do not return the point values.

Parameter	Typical Return
(none)	<points>
Returns the number of points in the dwell list: LIST:DWEL:POIN?	

[SOURce:]LIST:STEP ONCE|AUTO
[SOURce:]LIST:STEP?

Specifies how the list responds to triggers. **ONCE** causes the output to remain at the present step until a trigger advances it to the next step. Triggers that arrive during the dwell time are ignored. **AUTO** causes the output to automatically advance to each step, after the receipt of an initial starting trigger. Steps are paced by the dwell list. As each dwell time elapses, the next step is immediately output.

Parameter	Typical Return
ONCE|AUTO, *RST AUTO	ONCE or AUTO
Specifies the list steps to be paced by trigger signals: LIST:STEP ONCE	

[SOURce:]LIST:TERMinate:LAST 0|OFF|1|ON
[SOURce:]LIST:TERMinate:LAST?

Determines the output value when the list terminates. When ON (1), the output voltage or current remains at the last list step. The value of the last voltage or current list step becomes the IMMediate value when the list completes. When OFF (0), and also when the list is aborted, the output returns to the settings that were in effect before the list started.

Parameter	Typical Return
0|OFF|1|ON , *RST OFF	0 or 1
Terminate with the output at the last step value: LIST:TERM:LAST ON	

[SOURce:]LIST:TOUTput:BOSTep[:DATA] 0|OFF|1|ON {,0|OFF|1|ON }
[SOURce:]LIST:TOUTput:BOSTep[:DATA]?
[SOURce:]LIST:TOUTput:EOSTep[:DATA] 0|OFF|1|ON {,0|OFF|1|ON }
[SOURce:]LIST:TOUTput:EOSTep[:DATA]?

Specifies which list steps generate a trigger signal at the beginning of step (BOSTep) or end of step (EOSTep). A trigger is only generated when the state is set to ON. The trigger signal can be used as a trigger source for measurements and transients of other units, and for digital port pins configured as trigger outputs.

Parameter	Typical Return
0|OFF|1|ON	0 or 1
To generate triggers at the beginning of the second step of a 3-step list: LIST:TOUT:BOST OFF,ON,OFF	

LXI Command

LXI:IDENtify[:STATe] 0|OFF|1|ON
LXI:IDENtify[:STATe]?

Turns the front panel LXI identify indicator on or off. When turned on, the "LAN" status indicator on the front panel blinks on and off to identify the instrument that is being addressed.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
To blink the front panel LXI indicator: LXI:IDENT ON	

MEASure Subsystem

Measure commands measure the output voltage or current. They trigger the acquisition of new data before returning the reading. Measurements are performed by digitizing the instantaneous output voltage or current for a specified measurement time, storing the results in a buffer, and calculating the value for the specified measurement type.

```
MEASure
  [:SCALar]
    :CURRent
      [:DC]?        Takes a measurement; returns the averaged current.
      :ACDC?        Takes a measurement; returns the RMS current (AC + DC).
      :HIGH?        Takes a measurement; returns the High level of a current pulse.
      :LOW?         Takes a measurement; returns the Low level of a current pulse.
      :MAXimum?     Takes a measurement; returns the maximum current.
      :MINimum?     Takes a measurement; returns the minimum current.
    :POWer
      [:DC]?        Takes a measurement; returns the averaged power.
    :VOLTage
      [:DC]?        Takes a measurement; returns the averaged voltage.
      :ACDC?        Takes a measurement; returns the RMS voltage (AC + DC).
      :HIGH?        Takes a measurement; returns the High level of a voltage pulse.
      :LOW?         Takes a measurement; returns the Low level of a voltage pulse.
      :MAXimum?     Takes a measurement; returns the maximum voltage.
      :MINimum?     Takes a measurement; returns the minimum voltage.
  :ARRAY
    :CURRent
      [:DC]?        Takes a measurement; returns the instantaneous current.
    :POWer
      [:DC]?        Takes a measurement; returns the instantaneous power.
    :VOLTage
      [:DC]?        Takes a measurement; returns the instantaneous voltage.
```

MEASure[:SCALar]:CURRent[:DC]?
MEASure[:SCALar]:POWer[:DC]?
MEASure[:SCALar]:VOLTage[:DC]?

Initiates, triggers, and returns the averaged output measurement. Values returned are either in amperes, volts, or watts.

Parameter	Typical Return
(none)	<DC value>
Returns the measured DC current MEAS:CURR?	

MEASure[:SCALar]:CURRent:ACDC?
MEASure[:SCALar]:VOLTage:ACDC?

Initiates, triggers, and returns the total RMS measurement (AC + DC). Values returned are either in amperes, or volts.

Parameter	Typical Return
(none)	<ACDC value>
Returns the measured RMS voltage MEAS:VOLT:ACDC?	

MEASure[:SCALar]:CURRent:HIGH?
MEASure[:SCALar]:VOLTage:HIGH?

Initiates, triggers, and returns the High level of a pulse waveform. Values returned are either in amperes, or volts. See Measurement Types.

Parameter	Typical Return
(none)	<HIGH value>
Returns the measured high level current MEAS:CURR:HIGH?	

MEASure[:SCALar]:CURRent:LOW?
MEASure[:SCALar]:VOLTage:LOW?

Initiates, triggers, and returns the Low level of a pulse waveform. Values returned are either in amperes, or volts. See Measurement Types.

Parameter	Typical Return
(none)	<LOW value>
Returns the measured low level voltage MEAS:VOLT:LOW?	

MEASure[:SCALar]:CURRent:MAXimum?
MEASure[:SCALar]:VOLTage:MAXimum?
MEASure[:SCALar]:CURRent:MINimum?
MEASure[:SCALar]:VOLTage:MINimum?

Initiates, triggers, and returns the maximum or minimum values of a measurement. Values returned are either in amperes, or volts.

Parameter	Typical Return
(none)	<MIN value>, <MAX value>
Returns the measured maximum current MEAS:CURR:MAX? Returns the measured minimum voltage MEAS:VOLT:MIN?	

MEASure:ARRay:CURRent[:DC]? `N7900 models only`
MEASure:ARRay:VOLTage[:DC]? `N7900 models only`
MEASure:ARRay:POWer[:DC]? `N7900 models only`

Initiates and triggers a measurement; returns a list of the digitized output measurement samples. Values returned are either in amperes, volts, or watts.

The return format depends on the settings of the FORMat:BORDer and FORMat[:DATA] commands. When the data format is set to ASCII, returned values are comma separated. When the data format is set to REAL, data is returned as single precision floating point values in definite length arbitrary block response format.

Parameter	Typical Return
(none)	<value> [,<value>] or <Block>
Returns the measured current array MEAS:ARR:CURR?	

OUTPut Subsystem

The Output subsystem controls the output state, power-on, protection, and relay functions.

OUTPut

[:STATe] 0|OFF|1|ON	Enables or disables the output.
:COUPle	
[:STATe] 0|OFF|1|ON	Enables or disables output coupling.
:DOFFset <*value*>	Sets a delay offset to synchronize coupled output state changes.
:MAX	
:DOFFset?	Returns the delay offset required for this instrument.
:OFF	
:SOURce EXPRession<1-8>|NONE	Sets the off-couple signal source to an expression.
:ON	
:SOURce EXPRession<1-8>|NONE	Sets the on-couple signal source to an expression.
:DELay	
:FALL <*value*>	Sets the output turn-off sequence delay.
:RISE <*value*>	Sets the output turn-on sequence delay.
:INHibit	
:MODE LATChing|LIVE|OFF	Sets the operating mode of the remote inhibit digital pin.
:PON	
:STATe RST|RCL0	Sets the output power-on state.
:PROTection	
:CLEar	Resets the latched protection.
:TEMPerature	
:MARGin?	Returns the margin remaining before the over-temperature trips.
:USER	
[:STATe] 0|OFF|1|ON	Enables or disables the user-defined protection.
:SOURce EXPRession<1-8>|NONE	Sets the user-defined protection source to an expression.
:WDOG	
[:STATe] 0|OFF|1|ON	Enables or disables the I/O watchdog timer.
:DELay <*value*>	Sets the watchdog delay time.
:RELay	
:LOCK	
[:STATe] 0|OFF|1|ON	Enables or disables the locked-closed state of the output relays.
:POLarity NORMal|REVerse	Sets the polarity of the output relays.
:ENABle 0|OFF|1|ON	Enables or disables the polarity reversal function.

OUTPut [:STATe] 0|OFF|1|ON
OUTPut[STATe]?

Enables or disables the output. The state of a disabled output is a condition of zero output voltage and zero source current. If output and sense relays are installed, the relays will open when the output is disabled and close when the output is enabled.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
Turns the output off: OUTP OFF	

- When output is enabled, the front-panel status indicator changes from **OFF** to indicate the operating status of the instrument (**CV**, **CC**, etc.).

- Separate delays can be programmed for the off-to-on and the on-to-off transition using OUTPut:DELay:RISE and OUTput:DELay:FALL.

- Because of internal circuit start-up procedures and any installed relay options, OUTPut ON may take between 12 and 38 milliseconds to complete its function in voltage priority mode, and between 14 and 46 milliseconds in current priority mode.

OUTPut[:STATe]:COUPle[:STATe] 0|OFF|1|ON
OUTPut[:STATe]:COUPle[:STATe]?

Enables or disables output coupling. Output coupling allows the outputs of multiple instruments to turn on and off sequentially according to their specified OUTPut:DELay:RISE and OUTput:DELay:FALL programming delays. This parameter is saved in non-volatile memory.

Parameter	Typical Return
0|OFF|1|ON	0 or 1
Turns the output coupling state on: OUTP:COUP ON	

- You must connect and configure the ONCouple and OFFCouple digital connector pins of all synchronized instruments as described in the Output Couple Control section.

- Because some power supplies have different minimum delay offsets, you must also specify a common delay offset for all of the synchronized units. This value must be the largest delay offset of the synchronized group. Use OUTPut:COUPle:MAX:DOFFset? to query the delay offset for each unit. The largest value returned must be specified as the common delay offset for each unit.

OUTPut[:STATe]:COUPle:DOFFset <*value*>|MIN|MAX
OUTPut[:STATe]:COUPle:DOFFset? [MIN|MAX]

Sets a delay offset to synchronize coupled output state changes. Units are in seconds. Setting this time to the maximum delay offset specified for any instrument that is being coupled will cause all coupled outputs to synchronize to the turn-on times specified by OUTPut:DELay:RISE. This parameter is saved in non-volatile memory.

Parameter	Typical Return
0 to 1.023	<delay value>
Specifies a delay of 60 milliseconds: OUTP:COUP:DOFF 0.06	

OUTPut[:STATe]:COUPle:MAX:DOFFset?

Returns the delay offset required for this instrument. As a minimum, the OUTPut:COUPle:DELay:OFFSet value must be set to the maximum delay offset returned for any coupled output.

Parameter	Typical Return
(none)	<offset value>
Returns the maximum delay offset: OUTP:COUP:MAX:DOFF?	

OUTPut[:STATe]:COUPle:OFF:SOURce EXPRession <1-8>
OUTPut[:STATe]:COUPle:OFF:SOURce?
OUTPut[:STATe]:COUPle:ON:SOURce EXPRession <1-8>
OUTPut[:STATe]:COUPle:ON:SOURce?

Sets the source that drives the OFFCouple and ONCouple signals to an expression. The output state changes when the selected source transitions from false to true.

Parameter	Typical Return
EXPRession <1-8>	EXPR<1-8>
Sets the OFFCouple source to an expression: OUTP:COUP:OFF:SOUR EXPR1	

OUTPut[:STATe]:DELay:FALL <value>|MIN|MAX
OUTPut[:STATe]:DELay:FALL? [MIN|MAX]
OUTPut[:STATe]:DELay:RISE <value>|MIN|MAX
OUTPut[:STATe]:DELay:RISE? [MIN|MAX]

Specifies the delay in seconds that the instrument waits before turning the output on (rise) or off (fall). This allows multiple instruments to turn on or off in sequence. The output will not turn on or off until its delay time has elapsed. This command affects on-to-off state transitions. It does NOT affect transitions to off caused by protection functions. Delay times can be programmed with the following resolution:

Range in seconds	Resolution
0 to 1.023E−4	100 nanoseconds
1.03E−4 to 1.023E−3	1 microsecond
1.03E−3 to 1.023E−2	10 microseconds

Range in seconds	Resolution
1.03E–2 to 1.023E–1	100 microseconds
1.03E–1 to 1.023E+0	1 millisecond
1.03E+0 to 1.023E+1	10 milliseconds
1.03E+1 to 1.023E+2	100 milliseconds
1.03E+2 to 1.023E+3	1 second

Note that both Rise and Fall commands use the same resolution; which is determined by whichever delay time (fall or rise) is the longest.

Parameter	Typical Return
0 - 1023, *RST 0	<delay value>
Sets a delay of 0.5 s before turning the output on: OUTP:DEL:RISE 0.5	

- Each APS model exhibits a minimum delay offset that applies from the time that a command to turn on the output is received until the output actually turns on. If you specify a turn-on delay, this delay will be added to the minimum delay offset, resulting in a turn-on delay that is actually longer than the one you programmed.

- Use OUTput:COUPle:MAX:DOFFset? to query the delay offset that is required for each instrument.

OUTPut:INHibit:MODE LATChing|LIVE|OFF
OUTPut:INHibit:MODE?

Sets the operating mode of the remote inhibit digital pin. The inhibit function shuts down the output in response to an external signal on the Inhibit input pin. The Inhibit mode is stored in non-volatile memory. See Programming the Digital Port.

LATChing - a logic-true signal on the Inhibit input causes the output state to latch OFF. The output remains disabled until the Inhibit input is returned to logic-false and the latched INH status bit is cleared by sending the OUTPut:PROTection:CLEar command or a protection clear command from the front panel.

LIVE - allows the enabled output to follow the state of the Inhibit input. When the Inhibit input is true, the output is disabled. When the Inhibit input is false, the output is re-enabled.

OFF - The Inhibit input is ignored.

Parameter	Typical Return
LATChing|LIVE|OFF	LATC, LIVE, or OFF
Sets the Inhibit Input to Live mode: OUTP:INH:MODE LIVE	

OUTPut:PON:STATe RST|RCL0
OUTPut:PON:STATe?

Sets the output power-on state. This determines whether the power-on state is set to the *RST state (RST) or the state stored in memory location 0 (RCL0).Instrument states can be stored using the *SAV command. This parameter is saved in non-volatile memory.

Parameter	Typical Return
RST|RCL0	RST or RCL0
Sets the power-on state to the *RST state: OUTP:PON:STAT RST	

- If the power-on state is set to 0 with no state stored, a self-test error "file not found; 0 state" is generated and the instrument is set to the *RST state.

OUTPut:PROTection:CLEar

Resets the latched protection. This clears the latched protection status that disables the output when a protection condition occurs (see Programming Output Protection).

Parameter	Typical Return
(none)	(none)
Clears the latched protection status: OUTP:PROT:CLE	

- All conditions that generate the fault must be removed before the latched status can be cleared. The output is restored to the state it was in before the fault condition occurred.

- If a protection shutdown occurs during an output list, the list continues running even though the output is disabled. When the protection status is cleared and the output becomes enabled again, the output will be set to the values of the step that the list is presently at.

OUTPut:PROTection:TEMPerature:MARGin?

Returns the minimum difference between the internal temperature sensors and the over-temperature trip level. The margin is returned in degrees Celsius.

Parameter	Typical Return
(none)	<margin value>
Returns the temperature margin: OUTP:PROT:TEMP:MARG?	

OUTPut:PROTection:USER[:STATe] 0|OFF|1|ON
OUTPut:PROTection:USER[:STATe]?

Enables or disables the user-defined protection.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
Enables the user-defined protection: OUTP:PROT:USER ON	

OUTPut:PROTection:USER:SOURce EXPRession<1-8>|NONE
OUTPut:PROTection:USER:SOURce?

Sets the user-defined protection source to an expression. When an expression is specified, the output is disabled if the expression is true. See Programming Output Protection.

Parameter	Typical Return
EXPRession<1-8>|NONE, *RST NONE	EXPR<1-8>
Sets the user protect source to an expression: OUTP:PROT:USER:SOUR EXPR1	

OUTPut:PROTection:WDOG[:STATe] 0|OFF|1|ON
OUTPut:PROTection:WDOG[:STATe]?

Enables or disables the I/O watchdog timer. When enabled, the output will be disabled if there is no I/O activity on any remote interface within the time period specified by OUTput:PROTection:WDOG:DELay. The output is latched off but the programmed output state is not changed.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
Enables the watchdog timer protection: OUTP:PROT:WDOG ON	

OUTPut:PROTection:WDOG:DELay <*value*>|MIN|MAX
OUTPut:PROTection:WDOG:DELay? [MIN|MAX]

Sets the watchdog delay time. When the watchdog timer is enabled, the output is disabled if there is no SCPI I/O activity on any remote interface (USB, LAN, GPIB) within the delay time. The watchdog timer function is NOT reset by activity on the front panel - the output will still shut down after the time period has elapsed. Programmed values can range from 1 to 3600 seconds in 1 second increments.

Parameter	Typical Return
0 - 3600, *RST 60 seconds	<delay value>
Sets a watchdog delay for 600 seconds: OUTP:PROT:WDOG:DEL 600	

OUTPut:RELay:LOCK[:STATe]0|OFF|1|ON `N7900 models only`
OUTPut:RELay:LOCK[:STATe]?

Enables or disables the locked-closed state of the output relays. When locked, the output relays remain closed and do not change with the output state. This improves the output response time for applications that do not require a physical output disconnect. This parameter is saved in non-volatile memory.

Parameter	Typical Return
0|OFF|1|ON	0 or 1
Locks the output relays closed: OUTP:REL:LOCK ON	

OUTPut:RELay:POLarity NORMal|REVerse `N7900 models only`
OUTPut:RELay:POLarity?

Sets the polarity of the output relays. Polarity reversal affects both the output and the sense terminals. **Normal** causes the output polarity to be the same as the output connector labeling. **Reverse** causes the output polarity to be the reverse of the output connector labeling. This briefly turns the output off while the output and sense terminal polarities are switched.

Parameter	Typical Return
NORMal|REVerse, *RST NORMal	NORM or REV
Sets the output polarity to Reverse: OUTP:REL:POL REV	

OUTPut:RELay:POLarity:ENABle 0|OFF|1|ON `N7900 models only`
OUTPut:RELay:POLarity:ENABle?

Enables or disables the polarity reversal function. This prevents accidental output polarity reversal. This parameter is saved in non-volatile memory.

Parameter	Typical Return
0|OFF|1|ON	0 or 1
Disables the polarity reversal commands: OUTP:REL:POL:ENAB OFF	

POWer Query

[SOURce:]POWer:LIMit? [MIN|MAX]

Returns the output power limit of the instrument.

AC mains circuits rated at 100-120 VAC cannot supply enough current to power either the 1 kW or the 2 kW models when operated at their full rated output power. Use this query to return the maximum output power available when connected to 100-120 VAC mains. When the maximum available power limit is exceeded, the instrument turns off the output and sets the CP+ status bit.

Parameter	Typical Return
(none)	<power limit>
Query the power limit: POW:LIM?	

RESistance Subsystem

Resistance commands program the output resistance.

[SOURce:]RESistance[:LEVel][:IMMediate][:AMPLitude] *<value>*|MIN|MAX
[SOURce:]RESistance[:LEVel][:IMMediate][:AMPLitude]? [MIN|MAX]

Sets the output resistance level. Units are in ohms. Refer to Set the Output Resistance for the model-specific resistance programming ranges.

Parameter	Typical Return
0 to 6.4 Ω (model dependent)	MIN	MAX, *RST 0	0
Specifies an output resistance of 0.5 ohms: RES 0.5	

[SOURce:]RESistance:STATe 0|OFF|1|ON
[SOURce:]RESistance:STATe?

Enables or disables output resistance programming.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
Turns resistance programming on: RES:STAT ON	

SENSe Subsystem

Sense commands control the current measurement ranges and window as well as the data acquisition sequence.

SENSe	
:AHOur	
:RESet	Resets the amp-hour or watt-hour measurement to zero.
:BBR	
:PERiod *<value>*	Sets the recording period of the black box recorder in seconds.
:CURRent	
[:DC]	
:RANGe	
[:UPPer] *<value>*	Selects a DC current measurement range.
:AUTO 0|OFF|1|ON	Enables or disables seamless measurement auto ranging.
:ELOG	
:CURRent	
[:DC]	
:RANge	
[:UPPer] *<value>*	Selects the Elog current measurement range.
:AUTO 0|OFF|1|ON	Enables or disables Elog seamless measurement autoranging.
:FUNCtion	
:CURRent 0|OFF|1|ON	Enables/disables current data logging.
:MINMax 0|OFF|1|ON	Enables/disables min/max current data logging.
:VOLTage 0|OFF|1|ON	Enables/disables voltage data logging.
:MINMax 0|OFF|1|ON	Enables/disables min/max voltage data logging.
:PERiod *<value>*	Sets the integration time of an Elog measurement.
:FAULt	
:STATe 0|OFF|1|ON	Enables or disables remote sense fault detection.
:SWEep	
:NPLCycles *<value>*	Sets the measurement time in number of power line cycles.
:OFFSet	
:POINts *<value>*	Defines the offset in a data sweep for triggered measurements.
:POINts *<value>*	Defines the number of points in a measurement.
:TINTerval *<value>*	Defines the time period between measurement samples.
:THReshold<1|2|3|4>	
:AHOur	
[:LEVel] *<value>*	Sets the amp-hour level for comparator 1,2,3, or 4.
:CURRent	
[:LEVel] *<value>*	Sets the current level for comparator 1,2,3, or 4.
:FUNCtion VOLT|CURR|POW|AHO|WHO	Sets the sensing function for comparator 1,2,3, or 4.
:OPERation GT|LT	Sets the comparison type for comparator 1,2,3, or 4.
:POWer	

[:LEVel] *<value>*		Sets the power level for comparator 1,2,3, or 4.
:VOLTage		
[:LEVel] *<value>*		Sets the voltage level for comparator 1,2,3, or 4.
:WHOur		
[:LEVel] *<value>*		Sets the watt-hour level for comparator 1,2,3, or 4.
:WHOur		
:RESet		Resets the accumulated watt-hour measurement.
:WINDow		
[:TYPE] HANNing|RECTangular		Selects the measurement window.

SENSe:AHOur:RESet
SENSe:WHOur:RESet

Resets the amp-hour or watt-hour measurement to zero.

Parameter	Typical Return
(none)	(none)
Resets the amp-hour measurement: SENS:AHO:RES	

SENSe:BBR:PERiod *<value>*
SENSe:BBR:PERiod?

Sets the recording period of the black box recorder in seconds. This parameter is saved in non-volatile memory.

Parameter	Typical Return
0.01	0.1	<period>
Selects 0.01 seconds: SENS:BBR:PER 0.01	

SENSe:CURRent[:DC]:RANGe[:UPPer] *<value>*|MIN|MAX N7900 models only
SENSe:CURRent[:DC]:RANGe[:UPPer]? [MIN|MAX]

Selects a DC current measurement range. The value that you enter must be the highest value that you expect to measure. Units are in amperes. The instrument selects the range with the best resolution for the value entered.

Parameter	Typical Return
0 to maximum	<max current>
Selects the 2 A range: SENS:CURR:RANG 2	

- When queried, the returned value is the maximum DC current that can be measured on the range that is presently set.

SENSe:CURRent[:DC]:RANGe:AUTO 0|OFF|1|ON `N7900 models only`
SENSe:CURRent[:DC]:RANGe:AUTO?

Enables or disables seamless measurement auto ranging.

Parameter	Typical Return
0|OFF|1|ON, *RST ON	0 or 1
Enable current measurement autoranging: SENS:CURR:RANG:AUTO ON	

SENSe:ELOG:CURRent[:DC]:RANGe[:UPPer] <value>|MIN|MAX `N7900 models only`
SENSe:ELOG:CURRent[:DC]:RANGe[:UPPer]? [MIN|MAX]

Selects the Elog current measurement range. The value that you enter must be the highest value that you expect to measure. Units are in amperes. The instrument selects the range with the best resolution for the value entered.

Parameter	Typical Return
0 to maximum	<max current>
Selects the 1 A range: SENS:ELOG:CURR:RANG 1	

- When queried, the returned value is the maximum DC current that can be measured on the range that is presently set.

SENSe:ELOG:CURRent[:DC]:RANGe:AUTO 0|OFF|1|ON `N7900 models only`
SENSe:ELOG:CURRent[:DC]:RANGe:AUTO?

Enables or disables Elog seamless measurement autoranging.

Parameter	Typical Return
0|OFF|1|ON, *RST ON	0 or 1
Enable Elog current autoranging: SENS:ELOG:CURR:RANG:AUTO ON	

SENSe:ELOG:FUNCtion:CURRent 0|OFF|1|ON `N7900 models only`
SENSe:ELOG:FUNCtion:CURRent?

SENSe:ELOG:FUNCtion:VOLTage 0|OFF|1|ON `N7900 models only`
SENSe:ELOG:FUNCtion:VOLTage?

Enables or disables the Elog current or voltage measurement function.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1

Parameter	Typical Return
Enables datalog current measurements: SENS:ELOG:FUNC:CURR ON	

SENSe:ELOG:FUNCtion:CURRent:MINMax 0|OFF|1|ON (N7900 models only)
SENSe:ELOG:FUNCtion:CURRent:MINMax?

SENSe:ELOG:FUNCtion:VOLTage:MINMax 0|OFF|1|ON (N7900 models only)
SENSe:ELOG:FUNCtion:VOLTage:MINMax?

Enables or disables logging of the minimum and maximum current or voltage values.

Parameter	Typical Return
0|OFF|1|ON, *RST OFF	0 or 1
Enables MIN/MAX logging values: SENS:ELOG:FUNC:VOLT:MINM ON	

SENSe:ELOG:PERiod *<value>*|MIN|MAX (N7900 models only)
SENSe:ELOG:PERiod? [MIN|MAX]

Sets the integration time of an Elog measurement.

Although the absolute minimum logging period is 102.4 microseconds, the actual minimum varies as a function of the number of readings that are being logged (see Integration Period).

Parameter	Typical Return
0.0001024 to 60, *RST MAX	<period>
Specifies a datalog period of 0.01 seconds: SENS:ELOG:PER 0.01	

SENSe:FAULt:STATe 0|OFF|1|ON
SENSe:FAULt:STATe?

Enables or disables remote sense fault detection. This condition is annunciated by the SF status bit.

Parameter	Typical Return
0|OFF|1|ON, *RST ON	0 or 1
Disables remote sense fault detection: SENS:FAULt:STATe OFF	

SENSe:SWEep:NPLCycles *<value>*|MIN|MAX
SENSe:SWEep:NPLCycles? [MIN|MAX]

Sets the measurement time in number of power line cycles. Increasing the number of power line cycles reduces the measurement noise on current and voltage measurements. Changing the NPLC changes the number of points and time interval setting. The number of points in 1 NPLC depends on the line frequency (see SENSe:SWEep:POINts).

Parameter	Typical Return
0.0003072 to 1,258,290,000,000, *RST 1	<NPLC value>
Specifies 100 power line cycles: SENS:SWE:NPLC 100	

SENSe:SWEep:OFFSet:POINts *<value>*|MIN|MAX `N7900 models only`
SENSe:SWEep:OFFSet:POINts? [MIN|MAX]

Defines the offset in a data sweep for triggered measurements. Positive values represent the delay after the trigger occurs but before the samples are acquired. Negative values represent data samples taken prior to the trigger.

Parameter	Typical Return
−524,287 to 2,000,000,000, *RST 0	<offset points>
Specifies -2048 offset points: SENS:SWE:OFFS:POIN -2048	

SENSe:SWEep:POINts *<value>*|MIN|MAX `N7900 models only`
SENSe:SWEep:POINts? [MIN|MAX]

Defines the number of points in a measurement. The number of points depends on the line frequency (50 Hz or 60 Hz). The default number of points result in a measurement of 1 NPLC.

Parameter	Typical Return
1 to 524,288 MIN|MAX, *RST 3255 (60 Hz); 3906 (50 Hz)	<points>
Specifies 2048 points: SENS:SWE:POIN 2048	

SENSe:SWEep:TINTerval *<value>*|MIN|MAX `N7900 models only`
SENSe:SWEep:TINTerval? [MIN|MAX]

Defines the time period between measurement samples. Units are in seconds. Values are rounded to the nearest 20.48 microsecond increment. Below 20.48 microseconds, values are rounded to the nearest 10.24 or 5.12 microsecond increment respectively.

Parameter	Typical Return
0.00000512 to 40,000, *RST 0.00000512	<time interval>
Specifies an interval of 1 ms between points: SENS:SWE:TINT 0.001	

SENSe:THReshold<1|2|3|4>:FUNCtion AHOur|CURRent|POWer|VOLTage|WHOur
SENSe:THReshold<1|2|3|4>:FUNCtion?

Sets the sensing function for comparators THR1, THR2, THR3 or THR4.

AHOur selects the amp-hour function.

CURRent selects the current function.

POWer selects the power function.

VOLTage selects the voltage function.

WHOur selects the watt-hour function.

Parameter	Typical Return
AHOur|CURRent|POWer|VOLTage|WHOur, *RST VOLTage	AHO, CURR, POW, VOLT, or WHO
Selects the power function for comparator 1: SENS:THR1:FUNC POW	

SENSe:THReshold<1|2|3|4>:OPERation GT|LT
SENSe:THReshold<1|2|3|4>:OPERation?

Sets the operation type for comparator 1,2,3 or 4. **GT** (greater than) specifies that the signal will be true if the measurement is greater than the threshold level. **LT** (less than) specifies that the signal will be true if the measurements less than the threshold level.

Parameter	Typical Return
GT|LT, *RST GT	GT or LT
Selects the greater than operation for comparator 1: SENS:THR1:OPER GT	

SENSe:THReshold<1|2|3|4>:AHOur[:LEVel] <*value*>|MIN|MAX
SENSe:THReshold<1|2|3|4>:AHOur[:LEVel]? [MIN|MAX]
SENSe:THReshold<1|2|3|4>:CURRent[:LEVel] <*value*>|MIN|MAX
SENSe:THReshold<1|2|3|4>:CURRent[:LEVel]? [MIN|MAX]
SENSe:THReshold<1|2|3|4>:POWer[:LEVel] <*value*>|MIN|MAX
SENSe:THReshold<1|2|3|4>:POWer[:LEVel]? [MIN|MAX]
SENSe:THReshold<1|2|3|4>:VOLTage[:LEVel] <*value*>|MIN|MAX
SENSe:THReshold<1|2|3|4>:VOLTage[:LEVel]? [MIN|MAX]
SENSe:THReshold<1|2|3|4>:WHOur[:LEVel] <*value*>|MIN|MAX
SENSe:THReshold<1|2|3|4>:WHOur[:LEVel]? [MIN|MAX]

These commands select the threshold level for comparators 1,2,3 or 4. This becomes the qualifying measurement threshold for generating a true signal.

AHOur selects the amp-hour level in hours.

CURRent selects the current level in amperes.

POWer selects the power level in Watts.

VOLTage selects the voltage level in volts.

WHOur selects the watt-hour threshold level in hours.

Parameter	Typical Return
0 to maximum, *RST 0	<level value>
Selects a 1 watt-hour threshold for comparator 1: SENS:THR1:WHO 1	

SENSe:WINDow[:TYPE] HANNing|RECTangular N7900 models only
SENSe:WINDow[:TYPE]?

Selects the measurement window. This sets a signal conditioning function used in scalar DC measurement calculations. Neither window function alters the instantaneous voltage or current data returned in the measurement array.

Hanning window is a "raised cosine" function. It is a signal conditioning function that reduces errors in DC measurement calculations in the presence of periodic signals such as AC line ripple. This window only works up to 4883 measurement points. The instrument will revert to a rectangular window when the points exceed 4883.

Rectangular window returns measurement calculations with no signal conditioning.

Parameter	Typical Return
HANNing|RECTangular, *RST RECTangular	RECT or HANN
Specifies a Hanning window function: SENS:WIND HANN	

[SOURce] Subsystem

The SOURce keyword is optional in many commands that set parameters for a source or output, such as [SOURce:] CURRent <value>.

Because SOURce subsystem commands are often used without the optional SOURce keyword, these commands are listed by their individual subsystems, below:

Subsystems and Commands Using the Optional [SOURce:] Keyword

ARB

CURRent

DIGital

FUNCtion

LIST

POWer:LIMit?

RESistance

STEP:TOUTput

VOLTage

STATus Subsystem

Status register programming lets you determine the operating condition of the instrument at any time. The instrument has three groups of status registers; Operation, Questionable, and Standard Event. The Operation and Questionable status groups each consist of the Condition, Enable, and Event registers as well as NTR and PTR filters.

The Status subsystem is also programmed using Common commands. Common commands control additional status functions such as the Service Request Enable and the Status Byte registers. Refer to Status Tutorial for more information.

STATus	
:OPERation	
[:EVENt]?	Queries the operation event register.
:CONDition?	Queries the operation condition register.
:ENABle <*value*>	Sets the operation enable register.
:NTRansiton <*value*>	Sets the Negative transition filter
:PTRansiton <*value*>	Sets the Positive transition filter
:USER<1|2>	
:SOURce EXPRession<1-8>|NONE	Selects an expression to drive the user-defined status bits.
:PRESet	Presets all Enable, PTR, and NTR registers.
:QUEStionable<1|2>	
[:EVENt]?	Queries the questionable event register.
:CONDition?	Queries the questionable condition register.
:ENABle <*value*>	Sets the questionable enable register.
:NTRansiton <*value*>	Sets the Negative transition filter
:PTRansiton <*value*>	Sets the Positive transition filter

STATus:OPERation[:EVENt]

Queries the event register for the Operation Status group. This is a read-only register, which stores (latches) all events that are passed by the Operation NTR and/or PTR filter. Reading the Operation Status Event register clears it.

Parameter	Typical Return
(none)	<bit value>
Read the operation status event register: STAT:OPER?	

- The value returned is the binary-weighted sum of all bits set in the register. For example, with bit 3 (value 8) and bit 5 (value 32) set (and corresponding bits enabled), the query returns +40.

- *RST has no effect on this register.

STATus:OPERation:CONDition?

Queries the condition register for the Operation Status group. This is a read-only register, which holds the live (unlatched) operational status of the instrument. Reading the Operation Status Condition register does not clear it.

Parameter	Typical Return
(none)	<bit value>
Read the operation status condition register: STAT:OPER:COND?	

- The value returned is the binary-weighted sum of all bits set in the register. For example, with bit 3 (value 8) and bit 5 (value 32) set (and corresponding bits enabled), the query returns +40.

- The condition register bits reflect the current condition. If a condition goes away, the corresponding bit is cleared.

- *RST clears this register, other than those bits where the condition still exists after *RST.

STATus:OPERation:ENABle *<value>*
STATus:OPERation:ENABle?

Sets the value of the enable register for the Operation Status group. The enable register is a mask for enabling specific bits from the Operation Event register to set the OPER (operation summary) bit of the Status Byte register. STATus:PRESet clears all bits in the enable register.

Parameter	Typical Return
A decimal value corresponding to the binary-weighted sum of the register's bits.	<bit value>
Enable bit 3 and 4 in the enable register: STAT:OPER:ENAB 24	

- For example, with bit 3 (value 8) and bit 5 (value 32) set (and corresponding bits enabled), the query returns +40.

- *CLS does not clear the enable register, but does clear the event register.

STATus:OPERation:NTRansition *<value>*
STATus:OPERation:NTRansition?
STATus:OPERation:PTRansition *<value>*
STATus:OPERation:PTRansition?

Sets and queries the value of the NTR (Negative-Transition) and PTR (Positive-Transition) registers. These registers serve as a polarity filter between the Operation Condition and Operation Event registers.

When a bit in the NTR register is set to 1, then a 1-to-0 transition of the corresponding bit in the Operation Condition register causes that bit in the Operation Event register to be set.

When a bit in the PTR register is set to 1, then a 0-to-1 transition of the corresponding bit in the Operation Condition register causes that bit in the Operation Event register to be set.

STATus:PRESet sets all bits in the NTR and PTR registers to 0.

Parameter	Typical Return
A decimal value corresponding to the binary-weighted sum of the register's bits.	<bit value>

Parameter	Typical Return
Enable bit 3 and 4 in the NTR register: STAT:OPER:NTR 24	
Enable bit 3 and 4 in the PTR register: STAT:OPER:PTR 24	

- If the same bits in both NTR and PTR registers are set to 1, then any transition of that bit at the Operation Condition register sets the corresponding bit in the Operation Event register.

- If the same bits in both NTR and PTR registers are set to 0, then no transition of that bit at the Operation Condition register can set the corresponding bit in the Operation Event register.

- The value returned is the binary-weighted sum of all bits set in the register.

STATus:OPERation:USER<1|2>:SOURce EXPRession<1-8>|NONE
STATus:OPERation:USER<1|2>:SOURce?

Maps the specified expression to one of the two user-defined Operation Status bits (USER1 or USER2). When the specified expression is true, the selected user status bit will be set.

Parameter	Typical Return
EXPRession<1-8>|NONE *RST NONE	EXPR<1-8>
Maps a user-defined status bit to an expression: STAT:OPER:USER1:SOUR EXPR1	

STATus:PRESet

Presets all Enable, PTR, and NTR registers.

Operation register	Questionable register	Preset setting
STAT:OPER:ENAB	STAT:QUES:ENAB	all defined bits are disabled
STAT:OPER:NTR	STAT:QUES:NTR	all defined bits are disabled
STAT:OPER:PTR		all defined bits are enabled
	STAT:QUES1:PTR	all defined bits are enabled
	STAT:QUES2:PTR	all defined bits are enabled

Parameter	Typical Return
(none)	(none)
Preset the Operation and Questionable registers: STAT:PRES	

STATus:QUEStionable<1|2>[:EVENt]?

Queries the event register for the Questionable Status group. This is a read-only register, which stores (latches) all events that are passed by the Operation NTR and/or PTR filter. Reading the Questionable Status Event register clears it.

Parameter	Typical Return
(none)	<bit value>
Read questionable status event register #1: STAT:QUES1?	

- The value returned is the binary-weighted sum of all bits set in the register. For example, to enable bit 2 (decimal value = 4), bit 4 (decimal value = 16), the corresponding decimal value would be 20 (4 + 16).
- *RST has no effect on this register.

STATus:QUEStionable<1|2>:CONDition?

Queries the condition register for the Questionable Status group. This is a read-only register, which holds the live (unlatched) operational status of the instrument. Reading the Questionable Status Condition register does not clear it.

Parameter	Typical Return
(none)	<bit value>
Read questionable status condition register #1: STAT:QUES1:COND?	

- The value returned is the binary-weighted sum of all bits set in the register. For example, to enable bit 2 (decimal value = 4), bit 4 (decimal value = 16), the corresponding decimal value would be 20 (4 + 16).
- The condition register bits reflect the current condition. If a condition goes away, the corresponding bit is cleared.
- *RST clears this register, other than those bits where the condition still exists after *RST.

STATus:QUEStionable<1|2>:ENABle *<value>*
STATus:QUEStionable<1|2>:ENABle?

Sets the value of the enable register for the Questionable Status group. The enable register is a mask for enabling specific bits from the Operation Event register to set the OPER (operation summary) bit of the Status Byte register. STATus:PRESet clears all bits in the enable register.

Parameter	Typical Return
A decimal value corresponding to the binary-weighted sum of the register's bits.	<bit value>
Enable bit 2 and 4 in the questionable enable register #1: STAT:QUES1:ENAB 24	

- For example, to enable bit 2 (decimal value = 4), bit 4 (decimal value = 16), the corresponding decimal value would be 20 (4 + 16).
- *CLS does not clear the enable register, but does clear the event register.

STATus:QUEStionable<1|2>:NTRansition *<value>*
STATus:QUEStionable<1|2>:NTRansition?
STATus:QUEStionable<1|2>:PTRansition *<value>*
STATus:QUEStionable<1|2>:PTRansition?

Sets and queries the value of the NTR (Negative-Transition) and PTR (Positive-Transition) registers. These registers serve as a polarity filter between the Questionable Condition and Questionable Event registers.

When a bit in the NTR register is set to 1, then a 1-to-0 transition of the corresponding bit in the Questionable Condition register causes that bit in the Questionable Event register to be set.

When a bit in the PTR register is set to 1, then a 0-to-1 transition of the corresponding bit in the Questionable Condition register causes that bit in the Questionable Event register to be set.

STATus:PRESet sets all bits in the NTR and PTR registers to 0.

Parameter	Typical Return
A decimal value corresponding to the binary-weighted sum of the register's bits.	<bit value>
Enable bit 3 and 4 in the questionable NTR register #1: STAT:QUES:NTR 24 Enable bit 3 and 4 in the questionable PTR register #1: STAT:QUES:PTR 24	

- If the same bits in both NTR and PTR registers are set to 1, then any transition of that bit at the Questionable Condition register sets the corresponding bit in the Questionable Event register.

- If the same bits in both NTR and PTR registers are set to 0, then no transition of that bit at the Questionable Condition register can set the corresponding bit in the Questionable Event register.

- The value returned is the binary-weighted sum of all bits set in the register.

STEP Command

[SOURce:]STEP:TOUTput 0|OFF|1|ON
[SOURce:]STEP:TOUTput?

Specifies whether a trigger out is generated when a transient step occurs. A trigger is generated when the state is on (true).

Parameter	Typical Return
0|OFF|1|ON , *RST OFF	0 or 1
Sets the step trigger signal to ON: STEP:TOUT ON	

SYSTem Subsystem

System commands control system functions that are not directly related to output control, measurement, or status functions. Note that IEEE-488 Common commands also control system functions such as self-test, saving and recalling states, and others.

SYSTem	
:BBR	
:EVENt <*"string"*>	Adds an event string into the BBR event log.
:SNAPshot <value>	Captures a data snapshot of the specified length.
:STATus?	Returns the completion status of the snapshot in percent.
:STATe?	Returns true (1) if the Black Box Recorder is logging.
:TIME?	Returns the length of the Black Box Recorder data.
:COMMunicate	
:LAN|TCPip:CONTrol?	Returns the initial socket control connection port number.
:RLSTate LOCal|REMote|RWLock	Configures the remote/local state of the instrument.
:DATE <yyyy>,<mm>,<dd>	Sets the date of the system clock.
:ERRor?	Reads and clears one error from the error queue.
:LFRequency?	Returns the power-line reference frequency.
:LFRequency	
:MODE AUTO|MAN50|MAN60	Specifies automatic or manual line frequency detection.
:PASSword	
:FPANel	
:RESet	Resets the front panel lockout password to zero.
:REBoot	Reboots the instrument to its power-on state.
:SECurity	
:IMMediate	Clears all user memory and reboots the instrument.
:SIGNal	
:DEFine EXPRession<1-8>,<*"expression"*>	Defines up to eight signal expressions.
:TEMPerature	
:AMBient?	Returns the temperature at the air inlet.
:TIME <hh>,<mm>,<ss>	Sets the time of the system clock.
:VERSion?	Returns the SCPI version that the instrument complies with.

SYSTem:BBR:EVENt <*"string"*>

Adds an event string into the BBR event log. The BBR event log has room for 100,000 events. The maximum length of the event string is 53 characters.

Parameter	Typical Return
<*"string"*>String program data. Enclose string parameters in single or double quotes.	(none)

Parameter	Typical Return
Enter a message into the BBR data: SYST:BBR:EVEN "Starting BBR data"	

SYSTem:BBR:SNAPshot <time>

Captures a data snapshot of the specified length. The length is specified in seconds. The snapshot captures the most recent data going back from the time the snapshot command is received. The data is stored in an internal file where it can be retrieved with the software application. Subsequent snapshot commands will overwrite the existing snapshot file.

Parameter	Typical Return
1 - 86,400 (with 10 ms period) 1 - 864,000 (with 100 ms period)	(none)
Captures two hours of most recent snapshot data: SYST:BBR:SNAP 7200	

SYSTem:BBR:SNAPshot:STATus?

Returns the completion status of the snapshot in percent. The snapshot is finished when 100 is returned.

Parameter	Typical Return
(none)	<% complete>
Query the BBR snapshot completion: SYST:BBR:SNAP:STAT?	

SYSTem:BBR:STATe?

Returns true (1) if the Black Box Recorder is logging. Note that the BBR is momentarily stopped when the BBR period is changed, or when the system time is changed.

Parameter	Typical Return
(none)	0 or 1
Query the BBR state: SYST:BBR:STAT?	

SYSTem:BBR:TIME?

Returns the length of the Black Box Recorder data. The value is returned in seconds.

Parameter	Typical Return
(none)	<length>
Query the BBR time: SYST:BBR:TIME?	

SYSTem:COMMunicate:LAN:CONTrol?
SYSTem:COMMunicate:TCPip:CONTrol?

Returns the initial socket control connection port number. This connection is used to send and receive commands and queries. Unlike the data socket, which uses a fixed port number, the control socket port number varies and must be obtained using these queries.

Parameter	Typical Return
(none)	<port #> (0 if sockets not supported)
Query the Control connection port number: SYST:COMM:LAN:CONT? or SYST:COMM:TCP:CONT?	

SYSTem:COMMunicate:RLSTate LOCal|REMote|RWLock
SYSTem :COMMunicate:RLSTate?

Configures the remote/local state of the instrument. Remote and local do the same thing and are included for compatibility with other products. **LOCal** sets instrument to front panel control. **REMote** sets the instrument to front panel control. **RWLock** disables the front panel keys. The instrument can only be controlled via the remote interface. This programmable setting is completely independent from the front panel lock/unlock function.

Parameter	Typical Return
LOCal|REMote|RWLock , *RST LOCal	LOC, REM, or RWL
Sets the remote/local state to remote: SYST:COMM:RLST REM	

- The remote/local state is unaffected by *RST or any SCPI commands other than SYSTem:COMMunicate:RLState.

- The remote/local instrument state can also be set by other interface commands over the GPIB and some other I/O interface.

- When multiple remote programming interfaces are active, the interface with the most recently changed remote/local state determines the instrument's remote/local state.

SYSTem:DATE <yyyy>,<mm>,<dd>
SYSTem:DATE?

Sets the date of the system clock. Specify the year, month, and day.

Note that setting the date causes the optional BBR logging function to stop and then start using the new date.

Parameter	Typical Return
<yyyy,<mm>,<dd>	<date>
Sets the date (January 31, 2012): SYST:DATE 2012,01,31	

SYSTem:ERRor?

Reads and clears one error from the error queue.

Parameter	Typical Return
(none)	<+0,"No error">
Reads and clear first error in error queue: SYST:ERR?	

- The front-panel ERR annunciator turns on when one or more errors are currently stored in the error queue. Error retrieval is first-in-first-out (FIFO), and errors are cleared as you read them. When you have read all errors from the error queue, the ERR annunciator turns off.

- If more than 20 errors have occurred, the last error stored in the queue (the most recent error) is replaced with -350,"Error queue overflow". No additional errors are stored until you remove errors from the queue. If no errors have occurred when you read the error queue, the instrument responds with +0,"No error".

- The error queue is cleared by the *CLS and when power is cycled. It is not cleared by a *RST.

- Errors have the following format (the error string may contain up to 255 characters).
  <error code>,<error string>
  For a list of error codes and message strings, see SCPI Error Messages.

SYSTem:LFRequency?

Returns the power-line reference frequency. This determines the integration time used by SENSe:SWEep:NPLC command.

At power-on, if the line frequency mode is set to Auto, the power supply automatically detects the power-line frequency (50 Hz, 60 Hz, or 400 Hz) and uses this value to determine the integration time used. If the detected power line frequency is 400 Hz, the 50 Hz reference value is actually used (a subharmonic of 400 Hz).

If the auto line detect fails because the line is noisy or out of tolerance, it uses a setting of 60 Hz.

Parameter	Typical Return
(none)	50, 60, or 400
Query the power line frequency: SYST:LFR?	

SYSTem:LFRequency:MODE AUTO|MAN50|MAN60
SYSTem:LFRequency:MODE?

Specifies automatic or manual line frequency detection. **AUTO** specifies automatic detection. **MAN50** specifies a setting of 50 Hz. **MAN60** specifies a setting of 60 Hz. This parameter is saved in non-volatile memory.

Parameter	Typical Return
AUTO|MAN50|MAN60	AUTO, MAN50, or MAN60
Sets the line frequency mode to 60 Hz: SYST:LFR:MODE MAN60	

SYSTem:PASSword:FPANel:RESet

Resets the front panel lockout password to zero. This command does not reset the calibration password.

Parameter	Typical Return
(none)	(none)
Resets the front panel password: SYST:PASS:FPAN:RES	

SYSTem:REBoot

Reboots the instrument to its power-on state.

Parameter	Typical Return
(none)	(none)
Reboots the instrument: SYST:REB	

SYSTem:SECurity:IMMediate

Clears all user memory and reboots the instrument. This command is typically used to prepare the instrument for removal from a secure area. It sanitizes all user data except for black box recorder files. It writes all zeros to flash memory and then performs a chip erase as per manufacturer's data sheet. If the BBR option is installed, the drive must be removed and destroyed to sanitize the BBR data. Identification data (instrument firmware, model number, serial number, MAC address and calibration data) is not erased. After the data is cleared, the instrument is rebooted.

This procedure is not recommended for use in routine applications because of the possibility of unintended loss of data.

Parameter	Typical Return
(none)	(none)
Sanitizes the instrument: SYST:SEC:IMM	

SYSTem:SIGNal:DEFine EXPRession<1-8>, <"expression">
SYSTem:SIGNal:DEFine? EXPRession <1-8>

Defines up to eight signal expressions. Refer to Define Signal Expressions for a complete list of signal sources and operators that are used to "build" each signal expression.

Parameter	Typical Return
EXPRession <1-8>	(none)
<"expression">	<"expression">
Defines the first expression to be true whenever the output state is on: SYST:SIGN:DEF: EXPR1, "OutpOn"	

Expressions must be enclosed in quotes ("") inside SCPI commands. Expressions are case-insensitive. You can enter alpha characters as all caps , all lowercase, or mixed case. Spaces must be included on either side of the Boolean operators And, Or , and Not. Spaces are not required around parentheses.

SYSTem:TEMPerature:AMBient?

Returns the temperature at the air inlet. Values are returned in degrees C.

Parameter	Typical Return
(none)	<"ambient temp">
Return the ambient air temperature: SYST:TEMP?	

SYSTem:TIME <hh>,<mm>,<ss>
SYSTem:TIME?

Sets the time of the system clock. Specify hours (0 to 23), minutes (0 to 59), and seconds (0 to 59).

Parameter	Typical Return
<hh>,<mm>,<ss>	<hh,mm,ss>
Set the clock to 8:30 PM: SYST:TIME 20,30,0	

- Note that setting the time causes the optional BBR logging function to stop and restart using the new time.

SYSTem:VERSion?

Returns the SCPI version that the instrument complies with. Cannot be determined from front panel.

Parameter	Typical Return
(none)	<"version">
Return the SCPI version: SYST:VERS?	

- The command returns a string in the form "YYYY.V", where YYYY represents the year of the version and V represents a version for that year.

TRIGger Subsystem

Trigger commands control the transient and acquisition subsystems. Refer to Trigger Overview for more information.

TRIGger

  :ACQuire

    [:IMMediate]   Generates an immediate trigger.

    :CURRent

      [:LEVel]   *<value>*   Sets the triggered level of the output.

      :SLOPe POSitive|NEGative   Sets the slope of the signal.

    :INDices

      [:DATA]?   Returns the indices where triggers were captured.

      :COUNt?   Returns the number of triggers captured during the acquisition.

    :SOURce *<source>*   Selects the trigger source for the acquisition system: BUS |CURRent1 |EXTernal |EXPRession<1-8> |PIN<1-7> |TRANsient1 |VOLTage1

    :TOUTput

      [:ENABle] 0|OFF|1|ON   Enables measurement triggers to be sent to a digital port pin.

    :VOLTage

      [:LEVel] *<value>*   Sets the triggered level of the output.

      :SLOPe POSitive|NEGative   Sets the slope of the signal.

  :ARB

    :SOURce *<source>*   Selects the trigger source for arbitrary waveforms: BUS |EXTernal |IMMediate |EXPRession<1-8> |PIN<1-7>

  :ELOG

    [:IMMediate]   Generates an immediate trigger.

    :SOURce *<source>*   Selects the trigger source for external data logging: BUS |EXTernal |IMMediate| PIN<1-7>

  :TRANsient

    [:IMMediate]   Generates an immediate trigger.

    :SOURce *<source>*   Selects the trigger source for the transient system: BUS |EXTernal |IMMediate |EXPRession<1-8> |PIN<1-7>

TRIGger:ACQuire[:IMMediate]

TRIGger:ELOG[:IMMediate] N7900 models only
TRIGger:TRANsient[:IMMediate]

Generates an immediate trigger. This overrides any selected trigger source.

TRIGger:ACQuire triggers the acquisition system.

TRIGger:ELOG triggers the external datalogger.

TRIGger:TRANsient triggers the transient system.

Parameter	Typical Return
(none)	(none)
Generate a measurement trigger: TRIG:ACQ	

TRIGger:ACQuire:CURRent[:LEVel] *<value>*|MIN|MAX
TRIGger:ACQuire:CURRent[:LEVel]? [MIN|MAX]
TRIGger:ACQuire:VOLTage[:LEVel] *<value>*|MIN|MAX
TRIGger:ACQuire:VOLTage[:LEVel]? [MIN|MAX]

Sets the triggered level of the output. Applies when the measurement trigger source is set to a level. Values are specified in either amperes or volts. The minimum and maximum values depend on the ratings of the unit.

Parameter	Typical Return
Voltage: 0 to 102% of rating, *RST 0 Current: -10.2% to 102% of rating, *RST 0 Current with power dissipator: up to -102% to 102% of rating	<level value>
Set the triggered current level to 3 A: TRIG:ACQ:CURR 3 Set the triggered voltage level to 50 V: TRIG:ACQ:VOLT 50	

TRIGger:ACQuire:CURRent:SLOPe POSitive|NEGative
TRIGger:ACQuire:CURRent:SLOPe?
TRIGger:ACQuire:VOLTage:SLOPe POSitive|NEGative
TRIGger:ACQuire:VOLTage:SLOPe?

Sets the slope of the signal. Applies when the measurement trigger source is set to a level. **POSitive** specifies a rising slope of the output signal. **NEGative** specifies a falling slope of the output signal.

Parameter	Typical Return
POSitive|NEGative, *RST POSitive	POS or NEG
Set current slope to negative (falling edge): TRIG:ACQ:CURR:SLOP NEG Set voltage slope to negative (falling edge): TRIG:ACQ:VOLT:SLOP NEG	

TRIGger:ACQuire:INDices[:DATA]? N7900 models only

Returns the indices into the acquired data where triggers were captured during the acquisition. The number of indices returned is the same as the value returned by TRIGger:ACQuire:INDices:COUNt?

Parameter	Typical Return
(none)	<time>

Parameter	Typical Return
Returns the number of indices: TRIG:ACQ:IND?	

TRIGger:ACQuire:INDices:COUNt? N7900 models only

Returns the number of triggers captured during the acquisition.

Parameter	Typical Return
(none)	<time>
Return the number of triggers: TRIG:ACQ:IND:COUN?	

TRIGger:ACQuire:TOUTput[:ENABle] 0|OFF|1|ON
TRIGger:ACQuire:TOUTput[:ENABle]?

Enables measurement triggers to be sent to a digital port pin. The digital port pin must be configured as trigger output before it can be used as a trigger source (see External Trigger I/O).

Parameter	Typical Return
0|OFF|1|ON , *RST OFF	0 or 1
Enable sending measurement triggers to digital pins: TRIG:ACQ:TOUT ON	

TRIGger:ACQuire:SOURce <source>
TRIGger:ACQuire:SOURce?

Selects the trigger source for the acquisition system:

BUS	Selects a remote interface trigger command.
CURRent1	Selects an output current level.
EXTernal	Selects ALL digital port pins that have been configured as trigger sources.
EXPRession <1-8>	Selects a user-defined expression as the trigger source.
PIN<1-7>	Selects a digital port pin configured as a trigger input.
TRANsient1	Selects the transient system as the trigger source.
VOLTage1	Selects an output voltage level.

Parameter	Typical Return
BUS|CURRent1	EXTernal	EXPRession<1-8>	PIN<1-7>	TRANsient1	VOLTage1, *RST BUS	BUS, CURR1, EXT, EXPR<n>, PIN<n>, TRAN1, or VOLT1
Select digital port pin 1 as the measurement trigger source: TRIG:ACQ:SOUR PIN1	

TRIGger:ARB:SOURce *<source>* N7900 models only
TRIGger:ARB:SOURce?

Selects the trigger source for arbitrary waveforms:

BUS	Selects a remote interface trigger command.
EXTernal	Selects ALL digital port pins that have been configured as trigger sources.
EXPRession <1-8>	Selects a user-defined expression as the trigger source.
IMMediate	Triggers the transient as soon as it is INITiated.
PIN<1-7>	Selects a digital port pin configured as a trigger input.

Parameter	Typical Return
BUS | EXTernal | IMMediate | EXPRession<1-8>| PIN<1-7> *RST BUS	BUS, EXT, IMM, EXPR<n>, PIN<n>
Select digital port pin 1 as the Arb trigger source: TRIG:ARB:SOUR PIN1	

TRIGger:ELOG:SOURce *<source>* N7900 models only
TRIGger:ELOG:SOURce?

Selects the trigger source for external data logging:

BUS	Selects a remote interface trigger command.
EXTernal	Selects ALL digital port pins that have been configured as trigger sources.
IMMediate	Triggers the transient as soon as it is INITiated.
PIN<1-7>	Selects a digital port pin configured as a trigger input.

Parameter	Typical Return
BUS | EXTernal | IMMediate | PIN<1-7> *RST BUS	BUS, EXT, IMM, PIN<n>
Select digital port pin 1 as the Elog trigger source: TRIG:ELOG:SOUR PIN1	

TRIGger:TRANsient:SOURce *<source>*
TRIGger:TRANsient:SOURce?

Selects the trigger source for the transient system:

BUS	Selects a remote interface trigger command.
EXTernal	Selects ALL digital port pins that have been configured as trigger sources.
EXPRession <1-8>	Selects a user-defined expression as the trigger source.
IMMediate	Triggers the transient as soon as it is INITiated.
PIN<1-7>	Selects a digital port pin configured as a trigger input.

Parameter	Typical Return
BUS | EXTernal | IMMediate | EXPRession<1-8>| PIN<1-7>, *RST BUS	BUS, EXT, IMM, EXPR<n>, PIN<n>
Select digital port pin 1 as the transient trigger source: TRIG:TRAN:SOUR PIN1	

VOLTage Subsystem

Voltage commands program the output voltage of the instrument.

[SOURce:]
   VOLTage
      [:LEVel]
         [:IMMediate]
            [:AMPLitude] *<value>*   Sets the output voltage when in voltage priority mode.
         :TRIGgered
            [:AMPLitude] *<value>*   Sets the triggered output voltage.
      :BWIDth LOW|HIGH1   Sets the voltage bandwidth.
      :LIMit
         [:POSitive]
            [:IMMediate]
               [:AMPLitude] *<value>*   Sets the voltage limit when in current priority mode.
      :MODE FIXed|STEP|LIST|ARB   Sets the transient mode.
      :PROTection
         [:LEVel] *<value>*   Sets the over-voltage protection level.
      :SLEW
         [:IMMediate] *<value>*|INFinity Sets the voltage slew rate.
         :MAXimum 0|OFF|1|ON   Enables or disables the maximum slew rate override.

[SOURce:]VOLTage[:LEVel][:IMMediate][:AMPLitude] *<value>*|MIN|MAX
[SOURce:]VOLTage[:LEVel][:IMMediate][:AMPLitude]? [MIN|MAX]
[SOURce:]VOLTage[:LEVel]:TRIGgered[:AMPLitude] *<value>*|MIN|MAX
[SOURce:]VOLTage[:LEVel]:TRIGgered[:AMPLitude]? [MIN|MAX]

Sets the immediate or triggered voltage level when the output is operating in voltage priority mode. The triggered level is the value that is transferred to the output when an output Step is triggered. Units are in volts. The maximum value depends on the voltage rating of the unit.

Parameter	Typical Return
0.1% to 102% of rating, *RST 0.1% of rating	<voltage level>
Sets the output voltage to 20 V: VOLT 20 Sets the triggered voltage to 10 V: VOLT:TRIG 10	

[SOURce:]VOLTage:BWIDth LOW|HIGH1
[SOURce:]VOLTage:BWIDth?

Sets the voltage bandwidth. This lets you optimize output response time with capacitive loads.

These compensation modes only apply when the unit is operating in voltage priority mode. **HIGH1** provides maximum up-programming speed as well as the fastest transient response time when the output capacitance is restricted to small values. **LOW** is optimized for stability with a wide range of output capacitors. Refer to Set the Output Bandwidth for specific capacitive load limits.

Parameter	Typical Return
LOW|HIGH1, *RST HIGH1	HIGH1 or LOW
Sets the voltage bandwidth to Low: VOLT:BWID LOW	

[SOURce:]VOLTage:LIMit[:POSitive][:IMMediate][:AMPLitude] *<value>*|MIN|MAX
[SOURce:]VOLTage:LIMit[:POSitive][:IMMediate][:AMPLitude]? [MIN|MAX]

Sets the voltage limit when in current priority mode. Units are in volts.

Parameter	Typical Return
0.1% to 102% of rating, *RST 1% of rating	<voltage limit>
Sets the voltage limit to 20 V: VOLT:LIM 20	

[SOURce:]VOLTage:MODE FIXed|STEP|LIST|ARB
[SOURce:]VOLTage:MODE?

Sets the transient mode. This determines what happens to the output voltage when the transient system is initiated and triggered.

FIXed keeps the output voltage at its immediate value.

STEP steps the output to the triggered level when a trigger occurs.

LIST causes the output to follow the list values when a trigger occurs.

ARB causes the output to follow the arbitrary waveform values when a trigger occurs.

Parameter	Typical Return
FIXed|STEP|LIST|ARB, *RST FIXed	FIX, STEP, LIST, or ARB
Sets the voltage mode to Step: VOLT:MODE STEP	

[SOURce:]VOLTage:PROTection[:LEVel] *<value>*|MIN|MAX
[SOURce:]VOLTage:PROTection[:LEVel]? [MIN|MAX]

Sets the over-voltage protection level. Units are in volts. If the output voltage exceeds the OVP level, the output is disabled and the Questionable Condition status register OV bit is set.

Parameter	Typical Return
0 to 120% of rating,	<protect level>

Parameter	Typical Return
*RST 120% of rating	
Sets the over-voltage protection to 24 V: `VOLT:PROT 24`	

- An over-voltage condition can be cleared with the OUTput:PROTection:CLEar command after the cause of the condition has been removed.

[SOURce:]VOLTage:SLEW[:IMMediate] *<value>*|MIN|MAX|INFinity
[SOURce:]VOLTage:SLEW[:IMMediate]? [MIN|MAX]

Sets the voltage slew rate. The slew rate is set in volts per second and affects all programmed voltage changes, including those due to the output state turning on or off. The slew rate can be set to any value between 0 and 9.9E+37. For very large values, the slew rate will be limited by the analog performance of the output circuit. The keywords MAX or INFinity set the slew rate to maximum.

Parameter	Typical Return
0 – 9.9E+37, *RST MAX	<max value>
Sets the output slew rate to 5 V per second: `VOLT:SLEW 5`	

- The query returns the value that was sent, unless the value is less than the minimum slew rate, in which case the minimum value is returned. The resolution of the slew setting is also the minimum value, which can be queried using VOLTage:SLEW? MIN. The exact value varies slightly according to calibration.

[SOURce:]VOLTage:SLEW:MAXimum 0|OFF|1|ON
[SOURce:]VOLTage:SLEW:MAXimum?

Enables or disables the maximum slew rate override. When enabled, the slew rate is set to its maximum value. When disabled, the slew rate is set to the immediate value set by the [SOURce:]VOLTage:SLEW command. Use [SOURce:]VOLTage:SLEW? MAX to query the maximum slew rate that was set.

Parameter	Typical Return
0|OFF|1|ON, *RST ON	0 or 1
Enable the maximum slew rate override: `VOLT:SLEW:MAX ON`	

- The [SOURce:]VOLTage:SLEW:MAX command is coupled to the [SOURce:]VOLTage:SLEW command. If [SOURce:]VOLTage:SLEW sets the rate to MAX or INFinity, [SOURce:]VOLTage:SLEW:MAX is enabled. If the slew rate is set to any other value, [SOURce:]VOLTage:SLEW:MAX is disabled.

Status Tutorial

This section provides a detailed description of the individual registers and register groups. The status diagram provides an graphical view of how the status registers and groups are interconnected.

Status Registers

Operation Status Group

Questionable Status Group

Standard Event Status Group

Status Byte Register

Error and Output Queues

Status Diagram

Status Registers

The Operation and Questionable status groups use four different types of registers to track qualify, flag, and enable instrument events. The Standard Event group only uses Event and Enable registers.

- A Condition register continuously monitors the state of the instrument. The bits in the condition register are updated in real time and the bits are not latched.

- An PTR/NTR register qualifies the signal that passes to the event register. When a PTR bit is set, signals with positive edge transition pass to the event register. When an NTR bit is set, signals with a negative edge transition pass to the event register. When both bits are set, all signal pass. When neither bits are set, no signals pass.

- An Event register latches transitions that pass through the positive and negative transition registers. When an event bit is set, it remains set until the Event register is read. Reading the Event register clears it.

- An Enable register defines which bits in the event register will be reported to the Status Byte register. You can write to or read from an enable register.

Operation Status Group

These registers record signals that occur during normal operation. The group consists of a Condition, PTR/NTR, Event, and Enable register. The outputs of the Operation Status register group are logically-ORed into the OPERation summary bit (7) of the Status Byte register. Refer to Status Registers for a description of each register.

The following table describes the Operation Status register bit assignments.

Bit	Bit Name	Decimal Value	Definition
0	CV	1	Output is in constant voltage
1	CC	2	Output is in constant current

2	OFF	4	Output is programmed off
3	WTG-meas	8	Measurement system is waiting for a trigger
4	WTG-tran	16	Transient system is waiting for a trigger
5	MEAS-active	32	Measurement system is initiated or in progress
6	TRAN-active	64	Transient system is initiated or in progress
7	User1	128	The User1-defined expression is true
8	User2	256	The User2-defined expression is true
9-15	not used	not used	0 is returned

Questionable Status Group

These two register groups record signals that indicate abnormal operation. The group consists of a Condition, PTR/NTR, Event, and Enable register. The outputs of the Questionable Status group are logically-ORed into the QUEStionable summary bit (3) of the Status Byte register. Refer to for a description of each register.

The following table describes the Questionable1 Status register bit assignments.

Bit	Bit Name	Decimal Value	Definition
0	OV	1	Output is disabled by the over-voltage protection
1	OC	2	Output is disabled by the over-current protection
2	PF	4	Output is disabled by power-fail (low-line or brownout on AC line)
3	CP+	8	Output is disabled by the positive over-power limit
4	OT	16	Output is disabled by the over-temperature protection
5	CP-	32	Output is disabled by the negative over-power limit
6	OV-	64	Output is disabled by a negative OV due to reversed sense leads
7	LIM+	128	Output is in positive voltage or current limit
8	LIM-	256	Output is in negative current limit
9	INH	512	Output is disabled by an external INHibit signal
10	UNR	1024	Output is unregulated

Bit	Bit Name	Decimal Value	Definition
11	PROT	2048	Output is disabled by a watchdog timer protection
12	EDP	4096	Output is disabled by excessive output dynamic protection
13	SF	8192	A sense lead fault has been detected
14,15	not used	not used	0 is returned

The following table describes the Questionable2 assignments.

Bit	Bit Name	Decimal Value	Definition
0	UProt	1	Output is disabled by a user-defined protection signal
1	IPK+	2	Output is in positive peak current limit
2	IPK-	4	Output is in negative peak current limit
3	CSF	8	A current sharing fault has occurred
4-15	not used	not used	0 is returned

Standard Event Status Group

These registers are programmed by Common commands. The group consists of an Event and Enable register. The Standard Event event register latches events relating to communication status. It is a read-only register that is cleared when read. The Standard Event enable register functions similarly to the enable registers of the Operation and Questionable status groups. Refer to Status Registers for a description of each register.

The following table describes the Standard Event Status register bit assignments.

Bit	Bit Name	Decimal Value	Definition
0	Operation Complete	1	All commands before and including *OPC have been executed.
1	not used	not used	0 is returned
2	Query Error	4	The instrument tried to read the output buffer but it was empty, a new command line was received before a previous query has been read, or both the input and output buffers are full.
3	Device-specific Error	8	A device-specific error, including a self-test error, calibration error or other device-specific error occurred. Error Messages
4	Execution Error	16	An execution error occurred. Error Messages
5	Command	32	A command syntax error occurred. Error Messages

6	not used	not used	0 is returned
7	Power On	128	Power has been cycled since the last time the event register was read or cleared.

Status Byte Register

This register summarizes the information from all other status groups as defined in the IEEE 488.2 Standard Digital Interface for Programmable Instrumentation.

The following table describes the Status Byte register bit assignments.

Bit	Bit Name	Decimal Value	Definition
0	not used	not used	0 is returned
1	not used	not used	0 is returned
2	Error Queue	4	One or more errors in the Error Queue. Use SYSTem:ERRor? to read and delete errors.
3	Questionable Status Summary	8	One or more bits are set in the Questionable Data Register. Bits must be enabled, see STATus:QUEStionable:ENABle.
4	Message Available	16	Data is available in the instrument's output buffer.
5	Event Status Summary	32	One or more bits are set in the Standard Event Register. Bits must be enabled, see *ESE.
6	Master Status Summary	64	One or more bits are set in the Status Byte Register and may generate a Request for Service. Bits must be enabled, see *SRE.
7	Operation Status Summary	128	One or more bits are set in the Operation Status Register. Bits must be enabled, see STATus:OPERation:ENABle.

Master Status Summary and Request for Service Bits

MSS is a real-time (unlatched) summary of all Status Byte register bits that are enabled by the Service Request Enable register. MSS is set whenever the instrument has one or more reasons for requesting service. *STB? reads the MSS in bit position 6 of the response but does not clear any of the bits in the Status Byte register.

The RQS bit is a latched version of the MSS bit. Whenever the instrument requests service, it sets the SRQ interrupt line true and latches RQS into bit 6 of the Status Byte register. When the controller does a serial poll, RQS is cleared inside the register and returned in bit position 6 of the response. The remaining bits of the Status Byte register are not disturbed.

Error and Output Queues

The Error Queue is a first-in, first-out (FIFO) data register that stores numerical and textual description of an error or event. Error messages are stored until they are read with SYSTem:ERRor? If the queue overflows, the last error/event in the queue is replaced with error -350,"Queue overflow".

The Output Queue is a first-in, first-out (FIFO) data register that stores instrument-to-controller messages until the controller reads them. Whenever the queue holds messages, it sets the MAV bit (4) of the Status Byte register.

Status Diagram
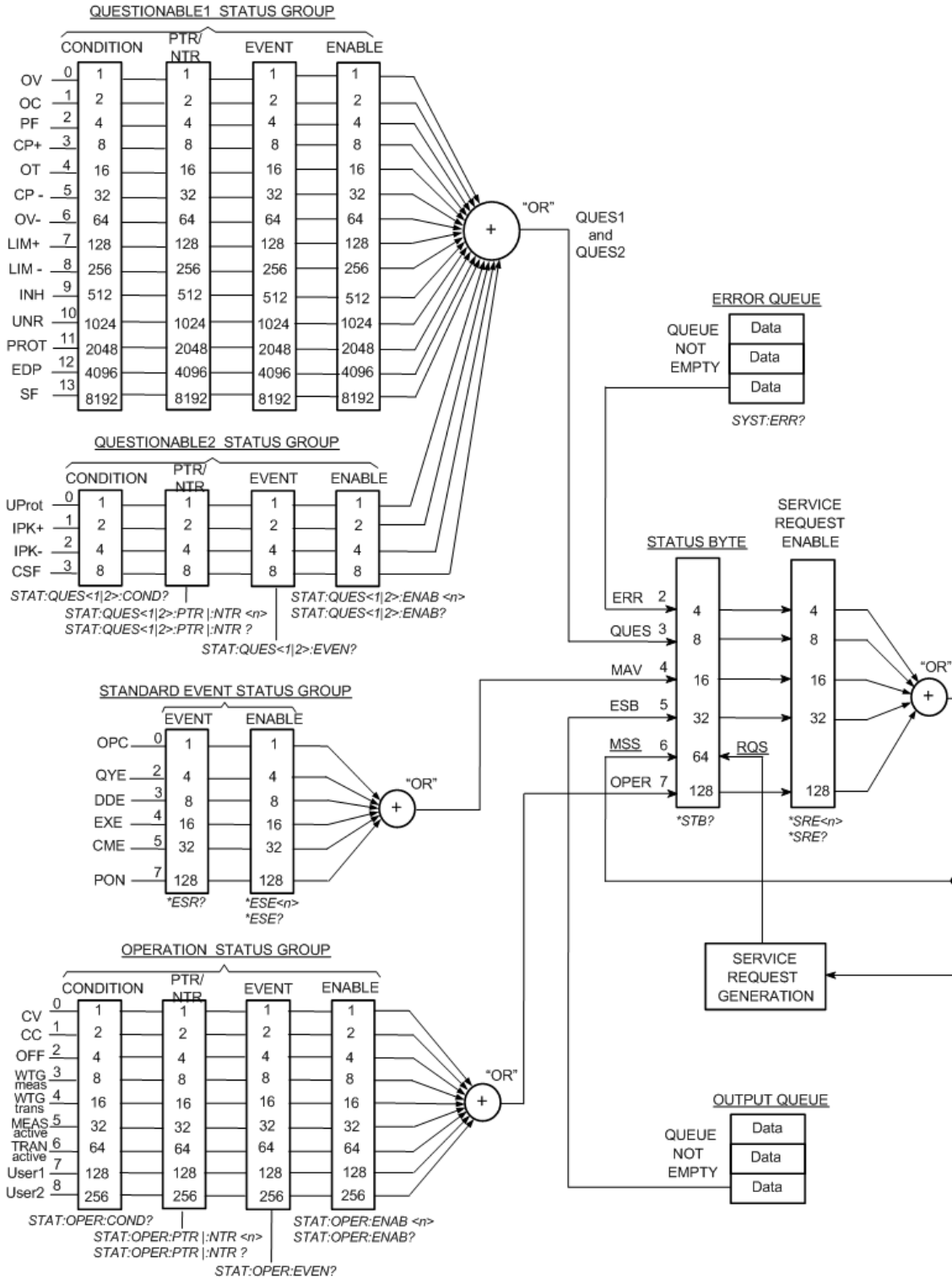
Trigger Tutorial

The APS trigger system is a flexible, multi-purpose system that controls the operation of the instrument to suit a variety of user-defined applications. The trigger diagram below provides an graphical view of how the trigger sources and destinations are interconnected.

Trigger Sources

Trigger Destinations

Trigger Diagram

Trigger Sources

The following table describes the available trigger sources, which are shown on the left of the trigger diagram. Note that not all trigger sources can be applied to every trigger subsystem.

Source	Description
BUS	Enables GPIB device triggers, *TRG, or <GET> (Group Execute Trigger).
CURR1	Selects an output current level.
EXPRession <1-8>	Selects one of eight user-defined expressions. See Using Expression Signal Routing.
IMMediate	Triggers the transient as soon as it is INITiated.
PIN<n>|EXTernal	Selects a digital port pin configured as a trigger input. <n> specifies the pin number. EXTernal selects ALL connector pins that have been configured as trigger inputs.
TRAN1	Selects the transient system as the trigger source.
TRIG:ACQ:IMM	Triggers the acquisition immediately.
TRIG:ELOG:IMM	Triggers the Elog immediately.
TRIG:TRAN:IMM	Triggers the transient immediately.
VOLT1	Selects an output voltage level.

Trigger Destinations

The following table describes the trigger system destinations. Note that the trigger system, when used in conjunction with user-defined signal routing, can generate a number of power supply actions that can control specific applications.

Destination	Description
Digital Pin	Sends the trigger output signal to the designated digital output pin. See Programming the Digital Port.
Elog	Starts external data logging (Elog). Note that external data logging must first be

	initiated. See External Data Logging.
Arb	Starts the arbitrary waveform. Note that the waveform must first be enabled and initiated. See Programming Output Transients.

Note that the trigger system can be combined with user-defined signal expressions to provide control signals for specific applications. See Using Expression Signal Routing.

Trigger Diagram
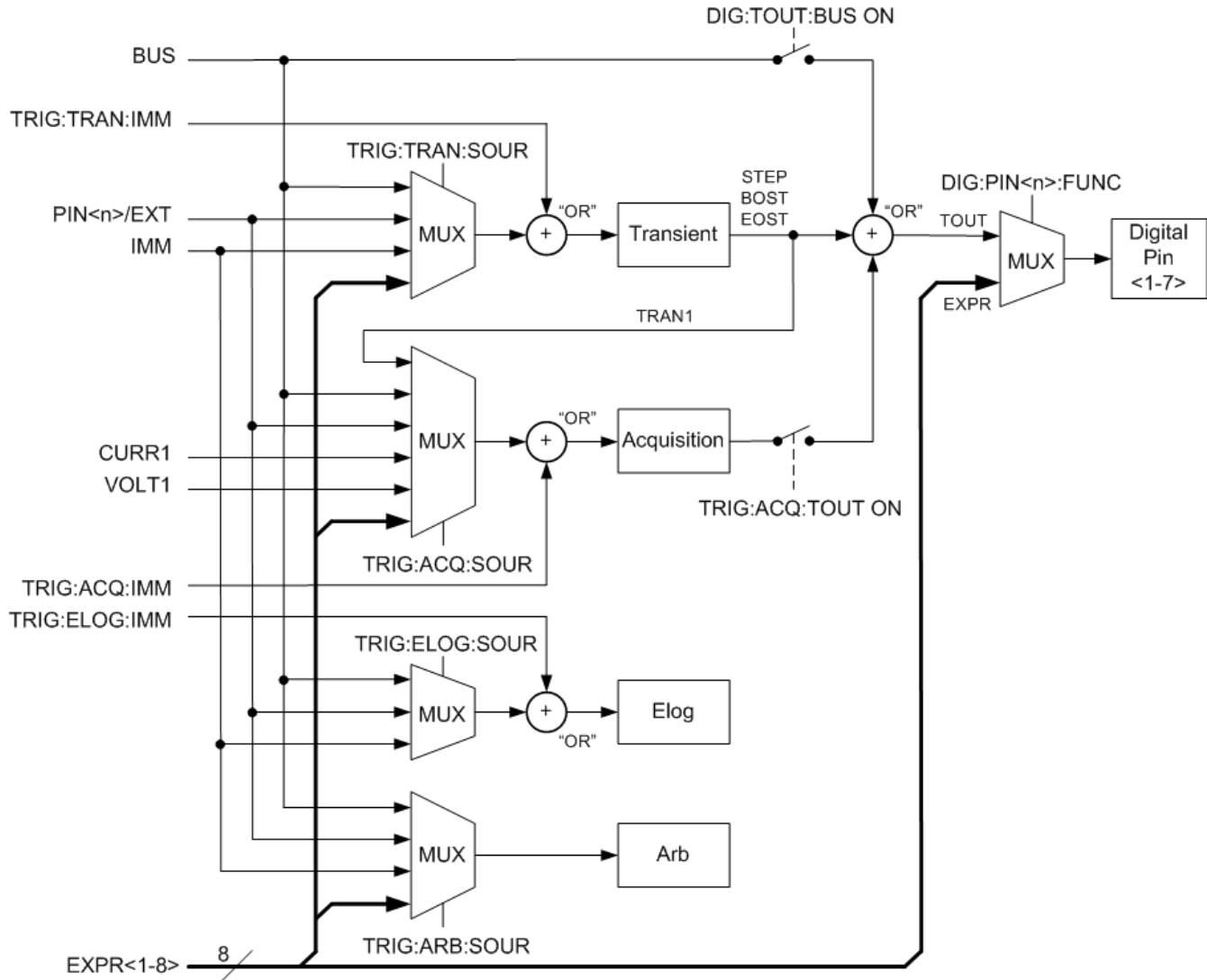
Command Quick Reference

Some [optional] commands have been included for clarity. All settings commands have a corresponding query. See the Syntax Conventions for SCPI.

ABORT Subsystem

ABORt

    :ACQuire   Cancels any triggered measurements.

    :ELOG   Stops external data logging.

    :TRANsient Cancels any triggered actions.

CALibrate Subsystem

CALibrate

:COUNt?	Returns the number of times the unit has been calibrated.
:CURRent	
:LEVel *<value>*	Calibrates the current programming and measurement.
:MEASure *<value>*	Calibrates the low range current measurement.
:SHARing	Calibrates the Imon signal for paralleled units.
:TC	Calibrates the temperature coefficient.
:DATA *<value>*	Enters the calibration value read by the external meter.
:DATE *<"date">*	Enters the calibration date in nonvolatile memory.
:LEVel P1|P2|P3	Advances to the next level in the calibration.
:PASSword *<value>*	Sets a numeric password to prevent unauthorized calibration.
:RESistance	
:BOUT	Calibrates the bottom out resistance.
:SAVE	Saves the calibration constants in non-volatile memory.
:STATe 0|OFF|1|ON	Enables or disables calibration mode.
:VOLTage	
:LEVel *<value>*	Calibrates the voltage programming and measurement.
:CMRR	Calibrates the voltage common mode rejection ratio.

DISPlay Subsystem

DISPlay

  [:WINDow]

[:STATe] 0|OFF|1|ON	Turns the front panel display on or off.
:VIEW METER_VI|METER_VP|METER_VIP	Selects the parameters to display on the front panel.

FETCh Subsystem

FETCh

  [:SCALar]

    :CURRent

      [:DC]? [*<start_index>*, *<points>*] Returns the averaged measurement.

      :ACDC? Returns the RMS measurement (AC + DC).

      :HIGH? Returns the High level of a pulse waveform.

      :LOW? Returns the Low level of a pulse waveform.

      :MAXimum?

      :MINimum? Returns the maximum or minimum value.

    :POWer

      [:DC]? [*<start_index>*, *<points>*] Returns the averaged measurement.

    :VOLTage

      [:DC]? [*<start_index>*, *<points>*] Returns the averaged measurement.

      :ACDC? Returns the RMS measurement (AC + DC).

      :HIGH? Returns the High level of a pulse waveform.

      :LOW? Returns the Low level of a pulse waveform.

      :MAXimum?

      :MINimum? Returns the maximum or minimum value.

  :AHOur? [IGNORE_OVLD] Returns the accumulated amp-hours.

  :ARRAY

    :CURRent

      [:DC]? [*<start_index>*, *<points>*] Returns the instantaneous measurement.

    :POWer

      [:DC]? [*<start_index>*, *<points>*] Returns the instantaneous measurement.

    :VOLTage

      [:DC]? [*<start_index>*, *<points>*] Returns the instantaneous measurement.

  :ELOG? *<maxrecords>* Returns the most recent external datalog records.

  :WHOur? [IGNORE_OVLD] Returns the accumulated watt-hours.

FORMat Subsystem

FORMat

  [:DATA] ASCII | REAL Specifies the format of the returned data.

  :BORDer NORMal | SWAPped Specifies how binary data is transferred.

HCOPy Subsystem

HCOPy
   :SDUMp
      :DATA? [BMP|GIF|PNG]   Returns an image of the front panel display.
      :DATA
          :FORMat BMP|GIF|PNG Specifies the format for front panel images returned.

IEEE-488 Common Commands

*CLS   Clear status command.
*ESE *<value>* Event status enable command and query.
*ESR?   Event status event query.
*IDN?   Identification Query.
*OPC   Sets the OPC (operation complete) bit in the standard event register.
*OPC?   Returns a 1 to the output buffer when all pending operations complete.
*OPT?   Returns a string identifying any installed options.
*RCL *<value>* Recalls a saved instrument state.
*RST   Resets the instrument to pre-defined values that are either typical or safe.
*SAV *<value>* Saves the instrument state to one of ten non-volatile memory locations.
*SRE *<value>* Service request enable command and query.
*STB?   Status byte query.
*TRG   Trigger command.
*TST?   Self-test query.
*WAI   Pauses additional command processing until all pending operations are complete.

INITiate Subsystem

INITiate
   [:IMMediate]
      :ACQuire   Initiates the measurement trigger system.
      :ELOG   Initiates external data logging.
      :TRANsient   Initiates the transient trigger system.
   :CONTinuous
      :TRANsient 0|OFF|1|ON Continuously initiates the transient trigger system.

LXI Command

LXI
   :IDENtify
      :STATe 0|OFF|1|ON   Turns the front panel LXI identify indicator on or off.

MEASure Subsystem

MEASure

  [:SCALar]

    :CURRent

      [:DC]?   Takes a measurement; returns the averaged current.

      :ACDC?   Takes a measurement; returns the RMS current (AC + DC).

      :HIGH?   Takes a measurement; returns the High level of a current pulse.

      :LOW?   Takes a measurement; returns the Low level of a current pulse.

      :MAXimum? Takes a measurement; returns the maximum current.

      :MINimum? Takes a measurement; returns the minimum current.

    :POWer

      [:DC]?   Takes a measurement; returns the averaged power.

    :VOLTage

      [:DC]?   Takes a measurement; returns the averaged voltage.

      :ACDC?   Takes a measurement; returns the RMS voltage (AC + DC).

      :HIGH?   Takes a measurement; returns the High level of a voltage pulse.

      :LOW?   Takes a measurement; returns the Low level of a voltage pulse.

      :MAXimum? Takes a measurement; returns the maximum voltage.

      :MINimum? Takes a measurement; returns the minimum voltage.

  :ARRAY

    :CURRent

      [:DC]?   Takes a measurement; returns the instantaneous current.

    :POWer

      [:DC]?   Takes a measurement; returns the instantaneous power.

    :VOLTage

      [:DC]?   Takes a measurement; returns the instantaneous voltage.

OUTPut Subsystem

OUTPut

  [:STATe] 0|OFF|1|ON   Enables or disables the output.

    :COUPle

      [:STATe] 0|OFF|1|ON   Enables or disables output coupling.

      :DOFFset *<value>*   Sets a delay offset to synchronize coupled output state changes.

      :MAX

        :DOFFset?   Returns the delay offset required for this instrument.

      :OFF

        :SOURce EXPRession<1-8>|NONE Sets the off-couple signal source to an expression.

      :ON

        :SOURce EXPRession<1-8>|NONE Sets the on-couple signal source to an expression.

:DELay		
:FALL *<value>*		Sets the output turn-off sequence delay.
:RISE *<value>*		Sets the output turn-on sequence delay.
:INHibit		
:MODE LATChing|LIVE|OFF		Sets the operating mode of the remote inhibit digital pin.
:PON		
:STATe RST|RCL0		Sets the output power-on state.
:PROTection		
:CLEar		Resets the latched protection.
:TEMPerature		
:MARGin?		Returns the margin remaining before the over-temperature trips.
:USER		
[:STATe] 0|OFF|1|ON		Enables or disables the user-defined protection.
:SOURce EXPRession<1-8>|NONE		Sets the user-defined protection source to an expression.
:WDOG		
[:STATe] 0|OFF|1|ON		Enables or disables the I/O watchdog timer.
:DELay *<value>*		Sets the watchdog delay time.
:RELay		
:LOCK		
[:STATe] 0|OFF|1|ON		Enables or disables the locked-closed state of the output relays.
:POLarity NORMal|REVerse		Sets the polarity of the output relays.
:ENABle 0|OFF|1|ON		Enables or disables the polarity reversal function.

SENSe Subsystem

SENSe		
:AHOur		
:RESet		Resets the amp-hour or watt-hour measurement to zero.
:BBR		
:PERiod *<value>*		Sets the recording period of the black box recorder in seconds.
:CURRent		
[:DC]		
:RANGe		
[:UPPer] *<value>*		Selects a DC current measurement range.
:AUTO 0|OFF|1|ON		Enables or disables seamless measurement auto ranging.
:ELOG		
:CURRent		
[:DC]		
:RANge		
[:UPPer] *<value>*		Selects the Elog current measurement range.
:AUTO 0|OFF|1|ON		Enables or disables Elog seamless measurement autoranging.

:FUNCtion	
:CURRent 0|OFF|1|ON	Enables/disables current data logging.
:MINMax 0|OFF|1|ON	Enables/disables min/max current data logging.
:VOLTage 0|OFF|1|ON	Enables/disables voltage data logging.
:MINMax 0|OFF|1|ON	Enables/disables min/max voltage data logging.
:PERiod *<value>*	Sets the integration time of an Elog measurement.
:FAULt	
:STATe 0|OFF|1|ON	Enables or disables remote sense fault detection.
:SWEep	
:NPLCycles *<value>*	Sets the measurement time in number of power line cycles.
:OFFSet	
:POINts *<value>*	Defines the offset in a data sweep for triggered measurements.
:POINts *<value>*	Defines the number of points in a measurement.
:TINTerval *<value>*	Defines the time period between measurement samples.
:THReshold<1|2|3|4>	
:AHOur	
[:LEVel] *<value>*	Sets the amp-hour level for comparator 1,2,3, or 4.
:CURRent	
[:LEVel] *<value>*	Sets the current level for comparator 1,2,3, or 4.
:FUNCtion VOLT|CURR|POW|AHO|WHO	Sets the sensing function for comparator 1,2,3, or 4.
:OPERation GT|LT	Sets the comparison type for comparator 1,2,3, or 4.
:POWer	
[:LEVel] *<value>*	Sets the power level for comparator 1,2,3, or 4.
:VOLTage	
[:LEVel] *<value>*	Sets the voltage level for comparator 1,2,3, or 4.
:WHOur	
[:LEVel] *<value>*	Sets the watt-hour level for comparator 1,2,3, or 4.
:WHOur	
:RESet	Resets the accumulated watt-hour measurement.
:WINDow	
[:TYPE] HANNing|RECTangular	Selects the measurement window.

[SOURce:]ARB Subsystem

[SOURce:]	
ARB	
:COUNt *<value>*|INFinity	Specifies the number of times the Arb repeats.
:CURRent	
:CDWell	
[:LEVel] *<value>*{,*<value>*}|*<Block>*	Specifies the level of each point in the Arb.
:DWELl *<value>*	Specifies the dwell time of each point in the Arb.

        :POINts?   Returns the number of points in the Arb.

:FUNCtion

    :TYPE CURRent|VOLTage   Specifies either a voltage or current Arb.

:TERMinate

    :LAST 0|OFF|1|ON   Selects the output setting after the Arb ends.

:VOLTage

    :CDWell

        [:LEVel] *<value>*{,*<value>*}|*<Block>* Specifies the level of each point in the Arb.

        :DWELl *<value>*   Specifies the dwell time of each point in the Arb.

        :POINts?   Returns the number of points in the Arb.

[SOURce:]CURRent Subsystem

[SOURce:]

   CURRent

      [:LEVel]

         [:IMMediate]

           [:AMPLitude] *<value>*   Sets the output current when in current priority mode

         :TRIGgered

           [:AMPLitude] *<value>*   Sets the triggered output current

      :LIMit

         [:POSitive]

           [:IMMediate]

              [:AMPLitude] *<value>*   Sets the current limit when in voltage priority mode.

         :NEGative

           [:IMMediate]

              [:AMPLitude] *<value>*   Sets the current limit when in voltage priority mode.

      :MODE FIXed|STEP|LIST|ARB   Sets the transient mode.

      :PROTection

        :DELay

          [:TIME] *<value>*   Sets the over-current protection delay.

          :STARt SCHange|CCTRans   Specifies what starts the over-current protection delay timer.

        :STATe 0|OFF|1|ON   Enables or disables the over-current protection.

      :SHARing

        [:STATe] 0|OFF|1|ON   Enables or disables current sharing on paralleled units.

      :SLEW

        [:IMMediate] *<value>*|INFinity Sets the current slew rate.

        :MAXimum 0|OFF|1|ON   Enables or disables the maximum slew rate override.

[SOURce:]DIGital Subsystem

[SOURce:]

DIGital

    :INPut

        :DATA?   Reads the state of the digital control port.

    :OUTput

        :DATA *<value>*   Sets the state of the digital control port.

    :PIN<1-7>

        :FUNCtion   Sets the function of the pins. DIO |DINPut |EXPRession<1-8> |FAULt |INHibit |ONCouple
<function> |OFFCouple |TOUTput |TINPut

        :POLarity   Sets the polarity of the pins.
POSitive|NEGative

        :TOUTput

            :BUS

                [:ENABle]   Enables or disables BUS triggers on digital port pins.
0|OFF|1|ON

[SOURce:]FUNCtion Command

[SOURce:]

    :FUNCtion CURRent|VOLTage   Sets the output regulation - voltage priority or current priority.

[SOURce:]LIST Subsystem

[SOURce:]

  LIST

    :COUNt *<value>*|INFinity   Sets the list repeat count.

    :CURRent

      [:LEVel] *<value>{,<value>}* Specifies the setting for each list step.

      :POINts?   Returns the number of list points.

    :DWELl *<value>{,<value>}* Specifies the dwell time for each list step.

      :POINts?   Returns the number of list points.

    :STEP ONCE|AUTO   Specifies how the list responds to triggers.

    :TERMinate

      :LAST 0|OFF|1|ON   Determines the output value when the list terminates.

    :TOUTput

      :BOSTep

        [:DATA] *<Bool>{,<Bool>}* Generates a trigger out at the Beginning Of STep

        :POINts?   Returns the number of list points.

      :EOSTep

        [:DATA] *<Bool>{,<Bool>}* Generates a trigger out at the End Of STep

        :POINts?   Returns the number of list points.

    :VOLTage

      [:LEVel] *<value>{,<value>}* Specifies the setting for each list step.

      :POINts?   Returns the number of list points.

[SOURce:]POWer Query

[SOURce:]

   :POWer

      :LIMit? Returns the output power limit of the instrument.

[SOURce:]Resistance Subsystem

[:SOURce]

   :RESistance

      [:LEVel]

         [:IMMediate]

            [:AMPLitude] *<value>* Sets the output resistance level.

      :STATe 0|OFF|1|ON Enables or disables output resistance programming.

[SOURce:]STEP Command

[SOURce:]

   :STEP

      :TOUTput0|OFF|1|ON Specifies whether a trigger out is generated when a transient step occurs.

[SOURce:]VOLTage Subsystem

[SOURce:]

   VOLTage

      [:LEVel]

         [:IMMediate]

            [:AMPLitude] *<value>* Sets the output voltage when in voltage priority mode.

         :TRIGgered

            [:AMPLitude] *<value>* Sets the triggered output voltage.

      :BWIDth LOW|HIGH1 Sets the voltage bandwidth.

      :LIMit

         [:POSitive]

            [:IMMediate]

               [:AMPLitude] *<value>* Sets the voltage limit when in current priority mode.

      :MODE FIXed|STEP|LIST|ARB Sets the transient mode.

      :PROTection

         [:LEVel] *<value>* Sets the over-voltage protection level.

      :SLEW

         [:IMMediate] *<value>*|INFinity Sets the voltage slew rate.

         :MAXimum 0|OFF|1|ON Enables or disables the maximum slew rate override.

STATus Subsystem

STATus

  :OPERation

    [:EVENt]?   Queries the operation event register.

    :CONDition?   Queries the operation condition register.

    :ENABle *<value>*   Sets the operation enable register.

    :NTRansiton *<value>*   Sets the Negative transition filter

    :PTRansiton *<value>*   Sets the Positive transition filter

    :USER<1|2>

      :SOURce EXPRession<1-8>|NONE Selects an expression to drive the user-defined status bits.

  :PRESet   Presets all Enable, PTR, and NTR registers.

  :QUEStionable<1|2>

    [:EVENt]?   Queries the questionable event register.

    :CONDition?   Queries the questionable condition register.

    :ENABle *<value>*   Sets the questionable enable register.

    :NTRansiton *<value>*   Sets the Negative transition filter

    :PTRansiton *<value>*   Sets the Positive transition filter

SYSTem Subsystem

SYSTem

  :BBR

    :EVENt *<"string">*   Adds an event string into the BBR event log.

    :SNAPshot <value>   Captures a data snapshot of the specified length.

      :STATus?   Returns the completion status of the snapshot in percent.

    :STATe?   Returns true (1) if the Black Box Recorder is logging.

    :TIME?   Returns the length of the Black Box Recorder data.

  :COMMunicate

    :LAN|TCPip:CONTrol?   Returns the initial socket control connection port number.

    :RLSTate LOCal|REMote|RWLock   Configures the remote/local state of the instrument.

  :DATE <yyyy>,<mm>,<dd>   Sets the date of the system clock.

  :ERRor?   Reads and clears one error from the error queue.

  :LFRequency?   Returns the power-line reference frequency.

  :LFRequency

    :MODE AUTO|MAN50|MAN60   Specifies automatic or manual line frequency detection.

  :PASSword

    :FPANel

      :RESet   Resets the front panel lockout password to zero.

  :REBoot   Reboots the instrument to its power-on state.

  :SECurity

:IMMediate	Clears all user memory and reboots the instrument.
:SIGNal	
:DEFine EXPRession<1-8>,<*"expression"*>	Defines up to eight signal expressions.
:TEMPerature	
:AMBient?	Returns the temperature at the air inlet.
:TIME <hh>,<mm>,<ss>	Sets the time of the system clock.
:VERSion?	Returns the SCPI version that the instrument complies with.

TRIGger Subsystem

TRIGger	
:ACQuire	
[:IMMediate]	Generates an immediate trigger.
:CURRent	
[:LEVel] <*value*>	Sets the triggered level of the output.
:SLOPe POSitive|NEGative	Sets the slope of the signal.
:INDices	
[:DATA]?	Returns the indices where triggers were captured.
:COUNt?	Returns the number of triggers captured during the acquisition.
:SOURce <*source*>	Selects the trigger source for the acquisition system: BUS |CURRent1 |EXTernal |EXPRession<1-8> |PIN<1-7> |TRANsient1 |VOLTage1
:TOUTput	
[:ENABle] 0|OFF|1|ON	Enables measurement triggers to be sent to a digital port pin.
:VOLTage	
[:LEVel] <*value*>	Sets the triggered level of the output.
:SLOPe POSitive|NEGative	Sets the slope of the signal.
:ARB	
:SOURce <*source*>	Selects the trigger source for arbitrary waveforms: BUS |EXTernal |IMMediate |EXPRession<1-8> |PIN<1-7>
:ELOG	
[:IMMediate]	Generates an immediate trigger.
:SOURce <*source*>	Selects the trigger source for external data logging: BUS |EXTernal |IMMediate| PIN<1-7>
:TRANsient	
[:IMMediate]	Generates an immediate trigger.
:SOURce <*source*>	Selects the trigger source for the transient system: BUS |EXTernal |IMMediate |EXPRession<1-8> |PIN<1-7>

Reset State (*RST)

NOTE   The power-on/reset state may differ from that shown below if you have enabled power-on state recall mode from the **States** menu (see Instrument State Storage).

The following table shows the reset state. These parameters are reset to the indicated values at power-on or after *RST.

Reset Settings

SCPI Command *RST Settings	
ARB:COUNt	1
ARB:CURRent:CDWell:DWELl	0.001
ARB:FUNCtion:SHAPe	NONE
ARB:FUNCtion:TYPE	VOLTage
ARB:TERMinate:LAST	OFF
ARB:VOLTage:CDWell:DWELl	0.001
CALibrate:STATe	OFF
CURRent	0
CURRent:LIMit	1.02% of rating
CURRent:LIMit:NEGative	-10.2% of rating
CURRent:MODE	FIXed
CURRent:PROTection:DELay	20 ms
CURRent:PROTection:DELay:STARt	SCHange
CURRent:PROTection:STATe	OFF
CURRent:SHARing	OFF
CURRent:SLEW	MAX
CURRent:SLEW:MAXimum	ON
CURRent:TRIGgered	0
DIGital:OUTPut:DATA	0
DIGital:TOUTput:BUS	OFF
DISPlay	ON
FUNCtion	VOLTage

LIST:COUNt	1
LIST:CURRent	1 step set to 0
LIST:DWELl	1 step set to 0.001
LIST:STEP	AUTO
LIST:TERMinate:LAST	OFF
LIST:TOUTput:BOSTep	1 step set to OFF
LIST:TOUTput:EOSTep	1 step set to OFF
LIST:VOLTage	1 step set to 0.1% of rating
LXI:IDENtify	OFF
OUTPut	OFF
OUTPut:DELay:FALL	0
OUTPut:DELay:RISE	0
OUTPut:PROTection:USER	OFF
OUTPut:PROTection:USER:SOURce	NONE
OUTPut:PROTection:WDOG	OFF
OUTPut:PROTection:WDOG:DELay	60
OUTPut:RELay:POLarity	NORMal
RESistance	0
RESistance:STATe	0
SENSe:CURRent:RANGe:AUTO	ON
SENSe:ELOG:CURRent:RANGe:AUTO	ON
SENSe:ELOG:FUNCtion:CURRent	OFF
SENSe:ELOG:FUNCtion:CURRent:MINMax	OFF
SENSe:ELOG:FUNCtion:VOLTage	OFF
SENSe:ELOG:FUNCtion:VOLTage:MINMax	OFF
SENSe:ELOG:PERiod	0.1
SENSe:FAULt:STATe	ON
SENSe:FUNCtion:CURRent	1

SENSe:FUNCtion:VOLTage	1
SENSe:SWEep:NPLCycles	1
SENSe:SWEep:OFFSet:POINts	0
SENSe:SWEep:POINts	3255 (60 Hz); 3906 (50 Hz)
SENSe:SWEep:TINTerval	5.12E−6
SENSe:THReshold<n>:AHOur	0
SENSe:THReshold<n>:CURRent	0
SENSe:THReshold<n>:FUNCtion	VOLTage
SENSe:THReshold<n>:OPERation	GT
SENSe:THReshold<n>:POWer	0
SENSe:THReshold<n>:VOLTage	0
SENSe:THReshold<n>:WHOur	0
SENSe:WINDow	RECTangular
STEP:TOUTput	OFF
TRIGger:ACQuire:CURRent	0
TRIGger:ACQuire:CURRent:SLOPe	POSitive
TRIGger:ACQuire:SOURce	BUS
TRIGger:ACQuire:TOUTput	OFF
TRIGger:ACQuire:VOLTage	0
TRIGger:ACQuire:VOLTage:SLOPe	POSitive
TRIGger:ARB:SOURce	BUS
TRIGger:ELOG:SOURce	BUS
TRIGger:TRANsient:SOURce	BUS
VOLTage	0.1% of rating
VOLTage:LIMit	1% of rating
VOLTage:MODE	FIXed
VOLTage:PROTection	120% of rating
VOLTage:SLEW	MAX

VOLTage:SLEW:MAXimum	ON
VOLTage:TRIGgered	0.1% of rating

The following table shows the as-shipped settings of the **non-volatile** parameters. These are not affected by power cycling or *RST.

Non-Volatile Settings

SCPI as-shipped settings	
CALibrate:DATE	March 5, 2003
CALibrate:PASSword	0
DIGital:PIN<all>:FUNCtion	DINput
DIGital:PIN<all>:POLarity	POSitive
DISPlay:VIEW	METER_VI
OUTPut:COUPle	OFF
OUTPut:COUPle:DOFFset	0
OUTPut:INHibit:MODE	OFF
OUTPut:PON:STATe	RST
OUTPut:RELay:LOCK	OFF
OUTPut:RELay:POLarity:ENABle	ON
SENSe:BBR:PERiod	0.01
SYSTem:LFRequency:MODE	AUTO
Front Panel as-shipped settings	
Front panel lockout password	Disabled
Firmware update password protected	Disabled
GPIB address	5
GPIB interface	Enabled
LAN interface	Enabled
USB interface	Enabled
Screen saver	Enabled
Screen saver delay	60 minutes

Wake on I/O	Enabled
Interface as-shipped settings	
Get GPIB Address	Automatic
IP Address	169.254.69.79
Subnet mask	255.255.0.0
Default gateway	0.0.0.0
Host name	A-<serial number>
mDNS service name	Agilent N79xxx Dynamic DC PowerSupply <serial number>
LAN service - VXI-11	Enabled
LAN service - Telnet	Enabled
LAN service - mDNS	Enabled
LAN service - Web server	Enabled
LAN service - sockets	Enabled
Web password	Blank

SCPI Error Messages

The Agilent instrument returns error messages in accord with the SCPI standard.

- Up to 20 errors can be stored in each interface-specific error queue (one each for GPIB, USB, VXI-11, and Telnet/Sockets.) Errors appear in the error queue of the I/O session that caused the error.

- The front-panel ERR annunciator turns on when there are one or more errors are in the error queue.

- A special global error queue holds all power-on and hardware-related errors (for example, over-temperature).

- Error retrieval is first-in-first-out (FIFO), and errors are cleared as you read them. Once you have read all interface-specific errors, the errors in the global error queue are retrieved. When you have read all errors from the error queue, the ERR annunciator turns off.

- If more than 20 errors have occurred, the last error stored in the queue (the most recent error) is replaced with -350,"Error queue overflow". No additional errors are stored until you remove errors from the queue. If no errors have occurred when you read the error queue, the instrument responds with +0,"No error".

- The front panel reports errors from all I/O sessions and the global error queue. To read the error queue from the front panel, press the SYSTEM button, then the "Help" softkey. Then select "View remote command error queue" in the Help menu.

- Error conditions are also summarized in the Status Byte Register. See Status Subsystem Introduction for details

- The interface-specific error queues are cleared by power cycles and *CLS. The error queue is not cleared by *RST.

- **SCPI:**

    SYSTem:ERRor?   *Read and clear one error from the queue*

    Errors have the following format (the error string may contain up to 255 characters):

Error Device-dependent Errors (these errors set Standard Event Status register bit #3)

0 No error

This is the response to the ERR? query when there are no errors.

101 Calibration state is off

Calibration is not enabled. The instrument will not accept calibration commands.

102 Calibration password is incorrect

The calibration password is incorrect.

103 Calibration is inhibited by switch setting

Calibration mode is locked out by the calibration switch.

104 Bad sequence of calibration commands

Calibration commands have not been entered in the proper sequence.

105 Unexpected output current

The measured output current is outside the acceptable range.

106 Zero measurement out of range error

The "zero" measurement value is outside the acceptable range.

107 Programming cal constants out of range

The programmed calibration constant is outside the acceptable range.

108 Measurement cal constants out of range

The measurement calibration constant is outside the acceptable range.

109 Over voltage cal constants out of range

The over voltage calibration constant is outside the acceptable range.

110 Wrong V+I

The instrument was unable to set the correct voltage or current value.

114 Wrong status

An incorrect status function has been reported.

116 Locked out by internal switch setting

This function has been locked out by an internal switch.

117 Calibration error

A calibration error has occurred. Do not save calibration constants. Try re-calibrating the unit.

200 Hardware error channel <1>

A hardware error has occurred on the output.

202 Selftest Fail

A selftest failure has occurred. See selftest failure list for details.

203 Compatibility function not implemented

The requested compatibility function is not available.

204 NVRAM checksum error

A checksum error has occurred in the instrument's nonvolatile random access memory.

205 NVRAM full

The nonvolatile random access memory of the instrument is full.

206 File not found

The internal calibration file or the internal channel attribute file was not found in NVRAM.

207 Cal file version error

The calibration file was written or read using old firmware. Firmware must be updated.

208 Running backup firmware

The instrument is presently running the backup (previous) version of the firmware.

210 Frame NVRAM error

A non-volatile RAM error has occurred in the instrument.

212 State file not loaded

A previously saved output state file has failed to load.

213 Sinkbox error

A cable has disconnected or a hardware error has occurred on the power dissipator.

214 Line frequency error

A discrepancy has occurred between the line frequency and the line frequency setting.

215 Hardware failure

A hardware failure has occurred on the power supply or the power dissipator

302 Option not installed

The option that is programmed by this command is not installed.

303 There is not a valid acquisition to fetch from

There is no valid data in the measurement buffer.

304 Volt and curr in incompatible transient modes

Voltage and current cannot be in Step and List mode at the same time.

305 A triggered value is on a different range

A triggered value is on a different range than the one that is presently set.

306 Too many list points

Too many list points have been specified.

307 List lengths are not equivalent

One or more lists are not the same length.

308 This setting cannot be changed while transient trigger is initiated

Setting cannot be changed while the instrument is waiting for or executing a trigger sequence.

309 Cannot initiate, voltage and current in fixed mode

Cannot initiate transient generator. Either the voltage or current function is set to Fixed mode.

310 The command is not supported by this model

This instrument either does not have the hardware capability or the options required to support this command.

314 Time of day clock has stopped

The time of day clock has stopped . Replace the internal battery. See service section.

315 Settings conflict error

A data element could not be programmed because of the present instrument state.

320 Firmware update error

This may be due to the instrument hardware not being able to support the firmware version.

Command Errors (these errors set Standard Event Status register bit #5)

-100 Command error

Generic syntax error.

-101 Invalid character

An invalid character was found in the command string.

-102 Syntax error

Invalid syntax was found in the command string. Check for blank spaces.

-103 Invalid separator

An invalid separator was found in the command string. Check for proper use of , ; :

-104 Data type error

A different data type than the one allowed was found in the command string.

-105 GET not allowed

A group execute trigger is not allowed in a command string.

-108 Parameter not allowed

More parameters were received than were expected.

-109 Missing parameter

Fewer parameters were received than were expected.

-110 Command header error

An error was detected in the header.

-111 Header separator error

A character that was not a valid header separator was found in the command string.

-112 Program mnemonic too long

The header contains more than 12 characters.

-113 Undefined header

A command was received that was not valid for this instrument.

-114 Header suffix out of range

The value of the numeric suffix is not valid.

-120 Numeric data error

Generic numeric data error.

-121 Invalid character in number

An invalid character for the data type was found in the command string.

-123 Exponent too large

The magnitude of the exponent was larger than 32000.

-124 Too many digits

The mantissa of a numeric parameter contained more than 255 digits, excluding leading zeros.

-128 Numeric data not allowed

A numeric parameter was received but a character string was expected.

-130 Suffix error

Generic suffix error

-131 Invalid suffix

A suffix was incorrectly specified for a numeric parameter.

-134 Suffix too long

The suffix contains more than 12 characters.

-138 Suffix not allowed

A suffix is not supported for this command.

-140 Character data error

Generic character data error

-141 Invalid character data

Either the character data element contains an invalid character, or the element is not valid.

-144 Character data too long

The character data element contains more than 12 characters.

-148 Character data not allowed

A discrete parameter was received, but a string or numeric parameter was expected.

-150 String data error

Generic string data error

-151 Invalid string data

An invalid character string was received. Check that the string is enclosed in quotation marks.

-158 String data not allowed

A character string was received, but is not allowed for this command.

-160 Block data error

Generic block data error

-161 Invalid block data

The number of data bytes sent does not match the number of bytes specified in the header.

-168 Block data not allowed

Data was sent in arbitrary block format but is not allowed for this command.

-170 Expression error

Generic expression error

-171 Invalid expression data

The expression data element was invalid.

-178 Expression data not allowed

Expression data element was sent but is not allowed for this command.

Execution Errors (these errors set Standard Event Status register bit #4)

-200 Execution error

Generic syntax error

-220 Parameter error

A data element related error occurred.

-221 Settings conflict

A data element could not be executed because of the present instrument state.

-222 Data out of range

A data element could not be executed because the value was outside the valid range.

-223 Too much data

A data element was received that contains more data than the instrument can handle.

-224 Illegal parameter value

An exact value was expected but not received.

-225 Out of memory

The device has insufficient memory to perform the requested operation.

-226 Lists not same length

One or more lists are not the same length.

-230 Data corrupt or stale

Possible invalid data. A new reading was started but not completed.

-231 Data questionable

The measurement accuracy is suspect.

-232 Invalid format

The data format or structure is inappropriate.

-233 Invalid version

The version of the data format is incorrect to the instrument.

-240 Hardware error

The command could not be executed because of a hardware problem with the instrument.

-241 Hardware missing

The command could not be executed because of missing hardware, such as an option.

-260 Expression error

An expression program data element related error occurred.

-261 Math error in expression

An expression program data element could not be executed due to a math error.

Query Errors (these errors set Standard Event Status register bit #2)

-400 Query Error

Generic error query

-410 Query INTERRUPTED

A condition causing an interrupted query error occurred.

-420 Query UNTERMINATED

A condition causing an unterminated query error occurred.

-430 Query DEADLOCKED

A condition causing a deadlocked query error occurred.

-440 Query UNTERMINATED after indefinite response

A query was received in the same program message after a query indicating an indefinite response was executed.

Compatibility Commands

The commands described in this section are provided for compatibility with existing N6700 series modular power systems (MPS). Specifically, because of their feature sets, only programs written for the N673xB, N674xB, and N677xA power modules are directly compatible with the APS models. Note that the compatibility commands discussed in this section have no or little effect on the operation of the APS models, as they access functions that are either redundant or not available.

Channel Parameter

Since the APS models are single channel units, SCPI commands do not require a channel list parameter. However, for code compatibility with the N6700 MPS, the APS models will accepts the channel list (, @1) for N6700 MPS commands that require this parameter. All channel-dependent commands sent to the APS models must be sent to channel 1 only.

Aliased Commands

Certain N6700 MPS commands are aliased or linked to newer APS commands for compatibility. This allows the N6700 MPS commands to be used in APS models without modification.

N6700 MPS command	Aliased to these APS commands
[SOURce:]CURRent Sets the output current.	[SOURce:]CURRent:LIMit[:POSitive] Sets the current limit when in voltage priority mode.
DISPlay:VIEW METER1 Displays a single output channel	DISPlay:VIEW METER_VI Displays output voltage and current.
DISPlay:VIEW METER4 Displays four output channels	DISPlay:VIEW METER_VI Displays output voltage and current.

Obsolete N6700 MPS commands	Aliased to these N6700 MPS and APS commands
OUTPut:PROT:DELay Sets the output protection delay.	[SOURce:]CURRent:PROTection:DELay Sets the output protection delay.

NOTE   It is not recommended to use obsolete commands in new application programs.

Code Compatible Commands

These Agilent N6700 MPS commands are not required for APS models, but are provided for better compatibility with code written for the N6700 MPS. In most cases these commands either do nothing, or specify a pre-defined parameter that is compatible with the APS models.

N6700 MPS command	Action on APS models
OUTPut:COUPle:CHANnel Couples output channels together.	Does nothing.

OUTPut:PROTection:COUPle Couples protection on output channels.	Does nothing.
SENSe:CURRent:COMPensate Sets the output current compensation.	Does nothing.
SENSe:FUNCtion:CURRent Enables current measurements.	Current measurements are always enabled.
SENSe:FUNCtion:VOLTage Enables voltage measurements.	Voltage measurements are always enabled.
SENSe:VOLTage:RANGe Sets the output voltage range.	Does nothing.
SENSe:ELOG:VOLTage:RANGe Sets the external datalog voltage range.	Does nothing.
[SOURce:]ARB:FUNCtion:SHAPe Selects an Arb function, or None.	The CDWell Arb function is always selected.
[SOURce:]CURRent:RANGe Sets the output current range.	Does nothing.
[SOURce:]VOLTage:RANGe Sets the output voltage range.	Does nothing.
SYSTem:CHANnel[:COUNt]? Returns the number of output channels.	Always returns a "1".
SYSTem:CHANnel:MODel? Returns the channel model number.	Returns the power supply model. Same as *IDN?
SYSTem:CHANnel:OPTion? Returns the channel options.	Returns the power supply options. Same as *OPT?
SYSTem:CHANnel:SERial? Returns the channel serial number.	Returns the power supply serial number. Same as *IDN?
SYSTem:GROUp:DEFine Groups up to four output channels.	Does nothing.
SYSTem:GROUp:CATalog? Returns the number of grouped channels.	Always returns a "1".
SYSTem:GROUp:DELete Ungroups the specified channels.	Does nothing.
SYSTem:GROUp:DELete:ALL Ungroups all channels.	Does nothing.

Commands and Parameters that Work Differently

STEP and LIST commands only apply to the priority mode that is presently active in the APS (either voltage-priority or current-priority mode). This is unlike the N6700 MPS commands, which can STEP and LIST voltage and current simultaneously.

N6700 MPS command	APS command
[SOURce:]CURRent:TRIGgered [SOURce:]VOLTage:TRIGgered Generates a step when either a voltage or current step occurs.	[SOURce:]CURRent:TRIGgered [SOURce:]VOLTage:TRIGgered Generates a step when a voltage step occurs in voltage priority mode. Generates a step when a current step occurs in current priority mode.
[SOURce:]LIST commands Generates an output voltage and output current list.	[SOURce:]LIST commands Generate a voltage list in voltage priority mode. Generate a current list in current priority mode.
QUEStionable:STATus? Constant current mode indicated by CC bit.	QUEStionable:STATus? Positive current limit indicated by +LIM bit.

Service and Maintenance

Further service and maintenance topics include:

Verification and Calibration

Self-Test Procedure

Firmware Update

Instrument Sanitize

Calibration Switches

Battery Replacement

Disassembly

Types of Service Available

If your instrument fails during the warranty period, Agilent Technologies will repair or replace it under the terms of your warranty. After your warranty expires, Agilent offers repair services at competitive prices.

Many Agilent products have optional service contracts that extend coverage after the standard warranty expires.

Obtaining Repair Service (Worldwide)

To obtain service for your instrument, contact your nearest Agilent Technologies Service Center. They will arrange to have your unit repaired or replaced, and can provide warranty or repair–cost information where applicable. Ask the Agilent Technologies Service Center for shipping instructions, including what components to ship. Agilent recommends that you retain the original shipping carton for return shipments.

Before Returning the Unit

Before returning the unit, make sure the failure is in the instrument rather than any external connections. Also make sure that the instrument was accurately calibrated within the last year (see Calibration Interval).

If the unit is inoperative, verify that:

- the AC power cord is securely connected to the instrument

- the AC power cord is plugged into a live outlet

- the front-panel Power On/Standby switch has been pushed

If self-test failed, verify that:

Ensure that all connections (front and rear) are removed when self-test is performed. During self-test, errors may be induced by signals present on external wiring, such as long test leads that can act as antennae.

Repackaging for Shipment

To ship the unit to Agilent for service or repair:

- Attach a tag to the unit identifying the owner and indicating the required service or repair. Include the model number and full serial number.

- Place the unit in its original container with appropriate packaging material.

- Secure the container with strong tape or metal bands.

- If the original shipping container is unavailable, use a container that will ensure at least 10 cm (4 in.) of compressible packaging material around the entire instrument. Use static-free packaging materials.

Agilent suggests that you always insure shipments.

Cleaning

WARNING   **SHOCK HAZARD To prevent electric shock, unplug the unit before cleaning.**

Clean the outside of the instrument with a soft, lint-free, slightly damp cloth. Do not use detergent. Disassembly is not required or recommended for cleaning.

Verification and Calibration

Further Verification and Calibration topics include:

Recommended Test Equipment and Setups

Verification Procedure

Calibration Procedure

Verification

The verification procedures verify that the APS is operating normally and is within published specifications. If the instrument fails any of the tests or if abnormal test results are obtained, try calibrating the unit. If calibration is unsuccessful, return the unit to an Agilent Technologies Service Center.

Agilent Technologies Calibration Services - Your local Agilent Technologies Service Center offers low-cost calibration. The service center uses automated calibration systems that allow Agilent to provide calibration at competitive prices.

Agilent Technologies recommends that complete verification should always be performed at the calibration interval. If the power supply passes the verification tests, the unit is operating within its calibration limits and does not need to be re-calibrated. This ensures that the instrument will remain within specifications for the next calibration interval and provides the best long-term stability. Performance data measured using this method can be used to extend future calibration intervals.

Calibration Interval

One Year Calibration Interval

The instrument should be calibrated on a regular interval determined by the accuracy requirements of your application. A **one-year** interval is adequate for most applications. Accuracy specifications are warranted only if adjustment is made at regular calibration intervals. Published accuracy specifications are not warranted beyond the one-year calibration interval.

Three Year Calibration Interval

Voltage and current programming and measurement accuracy specifications can be extended to a three-year period calibration interval by multiplying (or increasing) the one-year calibration accuracy specifications shown in the verification Test Record Forms by a factor of three.

Test Considerations

For optimum performance, all verification and calibration procedures should comply with the following recommendations:

- Ambient temperature is stable, between 18 and 28 °C.
- Ambient relative humidity is less than 80%.
- 30 minute warm-up period before verification or adjustment.
- Cables as short as possible, twisted or shielded to reduce noise.

Measurement Techniques

Voltmeter

To ensure that the values read by the voltmeter during both the verification procedure and the calibration procedure are not affected by the instantaneous measurement of the AC peaks of the output current ripple, make several DC measurements and average them.

If you are using an Agilent 3458A DMM, you can set up the voltmeter to do this automatically. From the instrument's front panel, program 100 power line cycles per measurement. Press NPLC 100 ENTER. Additionally, turn on auto-calibration (ACAL) and the autorange function (ARANGE).

Current Shunt

The 4-terminal current shunt is used to eliminate output current measurement error caused by voltage drops in the load leads and connections. It has special current-monitoring terminals inside the load connection terminals. Connect the voltmeter directly to these current-monitoring terminals.

Electronic Load

Many of the test procedures require the use of a variable load capable of dissipating the required power. If a variable resistor is used, switches should be used to connect, disconnect, or short the load resistor. For most tests, an electronic load can be used. The electronic load is considerably easier to use than load resistors, but it may not be fast enough to test transient recovery time and may be too noisy for the noise (PARD) tests.

Fixed load resistors may be used in place of a variable load, with minor changes to the test procedures. Also, if computer controlled test setups are used, the relatively slow (compared to computers and system voltmeters) settling times and slew rates of the power system may have to be taken into account. "Wait" statements can be used in the test program if the test system is faster than the power system.

Recommended Test Equipment and Setups

Test Equipment

Verification Setups

Calibration Setups

Test Equipment

The test equipment recommended for the performance verification and adjustment procedures is listed below. If the exact instrument is not available, substitute calibration standards of equivalent accuracy.

Instrument	Requirements	Recommended Model	Use[*]
Digital Multimeter	Resolution: 10 nV @ 1V; Readout: 8 1/2 digits Accuracy: 20 ppm	Agilent 3458A	V, C
Current Shunt	15 A (0.1Ω) 0.04%, TC=5ppm/ΩC 100 A (0.01Ω) 0.04%, TC=5ppm/ΩC 300 A (0.001Ω) 0.04%, TC=5ppm/ΩC	Guildline 9230/15 Guildline 9230/100 Guildline 9230/300	V, C
Electronic load	80 V, 200 A minimum	2 - Agilent N3300A mainframes; 6 - Agilent N3305A modules	V
GPIB controller	Full GPIB capabilities	Agilent 82350B or equivalent	V, C
Oscilloscope	Sensitivity: 1 mV Bandwidth Limit: 20 MHz Probe: 1:1 with RF tip	Agilent Infiniium or equivalent	V
RMS Voltmeter	True RMS Bandwidth: 20 MHz Sensitivity: 100 µV	Rhode and Schwartz Model URE3 or equivalent	V
Differential Amplifier	Bandwidth: 20 MHz	LeCroy 1855A, DA1850A, or equivalent	V
Terminations	1 – 50Ω BNC termination 2 – 50Ω, 1/8 W termination resistors		V
Power Supply	80 V, 200 A, 2kW	Agilent N8754A, N8758A	V, C

* V=Verification C=Calibration

Verification Setups

A.

B.

C.

D.

Calibration Setups

DC voltmeter (A)
or
DC Power supply (E)

A. and E.

DC voltmeter

Current
shunt

B.

short

C.

SHARING
1 2 3

DC voltmeter

short

D.

Performance Verification

Voltage Programming and Readback Accuracy

Constant Voltage Load Effect

Constant Voltage Ripple and Noise

Transient Recovery Time

Current Programming and Readback Accuracy

Constant Current Load Effect

Current Sink Capability Verification

Introduction

Use the performance verification tests to verify that the power supply is operating normally and meets its published specifications. You can perform two different levels of performance verification tests:

- **Self-Test** A brief power-on self-test occurs automatically whenever you turn on the instrument. This limited test assures that the instrument is operational. For details, see Self-Test Procedures.

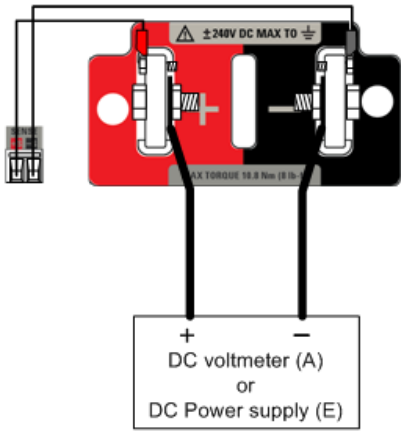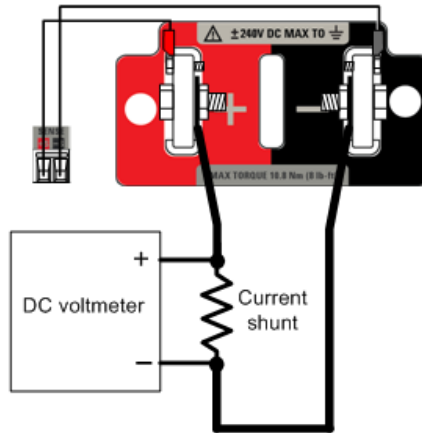- **Performance Verification Tests** An extensive set of tests that are recommended as an acceptance test when you first receive the instrument or after performing adjustments.

The performance verification tests are recommended as acceptance tests when you first receive the instrument. The acceptance test results should be compared against the instrument specifications. After acceptance, you should repeat the performance verification tests at every calibration interval.

Perform the verification tests before calibrating your power system. If the power supply passes the verification tests, the unit is operating within its calibration limits and does not need to be re-calibrated.

If the instrument fails any of the tests or if abnormal test results are obtained, try calibrating the unit. If calibration is unsuccessful, return the unit to an Agilent Technologies Service Center.

Refer to the Recommended Test Equipment and Setups section for a list of the equipment and test setups required for verification. Also refer to the Measurement Techniques section for information about connecting the voltmeter, current shunt, and load.

Voltage Programming and Readback Accuracy

This test verifies that the voltage programming and measurement functions are within specifications.

Step 1. Turn off the power supply and connect a DMM across the sense terminals (see Test Setup A). Do not connect the load.

Step 2. Turn on the power supply and program the instrument settings as described in the test record form under "Voltage Programming & Readback, Min Voltage". Turn the output on. The output status should be "CV" and the output current should be close to zero.

Step 3. Record the output voltage reading from the DMM and the voltage measured over the interface. The readings should be within the limits specified in the test record form for the appropriate model under "Voltage Programming & Readback, Minimum Voltage".

Step 4. Program the instrument settings as described in the test record form under "Voltage Programming & Readback, High Voltage".

Step 5. Record the output voltage reading from the DMM and the voltage measured over the interface. The readings should be within the limits specified in the test record form for the appropriate model under "Voltage Programming & Readback, High Voltage".

Constant Voltage Load Effect

This test measures the change in output voltage resulting from a change in output current from full load to no load.

Step 1. Turn off the power supply and connect a DMM and an electronic load (see Test Setup A).

Step 2. Turn on the power supply and program the instrument settings as described in the test record form under "CV Load Effect".

Step 3. Set the electronic load for the output current as described in the test record form under "CV Load Effect". The output status should be "CV". If it isn't, adjust the load so that the output current drops slightly.

Step 4. Record the output voltage reading from the DMM.

Step 5. Open the load. Record the voltage reading from the DMM again. The difference between the DMM readings in steps 4 and 5 is the load effect, which should not exceed the value listed in the test record form for the appropriate model under "CV Load Effect".

Constant Voltage Ripple and Noise

Periodic and random deviations in the output combine to produce a residual AC voltage superimposed on the DC output voltage. This residual voltage is specified as the rms or peak-to-peak noise in the indicated frequency range (see Specifications).

Step 1. Turn off the power supply and connect an electronic load, differential amplifier, and an oscilloscope (ac coupled) to the output (see Test Setup C).

Step 2. As shown in the diagram, use two BNC cables terminated by a 50 Ω resistor to connect the differential amplifier to the + and - output terminals. The shields of the two BNC cables should be connected together. Connect the output of the differential amplifier to the oscilloscope with a 50 Ω termination at the input of the oscilloscope.

Step 3. Set the differential amplifier to multiply by ten, divide by one, and 1 MΩ input resistance. The positive and negative inputs of the differential amplifier should be set to AC coupling. Set the oscilloscope's time base to 5 ms/div, and the vertical scale to 10 mV/div. Turn the bandwidth limit on (usually 20 MHz), and set the sampling mode to peak detect.

Step 4. Program the power system to the settings indicated in the in the test record form for the appropriate model under "CV Ripple and Noise" and enable the output. Let the oscilloscope run for a few seconds to generate enough measurement points. On the Agilent Infiniium scope, the maximum peak-to-peak voltage measurement is indicated at the bottom of the screen on the right side. Divide this value by 10 to get the CV peak-to-peak noise measurement. The result should not exceed the peak-to-peak limits in the test record form for the appropriate model under "CV Ripple and Noise, peak-to-peak".

> **NOTE** If the measurement contains any question marks, clear the measurement and try again. This means that some of the scope data received was questionable.

Step 5. Disconnect the oscilloscope and connect an rms voltmeter in its place. Do not disconnect the 50 ohm termination. Divide the reading of the rms voltmeter by 10. The result should not exceed the rms limits in the test record form for the appropriate model under "CV Ripple and Noise, rms".

Transient Recovery Time

This test measures the time for the output voltage to recover to within the specified value following a 50% change in the load current.

Step 1. Turn off the power supply and connect an oscilloscope across the sense terminals (see Test Setup A). Connect an electronic load to the output terminals.

Step 2. Turn on the power supply and program the instrument settings as described in the test record form under "Transient Response".

Step 3. Set the electronic load to operate in constant current mode. Program its load current to the lower current value indicated in the test record form under "Transient Response".

Step 4. Set the electronic load's transient generator frequency to 100 Hz and its duty cycle to 50%.

Step 5. Program the load's transient current level to the higher current value indicated in the test record form under "Transient Response", and turn the transient generator on.

Step 6. Adjust the oscilloscope for a waveform similar to that shown in the following figure.
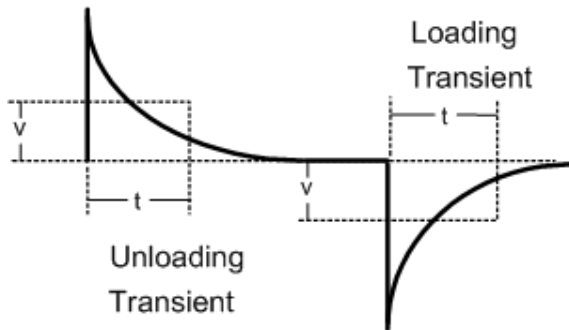
Step 7. The output voltage should return to within the specified voltage at the specified time following the 50% load change. Check both loading and unloading transients by triggering on the positive and negative slope. Record the voltage at time "t" in the performance test record form under "Transient Response".

Current Programming and Readback Accuracy

This test verifies that the current programming and measurement functions are within specifications.

Step 1. Turn off the power supply and connect the current shunt directly across the output terminals. Connect the DMM directly across the current shunt (see Test Setup B). Note that the electronic load is not used in this portion of the test.

Step 2. Turn on the power supply and program the instrument settings as described in the test record form under "Current Programming & Readback, Min Current". The output status should be "CC", and the output voltage should be close to zero. Then wait 5 minutes for the temperature to settle before continuing.

Step 3. Divide the voltage drop (DMM reading) across the current shunt by the shunt resistance to convert to amps and record this value. Also, record the current measured over the interface. The readings should be within the limits specified in the test record form for the appropriate model under "Current Programming & Readback, Minimum Current".

Step 4. Program the instrument settings as described in the test record form under "Current Programming & Readback, High Current". Then wait 5 minutes for the temperature to settle before continuing.

Step 5. Divide the voltage drop (DMM reading) across the current shunt by the shunt resistance to convert to amps and record this value. Also, record the current reading measured over the interface. The readings should be within the limits specified in the test record form for the appropriate model under "Current Programming & Readback, High Current".

Step 6. For N7900 models only, set the current measurement to the low range. Set the instrument as described under "Current Readback, Low Current". Then wait 5 minutes for the temperature to settle before continuing.

Step 7. Record the current measured over the interface. The readings should be within the limits specified under "Low Current Readback Low Range".

Constant Current Load Effect

This test measures the change in output current resulting from a change in output voltage from full scale to short circuit.

Step 1. Turn off the power supply and connect the current shunt, DMM, and electronic load (see Test Setup B). Connect the DMM directly across the current shunt.

Step 2. Turn on the power supply and program the instrument settings as described in the test record under "CC Load Effect".

Step 3. Set the electronic load for CV mode and program it to the output's voltage as described in the test record under "CC Load Effect". The output status should be "CC". If it isn't, adjust the load so that the output voltage drops slightly.

Step 4. Divide the voltage drop (DMM reading) across the current shunt by the shunt resistance to convert to amps and record this value.

Step 5. Short the electronic load. Divide the voltage drop (DMM reading) across the current shunt by the shunt resistance to convert to amps and record this value. The difference in the current readings in steps 4 and 5 is the load effect, which should not exceed the value listed in the test record for the appropriate model under "CC Load Effect".

Current Sink Capability Verification

This test checks the ability of the power supply to sink up to 10% of its rated output current. If one or more Agilent N6709A Power Dissipators are connected, this test verifies that the power supply can sink up to 100% of its rated output current.

Step 1. Turn off the power supply and connect an external power supply to the + and - output terminals (see Test Setup D). Connect the power dissipator as shown if you are verifying 100 % of the current sinking capability the power supply.

Step 2. Set the external supply as follows: Voltage setting = 100 % of the rated output voltage of the power supply under test. Current limit setting = 110 % of the rated output current of the power supply under test.

Step 3. Turn on the power supply under test. Set the operating mode to Current Priority. Program the instrument settings as described in the test record under "Current Sink Verification".

Step 4. Check the front panel display of the power supply and verify that the supply is sinking either 10% or 100 % of its rated current. Divide the voltage drop (DMM reading) across the current shunt by the shunt resistance to convert to amps and record this value. The readings should be within the limits specified in the test record form for the appropriate model under "Current Sink Tests".

NOTE   If you are checking the current sink capability of a 2 kW unit connected to only one power dissipator unit (@ 50% of the power supply's rated current), divide the 100% values in the test record form in half.

Calibration Procedure

Enter Calibration Mode

Voltage Calibration

Voltage Common Mode Rejection Ratio Calibration

Current Calibration

Current Temperature Coefficient Calibration

Current Sharing Calibration

Resistance Bottom-Out Calibration

Enter a Calibration Date

Save Calibration and Log Out

Introduction

The instrument features closed-case electronic calibration; no internal mechanical adjustments are required. The instrument calculates correction factors based on input reference values that you set and stores correction factors in non-volatile memory until the next calibration adjustment is performed. This EEPROM calibration memory is not changed by cycling power or *RST.

Refer to the Recommended Test Equipment and Setups section for a list of the equipment and test setups required for calibration. Also refer to the Measurement Techniques section for information about connecting the voltmeter, current shunt, and load. Additional information about calibration follows.

- The correct password is required to enter the Admin menu, which contains the calibration function. The password is pre-set to 0 (zero). You can change the password once calibration mode is entered to prevent unauthorized access to the calibration mode. Refer to Password Protection for more information.

- When calibrating the unit using SCPI commands, most steps involve sending a *OPC? query to synchronize with the power system's command completion before proceeding. The response from the instrument must be read each time *OPC? is given. In some steps, it may take up to 30 seconds for *OPC? to respond.

- Once started, you must perform the complete calibration procedure in its entirety. As each calibration section is completed, the instrument calculates new calibration constants and begins using them. However, these constants are not saved in nonvolatile memory until a SAVE command is explicitly given.

- Exit the calibration mode either by logging out of the Admin menu or by sending CAL:STAT OFF. Note that any calibration section that was calibrated but not saved will revert to its previous calibration constants.

Enter Calibration Mode

Front Panel	SCPI Command
Select **System\Admin\Login**. Enter your password in the Password field. Then press **Select**.	CAL:STAT ON <password>

Voltage Calibration

Voltage Programming and Measurement

Step 1. Connect the voltage input of the Agilent 3458A DMM to the output (see Cal Setup A).

Step 2. Select the voltage programing and measurement calibration.

Front Panel	SCPI Command
Select **System\Admin\CAL\Vprog**.	Specify the full-scale voltage range. Full scale ranges vary by model. This selects the 60 V range: CAL:VOLT 60

Step 3. Select the first voltage calibration point.

Front Panel	SCPI Command
Check that the voltmeter is connected and select Next.	CAL:LEV P1 *OPC?

Step 4. Measure the output voltage with the DMM and enter the data.

Front Panel	SCPI Command
Display shows: "Enter P1 measured data" Select the Measured Data field. Enter the data from the external DMM. Press Enter when done.	CAL:DATA <data>

Step 5. Select the second voltage calibration point.

Front Panel	SCPI Command
Select Next.	CAL:LEV P2 *OPC?

Step 6. Measure the output voltage with the DMM and enter the data.

Front Panel	SCPI Command
Display shows: "Enter P2 measured data" Select the Measured Data field. Enter the data from the external DMM. Press Enter when done. Press Back to finish.	CAL:DATA <data>

Voltage Common Mode Rejection Ratio Calibration

Step 1. Make the connections shown in Cal Setup C. Connect an external jumper between the +sense and the - sense terminals. Also connect the + sense terminal to the +output terminal. Do not connect anything to the −output terminals The procedure is automatic and only takes a few seconds.

Step 2. Select the common mode rejection ratio calibration.

Front Panel	SCPI Command
Select **System\Admin\CAL\Misc\CMRR**. Check that the leads are connected as described and select Next.	CAL:VOLT:CMRR *OPC?

Step 3. After the calibration completes, reconnect the sense wiring.

Current Temperature Coefficient Calibration

NOTE The temperature coefficient calibration procedure must be performed **Before** any other current calibration procedures.

Step 1. Connect a precision shunt resistor to the output. The shunt resistor must be able to measure the output's **full-scale** current (see Cal Setup B). Connect the Agilent 3458A DMM across the shunt resistor.

Step 2. Select the temperature coefficient calibration.

Front Panel	SCPI Command
Select **System\Admin\CAL\Misc\CurrTC**.	CAL:CURR:TC

Step 3. Select the first current calibration point. Then wait 5 minutes for the temperature to settle before continuing.

Front Panel	SCPI Command
Check that the shunt is connected and select Next. Wait 5 minutes, then select Next again.	CAL:LEV P1 *OPC?

Step 4. Calculate the shunt current (I=V/R) and enter the data..

Front Panel	SCPI Command
Display shows: "Enter P1 measured data" Select the Measured Data field. Enter the data from the external DMM. This should be about 50% of the full-scale current rating. Press Enter when done.	CAL:DATA <data>

Step 5. Select the second current calibration point. Then wait 5 minutes for the temperature to settle before continuing.

Front Panel	SCPI Command
Wait 5 minutes, then select Next.	CAL:LEV P2 *OPC?

Step 6. Calculate the shunt current (I=V/R) and enter the data..

Front Panel	SCPI Command
Display shows: "Enter P2 measured data" Select the Measured Data field. Enter the data from the external DMM. This should be about 79% of the full-scale current rating. Press Enter when done.	CAL:DATA <data>

Step 7. Select the third current calibration point. Then wait 5 minutes for the temperature to settle before continuing.

Front Panel	SCPI Command
Wait 5 minutes, then select Next.	CAL:LEV P3 *OPC?

Step 8. Calculate the shunt current (I=V/R) and enter the data.

Front Panel	SCPI Command
Display shows: "Enter P3 measured data" Select the Measured Data field. Enter the data from the external DMM. This should be about 100% of the full-scale current rating. Press Enter when done. Press Back to finish.	CAL:DATA <data>

Current Calibration

Current Programming and High Range Measurement

Step 1. Disconnect all equipment form the output terminals.

Step 2. Select the current programing and high range measurement calibration.

Front Panel	SCPI Command
Select **System\Admin\CAL\Curr\Iprog**.	Specify the full-scale current range. Full scale ranges vary by model. This selects the 50 A range: CAL:CURR 50

Step 3. Select the first current calibration point. Then wait 5 minutes for the temperature to settle before continuing.

Front Panel	SCPI Command
Check that nothing is connected to the output and select Next. Wait 5 minutes, then select Next again.	CAL:LEV P1 *OPC?

Step 4. Connect a precision shunt resistor to the output. The shunt resistor should be able to measure at least 70% of the output's full-scale current (see Cal Setup B). Connect the Agilent 3458A DMM across the shunt resistor.

Step 5. Select the second current calibration point. Then wait 5 minutes for the temperature to settle before continuing.

Front Panel	SCPI Command
Check that the shunt is connected and select Next. Wait 5 minutes, then select Next again.	CAL:LEV P2 *OPC?

Step 6. Calculate the shunt current (I=V/R) and enter the data.

Front Panel	SCPI Command
Display shows: "Enter P2 measured data" Select the Measured Data field. Enter the data from the external DMM. This should be about 70% of the full-scale current rating. Press Enter when done. Press Back to finish.	CAL:DATA <data>

Current Low Range Measurement

Step 1. Disconnect all equipment form the output terminals.

Step 2. Select the current low range measurement calibration.

Front Panel	SCPI Command
Select **System\Admin\CAL\Curr\Imeas**.	Specify the low range measurement. Low ranges vary by model. This selects the 2 A range: CAL:CURR:MEAS 2

Step 3. Select the first current calibration point. Then wait 5 minutes for the temperature to settle before continuing.

Front Panel	SCPI Command
Check that the shunt is connected and select Next. Wait 5 minutes, then select Next again.	CAL:LEV P1 *OPC?

Step 4. Connect a precision shunt resistor to the output. The shunt resistor should be able to measure the full-scale current of the low range (see Cal Setup B). Connect the Agilent 3458A DMM across the shunt resistor.

Step 5. Select the second current calibration point. There is no wait required for the second point.

Front Panel	SCPI Command
Check that the shunt is connected and select Next.	CAL:LEV P2 *OPC?

Step 6. Calculate the shunt current (I=V/R) and enter the data..

Front Panel	SCPI Command
Display shows: "Enter P2 measured data" Select the Measured Data field. Enter the data from the external DMM. This should be about 100% of the full-scale low range rating. Press Enter when done. Press Back to finish.	CAL:DATA <data>

Current Sharing Calibration

This procedure calibrates the Imon signal that is used when units are connected in parallel.

Step 1. Connect a short across the + and - output terminals. Connect the Agilent 3458A DMM across pins 2 and 3 of the Sharing connector (see Cal Setup D).

Step 2. Select the current sharing calibration.

Front Panel	SCPI Command
Select **System\Admin\CAL\Misc\CurrShar**.	CAL:CURR:SHAR

Step 3. Select the first calibration point.

Front Panel	SCPI Command
Check that the short is connected and select Next.	CAL:LEV P1 *OPC?

Step 4. Measure the voltage across the sharing connector and enter the data.

Front Panel	SCPI Command
Display shows: "Enter P1 measured data" Select the Measured Data field. Enter the data from the external DVM. This should be about -1 volt. Press Enter when done. Press Back to finish.	CAL:DATA <data>

Step 5. After the calibration completes, disconnect the voltmeter and short.

Resistance Bottom-Out Calibration

This procedure calibrates the minimum voltage that can be achieved while sinking current.

Step 1. Connect an external power supply to the + and - output terminals (see Cal Setup E).

Step 2. Set the external supply as follows: Voltage setting = (0.9 V + 0.08 * rated output voltage of the power supply) volts. The voltage must be within 10% of this value. Current limit = (0.95 * rated output current of the power supply) amps. The current limit must be within 2% of this value.

Step 3. Select the resistance bottom-out calibration. Calibration takes approximately 5 seconds.

Front Panel	SCPI Command
Select **System\Admin\CAL\Misc\ResBout**. Check that the power supply is connected and select Next.	CAL:RES:BOUT *OPC?

Step 4. After the calibration completes, disconnect the power supply.

Enter a Calibration Date

Front Panel	SCPI Command
Select **System\Admin\CAL\DATE**. Enter the calibration date in the Date field. If desired, you can enter alphanumeric data in this field.	CAL:DATE "<date>"

Save Calibration and Log Out

Front Panel	SCPI Command
Select **System\Admin\CAL\SAVE**. Select Save to save all calibration data. Select **System\Admin\Logout** to exit calibration mode.	To save calibration data: CAL:SAVE To exit calibration mode: CAL:STAT OFF

Test Record Forms

N6950A/N6970A

N6950A/N6970A Test Record	Report Number _____		Date_____	
Test Description	**Model**	**Min. Specs**	**Results**	**Max. Specs**

Voltage Programming & Readback
  Minimum voltage (Vout):
  Voltage measured over interface:
  High voltage (Vout):
  Voltage measured over interface:
	
	Both
	Both
	Both
	Both
		
		− 7.5 mV
		Vout − 1.5 mV
		8.9958 V
		Vout − 4.2 mV
			
			_____
			_____
			_____
			_____
				
				+ 10.5 mV
				Vout + 1.5 mV
				9.0042 V
				Vout + 4.2 mV

CV Load Effect:	Both	− 0.5 mV	_____	+ 0.5 mV

CV Ripple and Noise
  peak-to-peak:
  rms:
	
	Both
	Both
		
		N/A
		N/A
			
			_____
			_____
				
				+ 9 mV
				+ 1 mV

Transient response @ 100 µs:	Both	− 150 mV	_____	+ 150 mV

Current Programming & Readback
  Minimum current (Iout):
 	
  Current measured over interface:
 	
  High current (Iout):
 	
  Current measured over interface:
	
	N6950A
	N6970A
	N6950A
	N6970A
	N6950A
	N6970A
	N6950A
	N6970A
		
		− 30 mA
		− 60 mA
		Iout − 30 mA
		Iout − 60 mA
		99.87 A
		199.74 A
		Iout − 0.13 A
		Iout − 0.26 A
			
			_____
			_____
			_____
			_____
			_____
			_____
			_____
			_____
				
				+ 30 mA
				+ 60 mA
				Iout + 30 mA
				Iout + 60 mA
				100.13 A
				200.26 A
				Iout + 0.13 A
				Iout + 0.26 A

CC Load Effect:	N6950A N6970A	− 8 mA − 15 mA	_____ _____	+ 8 mA + 15 mA

Current Sink Tests
  10% of current rating:
 	
  100% of current rating:
	
	N6950A
	N6970A
	N6950A
	N6970A
		
		− 9.96 A
		− 19.92 A
		− 99.87 A
		− 199.74 A
			
			_____
			_____
			_____
			_____
				
				− 10.04 A
				− 20.08 A
				− 100.13 A
				− 200.26 A

	N6950A Settings		**N6970A Settings**	
Voltage Programming & Readback Min: Voltage Programming & Readback High: CV Load Effect, CV Ripple and Noise: Transient Response: Current Programming & Readback Min: Current Programming & Readback High: CC Load Effect: 10% of current rating (Isink): 100% of current rating (Isink):	Voltage priority: 9 mV, 100 A Voltage priority: 9 V, 100 A Voltage priority: 9 V, 100 A Voltage priority: 9 V, 50 A to 100 A Current priority: 9 V, 0 A Current priority: 9 V, 100 A Current priority: 9 V, 100 A Current priority: 9 V, - 10 A External supply: 9 V, 11 A Current priority: 9 V, - 100 A External supply: 9 V, 110 A		Voltage priority: 9 mV, 200 A Voltage priority: 9 V, 200 A Voltage priority: 9 V, 200 A Voltage priority: 9 V, 100 A to 200 A Current priority: 9 V, 0 A Current priority: 9 V, 200 A Current priority: 9 V, 200 A Current priority: 9 V, - 20 A External supply: 9 V, 22 A Current priority: 9 V, - 200 A External supply: 9 V, 220 A	

N6951A/N6971A

N6951A/N6971A Test Record	Report Number _____		Date_____	
Test Description	**Model**	**Min. Specs**	**Results**	**Max. Specs**

Voltage Programming & Readback
    Minimum voltage (Vout):
    Voltage measured over interface:
    High voltage (Vout):
    Voltage measured over interface:
	Both
	Both
	Both
	Both
		– 17 mV
		Vout – 3 mV
		19.991 V
		Vout – 9 mV
			_____
			_____
			_____
			_____
				+ 23 mV
				Vout + 3 mV
				20.009 V
				Vout + 9 mV

CV Load Effect:	Both	– 0.75 mV	_____	+ 0.75 mV

CV Ripple and Noise
    peak-to-peak:
    rms:
	Both
	Both
		N/A
		N/A
			_____
			_____
				+ 9 mV
				+ 1 mV

Transient response @ 100 µs:	Both	– 150 mV	_____	+ 150 mV

Current Programming & Readback
    Minimum current (Iout):
 	
    Current measured over interface:
 	
    High current (Iout):
 	
    Current measured over interface:
	N6951A
	N6971A
	N6951A
	N6971A
	N6951A
	N6971A
	N6951A
	N6971A
		– 15 mA
		– 30 mA
		Iout – 15 mA
		Iout – 30 mA
		49.935 A
		99.87 A
		Iout – 0.065 A
		Iout – 0.13 A
			_____
			_____
			_____
			_____
			_____
			_____
			_____
			_____
				+ 15 mA
				+ 30 mA
				Iout + 15 mA
				Iout + 30 mA
				50.065 A
				100.013 A
				Iout + 0.065 A
				Iout + 0.013 A

CC Load Effect:	N6951A N6971A	– 3 mA – 6 mA	_____ _____	+ 3 mA + 6 mA

Current Sink Tests
    10% of current rating:
 	
    100% of current rating:
	N6951A
	N6971A
	N6951A
	N6971A
		– 4.98 A
		– 9.96 A
		– 49.935 A
		– 99.87 A
			_____
			_____
			_____
			_____
				– 5.02 A
				– 10.04 A
				– 50.065 A
				– 100.13 A

		N6951A Settings	**N6971A Settings**	
Voltage Programming & Readback Min: Voltage Programming & Readback High: CV Load Effect, CV Ripple and Noise: Transient Response: Current Programming & Readback Min: Current Programming & Readback High: CC Load Effect: 10% of current rating (Isink): 100% of current rating (Isink):		Voltage priority: 20 mV, 50 A Voltage priority: 20 V, 50 A Voltage priority: 20 V, 50 A Voltage priority: 20 V, 25 A to 50 A Current priority: 20 V, 0 A Current priority: 20 V, 50 A Current priority: 20 V, 50 A Current priority: 20 V, - 5 A External supply: 20 V, 5.5 A Current priority: 20 V, - 50 A External supply: 20 V, 55 A	Voltage priority: 20 mV, 100 A Voltage priority: 20 V, 100 A Voltage priority: 20 V, 100 A Voltage priority: 20 V, 50 A to 100 A Current priority: 20 V, 0 A Current priority: 20 V, 100 A Current priority: 20 V, 100 A Current priority: 20 V, - 10 A External supply: 20 V, 11 A Current priority: 20 V, - 100 A External supply: 20 V, 110 A	

N6952A/N6972A

N6952A/N6972A Test Record	Report Number _____		Date_____	
Test Description	**Model**	**Min. Specs**	**Results**	**Max. Specs**

Voltage Programming & Readback
   Minimum voltage (Vout):
   Voltage measured over interface:
   High voltage (Vout):
   Voltage measured over interface:
	Both
	Both
	Both
	Both
		– 34 mV
		Vout – 6 mV
		39.982 V
		Vout – 18 mV
			_____
			_____
			_____
			_____
				+ 46 mV
				Vout + 6 mV
				40.018 V
				Vout + 18 mV

CV Load Effect:	Both	– 1.5 mV	_____	+ 1.5 mV

CV Ripple and Noise
   peak-to-peak:
   rms:
	Both
	Both
		N/A
		N/A
			_____
			_____
				+ 9 mV
				+ 1 mV

Transient response @ 100 µs:	Both	– 100 mV	_____	+ 100 mV

Current Programming & Readback
   Minimum current (Iout):
 	
   Current measured over interface:
 	
   High current (Iout):
 	
   Current measured over interface:
	N6952A
	N6972AN6952A
	N6972A
	N6952A
	N6972A
	N6952A
	N6972A
		– 8 mA
		– 15 mA
		Iout – 8 mA
		Iout – 15 mA
		24.967 A
		49.935 A
		Iout – 0.033 A
		Iout – 0.065 A
			_____
			_____
			_____
			_____
			_____
			_____
			_____
			_____
				+ 8 mA
				+ 15 mA
				Iout + 8 mA
				Iout + 15 mA
				25.033 A
				50.065 A
				Iout + 0.033 A
				Iout + 0.065 A

CC Load Effect:	N6952A N6972A	– 1 mA – 1.5 mA	_____ _____	+ 1 mA + 1.5 mA

Current Sink Tests
   10% of current rating:
 	
   100% of current rating:
	N6952A
	N6972A
	N6952A
	N6972A
		– 2.4895 A
		– 4.98 A
		– 24.967 A
		– 49.935 A
			_____
			_____
			_____
			_____
				– 2.5105 A
				– 5.02 A
				– 25.033 A
				– 50.065 A

		N6952A Settings	**N6972A Settings**	
Voltage Programming & Readback Min: Voltage Programming & Readback High: CV Load Effect, CV Ripple and Noise: Transient Response: Current Programming & Readback Min: Current Programming & Readback High: CC Load Effect: 10% of current rating (Isink): 100% of current rating (Isink):		Voltage priority: 40 mV, 25 A Voltage priority: 40 V, 25 A Voltage priority: 40 V, 25 A Voltage priority: 40 V, 12.5 A to 25 A Current priority: 40 V, 0 A Current priority: 40 V, 25 A Current priority: 40 V, 25 A Current priority: 40 V, - 2.5 A External supply: 40 V, 2.75 A Current priority: 40 V, - 25 A External supply: 40 V, 27.5 A	Voltage priority: 40 mV, 50 A Voltage priority: 40 V, 50 A Voltage priority: 40 V, 50 A Voltage priority: 40 V, 25 A to 50 A Current priority: 40 V, 0 A Current priority: 40 V, 50 A Current priority: 40 V, 50 A Current priority: 40 V, - 5 A External supply: 40 V, 5.5 A Current priority: 40 V, - 50 A External supply: 40 V, 55 A	

N6953A/N6973A

N6953A/N6973A Test Record	Report Number _____		Date_____	
Test Description	**Model**	**Min. Specs**	**Results**	**Max. Specs**

Voltage Programming & Readback
  Minimum voltage (Vout):
  Voltage measured over interface:
  High voltage (Vout):
  Voltage measured over interface:
	
	Both
	Both
	Both
	Both
		
		− 51 mV
		Vout − 9 mV
		59.973 V
		Vout − 27 mV
			
			_____
			_____
			_____
			_____
				
				+ 69 mV
				Vout + 9 mV
				60.027 V
				Vout + 27 mV

CV Load Effect:	Both	− 2 mV	_____	+ 2 mV

CV Ripple and Noise
  peak-to-peak:
  rms:
	
	Both
	Both
		
		N/A
		N/A
			
			_____
			_____
				
				+ 9 mV
				+ 1 mV

Transient response @ 100 μs:	Both	− 150 mV	_____	+ 150 mV

Current Programming & Readback
  Minimum current (Iout):
 	
  Current measured over interface:
 	
  High current (Iout):
 	
  Current measured over interface:
	
	N6953A
	N6973A
	N6953A
	N6973A
	N6953A
	N6973A
	N6953A
	N6973A
		
		− 5 mA
		− 10 mA
		Iout − 5 mA
		Iout − 10 mA
		16.6783 A
		33.2567 A
		Iout − 0.0217 A
		Iout − 0.0433 A
			
			_____
			_____
			_____
			_____
			_____
			_____
			_____
			_____
				
				+ 5 mA
				+ 10 mA
				Iout + 5 mA
				Iout + 10 mA
				16.7217 A
				33.3433 A
				Iout + 0.0217 A
				Iout + 0.0433 A

CC Load Effect:	N6953A N6973A	− 1 mA − 1.5 mA	_____ _____	+ 1 mA + 1.5 mA

Current Sink Tests
  10% of current rating:
 	
  100% of current rating:
	
	N6953A
	N6973A
	N6953A
	N6973A
		
		− 1.6633 A
		− 3.3167 A
		− 16.6783 A
		− 33.2567 A
			
			_____
			_____
			_____
			_____
				
				− 1.6767 A
				− 3.3433 A
				− 16.7217 A
				− 33.3433 A

		N6953A Settings	**N6973A Settings**	
Voltage Programming & Readback Min: Voltage Programming & Readback High: CV Load Effect, CV Ripple and Noise: Transient Response: Current Programming & Readback Min: Current Programming & Readback High: CC Load Effect: 10% of current rating (Isink): 100% of current rating (Isink):		Voltage priority: 60 mV, 16.7 A Voltage priority: 60 V, 16.7 A Voltage priority: 60 V, 16.7 A Voltage priority: 60 V, 8.35 A to 16.7 A Current priority: 60 V, 0 A Current priority: 60 V, 16.7 A Current priority: 60 V, 16.7 A Current priority: 60 V, - 1.67 A External supply: 60 V, 1.837 A Current priority: 60 V, - 16.7 A External supply: 60 V, 18.37 A	Voltage priority: 60 mV, 33.3 A Voltage priority: 60 V, 33.3 A Voltage priority: 60 V, 33.3 A Voltage priority: 60 V, 16.7 A to 33.3 A Current priority: 60 V, 0 A Current priority: 60 V, 33.3 A Current priority: 60 V, 33.3 A Current priority: 60 V, - 3.33 A External supply: 60 V, 3.66 A Current priority: 60 V, - 33.3 A External supply: 60 V, 36.6 A	

N6954A/N6974A

N6954A/N6974A Test Record	Report Number _____		Date_____	
Test Description	Model	Min. Specs	Results	Max. Specs

Voltage Programming & Readback
    Minimum voltage (Vout):
    Voltage measured over interface:
    High voltage (Vout):
    Voltage measured over interface:
	Both
	Both
	Both
	Both
		– 68 mV
		Vout – 12 mV
		79.964 V
		Vout – 36 mV
			_____
			_____
			_____
			_____
				+ 92 mV
				Vout + 12 mV
				80.036 V
				Vout + 36 mV

CV Load Effect:	Both	– 2 mV	_____	+ 2 mV

CV Ripple and Noise
    peak-to-peak:
    rms:
	Both
	Both
		N/A
		N/A
			_____
			_____
				+ 9 mV
				+ 1 mV

Transient response @ 100 µs:	Both	– 200 mV	_____	+ 200 mV

Current Programming & Readback
    Minimum current (Iout):
 	
    Current measured over interface:
 	
    High current (Iout):
 	
    Current measured over interface:
	N6954A
	N6974A
	N6954A
	N6974A
	N6954A
	N6974A
	N6954A
	N6974A
		– 4 mA
		– 8 mA
		Iout – 4 mA
		Iout – 8 mA
		12.4835 A
		24.967 A
		Iout – 0.0165 A
		Iout – 0.033 A
			_____
			_____
			_____
			_____
			_____
			_____
			_____
			_____
				+ 4 mA
				+ 8 mA
				Iout + 4 mA
				Iout + 8 mA
				12.5165 A
				25.033 A
				Iout + 0.0165 A
				Iout + 0.033 A

CC Load Effect:	N6954A N6974A	– 0.8 mA – 1.5 mA	_____ _____	+ 0.8 mA + 1.5 mA

Current Sink Tests
    10% of current rating:
 	
    100% of current rating:
	N6954A
	N6974A
	N6954A
	N6974A
		– 1.2488 A
		– 2.4895 A
		– 12.4835 A
		– 24.967 A
			_____
			_____
			_____
			_____
				– 1.2553 A
				– 2.5105 A
				– 12.5165 A
				– 25.033 A

		N6954A Settings	N6974A Settings	
Voltage Programming & Readback Min: Voltage Programming & Readback High: CV Load Effect, CV Ripple and Noise: Transient Response: Current Programming & Readback Min: Current Programming & Readback High: CC Load Effect: 10% of current rating (Isink): 100% of current rating (Isink):		Voltage priority: 80 mV, 12.5 A Voltage priority: 80 V, 12.5 A Voltage priority: 80 V, 12.5 A Voltage priority: 80 V, 6.25 A to 12.5 A Current priority: 80 V, 0 A Current priority: 80 V, 12.5 A Current priority: 80 V, 12.5 A Current priority: 80 V, - 1.25 A External supply: 80 V, 1.375 A Current priority: 80 V, - 12.5 A External supply: 80 V, 13.75 A	Voltage priority: 80 mV, 25 A Voltage priority: 80 V, 25 A Voltage priority: 80 V, 25 A Voltage priority: 80 V, 12.5 A to 25 A Current priority: 80 V, 0 A Current priority: 80 V, 25 A Current priority: 80 V, 25 A Current priority: 80 V, - 2.5 A External supply: 80 V, 2.75 A Current priority: 80 V, - 25 A External supply: 80 V, 27.5 A	

N7950A/N7970A

N7950A/N7970A Test Record	Report Number _____		Date_____	
Test Description	**Model**	**Min. Specs**	**Results**	**Max. Specs**
Voltage Programming & Readback Minimum voltage (Vout): Voltage measured over interface: High voltage (Vout): Voltage measured over interface:	Both Both Both Both	– 8 mV Vout – 1 mV 8.9963 V Vout – 3.7 mV	_____ _____ _____ _____	+ 10 mV Vout + 1 mV 9.0037 V Vout + 3.7 mV
CV Load Effect:	Both	– 0.5 mV	_____	+ 0.5 mV
CV Ripple and Noise peak-to-peak: rms:	Both Both	N/A N/A	_____ _____	+ 9 mV + 1 mV
Transient response @ 100 µs:	Both	– 150 mV	_____	+ 150 mV
Current Programming & Readback Minimum current (Iout): Current measured over interface: High current (Iout): Current measured over interface:	N7950A N7970A N7950A N7970A N7950A N7970A N7950A N7970A	– 15 mA – 30 mA Iout – 15 mA Iout – 30 mA 99.945 A 199.89 A Iout – 0.055 A Iout – 0.11 A	_____ _____ _____ _____ _____ _____ _____ _____	+ 15 mA + 30 mA Iout + 15 mA Iout + 30 mA 100.055 A 200.11 A Iout + 0.055 A Iout + 0.11 A
Low Current Measurement Range:	N7950A N7970A	Iout – 0.008 A Iout – 0.016 A	_____ _____	Iout + 0.008 A Iout + 0.016 A
CC Load Effect:	N7950A N7970A	– 8 mA – 15 mA	_____ _____	+ 8 mA + 15 mA
Current Sink Tests 10% of current rating: 100% of current rating:	N7950A N7970A N7950A N7970A	– 9.981 A – 19.962 A – 99.945 A – 199.89 A	_____ _____ _____ _____	– 10.019 A – 20.038 A – 100.055 A – 200.11 A
	N7950A Settings		**N7970A Settings**	
Voltage Programming & Readback Min: Voltage Programming & Readback High: CV Load Effect, CV Ripple and Noise: Transient Response: Current Programming & Readback Min: Current Programming & Readback High: Low Current Measurement Range: CC Load Effect: 10% of current rating (Isink): 100% of current rating (Isink):	Voltage priority: 9 mV, 100 A Voltage priority: 9 V, 100 A Voltage priority: 9 V, 100 A Voltage priority: 9 V, 50 A to 100 A Current priority: 9 V, 0 A Current priority: 9 V, 100 A Current priority: 9 V, 10 A Current priority: 9 V, 100 A Current priority: 9 V, - 10 A External supply: 9 V, 11 A Current priority: 9 V, - 100 A External supply: 9 V, 110 A		Voltage priority: 9 mV, 200 A Voltage priority: 9 V, 200 A Voltage priority: 9 V, 200 A Voltage priority: 9 V, 100 A to 200 A Current priority: 9 V, 0 A Current priority: 9 V, 200 A Current priority: 9 V, 20 A Current priority: 9 V, 200 A Current priority: 9 V, - 20 A External supply: 9 V, 22 A Current priority: 9 V, - 200 A External supply: 9 V, 220 A	

N7951A/N7971A

N7951A/N7971A Test Record	Report Number _____		Date_____	
Test Description	**Model**	**Min. Specs**	**Results**	**Max. Specs**
Voltage Programming & Readback				
Minimum voltage (Vout):	Both	− 18 mV	_____	+ 22 mV
Voltage measured over interface:	Both	Vout − 2 mV	_____	Vout + 2 mV
High voltage (Vout):	Both	19.992 V	_____	20.008 V
Voltage measured over interface:	Both	Vout − 8 mV	_____	Vout + 8 mV
CV Load Effect:	Both	− 0.75 mV	_____	+ 0.75 mV
CV Ripple and Noise				
peak-to-peak:	Both	N/A	_____	+ 9 mV
rms:	Both	N/A	_____	+ 1 mV
Transient response @ 100 μs:	Both	− 150 mV	_____	+ 150 mV
Current Programming & Readback				
Minimum current (Iout):	N7951A	− 8 mA	_____	+ 8 mA
	N7971A	− 15 mA	_____	+ 15 mA
Current measured over interface:	N7951A	Iout − 8 mA	_____	Iout + 8 mA
	N7971A	Iout − 15 mA	_____	Iout + 15 mA
High current (Iout):	N7951A	49.972 A	_____	50.028 A
	N7971A	99.945 A	_____	100.055 A
Current measured over interface:	N7951A	Iout − 0.028 A	_____	Iout + 0.028 A
	N7971A	Iout − 0.055 A	_____	Iout + 0.055 A
Low Current Measurement Range:	N7951A	Iout − 0.0035 A	_____	Iout + 0.0035 A
	N7971A	Iout − 0.007 A	_____	Iout + 0.007 A
CC Load Effect:	N7951A	− 3 mA	_____	+ 3 mA
	N7971A	− 6 mA	_____	+ 6 mA
Current Sink Tests				
10% of current rating:	N7951A	− 4.99 A	_____	− 5.01 A
	N7971A	− 9.981 A	_____	− 10.019 A
100% of current rating:	N7951A	− 49.972 A	_____	− 50.028 A
	N7971A	− 99.945 A	_____	− 100.055 A
	N7951A Settings		**N7971A Settings**	
Voltage Programming & Readback Min:	Voltage priority: 20 mV, 50 A		Voltage priority: 20 mV, 100 A	
Voltage Programming & Readback High:	Voltage priority: 20 V, 50 A		Voltage priority: 20 V, 100 A	
CV Load Effect, CV Ripple and Noise:	Voltage priority: 20 V, 50 A		Voltage priority: 20 V, 100 A	
Transient Response:	Voltage priority: 20 V, 25 A to 50 A		Voltage priority: 20 V, 50 A to 100 A	
Current Programming & Readback Min:	Current priority: 20 V, 0 A		Current priority: 20 V, 0 A	
Current Programming & Readback High:	Current priority: 20 V, 50 A		Current priority: 20 V, 100 A	
Low Current Measurement Range:	Current priority: 20 V, 5 A		Current priority: 20 V, 10 A	
CC Load Effect:	Current priority: 20 V, 50 A		Current priority: 20 V, 100 A	
10% of current rating (Isink):	Current priority: 20 V, - 5 A		Current priority: 20 V, - 10 A	
	External supply: 20 V, 5.5 A		External supply: 20 V, 11 A	
100% of current rating (Isink):	Current priority: 20 V, - 50 A		Current priority: 20 V, - 100 A	
	External supply: 20 V, 55 A		External supply: 20 V, 110 A	

N7952A/N7972A

N7952A/N7972A Test Record	Report Number _____		Date_____	
Test Description	**Model**	**Min. Specs**	**Results**	**Max. Specs**

Voltage Programming & Readback
    Minimum voltage (Vout):
    Voltage measured over interface:
    High voltage (Vout):
    Voltage measured over interface:
	
	Both
	Both
	Both
	Both
		
		– 36 mV
		Vout – 4 mV
		39.984 V
		Vout – 16 mV
			
			_____
			_____
			_____
			_____
				
				+ 44 mV
				Vout + 4 mV
				40.016 V
				Vout + 16 mV

CV Load Effect:	Both	– 1.5 mV	_____	+ 1.5 mV

CV Ripple and Noise
    peak-to-peak:
    rms:
	
	Both
	Both
		
		N/A
		N/A
			
			_____
			_____
				
				+ 9 mV
				+ 1 mV

Transient response @ 100 µs:	Both	– 100 mV	_____	+ 100 mV

Current Programming & Readback
    Minimum current (Iout):
 	
    Current measured over interface:
 	
    High current (Iout):
 	
    Current measured over interface:
	
	N7952A
	N7972A
	N7952A
	N7972A
	N7952A
	N7972A
	N7952A
	N7972A
		
		– 4 mA
		– 8 mA
		Iout – 4 mA
		Iout – 8 mA
		24.986 A
		49.972 A
		Iout – 0.014 A
		Iout – 0.028 A
			
			_____
			_____
			_____
			_____
			_____
			_____
			_____
			_____
				
				+ 4 mA
				+ 8 mA
				Iout + 4 mA
				Iout + 8 mA
				25.014 A
				50.028 A
				Iout + 0.014 A
				Iout + 0.028 A

Low Current Measurement Range:	N7952A N7972A	Iout – 0.0019 A Iout – 0.0037 A	_____ _____	Iout + 0.0019 A Iout + 0.0037 A
CC Load Effect:	N7952A N7972A	– 1 mA – 1.5 mA	_____ _____	+ 1 mA + 1.5 mA

Current Sink Tests
    10% of current rating:
 	
    100% of current rating:
	
	N7952A
	N7972A
	N7952A
	N7972A
		
		– 2.495 A
		– 4.99 A
		– 24.986 A
		– 49.972 A
			
			_____
			_____
			_____
			_____
				
				– 2.505 A
				– 5.01 A
				– 25.014 A
				– 50.028 A

	N7952A Settings		**N7972A Settings**	
Voltage Programming & Readback Min: Voltage Programming & Readback High: CV Load Effect, CV Ripple and Noise: Transient Response: Current Programming & Readback Min: Current Programming & Readback High: Low Current Measurement Range: CC Load Effect: 10% of current rating (Isink): 100% of current rating (Isink):	Voltage priority: 40 mV, 25 A Voltage priority: 40 V, 25 A Voltage priority: 40 V, 25 A Voltage priority: 40 V, 12.5 A to 25 A Current priority: 40 V, 0 A Current priority: 40 V, 25 A Current priority: 40 V, 2.5 A Current priority: 40 V, 25 A Current priority: 40 V, - 2.5 A External supply: 40 V, 2.75 A Current priority: 40 V, - 25 A External supply: 40 V, 27.5 A		Voltage priority: 40 mV, 50 A Voltage priority: 40 V, 50 A Voltage priority: 40 V, 50 A Voltage priority: 40 V, 25 A to 50 A Current priority: 40 V, 0 A Current priority: 40 V, 50 A Current priority: 40 V, 5 A Current priority: 40 V, 50 A Current priority: 40 V, - 5 A External supply: 40 V, 5.5 A Current priority: 40 V, - 50 A External supply: 40 V, 55 A	

N7953A/N7973A

N7953A/N7973A Test Record	Report Number _____		Date_____	
Test Description	**Model**	**Min. Specs**	**Results**	**Max. Specs**
Voltage Programming & Readback				
Minimum voltage (Vout):	Both	– 54 mV	_____	+ 66 mV
Voltage measured over interface:	Both	Vout – 6 mV	_____	Vout + 6 mV
High voltage (Vout):	Both	59.976 V	_____	60.024 V
Voltage measured over interface:	Both	Vout – 24 mV	_____	Vout + 24 mV
CV Load Effect:	Both	– 2 mV	_____	+ 2 mV
CV Ripple and Noise				
peak-to-peak:	Both	N/A	_____	+ 9 mV
rms:	Both	N/A	_____	+ 1 mV
Transient response @ 100 µs:	Both	– 150 mV	_____	+ 150 mV
Current Programming & Readback				
Minimum current (Iout):	N7953A	– 2.5 mA	_____	+ 2.5 mA
	N7973A	– 5 mA	_____	+ 5 mA
Current measured over interface:	N7953A	Iout – 2.5 mA	_____	Iout + 2.5 mA
	N7973A	Iout – 5 mA	_____	Iout + 5 mA
High current (Iout):	N7953A	16.6908 A	_____	16.7092 A
	N7973A	33.2817 A	_____	33.3183 A
Current measured over interface:	N7953A	Iout – 0.0092 A	_____	Iout + 0.0092 A
	N7973A	Iout – 0.0183 A	_____	Iout + 0.0183 A
Low Current Measurement Range:	N7953A	Iout – 0.0011 A	_____	Iout + 0.0011 A
	N7973A	Iout – 0.0023 A	_____	Iout + 0.0023 A
CC Load Effect:	N7953A	– 1 mA	_____	+ 1 mA
	N7973A	– 1.5 mA	_____	+ 1.5 mA
Current Sink Tests				
10% of current rating:	N7953A	– 1.6668 A	_____	– 1.6732 A
	N7973A	– 3.3237 A	_____	– 3.3363 A
100% of current rating:	N7953A	– 16.6908 A	_____	– 16.7092 A
	N7973A	– 33.2817 A	_____	– 33.3183 A
	N7953A Settings		**N7973A Settings**	
Voltage Programming & Readback Min:	Voltage priority: 60 mV, 16.7 A		Voltage priority: 60 mV, 33.3 A	
Voltage Programming & Readback High:	Voltage priority: 60 V, 16.7 A		Voltage priority: 60 V, 33.3 A	
CV Load Effect, CV Ripple and Noise:	Voltage priority: 60 V, 16.7 A		Voltage priority: 60 V, 33.3 A	
Transient Response:	Voltage priority: 60 V, 8.35 A to 16.7 A		Voltage priority: 60 V, 16.7 A to 33.3 A	
Current Programming & Readback Min:	Current priority: 60 V, 0 A		Current priority: 60 V, 0 A	
Current Programming & Readback High:	Current priority: 60 V, 16.7 A		Current priority: 60 V, 33.3 A	
Low Current Measurement Range:	Current priority: 60 V, 1.67 A		Current priority: 60 V, 3.33 A	
CC Load Effect:	Current priority: 60 V, 16.7 A		Current priority: 60 V, 33.3 A	
10% of current rating (Isink):	Current priority: 60 V, - 1.67 A		Current priority: 60 V, - 3.33 A	
	External supply: 60 V, 1.837 A		External supply: 60 V, 3.66 A	
100% of current rating (Isink):	Current priority: 60 V, - 16.7 A		Current priority: 60 V, - 33.3 A	
	External supply: 60 V, 18.37 A		External supply: 60 V, 36.6 A	

N7954A/N7974A

N7954A/N7974A Test Record	Report Number _____		Date_____	
Test Description	**Model**	**Min. Specs**	**Results**	**Max. Specs**
Voltage Programming & Readback 　Minimum voltage (Vout): 　Voltage measured over interface: 　High voltage (Vout): 　Voltage measured over interface:	Both Both Both Both	− 72 mV Vout − 8 mV 79.968 V Vout − 32 mV	_____ _____ _____ _____	+ 88 mV Vout + 8 mV 80.032 V Vout + 32 mV
CV Load Effect:	Both	− 2 mV	_____	+ 2 mV
CV Ripple and Noise 　peak-to-peak: 　rms:	Both Both	N/A N/A	_____ _____	+ 9 mV + 1 mV
Transient response @ 100 µs:	Both	− 200 mV	_____	+ 200 mV
Current Programming & Readback 　Minimum current (Iout): 　Current measured over interface: 　High current (Iout): 　Current measured over interface:	N7954A N7974A N7954A N7974A N7954A N7974A N7954A N7974A	− 2 mA − 4 mA Iout − 2 mA Iout − 4 mA 12.493 A 24.986 A Iout − 0.007 A Iout − 0.014 A	_____ _____ _____ _____ _____ _____ _____ _____	+ 2 mA + 4 mA Iout + 2 mA Iout + 4 mA 12.507 A 25.014 A Iout + 0.007 A Iout + 0.014 A
Low Current Measurement Range:	N7954A N7974A	Iout − 0.000875 A Iout − 0.0018 A	_____ _____	Iout + 0.000875 A Iout + 0.0018 A
CC Load Effect:	N7954A N7974A	− 0.8 mA − 1.5 mA	_____ _____	+ 0.8 mA + 1.5 mA
Current Sink Tests 　10% of current rating: 　100% of current rating:	N7954A N7974A N7954A N7974A	− 1.2475 A − 2.495 A − 12.493 A − 24.986 A	_____ _____ _____ _____	− 1.2525 A − 2.505 A − 12.507 A − 25.014 A
	N7954A Settings		**N7974A Settings**	
Voltage Programming & Readback Min: Voltage Programming & Readback High: CV Load Effect, CV Ripple and Noise: Transient Response: Current Programming & Readback Min: Current Programming & Readback High: Low Current Measurement Range: CC Load Effect: 10% of current rating (Isink): 100% of current rating (Isink):	Voltage priority: 80 mV, 12.5 A Voltage priority: 80 V, 12.5 A Voltage priority: 80 V, 12.5 A Voltage priority: 80 V, 6.25 A to 12.5 A Current priority: 80 V, 0 A Current priority: 80 V, 12.5 A Current priority: 80 V, 1.25 A Current priority: 80 V, 12.5 A Current priority: 80 V, - 1.25 A External supply: 80 V, 1.375 A Current priority: 80 V, - 12.5 A External supply: 80 V, 13.75 A		Voltage priority: 80 mV, 25 A Voltage priority: 80 V, 25 A Voltage priority: 80 V, 25 A Voltage priority: 80 V, 12.5 A to 25 A Current priority: 80 V, 0 A Current priority: 80 V, 25 A Current priority: 80 V, 2.5 A Current priority: 80 V, 25 A Current priority: 80 V, - 2.5 A External supply: 80 V, 2.75 A Current priority: 80 V, - 25 A External supply: 80 V, 27.5 A	

Self-Test Procedure

Power-On Self-Test

Each time the instrument is powered on, a self-test is performed. This test assures you that the instrument is operational.

Self-test checks that the minimum set of logic and power mesh systems are functioning properly. Self-test does not enable the output or place any voltages on the output. It leaves the instrument in the reset state.

User-Initiated Self-Test

The user-initiated self-test is the same as the power-on self-test.

Front Panel	SCPI Command
Cycle ac power. If self-test fails, the front panel ERR indicator comes on. Press the Error key to display the list of errors.	*TST? If 0, self-test passed. If 1, self-test failed. If self test-fails, use SYSTem:ERRor? to view the self-test error.

For a list of errors, see SCPI Error Messages.

Firmware Update

| NOTE | Refer to Instrument Identification to determine which firmware version is installed on your instrument. |

Software Required

To update the firmware you need to download the following two items onto your computer from the APS product page at www.agilent.com/find/APS

- The latest firmware version

- The Universal Firmware Update Utility

Update Procedure

Once you have copied both items to your computer, proceed as follows:

1. Run the Universal Firmware Update Utility

2. Browse to the location of the firmware that you just downloaded. Press Next.

3. Select the interface that you are using to communicate with your instrument and enter the address or connections string. Press Next.

4. Verify that the information is correct for the instrument you are updating. Press Begin Update.

The update utility will now update the firmware and restart your instrument.

Restricting Access

Note that you can restrict access to the instrument by the firmware update utility. This prevents unauthorized users from updating the firmware.

Front Panel	SCPI Command
Select **System\Admin\Update** Check the Must log in as admin box. This requires a user to log into the Admin menu before the firmware update utility performs a firmware update.	Not available

Instrument Sanitize

NOTE	This procedure is not recommended for use in routine applications because of the possibility of unintended loss of data.

This procedure sanitizes all user data except for the black box recorder data. It writes all zeros to flash memory and then performs a full chip erase as per the manufacturer's data sheet. Identification data such as instrument firmware, model number, serial number, MAC address, and calibration data is not erased. After the data is cleared, the instrument is rebooted.

If you cannot access the Admin menu, it may be password protected.

Front Panel	SCPI Command
Select **System\Admin\Sanitize** Select Sanitize. Selecting Sanitize removes all user-data from the instrument and cycles power.	Not available

Sanitizing the Black Box Recorder

The **System\Admin\Sanitize** command deletes the BBR log and snapshot files, but will not sanitize the Black Box Recorder drive.

To sanitize the N7908A Black Box Recorder drive requires that you removed the board from the instrument and destroy it (see Black Box Recorder).

When the BBR board has been removed from the instrument, use the front panel **System\BBR\Status** menu to remove the BBR accessory from the instrument's option list.
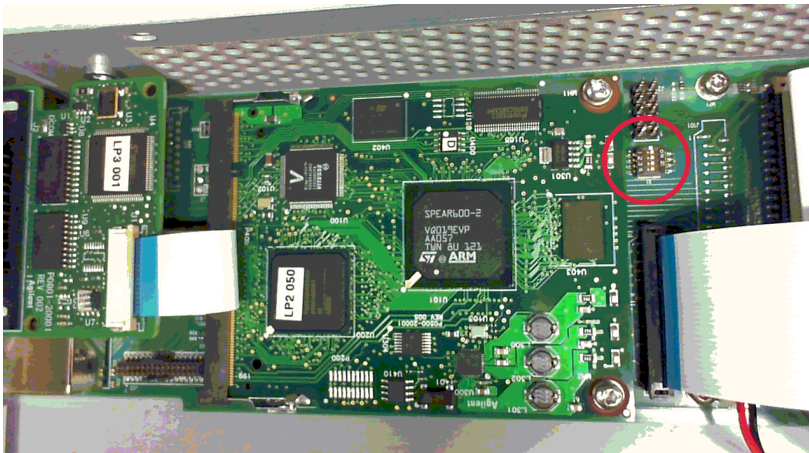
Calibration Switches

WARNING **SHOCK HAZARD Only qualified, service-trained personnel who are aware of the hazards involved should remove instrument covers. Always disconnect the power cable and any external circuits before removing the instrument cover. Some circuits are active and have power for a short time even when the power switch is turned off.**

Two switches control the access to calibration commands. The switches are on the interface board and are accessible by removing the top cover. To access the calibration switches:

Accessing the Calibration Switch

1. Remove the instrument cover as described under Disassembly.

2. The calibration switch is on the interface board near the ribbon cable. To change the calibration switch settings, use a small screwdriver to move the switches. As shipped, all switches are set toward the ON position (see below).

3. Replace the top cover when finished.

CAUTION Do not use a pencil to move the switches. Any graphite dust that gets on the switches will conduct electricity.
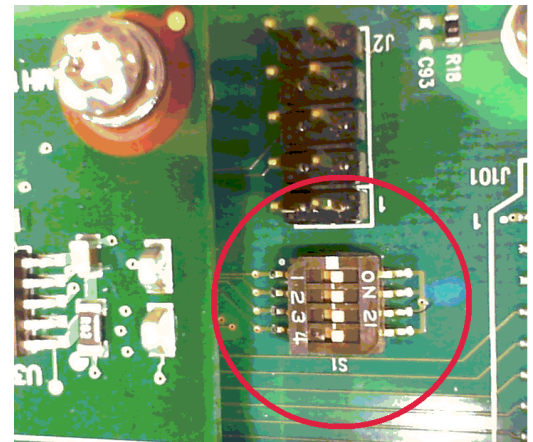
Switch Functions

Switches 1 and 2 set the calibration configuration as follows. Switches 3 and 4 are not used.

	Switch 1	Switch 2	Description
Normal	ON	ON	This is the as-shipped switch setting. The calibration functions are accessible after entering a numeric password. The default password is 0 (zero).
Clear Password	OFF	ON	The admin/calibration password is reset to 0 when the instrument is first powered on. Use this setting if you have forgotten the password.
Inhibit Calibration	ON	OFF	All calibration commands are disabled. This is useful where access is guarded by instrument seals.

Battery Replacement

SHOCK HAZARD Only qualified, service-trained personnel who are aware of the hazards involved should remove instrument covers. Always disconnect the power cable and any external circuits before removing the instrument cover. Some circuits are active and have power for a short time even when the power switch is turned off.

The internal battery powers the real-time clock. The primary function of the clock it to provide a time stamp for the internal file system. If the battery fails, the clock and time stamp function will not be available. No other instrument functions are affected.

Under normal use at room temperature, the lithium battery has a life expectancy between seven and ten years. Note that battery life will be reduced if the instrument is stored for a prolonged period at temperatures above 40 degrees C.
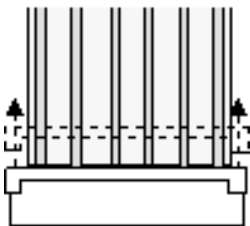
The part number of the battery is Panasonic CR 2032.

Installing the Instrument

1. Remove the instrument cover as described under Disassembly.

2. The battery is located near the calibration switches, under two ribbon cables.
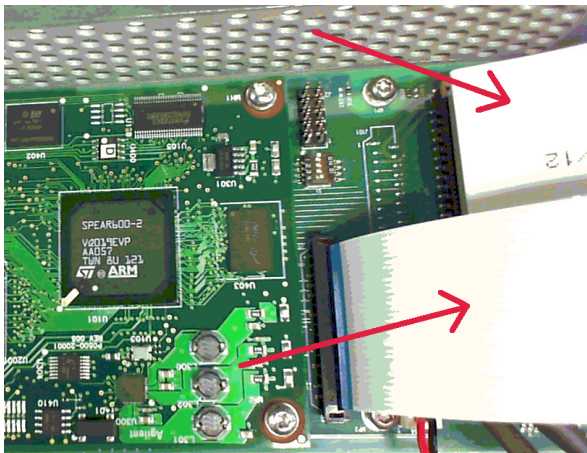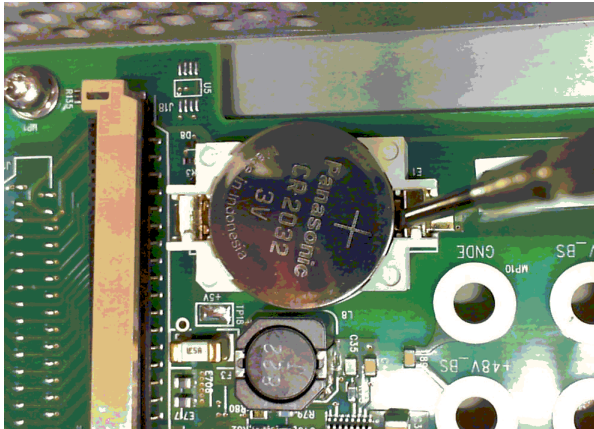

3. To access the battery, release the ribbon cables by pulling up on the locking tab.


4. Use a flat-bladed screwdriver and carefully pry up on the side of the battery that is *opposite* the ribbon cable connector

5. Install the new battery. Make sure that the positive side (+) is facing up. Place the battery *under* the small spring clips closest to the ribbon cable connector, then push down on the opposite end of the battery to seat the battery (see red arrow below). The top of the small spring clips should be visible after the battery is seated (see red circle below).
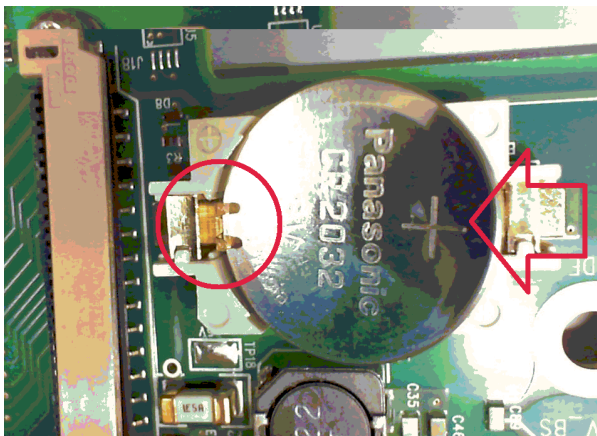
6. Replace the ribbon cables by fully inserting the cables into the connector; then pushing down on the locking tab to secure the cables.

7. Replace the top cover when finished.

8. Reset the date and time (see Clock Setup).

| NOTE | Properly dispose of the old battery in accordance with local laws and regulations. |

Disassembly

WARNING **SHOCK HAZARD Only qualified, service-trained personnel who are aware of the hazards involved should remove instrument covers. Always disconnect the power cable and any external circuits before removing the instrument cover. Some circuits are active and have power for a short time even when the power switch is turned off.**

Electrostatic Discharge (ESD) Precautions

Almost all electrical components can be damaged by electrostatic discharge (ESD) during handling. Component damage can occur at electrostatic discharge voltages as low as 50 V.

The following guidelines will help prevent ESD damage during service operations:
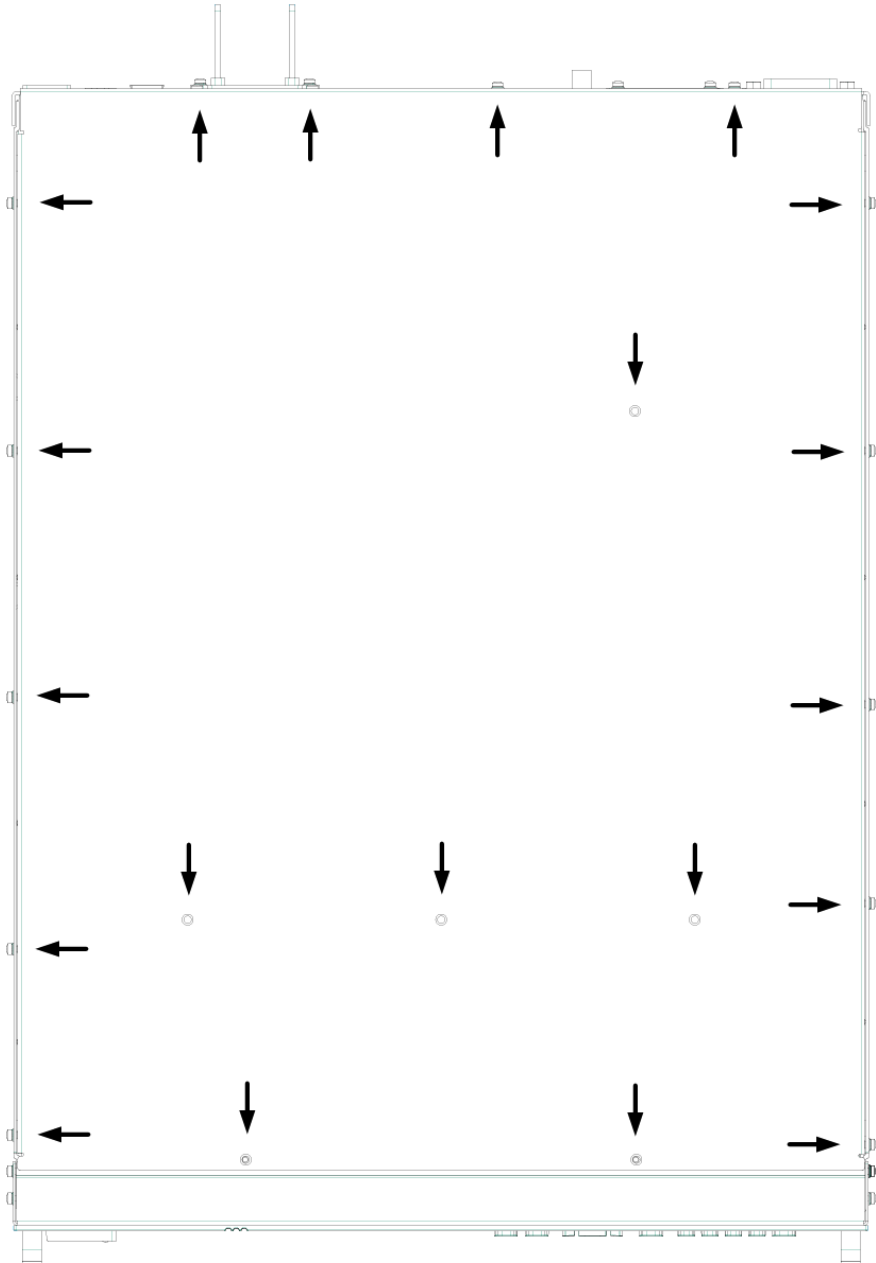
- Disassemble instruments only in a static-free work area.
- Use a conductive work area to reduce static charges.
- Use a conductive wrist strap to reduce static charge accumulation.
- Minimize handling.
- Keep replacement parts in original static-free packaging.
- Remove all plastic, foam, vinyl, paper, and other static-generating materials from the immediate work area.

Tools Required

- T10 Torx driver (cover disassembly)
- Small flat bladed screwdriver

General Disassembly Procedure

1. Turn off the power. Remove all cables from the instrument.
2. Remove the 6 flat-head screws locate on the top, and the 14 pan-head screws on the sides (see figure below). Place the screws in a container so that you do not lose them.
3. Remove off the instrument cover.

Cover screws