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HP 4142B Modular DC Source/Monitor

Control Software Programming Manual

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Agilent Technologies

HP Part No. 04142-90310
Printed in Japan Jun 1991

Edition 1
E0691

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ENGLISH: Safety Precautions for the HP 4142B

WARNING



HIGH VOLTAGE SHOCK HAZARD (MAX. 1000 V dc)

The HP 41423A HVU (±1000 V), HP 41420A SMU (±200 V), and HP 41421B SMU (±100 V) force dangerous voltages on the FORCE, GUARD, and SENSE terminals. To prevent an electrical shock, the following safety precautions must be observed.

- Ground the HP 4142B using a three-conductor ac power cable.
- Connect the Interlock (INTLK) terminal to a switch that turns off when the shielding box access door is opened.
- For HVU, connect the OUTPUT ON/OFF STATUS terminal to a warning indicator.
- For HVU, perform the operation tests of the INTLK and OUTPUT ON/OFF STATUS circuits at least once a day, before using the HP 4142B.
- Before touching the connections of the FORCE, GUARD, and SENSE terminals, turn the HP 4142B off, and discharge any capacitors (if connected).

  If you do not turn the HP 4142B off, perform the following four steps:
  1) Set the HVU and SMU output switches to off.
  2) For HVU, confirm that the warning indicator is not lit.
  3) Open the shielding box access door (open the INTLK terminal).
  4) Discharge any capacitors, if connected.
- Warn workers around the HP 4142B about dangerous conditions.

JAPANESE: HP 4142Bの安全上の注意



高電圧感電注意 (最大 1000 V dc)

HP 41423A HVU (±1000 V)、HP 41420A SMU (±200 V)、およびHP 41421B SMU (±100 V)は、危険電圧をFORCE端子、GUARD端子、およびSENSE端子に出力します。感電事故防止のため、必ず下記の事項を実施してください。

- 3極電源ケーブルを使用して、HP 4142Bを接地する
- インターロック(INTLK)端子を、シールド·ボックスの蓋が開いたときにオープンとなるよう接続する
- OUTPUT ON/OFF STATUS端子を警告インジケータに接続する(HVU使用時)
- INTLK回路およびOUTPUT ON/OFF STATUS回路の動作テストを、1日に1回以上、使用前に行う(HVU使用時)
- FORCE端子、GUARD端子、およびSENSE端子の接続に触れる前に、HP 4142Bの電源をオフにし、キャパシタが接続されているならば、キャパシタを放電する

  電源をオフにしない場合には、下記の4事項をすべて実施する
  1) HVUおよびSMUの出力スイッチをオフにする
  2) 警告インジケータが消灯していることを確認する(HVU使用時)
  3) シールド·ボックスの蓋をあける(INTLK端子をオープンにする)
  4) キャパシタが接続されているならば、キャパシタを放電する
- 周囲の他の作業者に対しても、高電圧危険に対する注意を徹底する

Printed in Japan 2/91
04142-90902

GERMAN: Sicherheitsmaßnahmen für den HP 4142B

WARNUNG



HOCHSPANNUNGS-BERÜHRUNGSGEFAHR (MAX. 1000 VDC)

Bei den Geräten HP 41423A HVU (±1000 V), HP 41420A SMU (±200 V) und HP 41421B SMU (±100 V) gefährliche spannungen an den FORCE-, GUARD- und SENSE-Klemmen. Um einen Elektroschock zu vermeiden, sind folgende Sicher-heitsmaßnahmen zu beachten.

- Gerät HP 4142B mit einem Dreileiter-AC-Starkstromkabel erden.
- Die Interlock-Klemme (INTLK) mit einem Schalter ver-binden, der beim Öffnen der Abschirmkasten-Zugangatür ausgeschaltet wird.
- Bei Gerät HVU die Klemme OUTPUT ON/OFF STATUS mit einer Warnanzeige verbinden.
- Bei Gerät HVU die Funktionsprüfungen der Schaltkreise INTLK und OUTPUT ON/OFF STATUS mindestens einmal täglich durchführen, bevor HP 4142B verwendet wird.
- Vor Berühren der Verbindungen an den FORCE-, GUARD- und SENSE-Klemmen, Gerät HP 4142B ausschalten und (falls angeschlossen), die Kondenaatoren entladen.

  Falls HP 4142B nicht ausgeschaltet wird, sind fol-gende vier Schritte durchzuführen:
  1) Die Ausgangschalter von HVU und SMU auf AUS stellen.
  2) Bei HVU kontrollieren, ob die Warnanzeige nicht leuchtet.
  3) Die Zugangstür des abgeschirmten Kasten öffnen (die Klemme INTLK öffnen).
  4) Vorhandene Kondensatoren entladen.
- Die Arbeitskräfte im Bereich des HP 4142B über die be-stehende Gafahr unterrichten.

FRENCH: Consignes de sécurité relatives à l'équipement HP 4142B

DANGER D'ELECTROCUTION



HAUTE TENSION CONTINUE (JUSQU'A 1000 Vc.c.)

Les instruments HP 41423A HVU (±1000 V), HP 41420A SMU (±200 V) et HP 41421B SMU (±100 V) présentent des tensions dangereuses aux bornes "FORCE", "GUARD" et "SENSE". Pour éviter tout risque d'électrocution, respecter les consignes suivantes.

- Mettre à la terre l'équipement HP 4142B en utilisant un câble secteur triphasé.
- Connecter la borne de verrouillage "INTLK" à un commutateur coupant l'alimentation lorsque la porte d'accès à la boite blindée est ouverte.
- Pour le module HVU, connecter la borne "OUTPUT ON/OFF STATUS" à une lampe d'avertissement.
- Pour le module HVU, effectuer les essais de fonctionnement des circuits "INTLK" et "OUTPUT ON/OFF STATUS" au moins une fois par jour, avant d'utiliser l'équipement HP 4142B.
- Avant de toucher les connexions des bornes "FORCE" "GUARD" et "SENSE", mettre hors tension l'équipement HP 4142B et décharger tous les condensateurs éventuellement raccordés.

  Au lieu de mettre l'équipement HP 4142B hors tension, l'on peut procéder de la manière suivante:
  1) Mettre les commutateurs de sortie des modules HVU et SMU en position d'arrét.
  2) Pour le module HVU, s'assurer que la lampe d'avertissement est éteinte.
  3) Ouvrir la porte d'accès à la boîte blindée (pour mettre hors circuit la borne "INTLK").
  4) Décharger tous les condensateurs éventuellement raccordés.
- Avertir toute personne travaillant à proximité de l'équipement HP 4142B des dangers que présente cet équipement.

Printed in Japan 2/91
04142-90902

Printing History

The manual printing date and part number indicate its current edition. The printing date changes when a new edition is printed. (Minor corrections and updates which are incorporated at reprint do not cause the date to change.) The manual part number changes when extensive technical changes are incorporated.

June 1991 ... Edition 1

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1

General Information

How To Use This Manual

This manual contains the information required to program the HP 4142B Modular DC Source/Monitor using the furnished Control Software.

Chapter 1 provides general control software information; Chapter 2 describes control software programming basics and provides an example program; Chapter 3 describes the types of measurements that can be performed using the control software; Chapter 4 provides an alphabetical listing of control software subprograms and user-defined functions, including syntax and other usage rules; and Appendix A contains the source code for the subprograms and user-defined functions.

Detailed HP 4142B hardware information and operating procedures are discussed in the Operation Manual.

What Is Control Software?

The HP 4142B's control software is a library of subprograms and user defined functions written in BASIC, which allows you to easily modify and enhance the software to suit your measurement requirements. Control software is designed for use on HP 9000 Series 200/300 computers running BASIC 3.0 or later versions, and is provided on a 3.5 inch micro-flexible disc (single-sided format). The three main functions of the 4142B's control software are:

- To control the HP 4142B's plug-in units (HP4142_DRV).
- To display measurement data in a graphics format (GRAPHICS).
- To measure and calculate semiconductor DC parameters (PARA_4142).

Control Software Files

Control software consists of three files, HP4142_DRV, GRAPHICS, and PARA_4142, as briefly described in the following paragraphs.

HP4142_DRV — Contains subprograms for controlling HP 4142B operation. You can use these subprograms just as you would BASIC keywords, thus simplifying measurement programming.

GRAPHICS — Contains utility subprograms for displaying measurement results in a graphics format. These subprograms simplify the scaling, labeling, and plotting of graph axes, and can even provide an optional grid pattern.

PARA_4142 — Contains user-defined functions for obtaining complex DC semiconductor parameter measurement results with a minimum of time and effort.

For more complete control software information, refer to Chapters 3 and 4.

Required Bin Files

The HP 4142B's control software requires the following BIN files.

Driver	HPIB
Language Extensions	GRAPH, GRAPHX, IO, MAT, PDEV, KBD, ERR

If you're using an external disc drive or other storage medium, you may need to load other BIN files in addition to these. Refer to the BASIC User's Guide for more details.

2

Programming Basics

Introduction

This chapter describes basic control software programming procedures for controlling the HP 4142B. To simplify the explanation procedure, a practical example for measuring the collector characteristics (I_C-V_C curve) of a bipolar transistor is included.

Before Programming

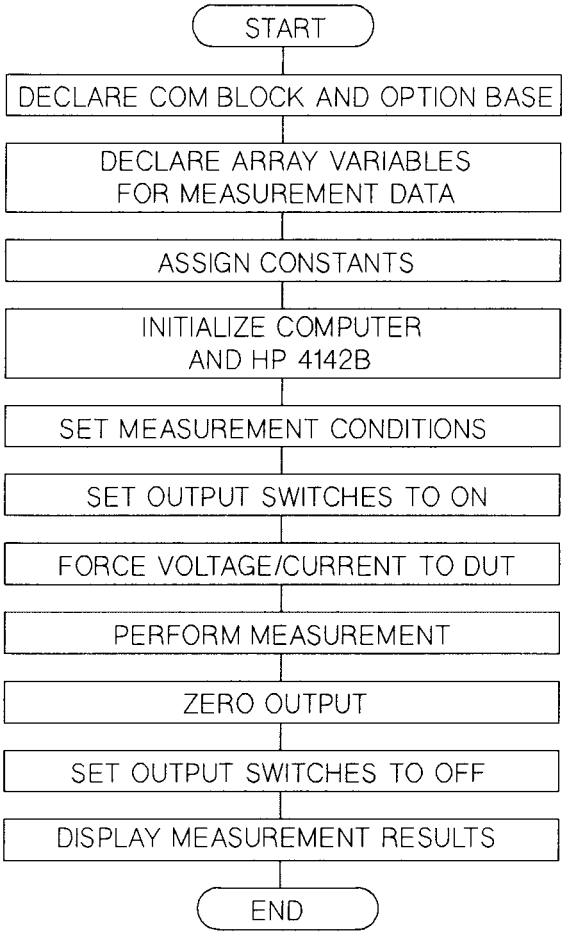
Before you begin to program your HP 4142B, the control software requires the following BIN files:

Driver	HPIB
Language Extensions	GRAPH, GRAPHX, IO, MAT, PDEV, KBD, ERR

Programming Procedures

Measurement Program Flow

Following figure shows the basic flow of a typical measurement program.



Measurement Program Flow Chart

Collector Characteristics Example Program

The following figure shows an example program for measuring the collector characteristics of a bipolar transistor. This program follows the program flow shown in the above figure, and is fully executable when linked with the appropriate control software subprograms. Descriptions for each program section are contained in succeeding paragraphs. Refer to Chapter 4 for complete subprogram information.

```
10   ! Bipolar Tr Ic-Vc Measurement using Sweep Function
20   !
30   !   LOADSUB ALL FROM "HP4142_DRV"
40   !   LOADSUB ALL FROM "GRAPHICS"
50   !
60   OPTION BASE 1
70   ASSIGN @Hp4142 TO 717
80   COM @Hp4142
90   !
100  DIM Vc(101), IC(101)
110  INTEGER Collector, Base, Emitter, Point
120  Collector=2
130  Base=3
140  Emitter=4
150  Vstart=0
160  Vstop=1
170  Point=101
180  Ib=1.0E-5
190  Ve=0
200  !
210  Init_computer
220  Init_hp4142
230  Set_smu(1)
240  !
250  Ch_sw_on
260  Force_i(Base, Ib, 0, 5)
270  Force_v(Emitter, Ve, 0, 1.00E-1)
280  Set_iv(Collector, 1, 0, Vstart, Vstop, Point, 0, 0, .01)
290  Sweep_iv(Collector, 2, 0, Ic(*), Vc(*))
300  Zero_output
310  Ch_sw_off
320  !
330  Lingraph(Vstart, Vstop, 0, Ic(Point)*1000, "Collector
  Voltage (V)", "Collector Current (mA)", "Ic-Vc Curve",1)
340  FOR I=1 TO Point
350    DRAW Vc(I),IC(I)*1000
360  NEXT I
370  !
380  END
```

Figure 2-1. Example Program for Measuring Collector Characteristics

Declare Com Block and Option Base

In the HP 4142B's control software, subprograms communicate with the main program and with other subprograms via a COM block. It is necessary, therefore, to declare a COM block at the beginning of your measurement program. If you want the default lower array boundary to be 1, instead of 0, include the OPTION BASE 1 statement at the beginning of your measurement program. Program lines 60 - 80 declare a COM block and OPTION BASE 1.

```
60   OPTION BASE 1              where 717 is the HP 4142B's HP-IB address
70   ASSIGN @Hp4142 TO 717
80   COM @Hp4142
```

Declare Array Variables for Measurement Data

The DIM statement dimensions and reserves array variable memory for measurement data. In this example, the lower array boundary is set to 1 because the default was set to 1 by the OPTION BASE 1 statement.

```
100  DIM Vc (101), Ic (101)
```

Assign Constants

Program lines 110 to 190 assign constants to the program variables that will be used as parameters for the subprograms.

```
110  INTEGER Collector,Base,    declares variables as type integer
Emitter,Point
120  Collector=2                assigns channel#2 SMU to the collector
130  Base=3                     assigns channel#3 SMU to the base
140  Emitter=4                  assigns channel#4 SMU to the emitter
150  Vstart=0                   sets the sweep start voltage value to 0 V
160  Vstop=1                    sets the sweep stop voltage value to 1 V
170  Point=101                  specifies the number of measurement points
180  Ib=1.0E-5                  sets the base current value to 1.0E-5A
190  Ve=0                       sets the emitter voltage value to 0 V
```

Initialize Computer and HP 4142B

The Init_computer and Init_hp4142 control software subprograms initialize the display of the computer and the HP 4142B prior to measurement execution.

```
210  Init_computer
220  Init_hp4142
```

When using these subprograms in your measurement programs, be sure they precede other control software subprograms.

Set Measurement Conditions

The Set_smu subprogram sets the number of samples that will be taken and averaged for each measurement.

```
230  Set_smu (1)      sets the number of samples for averaging to 1
```

Set Output Switches to ON

The Ch_sw_on subprogram sets the output switch of specified SMUs, HVUs, HCUs, and VSs to ON, thus enabling output.

```
250  Ch_sw_on
```

Line 250 sets the output switch of all SMUs, HVUs,HCUs, and VSs to ON.

Force Voltage/Current

The Force_i and Force_v subprograms force the specified current and voltage. Voltage can be forced from SMUs, HVU or VSs; current can be forced from SMUs or HVUs.

```
260  Force_i (Base, Ib, 0, 5)
270  Force_v (Emitter, Ve, 0, 1.00E-1)
```

In line 260, the specified current, *Ib* (line 180), is forced to the *Base* (from the *ch#3* SMU—line 130) with AUTO ranging, and *V compliance* set to 5 V.

In line 270, the specified voltage, *Ve* (line 190), is forced to the *Emitter* (from the *ch#4* SMU—line 140) with AUTO ranging, and *I compliance* set to 100 mA.

Perform Measurement

The Set_iv subprogram sets the parameters for a staircase sweep measurement. The Sweep_iv subprogram triggers a staircase sweep measurement in accordance with the parameters specified in the Set_iv program and returns the measurement results.

```
280  Set_iv (Collector, 1, 0, Vstart, Vstop, Point, 0, 0, .01)
290  Sweep_iv (Collector, 2, 0, Ic ( * ), Vc ( * ))
```

In line 280, the source unit (*ch#2* SMU—line 120) is connected to the *Collector*, and set for a linear voltage sweep with AUTO ranging, 0 s *hold time*, 0 s *delay time*, and 10 mA *I compliance*.

In line 290, the voltage sweep is triggered, and the collector current is measured at each step with AUTO ranging. Measurement data and source data are returned to *Ic (*)* and *Vc (*)*, respectively.

Zero Output

Line 300 memorizes the present settings for all modules, then sets all modules to 0 V output.

```
300  Zero_output
```

Set Output Switches to OFF

Line 310 sets the output switch of all SMUs, HVUs and VSs to OFF.

```
310  Ch_sw_off
```

Display Measurement Results

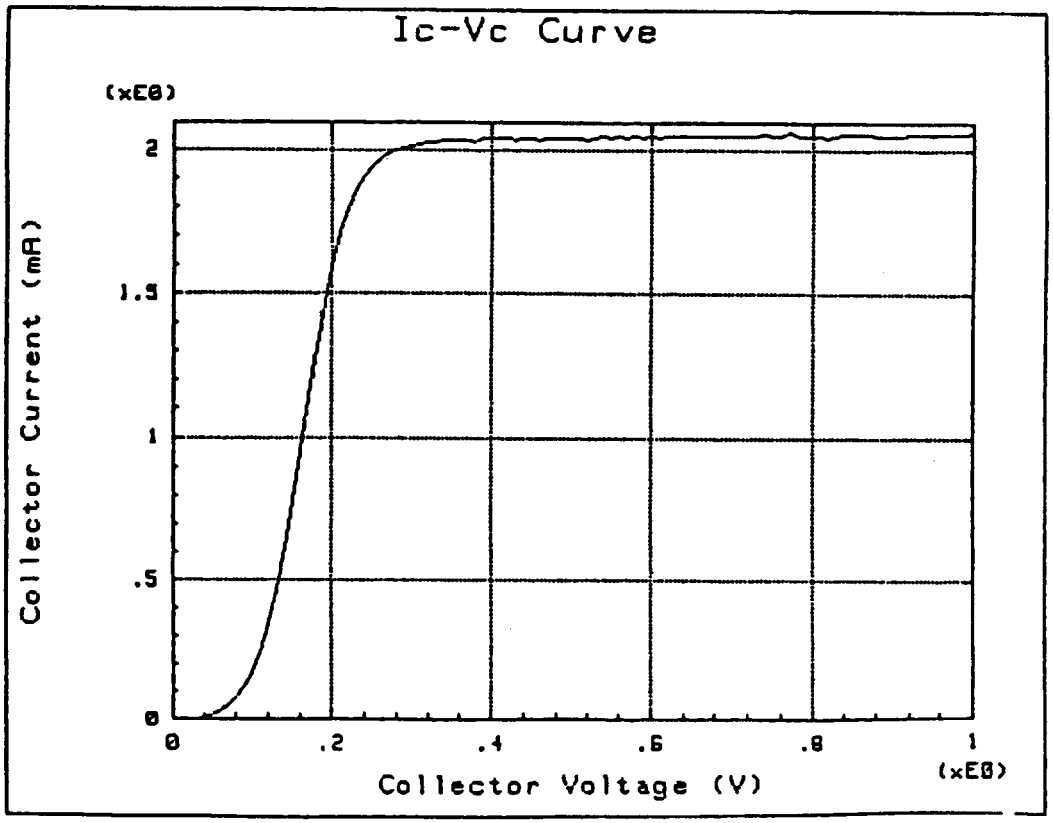
Line 330 draws, numbers, and labels the axes for a linear X-Y graph.

```
330  Lingraph (Vstart, Vstop, 0, Ic(Point) * 1000,  "Collector  Voltage
 (V)", "Collector Current (mA)", "Ic-Vc Curve", 1)
```

Lines 340 to 360 draws the measurement data in the graph created by line 330.

```
340  FOR I=1 TO Point
350   DRAW Vc ( I ), Ic ( I ) * 1000
360  NEXT I
```

The following figure shows example output from this measurement program.



Example Output from Measurement Program

Executing Measurement Programs

To use the HP 4142B's control software, you must link the required control software subprograms to your measurement program using HP BASIC's LOADSUB statement. To execute the example program, you'll need to link it to the HP4142_DRV and GRAPHICS files by removing the comment symbols (!) from lines 30 and 40.

3

Control Software Description

Introduction

This chapter provides a brief description of each control software subprogram and user-defined function, and gives examples of the types of measurements that can be made using the control software.

The HP4142_DRV subprograms let you perform High Speed Spot, Staircase Sweep, 1-ch Pulsed Spot, Pulsed Sweep, Staircase Sweep with Pulsed Bias, 2-ch Pulsed Spot, Pulsed Sweep with Pulsed Bias, Analog Search, Quasi-Pulsed measurements.

The user-defined functions in PARA_4142 facilitate measurements of some of the more common dc semiconductor parameters, and the utility subprograms in GRAPHICS facilitate displaying measurement results in an X-Y graphics format.

Subprogram Descriptions

The following tables list the control software subprograms and user-defined functions contained in the HP4142_DRV, GRAPHICS, and PARA_4142 files, respectively, and give a brief description of each.

HP4142_DRV Subprograms

Subprogram	Description
Auto_cal	Enables/disables the Auto-Calibration function.
Cal_hp4142	Performs self-calibration.
Ch_sw_on	Sets SMU/HVU/HCU/VS output switches to ON.
Ch_sw_off	Sets SMU/HVU/HCU/VS output switches to OFF.
Zero_output	Sets SMU/HVU/HCU/VS output to 0 V.
Recover_output	Resets SMU/HVU/HCU/VS output from Zero Output to previous settings.
Set_pol	Sets the polarity of the HVU output.
Set_smu	Sets number of samples for averaging.
Set_vm	Sets VM operation mode.
Init_hp4142	Resets the HP 4142B.
Self_test	Initiates Self-Test and displays results.
Force_i	Forces specified current from a specified SMU or HVU.
Force_v	Forces specified voltage from a specified SMU, HVU or VS.
Measure_i	Performs high speed spot I measurement using a specified SMU, HVU or VS.
Measure_v	Performs high speed spot V measurement using a specified SMU, HVU or VM.
Set_iv	Sets staircase sweep measurement parameters.
Sweep_iv	Performs staircase sweep measurements.
Sweep_miv	Performs multichannel staircase sweep measurements.
Sweep_mode	Sets miscellaneous sweep operation parameters.
Pulse_i	Sets a specified SMU, HVU or HCU to pulsed current source mode.
Pulse_v	Sets a specified SMU, HVU, HCU or VS to pulsed voltage source mode.
Dpulse_i	Sets a specified SMU or HCU to pulsed current source mode.
Dpulse_v	Sets a specified SMU, HCU or VS to pulsed voltage source mode.
Pulse_measure	Performs 1-ch pulsed spot measurement.
Dpulse_measure	Performs 2-ch pulsed spot measurement.
Set_piv	Sets pulsed sweep measurement parameters.

Sweep_piv	Performs pulsed sweep measurements.
Sweep_pbias	Performs staircase sweep with pulsed bias measurements.
Dsweep_piv	Performs pulsed sweep with pulsed bias measurements.
Para_hfe	Calculates parameters required for h_{FE} measurement using AFU.
Para_vth	Calculates parameters required for V_{TH} measurement using AFU.
Set_asource	Sets search SMU parameters for an analog search measurement.
Set_amonitor	Sets sense SMU parameters for an analog search measurement.
Measure_asearch	Performs analog search measurement.
Set_bdm	Sets quasi-pulsed measurement parameters.
Measure_bdm	Performs quasi-pulsed measurement.
Connect_relay1	Sets the output of the control pins for module selector.
Connect_relay2	Sets the output of the control pins for external relay control.

GRAPHICS Subprograms

Subprogram	Description
Wbuild_file	Generates BSDM format measurement data file.
Lingraph	Generates linear-linear X-Y axes and grid pattern.
Loggraph	Generates linear-log X-Y axes and grid pattern.
Dump_screen	Performs a screen dump to a printer.
Init_computer	Initializes the computer and display.

PARA_4142 User-Defined Functions

Function	Description
FNHfe	Uses AFU to measure forward current transfer ratio (h_{FE}) of bipolar transistors.
FNBvcbo	Measures collector-base breakdown voltage.
FNBvces	Measures collector-emitter breakdown voltage.
FNIds	Measures drain current for a specified drain and gate voltage.
FNVth1	Measures gate-source threshold voltage of an enhancement-type FET when a specified drain current is forced.
FNVth2	Measures gate-source voltage at two different drain currents and calculates V_{TH} using linear extrapolation.
FNVth3	Uses AFU to measure V_{TH}.
FNR_measure	Performs a two-terminal or four terminal (Kelvin connection) resistance measurement.

High Speed Spot Measurements

For high speed spot measurements, the control software provides the Force_i, Force_v, Measure_i, and Measure_v subprograms. Force_i specifies an SMU as a constant current source, and sets and outputs the specified current. Force_v specifies an SMU or VS as a constant voltage source, and sets and outputs the specified voltage. Measure_i specifies an SMU or VS as a measurement unit, and performs a high speed spot current measurement. Measure_v specifies an SMU or VM as a measurement unit, and performs a high speed spot current measurement. The following is an example high speed spot measurement program:

```
10   ASSIGN @Hp4142 TO 717
20   COM @Hp4142
30   INTEGER B_ch, C_ch
40   !                                Emitter      : GNDU
50   B_ch=3                         ! Base         : Ch#3
60   C_ch=2                         ! Collector    : Ch#2
70   Ib=2.E-5
80   Vc=2
90   !
100  Init_hp4142
110  Ch_sw_on
120  Force_i (B_ch, Ib, 0, 2)
130  Force_v (C_ch, Vc, 0, 1.E-2)
140  Measure_i (C_ch, Imeas)
150  Zero_output
160  Ch_sw_off
170  END
```

120: Forces current from ch#3 unit.

130: Forces voltage from ch#2 unit.

140: Measures current at ch#2 unit, and stores result in Imeas.

Staircase Sweep Measurements

For staircase sweep measurements, the control software provides the Set_iv, Sweep_iv, Sweep_miv, and Sweep_mode subprograms. Set_iv specifies an SMU or VS as a staircase sweep source and establishes sweep parameters. Sweep_iv specifies an SMU or VM as a measurement unit, triggers the units, and performs single channel measurement using the specified measurement unit. Sweep_miv specifies multiple SMUs or VMs as measurement units, triggers the units, and performs multichannel measurements using the specified measurement units. Sweep_mode lets you set the automatic sweep abort function and output after sweep parameters. The following is an example staircase sweep measurement program:

```
10   OPTION BASE 1
20   ASSIGN @Hp4142 TO 717
30   COM @Hp4142
40   INTEGER B_ch, C_ch, Vc_no_step
50   DIM Imeas(101)
60   !                                Emitter      : GNDU
70   B_ch=3                         ! Base         : Ch#3
80   C_ch=2                         ! Collector    : Ch#2
90   Vc_start=0
100  Vc_stop=1
110  Vc_no_step=1-1
120  Ic_comp=.01
130  Ib=1.E-5
140  !
150  Init_hp4142
160  Ch_sw_on
170  Set_iv (C_ch, 1, 0, Vc_start, Vc_stop, Vc_no_step, 0, 0,
 Ic_comp)
180  Sweep_mode (2,2)
190  Force_i (B_ch, Ib, 0, 2)
200  Sweep_iv (C_ch, 2, 0, Imeas(*))
210  Zero_output
220  Ch_sw_off
230  END
```

170: Sets ch#2 unit as a staircase voltage sweep source.

180: Sets sweep conditions.

200: Triggers a staircase voltage sweep at ch#2 unit, measures current at ch#2 unit for each sweep step, and stores the results in *Imeas(*)*.

1-ch Pulsed Spot Measurements

For 1-ch pulsed spot measurements, the control software provides the Pulse_v, Pulse_i, and Pulse_measure subprograms. Pulse_i specifies an SMU or HCU as a pulsed current source. Pulse_v specifies a SMU, HCU, or VS as a pulsed voltage source and establishes pulse parameters. Pulse_measure specifies an SMU, HCU, or VM as a measurement unit, triggers the units, and performs a single channel measurement using the specified measurement unit. The following is an example pulsed spot measurement program:

```
10   ASSIGN @Hp4142 TO 717
20   COM @Hp4142
30   INTEGER B_ch, C_ch
40   !                                Emitter      : GNDU
50   B_ch=3                         ! Base         : Ch#3
60   C_ch=2                         ! Collector    : Ch#2
70   Ib=5.E-3
80   Ic=5.E-2
90   !
100  Init_hp4142
110  Ch_sw_on
120  Pulse_i (B_ch, 0, 0, Ib, 1.E-3, 0, 1.E-1, 2)
130  Force_i (C_ch, Ic, 0, 2)
140  Pulse_measure (C_ch, 1, Vmeas,)
150  Zero_output
160  Ch_sw_off
170  END
```

120: Sets ch#3 unit as a pulsed current source.

140: Triggers a pulse current at ch#2 unit, measures voltage at ch#2 unit, and stores the result in *Vmeas*.

Pulsed Sweep Measurements

For pulsed sweep measurements, the control software provides Set_piv and Sweep_piv subprograms. Set_piv specifies an SMU, HCU, or VS as a pulsed sweep source and establishes sweep parameters. Sweep_piv specifies an SMU, HCU, or VM as a measurement unit, triggers the units, and performs a single channel measurement using the specified measurement unit. The following is an example pulsed sweep measurement program:

```
10   OPTION BASE 1
20   ASSIGN @Hp4142 TO 717
30   COM @Hp4142
40   INTEGER A_ch, No_step
50   DIM Imeas(101),Vsource(101)
60   !                                Cathode       : GNDU
70   A_ch=2                         ! Anode         : Ch#2
80   Pv_start=0
90   Pv_stop=.9
100  No_step=91
110  If_comp=.1
120  !
130  Init_hp4142
140  Ch_sw_on
150  Set_piv (A_ch, 1, 0, 0, Pv_start, Pv_stop, No_step, 1.E-3, 1.E-
2, 0, If_comp)
160  Sweep_piv (A_ch, 2, 0, Imeas(*), Vsource(*))
170  Zero_output
180  Ch_sw_off
190  END
```

150: Sets ch#2 unit as a pulsed voltage sweep source.

160: Triggers a pulsed voltage sweep at ch#2 unit, measures current at ch#2 unit for each sweep step, and stores the results in *Imeas(*)*, and *Vsource(*)*.

Staircase Sweep With Pulsed Bias Measurements

For staircase sweep with pulsed bias measurements, the control software provides Pulse_v, Pulse_i, Set_iv, and Sweep_pbias subprograms. Set_iv specifies an SMU or VS as a staircase sweep source, and establishes sweep parameters. Pulse_i or Pulse_v specifies an SMU, HCU, or VS as a pulsed bias source, and establishes pulse parameters. Sweep_pbias specifies an SMU, HCU, or VM as a measurement unit, triggers the units, and performs a single channel measurement using the specified measurement unit. The following is an example staircase sweep with pulsed bias measurement program:

```
10   OPTION BASE 1
20   ASSIGN @Hp4142 TO 717
30   COM @Hp4142
40   INTEGER B_ch, C_ch, Vc_no_step
50   DIM Imeas(101),Vsource(101)
60   !                                  Emitter      : GNDU
70   B_ch=3                           ! Base         : Ch#3
80   C_ch=2                           ! Collector    : Ch#2
90   Vc_start=0
100  Vc_stop=20
110  Vc_no_step=101
120  Ic_comp=.1
130  Ib=3.E-4
140  !
150  Init_hp4142
160  Ch_sw_on
170  Pulse_i (B_ch, 0, 0, Ib, 1.E-3, 0, 5.E-2, 2)
180  Set_iv (C_ch, 1, 0, Vc_start, Vc_stop, Vc_no_step, 0, 0,
 Ic_comp)
190  Sweep_iv (C_ch, 2, 0, Imeas(*),Vsource(*))
200  Zero_output
210  Ch_sw_off
220  END
```

170: Sets ch#3 unit as a pulsed current bias source.

180: Sets ch#2 unit as a staircase voltage sweep source.

190: Triggers a staircase voltage sweep at ch#2 unit, and for each sweep step, the pulsed current bias is forced to ch#1 unit and the current is measured at ch#2 unit. Results are stored in *Imeas(*)* and *Vsource(*)*.

2-ch Pulsed Spot Measurements

For 2-ch pulsed spot measurements, the control software provides Pulse_v, Pulse_i, Dpulse_v, Dpulse_i, Set_iv, and Dpulse_measure subprograms. Pulse_i or Pulse_v specifies an SMU or HCU as one pulsed source, and establishes pulse parameters. Dpulse_i or Dpulse_v specifies an SMU or HCU as the other pulsed source, and establishes pulse parameters. At least one HCU is required. Dpulse_measure specifies an SMU, HCU, or VM as a measurement unit, triggers the units, and performs a single channel measurement using the specified unit. The following is an example 2-ch pulsed spot measurement program:

```
10   ASSIGN @Hp4142 TO 717
20   COM @Hp4142
30   INTEGER B_ch, C_ch
40   !                                  Emitter      : GNDU
50   B_ch=2                           ! Base         : HPSMU (Ch#2)
60   C_ch=5                           ! Collector    : HCU (Ch#5)
70   Ib=1
80   Ic=10
90   !
100  Init_hp4142
110  Ch_sw_on
120  Pulse_i (B_ch, 0, 0, Ib, 1.E-4, 0, 1.E-3, 2)
130  Dpulse_i (C_ch, 0, 0, Ic, 5)
140  Dpulse_measure (C_ch, 1, Vce)
150  Zero_output
160  Ch_sw_off
170  END
```

120: Sets ch#2 unit as a pulsed current source.

130: Sets ch#5 unit as a pulsed current source

140: Triggers a pulse current at ch#5 unit, measures voltage at ch#5 unit, and stores the result in *Vce*.

Pulsed Sweep With Pulsed Bias Measurements

For pulsed sweep with pulsed bias measurements, the control software provides Dpulse_i, Dpulse_v, Set_piv, and Dsweep_piv subprograms. Set_piv specifies an SMU or HCU as the pulsed sweep source, and establishes sweep parameters. Dpulse_i or Dpulse_v specifies an SMU or HCU as the pulse bias source, and establishes pulse parameters. At least one HCU is required. Dsweep_piv specifies an SMU, HCU, or VM as a measurement unit, triggers the units, and performs a single channel measurement using the specified measurement unit. The following is an example pulsed sweep with pulsed bias measurement program:

```
10   OPTION BASE 1
20   ASSIGN @Hp4142 TO 717
30   COM @Hp4142
40   INTEGER B_ch, C_ch, Vc_no_step
50   DIM Ic(100)
60   !                                Emitter      : GNDU
70   B_ch=2                         ! Base         : HPSMU (Ch#2)
80   C_ch=5                         ! Collector    : HCU (Ch#5)
90   Vc_start=.1
100  Vc_stop=10
110  Vc_no_step=100
120  Ic_comp=10
130  Ib=5.E-2
140  !
150  Init_hp4142
160  Ch_sw_on
170  Set_piv (C_ch, 1, 0, 0, Vc_start, Vc_stop, Vc_no_step, 2.E-4,
 2.E-2, 0, Ic_comp)
180  Dpulse_i (B_ch, 0, 0, Ib, 2)
190  Dsweep_piv (C_ch, 2, 0, Ic(*))
200  Zero_output
210  Ch_sw_off
220  END
```

170: Sets ch#5 HCU as a pulsed voltage sweep source.

180: Sets ch#2 HPSMU as a pulsed current bias source.

190: Triggers a pulsed voltage sweep at ch#5 HCU, and for each sweep step, the pulsed current bias is forced to ch#2 HPSMU and the current is measured at ch#5 HCU. Results are stored in *Ic(*)*.

Analog Search Measurements

For analog search measurements, the control software provides the Para_hfe, Para_vth, Set_asource, Set_amonitor, and Measure_asearch subprograms. Para_hfe and Para_vth calculate and return optimized variables for performing h_{FE} and V_{TH} measurements using the AFU. Set_asource and Set_amonitor set analog search parameters, and Measure_asearch triggers the analog search, and returns measurement values. The following is an example analog search measurement program:

```
10   ASSIGN @Hp4142 TO 717
20   COM @Hp4142
30   INTEGER B_ch, C_ch, Status
40   !                                Emitter      : GNDU
50   B_ch=3                         ! Base         : Ch#3
60   C_ch=2                         ! Collector    : Ch#2
70   Vb_start=0
80   Vb_stop=1
90   Vb_rate=200
100  Ib_comp=1.15E-4
110  Vc=1
120  Ic_target=1.E-3
130  Ic_comp=1.15E-3
140  Integ_time=4.5E-4
150  Delay_time=1.E-4
160  !
170  Init_hp4142
180  Ch_sw_on
190  Set_asource (B_ch, Vb_start, Vb_stop, Vb_rate, 0, Delay_time,
 Ib_comp)
200  Set_amonitor (C_ch, 1, Vc, Ic_target, Ic_comp)
210  Measure_asearch (1, 4, Integ_time, Search_data, Sense_data,
 Status)
220  Zero_output
230  Ch_sw_off
240  END
```

190: Sets ch#3 SMU as a search SMU.

200: Sets ch#2 SMU as a sense SMU.

210: Triggers the analog search, and stores results in *Search_data* and *Sense_data*.

Quasi-Pulsed Measurements

For quasi-pulsed measurements, the control software provides the Set_bdm and Measure_bdm subprograms.

Set_bdm specifies an HVU or SMU as a quasi-pulsed source and establishes parameters for quasi-pulsed measurements.

Measure_bdm specifies an HVU or SMU as a measurement unit, triggers the units, and performs quasi-pulsed measurements.

The following is an example quasi-pulsed measurement program:

```
10   OPTION BASE 1
20   ASSIGN @Hp4142 TO 717
30   COM @Hp4142
40   INTEGER C_ch,Status
50   !
60   C_ch=2
70   Vrange=1000
80   Vstart=500
90   Vstop=1000
100  Hold_time=0
110  Delay_time=0
120  Icomp=1.0E-3
130  !
140  Init_hp4142
150  Ch_sw_on
160  Set_bdm(C_ch,Vrange,Vstart,Vstop,Hold_time,Delay_time,Icomp)
170  Measure_bdm (C_ch,0,0,Bvces,Status)
180  Zero_output
190  Ch_sw_off
200  PRINT "BVces="; Bvces
210  END
```

160: Sets ch#2 unit as a quasi-pulsed source.

170: Triggers a quasi-pulsed voltage at ch#2 unit, measures voltage at ch#2 unit, and stores the result in *Bvces*.

Parameter Measurements Using Para_4142 Functions

The PARA_4142 file contains user-defined functions that simplify the measurement of common dc semiconductor parameters, thereby minimizing programming requirements.

PARA_4142 contains the FNBvcbo, FNBvces, FNHfe, FNIds, FNVth1, FNVth2, and FNVth3 functions for measuring transistor dc parameters, and the FNR_measure function for performing resistance measurements. The following is an example h_{FE} measurement program using the FNHfe function:

```
10   OPTION BASE 1
20   ASSIGN @Hp4142 TO 717
30   COM @Hp4142
40   INTEGER Channel(3)
50   Channel(1)=1                  ! Collector     : Ch#1 SMU
60   Channel(2)=2                  ! Base          : Ch#2 SMU
70   Channel(3)=3                  ! Emitter       : Ch#3 SMU
80   Vc=5
90   Ic=1.E-3
100  Vb_start=0
110  Vb_stop=5
120  Hfe=FNHfe(Channel(*), Vc, Ic, Vb_start, Vb_stop)
130  END
```

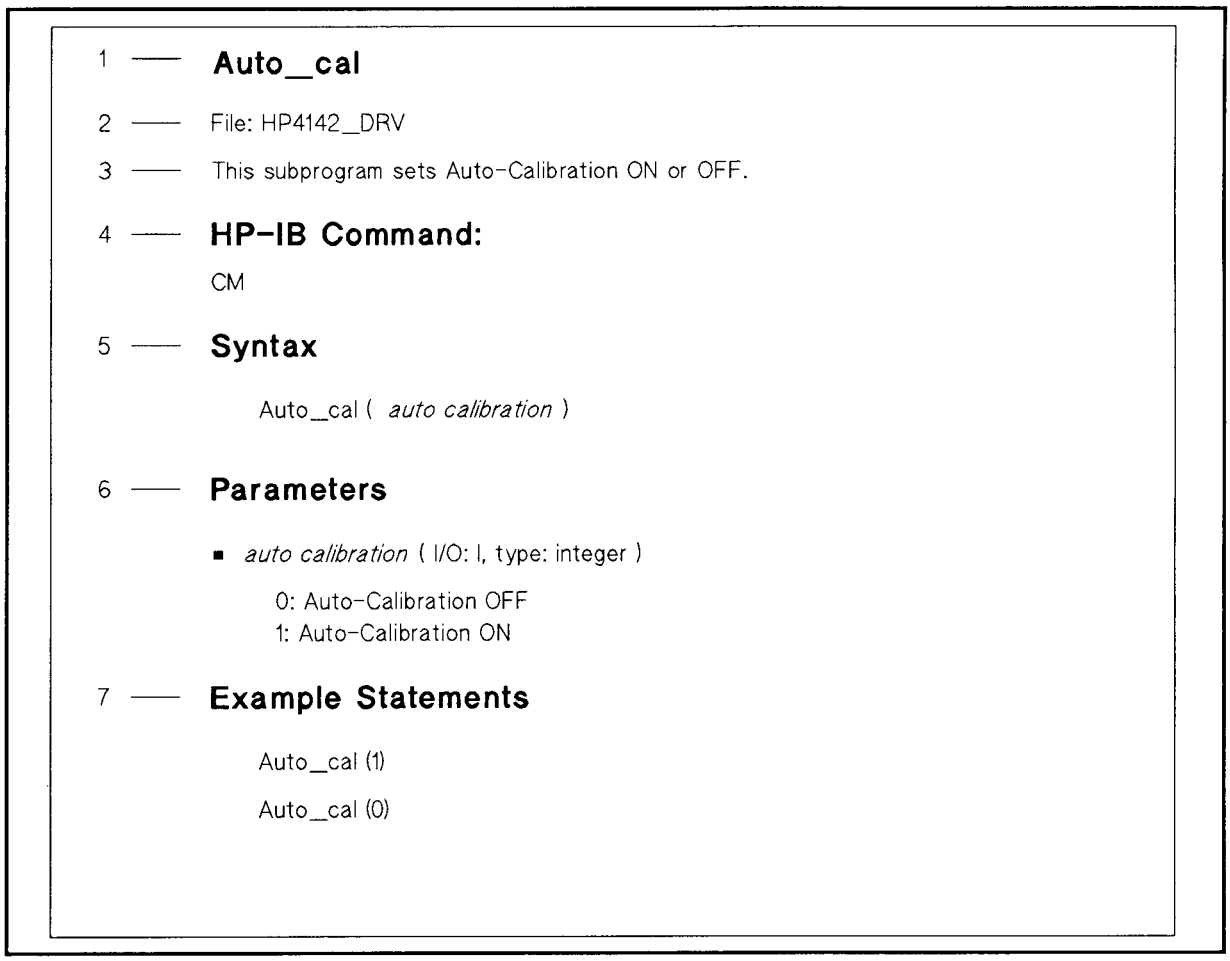
120: Performs measurements and calculates h_{FE}.

4

Programming Reference

Introduction

This chapter contains an alphabetical listing of the HP 4142B Control Software subprograms that can be called in user-written programs. Each entry lists the subprogram name and the file that contains the subprogram, shows the syntax of the calling context, explains pass parameters, and gives example statements, as shown below.



1. Subprogram name
2. Name of the Control Software File that contains this subprogram
3. Subprogram description
4. Name of the HP-IB command that is used in this subprogram

5. Syntax of the calling context
6. Pass parameter explanation
7. Example statements

Conventions

The following conventions are used throughout this chapter.

Reading the Syntax

Required parameters, in which you must substitute a value or variable, are shown in *standard italics* in the syntax calling context.

Optional parameters, in which you may substitute a value or variable, are shown in *standard italics* and are delimited by brackets [ ] in the syntax calling context.

Most optional parameters have default values assigned. The default values are listed in each parameter explanation.

In the following example, the *range* and *status* are both optional parameters, and the *status* parameter cannot be specified unless the range parameter is specified.

Measure_v (*measurement ch#, voltage value name* [, *range*] [, *status*])

CALL Statement

Except for the following three cases, the CALL statement can be omitted when calling the subprogram:

- If the subprogram is called from the keyboard.
- If the subprogram is called after the THEN keyword in an IF statement.
- In an ON [event] CALL statement.

Parameters

The parameters are written in standard italics. After the parameter, the following information is enclosed in parentheses.

I/O	If an I is indicated here, you can pass a parameter by value or by reference. The I parameter is used to pass actual values required by the subprogram. If an O is indicated here, you can pass a parameter only by reference. The O parameter is used to store any values returned by the subprogram.
type	Each parameter has a type (integer, real, string, or numeric array). If the type of the parameter is integer, use the INTEGER command to declare a variable for the parameter. If the type of the parameter is string or numeric array, use the DIM or REAL command to define the array as the parameter.
unit	If a parameter has a unit (V for voltage, I for current, etc.), the unit is indicated here.

Note



Pass by reference—the calling context actually gives the subprogram access to the calling context's value area (which is essentially access to the calling context's variable).

Auto_cal

File: HP4142_DRV

This subprogram sets Auto-Calibration ON or OFF.

HP-IB Command:

CM

Syntax

```
Auto_cal ( auto calibration )
```

Parameters

- *auto calibration* (I/O: I, type: integer)

  0: Auto-Calibration OFF
  1: Auto-Calibration ON

Example Statements

```
Auto_cal (1)

Auto_cal (0)
```

Cal_hp4142

File: HP4142_DRV

This subprogram performs Self-Calibration.

HP-IB Command:

CA

Syntax

```
Cal_hp4142 ( [slot#])
```

Parameters

- *slot#* (I/O: I, type: integer)

  The *slot#* parameter selects a unit to be calibrated. If you specify the *slot#* parameter, the unit that is installed in the specified slot is calibrated.

Unit	*ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HCU	2 to 8
HVU	2 to 8
VS/VMU	1 to 8
AFU	1 to 8

  Default= all units from slot#1 to #8.

Example Statements

```
Cal_hp4142

Cal_hp4142 (4)
```

Ch_sw_off

File: HP4142_DRV

This subprogram disables a specified unit by setting the output switches to OFF.

HP-IB Command:

CL

Syntax

```
Ch_sw_off ( [ch#][, ch#][, ch#][, ch#][, ch#][, ch#][, ch#][, ch#])
```

Parameters

- *ch#* (I/O: I, type: integer)

Unit	*ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HCU	2 to 8
HVU	2 to 8
VS	1 to 8, 11 to 18 or 21 to 28

Default = all units

Example Statements

```
Ch_sw_off (1)

Ch_sw_off (Ch1,Ch2,Ch3)

Ch_sw_off
```

Ch_sw_on

File: HP4142_DRV

This subprogram enables a specified unit by setting the output switches to ON.

HP-IB Command:

CN

Syntax

```
Ch_sw_on ( [ch#][, ch#][, ch#][, ch#][, ch#][, ch#][, ch#][, ch#])
```

Parameters

- *ch#* (I/O: I, type: integer)

Unit	*ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HCU	2 to 8
HCU	2 to 8
VS	1 to 8, 11 to 18, or 21 to 28

Default = all units

Example statements

```
Ch_sw_on (1)

Ch_sw_on (Ch1,Ch2,Ch3)

Ch_sw_on
```

Connect_relay1

File: HP4142_DRV

This subprogram controls the output of the CONTROL connector pins for the Module Selector control.

Note



Before controlling the output of the CONTROL connector pins, all source unit outputs are set to zero (the same conditions after a Zero_output execution). After controlling the output of the CONTROL connector pins, all outputs of the source units are returned to the output states previous to the execution of this subprogram.

HP-IB Command:

ERC

Syntax

```
Connect_relay1 ( control value )
```

Parameters

- *control value* (I/O: I, type: integer)

  0: Disconnects all units
  1: Connects SMU
  2: Connects HVU
  3: Connects HCU

Example Statement

```
Connect_relay1(1)
```

Connect_relay2

File: HP4142_DRV

This subprogram controls the output of the CONTROL connector pins for the 16 bit external relay control.

HP-IB Command:

ERC

Syntax

```
Connect_relay2 (dry switching [ , pin# ][ , pin# ][ , pin# ][ , pin# ][ , pin# ]
[ , pin# ][ , pin# ][ , pin# ][ , pin# ][ , pin# ][ , pin# ][ , pin# ][ , pin# ]
[ , pin# ][ , pin# ][ , pin# ])
```

Parameters

- *dry switching* (I/O: I, type: integer)

  0: Dry switching on

  The HP 4142B automatically sets all outputs of source units to zero (same as the conditions after the Zero_output execution), and changes the outputs of the CONTROL connector pins. Then the outputs are returned to the output states previous to subprogram execution.

  1: Dry switching off

  Without changing the source unit outputs, the HP 4142B changes the outputs of the CONTROL connector pins.

- *pin#* (I/O: I, type: integer)

  The pin number to be set to LOW. Unspecified pins are set to HIGH.

  1 to 16

Example Statement

```
Connect_relay2(0,1,3,5,7)
```

Dpulse_i

File: HP4142_DRV

This subprogram specifies an SMU or HCU as the pulsed current source and specifies the parameters for 2-ch pulsed spot or pulsed sweep with pulsed bias measurements.

HP-IB Command:

PDI

Syntax

For SMUs:

`Dpulse_i` (*output ch#, I output range, base current, pulse current* [, *V compliance*])

For HCUs:

`Dpulse_i` (*output ch#, I output range, base current, pulse current, V compliance*)

Parameters

- *output ch#* (I/O: I, type: integer)

Unit	*output ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HCU	2 to 8

- *I output range* (I/O: I, type: real)

0:	Auto ranging
1E−8:	10 nA Limited Auto ranging
1E−7:	100 nA Limited Auto ranging
1E−6:	1 μA Limited Auto ranging
1E−5:	10 μA Limited Auto ranging
1E−4:	100 μA Limited Auto ranging
1E−3:	1 mA Limited Auto ranging
1E−2:	10 mA Limited Auto ranging
1E−1:	100 mA Limited Auto ranging
1:	1 A Limited Auto ranging
10:	10 A Limited Auto ranging

- *base current* (I/O: I, type: real, unit: A)
  pulse current (I/O: I, type: real, unit: A)

Unit	*base current*[1]	*pulse current*[1]
HPSMU	0 to ±1	0 to ±1
MPSMU	0 to ±100E−3	0 to ±100E−3
HCU	0[2]	0 to ±10

1 The *pulse current* and *base current* polarity must be the same.

2 During base value output, the HCU output is 0 V and no current.

- *V compliance* (I/O: I, type: real, unit: V)

Unit	*V compliance*
HPSMU	0 to E200
MPSMU	0 to E100
HCU	0 to E10

Default:

- If the specified SMU is set to I source mode before the trigger:

  Default = the setting before trigger

- If the specified SMU is set to V source mode before the trigger:

  Default = none

Example Statements

```
Dpulse_i (1, 100E−6, 3E−5, 5E−5, 20)

Dpulse_i (3, 10E−6, 1E−7, 5E−6, 5)
```

Dpulse_measure

File: HP4142_DRV

This subprogram triggers a 2-ch pulsed spot measurement. A measurement is performed at the specified measurement ch#, and the measurement value is returned to a specified measurement variable.

HP-IB Command:

MM, FL, RV, RI, PDM, XE

Syntax

For Voltage Measurements:

`Dpulse_measure` (*measurement ch#*, `1`, *measurement variable* [, *primary pulse ch#*] [, *V measurement range*] [, *status*])

For Current Measurements:

`Dpulse_measure` (*measurement ch#*, `2`, *measurement variable* [, *primary pulse ch#*] [, *I measurement range*] [, *status*])

Parameters

- *measurement ch#* (I/O: I, type: integer)

Unit	*measurement ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HCU	2 to 8
HVU	2 to 8
VM	1 to 8, 11 to 18, or 21 to 28

- *measurement variable* (I/O: O, type: real, unit: V or A)

  The measured value is returned to this parameter.

- *primary pulse ch#* (I/O: I, type: integer)

  0: auto selection
  2 to 8: for HCU ch#

  When you use two HCUs as two pulse sources for the 2-ch pulsed spot measurements, specify this parameter to select the HCU in which the *pulse width* of the Pulse_i or Pulse_v subprogram is set. The pulse width of the other HCU is fixed to about 1 ms, and can not be specified. If you specify 0 as this parameter, the HCU that is set by the Dpulse_i or Dpulse_v subprogram is selected automatically.

When one pulse source is the SMU and the other pulse source is the HCU, the *pulse width* is always set to the HCU. In such a case, specify 0 for this parameter.

Default = 0

- *V measurement range* (I/O: I, type: real)

The *V measurement range* sets the voltage measurement range of VMs. The voltage measurement range of an SMU or HCU is set to the Compliance range automatically, regardless of the specified value.

0: 40 V range fixed
2: 2 V range fixed
20: 20 V range fixed
40: 40 V range fixed

Default = 0

- *I measurement range* (I/O: I, type: real)

0: Compliance range
−1E−8: 10 nA range fixed
−1E−7: 100 nA range fixed
−1E−6: 1 μA range fixed
−1E−5: 10 μA range fixed
−1E−4: 100 μA range fixed
−1E−3: 1 mA range fixed
−1E−2: 10 mA range fixed
−1E−1: 100 mA range fixed
−1: 1 A range fixed
−10: 10 A range fixed

Default = 0

- *status* (I/O: O, type: integer)

The measurement status information is returned to this parameter. See the status description in this chapter.

Example Statements

```
Dpulse_measure (1, 1, Voltage)

Dpulse_measure (Channel, 2, Current, 0, −1E−1, Status)
```

Dpulse_v

File: HP4142_DRV

This subprogram specifies an SMU or HCU as the pulsed V source and specifies its parameters for 2-ch pulsed spot or pulsed sweep with pulsed bias measurements.

HP-IB Command:

PDV

Syntax

`Dpulse_v` (*output ch#*, *V output range*, *base voltage*, *pulse voltage* [, *I compliance*])

Parameters

- *output ch#* (I/O: I, type: integer)

Unit	*output ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HCU	2 to 8

- *V output range* (I/O: I, type: real)

  0: Auto ranging
  2: 2 V Limited Auto ranging
  20: 20 V Limited Auto ranging
  40: 40 V Limited Auto ranging
  100: 100 V Limited Auto ranging
  200: 200 V Limited Auto ranging

- *base voltage* (I/O: I, type: real, unit: V)
  pulse voltage (I/O: I, type: real, unit: V)

Unit	*base voltage*	*pulse voltage*
HPSMU	0 to ±200	0 to ±200
MPSMU	0 to ±100	0 to ±100
HCU	0	0 to ±10

- *I compliance* (I/O: I, type: real, unit: A)

Unit	*I compliance*
HPSMU	±2E−9 to ±1
MPSMU	±2E−9 to ±100E−3
HCU	±1E−6 to ±10

Default:

- If the specified SMU or HCU is set to V source mode before the trigger:

  Default = the setting before trigger

- If the specified SMU or HCU is set to I source mode before the trigger:

  Default = none

Example Statements

```
Dpulse_v (1, 20, 0, 5, 1E−4)

Dpulse_v (5, 40, −10, 30, 1E−3)
```

Dsweep_piv

File: HP4142_DRV

This subprogram triggers pulsed sweep with pulsed bias measurements, performs the measurements at the specified *measurement ch#* for each sweep step, then returns the measurement values and sweep source values to the *measurement value array(*)* and *source value array(*)*, respectively.

HP-IB Command:

MM, WNU?, FL, RV, RI, PDM, XE

Syntax

For Voltage Measurements:

`Dsweep_piv` (*measurement ch#*, `1`, *V measurement range*, *measurement value array(*)* [, *primary pulse ch#*][, *source value array(*)*])

For Current Measurements:

`Dsweep_piv` (*measurement ch#*, `2`, *I measurement range*, *measurement value array(*)* [, *primary pulse ch#*][, *source value array(*)*])

Parameters

- *measurement ch#* (I/O: I, type: integer)

Unit	*measurement ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HCU	2 to 8
HVU	2 to 8
VM	1 to 8, 11 to 18, 21 to 28

- *V measurement range* (I/O: I, type: real)

  The *V measurement range* sets the voltage measurement range of VMs. The voltage measurement range of SMUs or HCUs is set to the Compliance range automatically, regardless of the specified value.

  0: 40 V range fixed
  2: 2 V range fixed
  20: 20 V range fixed
  40: 40 V range fixed

  Default = 0

- *I measurement range* (I/O: I, type: real)

0:	Compliance range
−1E−8:	10 nA range fixed
−1E−7:	100 nA range fixed
−1E−6:	1 μA range fixed
−1E−5:	10 μA range fixed
−1E−4:	100 μA range fixed
−1E−3:	1 mA range fixed
−1E−2:	10 mA range fixed
−1E−1:	100 mA range fixed
−1:	1 A range fixed
−10:	10 A range fixed

Default = 0

- *measurement value array(*)* (I/O: O, type: numeric array, unit: V or A)

  The measurement value of each sweep step is returned to this array. The number of elements of the *measurement value array(*)* must be larger than number of sweep steps.

- *primary pulse ch#* (I/O: I, type: integer)

0:	auto selection
2 to 8:	for HCU ch#

  When you use two HCUs as two pulse sources for the pulsed sweep with pulsed bias measurement, specify this parameter to select the HCU in which the *pulse width* of the Pulse_i or Pulse_v subprogram is set. The pulse width of the other HCU is fixed to about 1 ms, and can not be specified. If you specify 0 as this parameter, the HCU that is set by the Dpulse_i or Dpulse_v subprogram is selected automatically.

  When one pulse source is the SMU and the other pulse source is the HCU, the *pulse width* is always set to the HCU. In such a case, specify 0 for this parameter.

  Default = 0

- *source value array(*)* (I/O: O, type: numeric array, unit: V or A)

  The sweep source values of each sweep step is returned to this array. The number of elements of the *source value array(*)* must be larger than number of sweep steps.

Example Statements

```
Dsweep_piv (3, 1, 0, 2, Voltage(*), 3, Sweep_source(*))

Dsweep_piv (Ch, 2, −1, Current(*), 0, Source(*)
```

Note



When using this subprogram, it is recommended that you include OPTION BASE 1 at the beginning of your program. Including OPTION BASE 1 in your program causes array element numbering to start from 1 instead of 0. This makes it easier to keep track of the array elements in the *measurement value array(*)* and [*source value array(*)*] because the *nth* returned value is array element n instead of *n − 1*.

Dump_screen

File: GRAPHICS

This subprogram performs a screen dump to the printer. The printer's HP-IB address must be set to 01, and the select code must be 7.

Syntax

```
Dump_screen ( [expand output])
```

Parameters

- *expand output* (I/O: I, type: integer)

  Expanded output can be performed with this parameter.

  0: Does not expand output
  1: Expands output

  Default = 0

Example Statements

```
Dump_screen

Dump_screen (1)
```

FNBvcbo

File: PARA_4142

This function measures the collector-base breakdown voltage of a bipolar transistor, and returns the measurement result to a user-specified variable.

Syntax

```
FNBvcbo ( channel(*), test current [ , V compliance] [ , hold time ])
```

Parameters

- *channel(*)* (I/O: I, type: integer array)

  channel(*) is an integer array containing 1 to 3 elements as follows:

  - *channel(1)* is the ch# of the SMU or HVU that must be connected to the collector. This SMU forces test current.
  - *channel(2)* is the ch# of the SMU or GNDU that must be connected to the base.

    If an SMU is connected, this function sets the SMU to 0 V output.

    If a GNDU is connected instead of an SMU, you must specify only one element for *channel(*)*, or you must specify *channel(2)* = 99.
  - *channel(3)* is the ch# of the SMU that must be connected to the emitter.

    If an SMU is connected to the emitter, this function turns the output switch of the SMU to OFF.

    If you only specify one or two elements for *channel(*)*, the emitter must be opened.

- *test current* (I/O: I, type: real, unit: A)

  The output current value that is forced from the *channel(1)* unit.

Unit	*test current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3
HVU	0 to ±10E−3

- *V compliance* (I/O: I, type: real, unit: V)

  The voltage compliance value for the *channel(1)* unit.

Unit	*V compliance*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000

Default = 20

- *hold time* (I/O: I, type: real, unit: s)

  The wait time for a measurement by the *channel(1)* unit.

  Default = 0.4

Example Statements

```
Vcbo = FNBvcbo (Channel(*), 1.E-5)

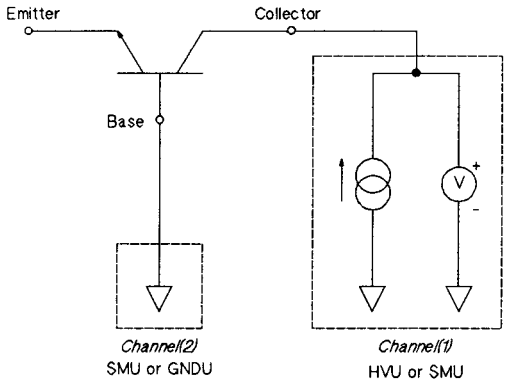
Vcbo = FNBvcbo (Channel(*), Ic, V_limit, Hold_time)
```

Semantics

When using this function, the units at *channel(*)* must be connected to the transistor as shown in the circuit below. The unit at *channel(1)* outputs *test current*, waits the *hold time*, and measures the transistor's collector-base voltage. The *hold time* is required to allow the current source to fully charge the output capacitance of the unit, and to allow the transistor to complete minority carrier generation.

The measurement result, which is the transistor's collector-base breakdown voltage, is returned to the user-specified variable.

Immediately after the measurement, this function sets all units to 0 V output, and sets all unit output switches to OFF.



Measurement Circuit

FNBvces

File: PARA_4142

This function measures the collector-emitter breakdown voltage of a bipolar transistor with the base and substrate both connected to the emitter. The function then returns the measurement result to a user-specified variable.

Syntax

FNBvces (*channel(*)*, *test current* [, *V compliance*] [, *hold time*])

Parameters

- *channel(*)* (I/O: I, type: integer array)

  channel(*) is an integer array containing 1 or 2 elements as follows:

  - *channel(1)* is the ch# of the SMU or HVU that must be connected to the collector. This unit outputs *test current*.
  - *channel(2)* is the ch# of the SMU or GNDU that must be connected to the base and emitter.

    If an SMU is connected, this function sets the SMU to 0 V output.

    If a GNDU is connected, you must specify only one element for *channel(*)*, or you must specify *channel(2)* = 99.

- *test current* (I/O: I, type: real, unit: A)

  The output current value that is forced from the *channel(1)* unit.

Unit	*test current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3
HVU	0 to ±10E−3

- *V compliance* (I/O: I, type: real, unit: V)

  The voltage compliance value for the *channel(1)* unit.

Unit	*V compliance*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000

  Default = 20

- *hold time* (I/O: I, type: real, unit: s)

The wait time for the measurement.

Default = 0.4

Example Statements

```
Vces = FNBvces (Channel(*), 1.E-3)

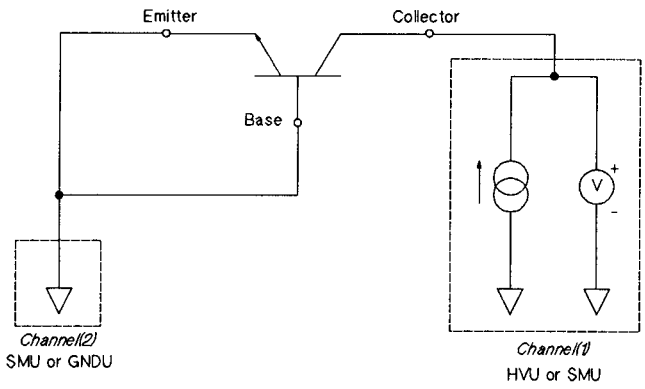
Vces = FNBvces (Channel(*), Ic, Vlimit, Hold_time)
```

Semantics

When using this function, the units at *channel(*)* must be connected to the transistor as shown in the circuit below. The unit at *channel(1)* outputs *test current*, waits the *hold time*, and measures the transistor's collector-emitter voltage. The *hold time* is required to allow the current source to fully charge the output capacitance of the unit, and to allow the transistor to complete minority carrier generation.

The measurement result, which is the transistor's collector-emitter breakdown voltage, is returned to the user-specified variable.

Immediately after the measurement, this function sets all units to 0 V output, and sets all unit output switches to OFF.



Measurement Circuit

FNHfe

File: PARA_4142

This function performs measurements and calculates the forward current transfer ratio (h_{FE}) of bipolar transistors by using an Analog Feedback Unit and two SMUs.

Syntax

FNHfe (*channel(*)*, *collector voltage*, *target collector current*, *start base voltage*, *stop base voltage* [, *ramp rate*] [, *feedback integration time*] [, h_{FE} *value*])

Parameters

- *channel(*)* (I/O: I, type: integer array)

  channel(*) is an integer array containing 2 or 3 elements as follows:

  - *channel(1)* is the sense SMU ch#, and must be connected to the collector.
  - *channel(2)* is the search SMU ch#, and must be connected to the base.
  - *channel(3)* is the ch# of the unit that must be connected to the emitter.

    If an SMU is connected, this function sets the SMU to 0 V output.

    If a GNDU is connected instead of an SMU, you must specify only two elements for *channel(*)*, or you must specify *channel(3)* = 99.

- *collector voltage* (I/O: I, type: real, unit: V)

  The output voltage value that is forced from the *channel(1)* SMU (sense SMU).

Unit	*collector voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

- *target collector current* (I/O: I, type: real, unit: A)

  The target current value that is sensed by the *channel(1)* SMU (sense SMU).

Unit	*target collector current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3

  This function sets the sense SMU I compliance equal to 1.1 × (*target collector current*).

- *start base voltage* (I/O: I, type: real, unit: V)

  The search start voltage value of the *channel(2)* SMU (search SMU).

Unit	*start base voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

- *stop base voltage* (I/O: I, type: real, unit: V)

  The search stop voltage value of the *channel(2)* SMU (search SMU).

Unit	*stop base voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

- *ramp rate* (I/O: I, type: real, unit: V/s)

  The ramp rate value of the *channel(2)* SMU (search SMU). The allowable values are 0.5 to 100000.

  Default = 500

  See the Set_asearch subprogram description.

- *feedback integration time* (I/O: I, type: real, unit: s)

  The feedback integration time for the analog feedback measurement. The allowable values are 0.5E−6 to 450E−3.

  Default = 0.005

  See the Measure_asearch subprogram description.

- h_{FE} *value* (I/O: I, type: real)

  The h_{FE} *value* is an expected value, and is used to calculate I compliance for the search SMU as shown in the following equation.

  I compliance = 1.1 × (*target collector current*) / h_{FE} *value*

  Default = 50

Example Statements

```
Hfe = FNHfe (Channel(*), 6, 1E-2, 0, 0.6)

Hfe = FNHfe (Channel(*), Vce, Ic, Vbmin, Vbmax)

Hfe = FNHfe (Channel(*), Vce, Ic, Vbmin, Vbmax, Ramp, Integ, hFE_value)
```

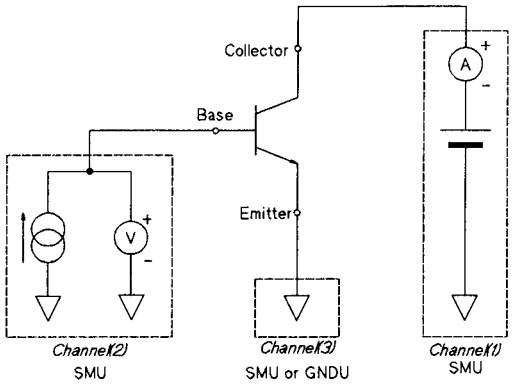
Semantics

When using this function, the SMUs and GNDU at *channel(∗)* must be connected to the transistor as shown in the circuit below. The specified *collector voltage* polarity must be positive for NPN transistors, and negative for PNP transistors.

For this measurement, the function uses the AFU and two SMUs. The function uses the *channel(2)* SMU to vary the base voltage until the *channel(1)* SMU senses that the *target collector current* has been reached. Then, the function calculates h_{FE} by dividing the *target collector current* by the base current, and returns the result to the user-specified variable.

If an abnormal condition is detected (see the status description in this chapter), or if the *target collector current* cannot be reached, −9999999.99999 is returned to the user-specified variable.

Immediately after the measurement, this function sets all SMUs to 0 V output, and sets all SMU output switches to OFF.



Measurement Circuit

FNIds

File: PARA_4142

This function measures the drain current for a specified *drain voltage* and *gate voltage*, and returns the measurement result to a user-specified variable.

Syntax

FNIds (*channel(*)*, *drain voltage*, *gate voltage* [, *drain current compliance*] [, *substrate voltages*])

Parameters

- *channel(*)* (I/O: I, type: integer array)

  channel(*) is an integer array containing 2 to 4 elements as follows:

  - *channel(1)* is the ch# of the SMU or HVU that must be connected to the drain.
  - *channel(2)* is the ch# of the SMU or HVU that must be connected to the gate.
  - *channel(3)* is the ch# of the module that must be connected to the source.

    If an SMU or HVU is connected, this function sets the module to 0 V output.

    If a GNDU is connected instead of an SMU, you must specify only two elements for *channel(*)*, or you must specify *channel(3)* = 99.
  - *Channel(4)* is the ch# of the SMU or HVU that must be connected to the substrate.

    This function turns the SMU or HVU output switch to ON, and forces *substrate voltage* to the substrate ONLY IF *channel(*)* has four elements and *substrate voltage* is specified.

- *drain voltage* (I/O: I, type: real, unit: V)

  The voltage value that is forced by the *channel(1)* unit.

Unit	*drain voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000

- *gate voltage* (I/O: I, type: real, unit: V)

  The voltage value that is forced by the *channel(2)* unit.

Unit	*gate voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000

- *drain current compliance* (I/O: I, type: real, unit: A)

  The current compliance for the *channel(1)* unit.

Unit	*drain current compliance*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3
HVU	0 to ±10E−3

  Default = 1E−6

- *substrate voltage* (I/O: I, type: real, unit: V)

  The voltage value that is forced by the *channel(4)* unit.

Unit	*substrate voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000

  Default = no connection

Example Statements

```
Ids = FNIds (Channel(*), 6, 0)

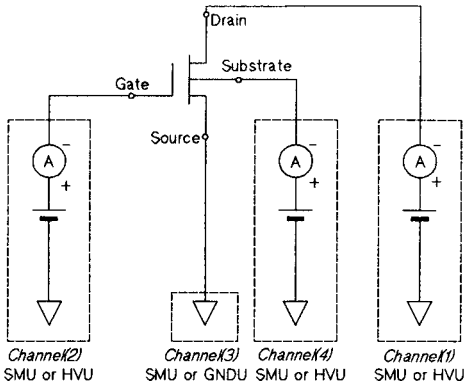
Ids = FNIds (Channel(*), Vds, Vgs, Id_limit, Vsub)
```

Semantics

When using this function, the SMUs, HVUs, and GNDU at *channel(*)* must be connected to the transistor as shown in the circuit below.

The measurement result obtained by the *channel(1)* SMU, which is the transistor's drain current, is returned to the user-specified variable. If an abnormal condition is detected (see the status description in this chapter), −9999999.99999 is returned to the user-specified variable.

Immediately after the measurement, this function sets all SMUs to 0 V output, and sets all SMU output switches to OFF.



Measurement Circuit

FNR_measure

File: PARA_4142

This function uses either a two-terminal or a four-wire (Kelvin connection) method, and performs measurements to determine an unknown resistance. The measurement result is then returned to a user specified variable.

Syntax

`FNR_measure` (*H-force ch#, L-force ch#, H-sense ch#, L-sense ch#, measurement mode, test current* [, *V compliance*])

Parameters

- *H-force ch#* (I/O: I, type: integer)
  L-force ch# (I/O: I, type: integer)

  The ch# of the SMU or HVU that must be connected to one of the resistor's terminals.

- *H-sense ch#* (I/O: I, type: integer)
  L-sense ch# (I/O: I, type: integer)

  The ch# of the SMU, HVU or VM that must be connected to one of the resistor's terminals.

- *measurement mode* (I/O: I, type: integer)

  Selects the resistance measurement mode.

  1: 2-channel measurement
  2: 4-channel measurement
  3: differential measurement

- *test current* (I/O: I, type: real, unit: A)

  This parameter specifies the following: *L-force* unit I output for measurement mode 1, *H-force* unit I output for measurement mode 2 or 3.

Unit	*test current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3
HVU	0 to ±10E−3

- *V compliance* (I/O: I, type: real, unit: V)

  This parameter specifies the following: *L-force* unit V compliance for measurement mode 1, *H-force* and *H-sense* unit V compliance for measurement mode 2, and *H-force* unit V compliance for measurement mode 3.

Unit	*V compliance*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000

Default = 20

Example Statements

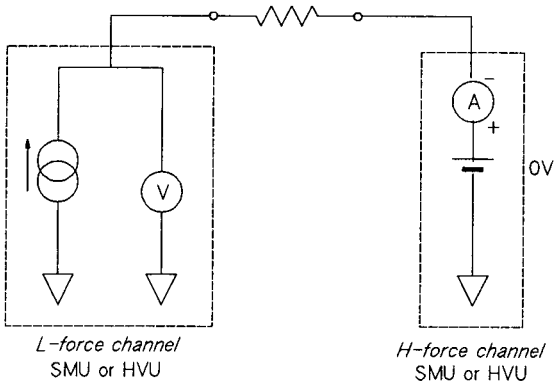
```
R = FNR_measure (1, 2, 3, 4, 2, 1.E-6)

Resistance = FNR_measure (H_force, L_force, H_sense,
 L_sense, Mode, Itest, Vlimit)
```

Semantics

- Measurement mode = 1

  Two SMUs or HVUs are used for the two-terminal resistance measurement. Refer to the circuit shown below.



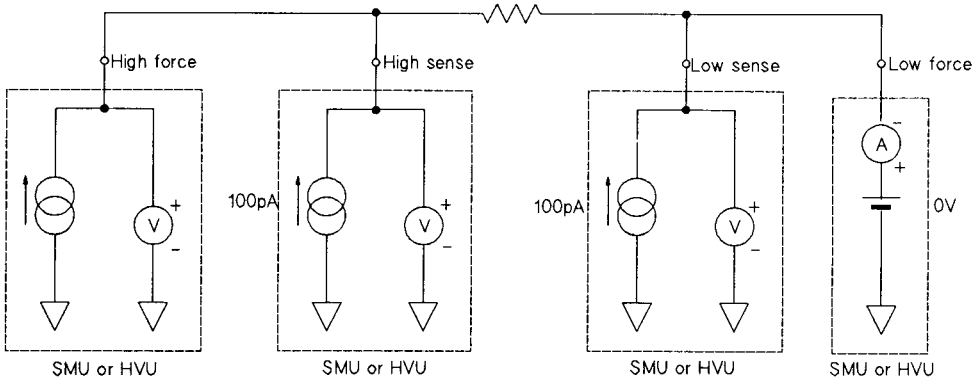
Measurement Circuit

  These two units are specified by *H-force ch#* and *L-force ch#*. *H-sense ch#* and *L-sense ch#* are ignored.

  This function sets the *H-force* unit to 0 V, and forces *test current* from the *L-force* unit. Then, the *H-force* unit measures current, and the *L-force* unit measures voltage. The function then calculates the unknown resistance using Ohm's law and these measurement values. This measurement result is returned to the user-specified variable.

- Measurement mode = 2

  Four SMUs or HVUs are used for the four-wire (Kelvin connection) resistance measurement. Refer to the circuit shown below.



Measurement Circuit

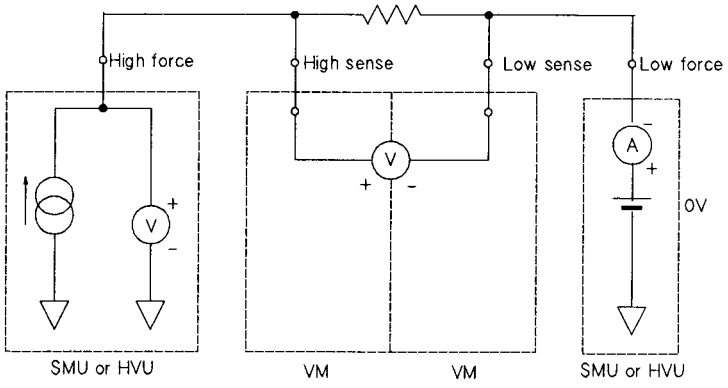
The units specified by *H-force ch#*, *L-force ch#*, *H-sense ch#*, and *L-sense ch#* must be connected as close to the unknown resistance as possible.

This function sets the units as shown in the circuit above, and forces *test current* from the *H-force* unit. Then, the function measures the *L-force* unit current, the *L-sense* unit voltage, and the *H-sense* unit voltage, and uses the equation below to calculate the unknown resistance. This measurement result is returned to the user-specified variable.

Rx = (*L-sense* Voltage − *H-sense* Voltage) / *L-force* Current

- Measurement mode = 3

Two SMUs or HVUs and two VMs are used for this differential measurement. Refer to the circuit shown below.



Measurement Circuit

This function forces *test current* from the *H-force* unit. Then, the *L-force* unit measures current, and the *H-sense* VM and the *L-sense* VM measure the voltage drop across the unknown resistance. The function then uses Ohm's law and these measurement values to calculate the unknown resistance. This measurement result is returned to the user-specified variable.

This function automatically includes a wait time (that is inversely proportional to the specified *test current*) to allow the SMU output capacitance and the DUT capacitance to fully charge before the measurement is made.

If a current measurement value is less than 9.E−7 A (9.E−10 A for *measurement mode* = 1), or a voltage measurement value is less than 1.E−2 V, or compliance is reached, then −9999999.99999 is returned to the user-specified variable. If *test current* is set to its upper limit (±1 A), the *L-force* SMU may reach current compliance.

Immediately after the measurement, this function sets all modules to 0 V output, and sets all module output switches to OFF.

FNVth1

File: PARA_4142

This function measures th gate-source threshold voltage of an enhancement-type FET when a specified *drain current* is forced. The function then returns the measurement result to a user-specified variable. The threshold voltage of an enhancement-type FET is defined as the gate voltage required to cause a predetermined value of drain current to flow.

Syntax

`FNVth1` (*channel(*)*, *drain current* [, *gate voltage compliance*][, *substrate voltage*])

Parameters

- *channel(*)* (I/O: I, type: integer array)

  channel(*) is an integer array containing 1 to 3 elements as follows:

  - *channel(1)* is the ch# of the SMU that must be connected to the drain and gate. The drain must be connected to the gate.
  - *channel(2)* is the ch# of the unit that must be connected to the source.

    If an SMU is connected, this function sets the SMU to 0 V output.

    If a GNDU is connected instead of an SMU, you must specify only one element for *channel(*)*, or you must specify *channel(2)* = 99.
  - *channel(3)* is the ch# of the SMU that must be connected to the substrate. This function turns the SMU output switch to ON, and forces *substrate voltage* to the substrate ONLY IF *channel(*)* has three elements and *substrate voltage* is specified.

- *drain current* (I/O: I, type: real, unit: A)

  The current value that is forced by the *channel(1)* SMU.

Unit	*drain current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3

- *gate voltage compliance* (I/O: I, type: real, unit: V)

  The voltage compliance value for the *channel(1)* SMU.

Unit	*gate voltage compliance*
HPSMU	0 to ±200
MPSMU	0 to ±100

  Default = 20

- *substrate voltage* (I/O: I, type: real, unit: V)

  The voltage value that is forced by the *channel(3)* SMU.

Unit	*substrate voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

  Default = no connection

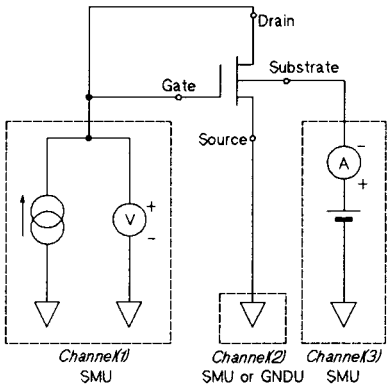
Example Statements

```
Vth = FNVth1 (Channel(*), 1.E-5)

Vth = FNVth1 (Channel(*), Id, Vgs_limit, Vsub)
```

Semantics

When using this function, the SMUs and GNDU at *channel(*)* must be connected to the transistor as shown in the circuit below.



Measurement Circuit

This function automatically includes a wait time (depending on the specified *drain current*) to allow the SMU capacitance to fully charge before the measurement is made.

The measurement result obtained by the *channel(1)* SMU is returned to the user-specified variable as the gate-source threshold voltage. If an abnormal condition is detected (see the status description in this chapter), −9999999.99999 is returned to the user-specified variable.

Immediately after the measurement, this function sets all SMUs to 0 V output, and sets all SMU output switches to OFF.

FNVth2

File: PARA_4142

This function determines the gate-source threshold voltage of an enhancement-type FET by measuring the gate-source voltage at two different *drain current* settings, then uses these values to calculate the threshold voltage as described in Semantics. The function then returns the calculated result to a user-specified variable.

Syntax

`FNVth2` (*channel(*), drain current 1, drain current 2* [, *gate voltage compliance*] [, *substrate voltage*])

Parameters

- *channel(*)* (I/O: I, type: integer array)

  channel(*) is an integer array containing from 1 to 3 elements

  - *channel(1)* is the ch# of the SMU that must be connected to the drain and gate. The drain must be connected to the gate.
  - *channel(2)* is the ch# of the module that must be connected to the source.

    If an SMU is connected, this function sets the SMU to 0 V output.

    If a GNDU is connected instead of an SMU, you must specify only one element for *channel(*)*, or you must specify *channel(2)* = 99.
  - *channel(3)* is the ch# of the SMU that must be connected to the substrate. This function turns the SMU output switch to ON, and forces *substrate voltage* to the substrate ONLY IF *channel(*)* has three elements and *substrate voltage* is specified.

- *drain current 1* (I/O: I, type: real, unit: A)
  drain current 2 (I/O: I, type: real, unit: A)

  The current value that is forced by the *channel(1)* SMU.

Unit	*drain current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3

- *gate voltage compliance* (I/O: I, type: real, unit: V)

  The voltage compliance value for the *channel(1)* SMU.

Unit	gate voltage compliance
HPSMU	0 to ±200
MPSMU	0 to ±100

Default = 20

- *substrate voltage* (I/O: I, type: real, unit: V)

  The voltage value that is forced by the *channel(3)* SMU.

Unit	*substrate voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

Default = no connection

Example Statements

```
Vth = FNVth2 (Channel(*), 1.E-6, 1.E-4)

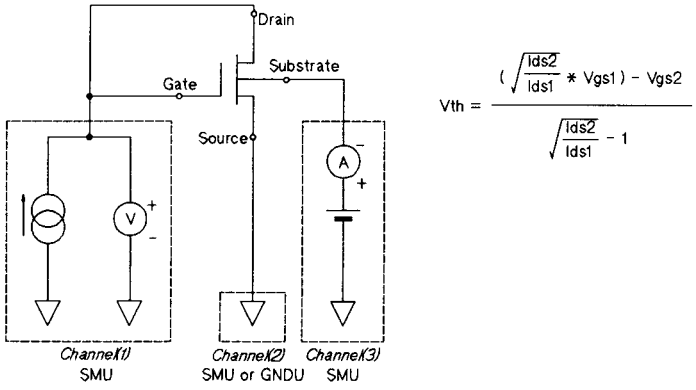
Vth = FNVth2 (Channel(*), Id1, Id2, Vgs_limit, Vsub)
```

Semantics

When using this function, the SMUs and GNDU at *channel(*)* must be connected to the transistor as shown in the circuit below.

This function automatically includes a wait time (depending on the specified *drain current*) to allow the SMU capacitance to fully charge before the measurement is made.

The transistor's gate voltage is measured twice: once when *drain current 1* is being forced, and again when *drain current 2* is being forced. The function then calculates the gate-source threshold voltage using the equation shown below:



Measurement Circuit

where Ids1 and Ids2 are the two specified drain currents, and Vgs1 and Vgs2 are the measured gate voltages. The calculated result is returned to the user-specified variable as the threshold voltage.

If an abnormal condition is detected (see the status description in this chapter), −9999999.99999 is returned to the user-specified variable.

Immediately after the measurement, this function sets all SMUs to 0 V output, and sets all SMU output switches to OFF.

FNVth3

File: PARA_4142

This function measures the gate-source threshold voltage of depletion- or enhancement-type FETs by using the Analog Feedback Unit and two SMUs. The function then returns the measurement result to a user-specified variable.

Syntax

`FNVth3` (*channel(*), target drain current, drain voltage, start gate voltage, stop gate voltage, gate current compliance* [, *ramp rate*] [, *feedback integration time*] [, *substrate voltage*])

Parameters

- *channel(*)* (I/O: I, type: integer array)

  channel(*) is an integer array containing 2 to 4 elements as follows:

  - *channel(1)* is the sense SMU ch#, and must be connected to the drain.
  - *channel(2)* is the search SMU ch#, and must be connected to the gate.
  - *channel(3)* is the ch# of the module that must be connected to the source.

    If an SMU is connected, this function sets the SMU to 0 V output.

    If a GNDU is connected, you must specify only two elements for *channel(*)*, or you must set *channel(3)* = 99.
  - *channel(4)* is the ch# of the SMU that must be connected to the substrate. This function turns the SMU output switch to ON, and forces *substrate voltage* to the substrate ONLY IF *channel(*)* has four elements and *substrate voltage* is specified.

- *target drain current* (I/O: I, type: real, unit: A)

  The target current value for the *channel(1)* SMU (sense SMU).

Unit	*target drain current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3

- *drain voltage* (I/O: I, type: real, unit: V)

  The voltage value that is forced by the *channel(1)* SMU.

Unit	*drain voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

- *start gate voltage* (I/O: I, type: real, unit: V)

  The search start voltage value for the *channel(2)* SMU.

Unit	*start gate voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

- *stop gate voltage* (I/O: I, type: real, unit: V)

  The search stop voltage value for the *channel(2)* SMU.

Unit	*stop gate voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

- *gate current compliance* (I/O: I, type: real, unit: A)

  The current compliance value for the *channel(2)* SMU.

Unit	*gate current compliance*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3

- *ramp rate* (I/O: I, type: real, unit: V/s)

  The ramp rate value of the *channel(2)* SMU (search SMU). The allowable values are 0.5 to 100000.

  Default = 500

  See the Set_asearch subprogram description.

- *feedback integration time* (I/O: I, type: real, unit: s)

  The feedback integration time for the analog feedback measurement.

  The allowable values are 0.5E−6 to 450E−3.

  Default = 0.1

  See the Measure_asearch subprogram description.

- *substrate voltage* (I/O: I, type: real, unit: V)

  The voltage value that is forced by the *channel(4)* SMU.

Unit	*substrate voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

Example Statements

```
Vth = FNVth3 (Channel(*),Id, Vds, Vgmin, Vgmax, Igmax, Ramp, Integ, Vsub)
```

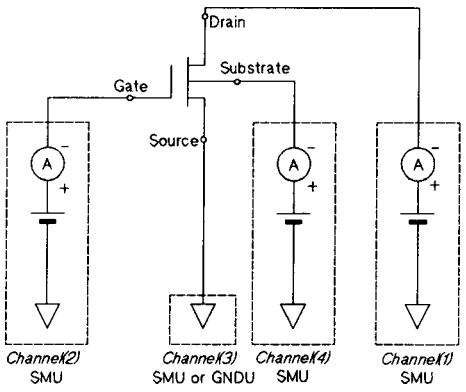
Semantics

When using this function, the SMUs and GNDU at *channel(*)* must be connected to the transistor as shown in the circuit below.

For this measurement, the function uses the AFU and two SMUs. The *channel(2)* SMU varies the gate voltage until the *channel(1)* SMU senses that the *target drain current* has been reached. Then, the function returns the gate voltage to the user-specified variable.

If an abnormal condition is detected (see the status description in this chapter), or if the threshold voltage is not between the *start gate voltage* and the *stop gate voltage*, the function returns −9999999.99999 to the user-specified variable.

Immediately after the measurement, this function sets all SMUs to 0 V output, and sets all SMU output switches to OFF.



Measurement Circuit

Force_i

File: HP4142_DRV

This subprogram forces *output current* from a specified SMU or HVU.

HP-IB Command:

DI

Syntax

`Force_i` (*output ch#, output current* [, *I output range*] [, *V compliance*] [, *compliance polarity mode*])

Parameters

- *output ch#* (I/O: I, type: integer)

Unit	*output ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8

- *output current* (I/O: I, type: real, unit: A)

Unit	*output current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3
HVU	0 to ±10E−3

- *I output range* (I/O: I, type: real)

0: Auto ranging
1E−9: 1 nA Limited Auto ranging
1E−8: 10 nA Limited Auto ranging
1E−7: 100 nA Limited Auto ranging
1E−6: 1 μA Limited Auto ranging
1E−5: 10 μA Limited Auto ranging
1E−4: 100 μA Limited Auto ranging
1E−3: 1 mA Limited Auto ranging
1E−2: 10 mA Limited Auto ranging
1E−1: 100 mA Limited Auto ranging
1: 1 A Limited Auto ranging

Default = 0

- *V compliance* (I/O: I, type: real, unit: V)

Unit	*V compliance*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000

Default:

- If the unit is set to I source mode:
  Default = the previous setting
- If the unit is set to V source mode:
  Default = none

- *compliance polarity mode* (I/O: I, type: integer)

  0: Auto mode
  1: Manual mode

Default = 0

Example Statements

```
Force_i (1, 1.0E-6, 0)

Force_i (Ch1, 1.0E-6, 0, 10.0, 0)

Force_i (Trbase, Current, Range, Compliance, Polarity)
```

Force_v

File: HP4142_DRV

This subprogram forces *output voltage* from a specified SMU, HVU, or VS.

HP-IB Command:

DV

Syntax

For SMUs or HVUs:

`Force_v` (*output ch#, output voltage* [, *V output range*][, *I compliance*] [, *compliance polarity mode*])

For VSs:

`Force_v` (*output ch#, output voltage* [, *V output range*])

Parameters

- *output ch#* (I/O: I, type: integer)

Unit	*output ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
VS	1 to 8, 11 to 18 or 21 to 28

- *output voltage* (I/O: I, type: real, unit: V)

Unit	*output voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000
VS	0 to ±40

- *V output range* (I/O: I, type: real)

0: Auto ranging
2: 2 V Limited Auto ranging
20: 20 V Limited Auto ranging
40: 40 V Limited Auto ranging
100: 100 V Limited Auto ranging
200: 200 V Limited Auto ranging

500: 500 V Limited Auto ranging
1000: 1000 V Limited Auto ranging

Default = 0

- *I compliance* (I/O: I, type: real, unit: A)

Unit	*I compliance*
HPSMU	±(1E−12 to 1)
MPSMU	±(1E−12 to 100E−3)
HVU	±(1E−9 to 10E−3)

Default:

- If the SMU is set to V source mode:

  Default = the previous setting

- If the SMU is set to I source mode:

  Default = none

- *compliance polarity mode* (I/O: I, type: integer)

  0: Auto mode
  1: Manual mode

Default = 0

Example Statements

```
Force_v (1, 10.0, 0)

Force_v (Drain, Vds, 0, 1.0E−3)

Force_v (Ch1, Voltage, Range, Compliance, Polarity)
```

Init_computer

File: GRAPHICS

This subprogram sets keyboard auto-repeat parameters, clears the screen and turns off softkey labels, and enables alpha and graphics screens.

If the computer has a color display, this subprogram sets yellow alpha characters on a blue background.

Syntax

```
Init_computer ( [separate pages])
```

Parameters

- *separate page* (I/O: I, type: integer)

  This optional parameter is available only for HP 9000 Series 300 computers that have a bit-mapped color display.

  0: separate page OFF
  1: separate page ON

  Default = 0

Example Statements

```
Init_computer (1)

Init_computer
```

Init_hp4142

File: HP4142_DRV

This subprogram sets all plug-in units to the initial settings, and clears the output data buffer and all error conditions. This subprogram also sets the trigger mode to TM2. After this subprogram is executed, all bits of the status byte are masked except bits 7, 6, 5, and 3.

To ensure correct measurement execution, include Init_hp4142 at the beginning of the your program, before other Control Software subprograms.

HP-IB Command:

*RST, *SRE, TM

Syntax

```
Init_hp4142
```

Example Statements

```
Init_hp4142
```

Lingraph

File: GRAPHICS

This subprogram clears the CRT, draws and numbers a linear graph with *X-min* and *Y-min* as the minimum values and *X-max* and *Y-max* as the maximum values, and labels both axes and the graph.

Syntax

`Lingraph` (*X-min*, *X-max*, *Y-minY*, *Y-max*, *X-axis name$*, *Y-axis name$*, *graph name$* [, *grid control*] [, *quadrant*] [, *right subtitle$*] [, *left subtitle$*])

Parameters

- *X-min* (I/O: I, type: real)
  X-max (I/O: I, type: real)
  Y-min (I/O: I, type: real)
  Y-max (I/O: I, type: real)

  These parameters define the lower left and upper right point of the graph. For the best results, you should set *X-min*, *X-max*, *Y-min*, and *Y-max* values that include all measurement values. The maximum and minimum values for an axis cannot be the same. *X-min* larger than *X-max*, and *Y-min* larger than *Y-max* are allowed.

- *X-axis name$* (I/O: I, type: string)
  Y-axis name$ (I/O: I, type: string)

  Maximum 30 characters are allowed. For *quadrant* values 1 to 4, less than 20 characters are recommended. Otherwise, titles overlap other areas or other titles.

- *graph name$* (I/O: I, type: string)

  The title of the graph. Maximum 35 characters are allowed.

- *grid control* (I/O: I, type: integer)

  0: no grid lines
  1: dotted grid lines
  2: solid grid lines

  Default = 0

- *quadrant* (I/O: I, type: integer)

  0: full screen
  1: upper right
  2: upper left
  3: lower left
  4: lower right

  Default = 0

- *right subtitle$* (I/O: I, type: string)
  left subtitle$ (I/O: I, type: string)

  Maximum 20 characters are allowed.

Default = none

Example Statements

```
Lingraph (-5, 5, -1E-3, 1E-3, "Vce",
 "Ic", "Vce-Ic Characteristics")

Lingraph (X_min, X_max, Y_min, Y_max, X_name$, Y_name$,
 Title$, Grid, Quadrant, Right_subtitle$, Left_subtitle$)
```

Loggraph

File: GRAPHICS

This subprogram clears the CRT, draws and numbers a log graph with *X-min* and *Y-min* as the minimum values and *X-max* and *Y-max* as the maximum values, and labels both axes and the graph.

Syntax

`Loggraph` (*X-min*, *X-max*, *Y-min*, *Y-max*, *X-axis name$*, *Y-axis name$*, *graph name$* [, *graph mode*] [, *grid control*] [, *quadrant*] [, *right subtitle$*] [,*left subtitle$*])

Parameters

- *X-min* (I/O: I, type: real)
  X-max (I/O: I, type: real)
  Y-min (I/O: I, type: real)
  Y-max (I/O: I, type: real)

  These parameters define the lower left and upper right point of the graph. For the best results, you should specify *X-min*, *X-max*, *Y-min*, and *Y-max* values that include all measurement values. The minimum and maximum values cannot be equal. For a log axis, the minimum and the maximum value for an axis must have the same polarity (0 is not allowed for a log axis). *X-min* larger than *X-max*, and *Y-min* larger than *Y-max* are allowed.

- *X-axis name$* (I/O: I, type: string)
  Y-axis name$ (I/O: I, type: string)

  Maximum 30 characters are allowed. For *quadrant* values 1 to 4, less than 20 characters are recommended. Otherwise, titles overlap other areas or other titles.

- *graph name$* (I/O: I, type: string)

  Maximum 35 characters are allowed.

- *graph mode* (I/O: I, type: integer)

  Selects each axis scaling mode.

  1: X-lin Y-log
  2: X-log Y-lin
  3: X-log Y-log

- *grid control* (I/O: I, type: integer)

  0: no grid lines
  1: dotted grid lines
  2: solid grid lines

  Default = 0

- *quadrant* (I/O: I, type: integer)

  0: full screen
  1: upper right
  2: upper left

3: lower left
4: lower right

Default = 0

- *right subtitle$* (I/O: I, type: string)
  left subtitle$ (I/O: I, type: string)

  Maximum 20 characters are allowed.

  Default = none

Example Statements

```
Loggraph (0, 5, 1.E-12, 1.E-6, "Vgs", "Id",
 "Vgs-Id Characteristics", 1)

Loggraph (Xmin, Xmax, Ymin, Ymax, Xname$, Yname$,
 Graph_name$, Mode, Griding)
```

Measure_asearch

File: HP4142_DRV

This subprogram triggers an analog search measurement, and returns the measurement value(s) as determined by the parameters specified in this subprogram and the parameters specified in the Set_asource and Set_amonitor subprograms.

HP-IB Command:

FMT, MM, ASM, XE

Syntax

Measure_asearch (*search operation mode*, *search measurement mode*, *feedback integration time*, *search data* [, *sense data*] [, *status*])

Parameters

- *search operation mode* (I/O: I, type: integer)

  1: negative feedback search
  2: positive feedback search
  3: ramp wave search (greater then target)
  4: ramp wave search (less then target)

- *search measurement mode* (I/O: I, type: integer)

  1: search SMU V measurement
  2: search SMU I measurement
  3: search SMU V and sense SMU V or I measurement
  4: search SMU I and sense SMU V or I measurement

  If the sense SMU is set to I source (voltage monitor) mode, a V measurement is made.

  If the sense SMU is set to V source (current monitor) mode, an I measurement is made.

- *feedback integration time* (I/O: I, type: real, unit: s)

Search SMU Output Range[1]	*feedback integration time*	Resolution
2 V	50E−6 to 450E−6	50E−6
	0.5E−3 to 4.5E−3	0.5E−3
	5E−3 to 45E−3	5E−3
	50E−3 to 450E−3	50E−3
20 V	5E−6 to 45E−6	5E−6
	50E−6 to 450E−6	50E−6
	0.5E−3 to 4.5E−3	0.5E−3
	5E−3 to 45E−3	5E−3
40 V	2.5E−6 to 4.5E−6	0.5E−6
	5E−6 to 45E−6	5E−6
	50E−6 to 450E−6	50E−6
	0.5E−3 to 4.5E−3	0.5E−3
	5E−3 to 25E−3	5E−3
100 V	1E−6 to 4.5E−6	0.5E−6
	5E−6 to 45E−6	5E−6
	50E−6 to 450E−6	50E−6
	0.5E−3 to 4.5E−3	0.5E−3
	5E−3 to 10E−3	5E−3
200 V	0.5E−6 to 4.5E−6	0.5E−6
	5E−6 to 45E−6	5E−6
	50E−6 to 450E−6	50E−6
	0.5E−3 to 4.5E−3	0.5E−3
	5E−3	

1 The *feedback integration time* allowed depends on the V output range that is automatically set for the search SMU. Refer to the Set_asource subprogram description.

The *feedback integration time* parameter has no meaning when the *search operation mode* parameter is set to 3 or 4.

- *search data* (I/O: O, type: real, unit: V or A)
  sense data (I/O: O, type: real, unit: V or A)

  If you specify *search measurement mode* = 1 or 2, the search SMU measurement value is returned to *search data*. If you specify *search measurement mode* = 3 or 4, the search SMU measurement value is returned to *search data*, and the sense SMU measurement value is returned to the *sense data*.

- *status* (I/O: O, type: integer)

If you specify *status*, you must declare it as integer type. After the measurement is performed, an integer is returned to *status*.

If the *status* parameter is not set and an illegal status occurs, a message is displayed on the CRT.

For the returned *status*, the tens digit corresponds to search SMU measurement data and the ones digit corresponds to sense SMU measurement data. For example, if the returned status is 60, then 6 is the search SMU data status and 0 is the sense SMU data status.

For the meanings of the returned *status*, refer to the status description in this chapter.

Example Statements

```
Measure_asearch (1, 1, 1E-3, Data)

Measure_asearch (Search_mode, Meas_mode, Integ,
 Search_value, Sense_value, Status)
```

Measure_bdm

File: HP4142_DRV

This subprogram triggers a quasi-pulsed measurement and returns the measurement value as determined by the parameters specified in this subprogram and the Set_bdm subprograms.

HP-IB Command:

MM, BDM, XE

Syntax

Measure_bdm (*measurement ch#, detection interval, V/I measurement, measured value* [, *status*])

Parameters

- *measurement ch#* (I/O: I, type: integer)

Unit	*measurement ch#*
HVU	2 to 8
HPSMU	2 to 8
MPSMU	1 to 8

- *detection interval* (I/O: I, type: integer)

  0: Short
  1: Long

- *V/I measurement* (I/O: I, type: integer)

  0: Voltage measurement
  1: Current measurement

- *measured value* (I/O: O, type: real, unit: V/A)

  The measured value is returned to this parameter.

- *status* (I/O: O, type: integer)

  If you specify status, you must declare it as integer type. After the measurement is performed, an integer is returned to *status*.

  Refer to the status description in this chapter.

Example Statements

```
Measure_bdm(2,0,1,Bvceo)
```

Measure_i

File: HP4142_DRV

This subprogram triggers a high speed spot current measurement using the specified unit independent of the source mode (V/I source mode), and returns the measurement value to the specified return current variable.

HP-IB Command:

FMT, TI

Syntax

`Measure_i` (*measurement ch#*, *return current variable* [, *I measurement range*] [, *status*])

Parameters

- *measurement ch#* (I/O: I, type: integer)

Unit	*measurement ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HCU	2 to 8
HVU	2 to 8
VS	1 to 8, 11 to 18, or 21 to 28

- *return current variable* (I/O: O, type: real, unit: A)

  The measured current value is returned to this parameter.

- *I measurement range* (I/O: I, type: real)

0:	Auto ranging
1E−9:	1 nA Limited Auto ranging
10E−9:	10 nA Limited Auto ranging
100E−9:	100 nA Limited Auto ranging
1E−6:	1 μA Limited Auto ranging
10E−6:	10 μA Limited Auto ranging
100E−6:	100 μA Limited Auto ranging
1E−3:	1 mA Limited Auto ranging
10E−3:	10 mA Limited Auto ranging
100E−3:	100 mA Limited Auto ranging
1:	1 A Limited Auto ranging
10:	10 A Limited Auto ranging
−1E−9:	1 nA range fixed
−10E−9:	10 nA range fixed

−100E−9:	100 nA range fixed
−1E−6:	1 μA range fixed
−10E−6:	10 μA range fixed
−100E−6:	100 μA range fixed
−1E−3:	1 mA range fixed
−10E−3:	10 mA range fixed
−100E−3:	100 mA range fixed
−1:	1 A range fixed
−10:	10 A range fixed

Default = 0

- *status* (I/O: O, type: integer)

  If you specify *status*, you must declare it as integer type. After the measurement is performed, an integer is returned to *status*.

  Refer to the status description in this chapter.

Example Statements

```
Measure_i (1, Current)

Measure_i (Ch1, Current, 0)

Measure_i (Ch1, Ids, 10E−6, Data_status)

Measure_i (Drain, Ids, Range, Data_status)
```

Measure_v

File: HP4142_DRV

This subprogram triggers a high speed spot voltage measurement using the specified unit independent of the source mode (V/I source mode), and returns the measurement value to the specified *return voltage variable*.

HP-IB Command:

FMT, TV

Syntax

Measure_v (*measurement ch#*, *return voltage variable* [, *V measurement range*] [, *status*])

Parameters

- *measurement ch#* (I/O: I, type: integer)

Unit	*measurement ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HCU	2 to 8
HVU	2 to 8
VM	1 to 8, 11 to 18 or 21 to 28

- *return voltage variable* (I/O: O, type: real, unit: V)

  The measured voltage value is returned to this parameter.

  V measurement range (I/O: I, type: real)

- The *V measurement range* sets the voltage measurement range of VMs. The voltage measurement range of SMUs, HVUs, or HCUs is set to the Compliance ranging automatically, regardless of specified value.

  0: Auto ranging
  0.2: 0.2 V range fixed
  2: 2 V range fixed
  20: 20 V range fixed
  40: 40 V range fixed

  Default = 0

- *status* (I/O: O, type: integer)

  If you specify *status*, you must declare it as integer type. After the measurement is performed, an integer is returned to *status*.

Refer to the status description in this chapter.

Example Statements

```
Measure_v (1, Voltage)

Measure_v (1, Voltage, 0)

Measure_v (Drain, Vds, Range, Data_status)
```

Para_hfe

File: HP4142_DRV

This subprogram calculates and returns parameters that are required for h_{FE} measurements using the Analog Feedback Unit (AFU). The parameter calculations are based on the measurement condition parameters and DUT characteristic parameters that you enter for this subprogram. This subprogram returns the optimized *base current compliance*, *feedback integration time*, *ramp rate*, and *delay time* values needed to perform the h_{FE}measurement.

Syntax

Para_hfe (*collector voltage*, *target collector current*, *collector current compliance*, *start base voltage*, *stop base voltage*, *hfe min*, *hfe max*, *transition frequency*, *input capacitance*, *base-collector capacitance*, *maximum base current*, *base current compliance*, *feedback integration time*, *ramp rate*, *delay time* [, *error*] [, *hold time*] [*collector capacitance*])

Parameters

- *collector voltage* (I/O: I, type: real, unit: V)

  Input the *output voltage* for Set_amonitor subprogram as this parameter.

  The allowable values are 0 to ±200.

- *target collector current* (I/O: I, type: real, unit: A)

  Input the *target current* for Set_amonitor subprogram as this parameter.

  The allowable values are ±1E−11 to ±0.9.

- *collector current compliance* (I/O: I, type: real, unit: A)

  Input the *I compliance* for the Set_amonitor subprogram as this parameter. It is recommended that the following equation is satisfied:

  collector current compliance = 1.05 × *target collector current*

  The allowable values are ±1.05E−11 to ±1.

- *start base voltage* (I/O: I, type: real, unit: V)

  Input the *search start voltage* for the Set_asource subprogram as this parameter.

  The allowable values are 0 to ±200.

- *stop base voltage* (I/O: I, type: real, unit: V)

  Input the *search stop voltage* for the Set_asource subprogram as this parameter.

  The allowable values are 0 to ±200.

- *hfe min* (I/O: I, type: real)
  hfe max (I/O: I, type: real)

  Input the h_{FE} MAX and MIN value of DUT as these parameters. See DUT data sheet.

- *transition frequency* (I/O: I, type: real, unit: Hz)

Input the transition frequency f_T (frequency when $h_{FE} = 1$) of DUT as this parameter. See DUT data sheet.

- *input capacitance* (I/O: I, type: real, unit: F)

  Input the search SMU's load capacitance as this parameter.

  You can calculate the search SMU's load capacitance by adding the base input capacitance Cib of DUT (see DUT data sheet) to your measurement circuit's residual capacitance.

  The allowable values are 0 to 20E−9.

- *base-collector capacitance* (I/O: I, type: real, unit: F)

  Add the base-collector capacitance Cbc of DUT (see DUT data sheet) to your measurement circuit's residual capacitance and input this figure for the parameter.

  The allowable values are 0 to 20E−9.

- *maximum base current* (I/O: O, type: real, unit: A)

  The *target collector current / hfe min* value is returned to this parameter.

- *base current compliance* (I/O: O, type: real, unit: A)

  The *I compliance* for the Set_asource subprogram is returned to this parameter.

- *feedback integration time* (I/O: O, type: real, unit: s)

  The *feedback integration time* for Measure_asearch subprogram is returned to this parameter.

- *ramp rate* (I/O: O, type: real, unit: V/s)

  The *ramp rate* for the Set_asource subprogram is returned to this parameter.

- *delay time* (I/O: O, type: real, unit: s)

  The *delay time* for the Set_asource subprogram is returned to this parameter.

- *error* (I/O: O, type: integer)

  If optimized parameters cannot be calculated from the parameters that you input, an error code is returned to the *error* and the operation stops. If you do not specify the *error* parameter, an error message is displayed on the CRT. The error code meanings are as follows:

  0: No error
  10: |*collector voltage*| > 200 is not allowed
  11: Allowed *target collector current* values are ±1E−11 to ±0.9
  12: *target collector current* and *collector voltage* must be the same polarity
  13: |*collector current compliance*| > 1 or |*collector current compliance*| < 1.05 × |*target collector current*| is not allowed
  14: *collector current compliance* and *target collector current* must be same polarity
  15: |*start base voltage*| > 200 is not allowed
  16: |*stop base voltage*| > 200 is not allowed
  17: (*stop base voltage* − *start base voltage*) and *collector voltage* must be same polarity
  19: *hfe min* < 1 or *hfe max* < 1 is not allowed
  20: *hfe max* ≤ *hfe min* is not allowed
  21: *transition frequency* ≤ 0 is not allowed
  22: *input capacitance* must be 0 to 20 nF

23: *base-collector capacitance* must be 0 to 20 nF
24: *collector capacitance* must be 0 to 20 nF
30: |*start base voltage* − *stop base voltage*| is too small
31: |*start base voltage* − *stop base voltage*| > 200 is not allowed

- *hold time* (I/O: O, type: real, unit: s)

  The *hold time* for the Set_asource subprogram is returned to this parameter.

- *collector capacitance* (I/O: I, type: real, unit: F)

  Input the sense SMU's load capacitance as this parameter.

  You can calculate the sense SMU's load capacitance by adding the collector capacitance Cc of DUT (see DUT data sheet) to your measurement circuit's residual capacitance.

  The allowable values are 0 to 20E−9.

Example Statements

```
Para_hfe (5, 1.E−2, 5.E−2, 0, .8, 25, 200,
 1.E+8, 5.E−12, 2.E−12, Ib, Ib_max, Integ,
 Rspeed, Dtime, Err)
```

Semantics

When using the AFU to perform an h_{FE} measurement, first execute the following subprogram to get the optimized parameters for the Set_asource and Measure_asearch subprograms:

```
Para_hfe (Vc, Ic, Ic_comp, Vb_start, Vb_stop, Hfe_min,
 Hfe_max, Ft, Cib, Cob, Ib_max, Ib_comp, Integ, Rspeed,
 Dtime, Err)
Set_asource (Ch1, Vb_start, Vb_stop, Rspeed, Htime, Dtime,
 Ib_comp)
Set_amonitor (Ch2, 1, Vc, Ic, Ic_comp)
Measure_asearch (1, 4, Integ, Ibmeas, Icmeas, Status)
Hfe = Icmeas/Ibmeas
```

Para_vth

File: HP4142_DRV

This subprogram calculates and returns parameters that are required for V_{TH} measurements using the AFU. The parameter calculations are based on the measurement condition parameters and DUT characteristic parameters that you enter for this subprogram. This subprogram returns the optimized *feedback integration time*, *ramp rate*, and *delay time* that are needed to perform the V_{TH} measurement.

The search SMU must be connected to the gate, the sense SMU must be connected to the drain, and the GNDU or a 0 V output SMU must be connected to the source.

Syntax

`Para_vth` (*drain voltage*, *target drain current*, *drain current compliance*, *start gate voltage*, *stop gate voltage*, *gate current compliance*, *input capacitance*, *gate-drain capacitance*, *feedback integration time*, *ramp rate*, *delay time* [, *error*] [, *hold time*] [, *gm*] [, *output capacitance*])

Parameters

- *drain voltage* (I/O: I, type: real, unit: V)

  Input the *output voltage* for the Set_amonitor subprogram as this parameter.

  The allowable values are 0 to ±200.

- *target drain current* (I/O: I, type: real, unit: A)

  Input the *target current* for the Set_amonitor subprogram as this parameter.

  The allowable values are ±1E−11 to ±0.9.

- *drain current compliance* (I/O: I, type: real, unit: A)

  Input the *I compliance* for the Set_amonitor subprogram as this parameter. It is recommended that the following equation is satisfied:

  drain current compliance = 1.05 × *target drain current*

  The allowable values are ±1.05E−11 to ±1.

- *start gate voltage* (I/O: I, type: real, unit: V)

  Input the *search start voltage* for the Set_asource subprogram as this parameter.

  The allowable values are 0 to ±200.

- *stop gate voltage* (I/O: I, type: real, unit: V)

  Input the *search stop voltage* for the Set_asource subprogram as this parameter.

  The allowable values are 0 to ±200.

- *gate current compliance* (I/O: I, type: real, unit: A)

  Input the *I compliance* for the Set_asource subprogram as this parameter.

  The allowable values are ±1E−12 to ±1.

- *input capacitance* (I/O: I, type: real, unit: F)

  Input the search SMU's load capacitance as this parameter.

  You can calculate the search SMU's load capacitance by adding the base input capacitance Ciss of DUT (see DUT data sheet) to your measurement circuit's residual capacitance.

  The allowable values are 0 to 2E−8.

- *gate-drain capacitance* (I/O: I, type: real, unit: F)

  Add the gate-drain capacitance Crss of DUT (see DUT data sheet) to your measurement circuit's residual capacitance and input this figure for the parameter.

  The allowable values are 0 to 2E−8.

- *feedback integration time* (I/O: O, type: real, unit: s)

  The *feedback integration time* for the Measure_asearch subprogram is returned to this parameter.

- *ramp rate* (I/O: O, type: real, unit: V/s)

  The *ramp rate* for the Set_asource subprogram is returned to this parameter.

- *delay time* (I/O: O, type: real, unit: s)

  The *delay time* for the Set_asource subprogram is returned to this parameter.

- *error* (I/O: O, type: integer)

  If optimized parameters cannot be calculated from the parameters that you input, an error code is returned to the *error* parameter and the operation stops. If you do not specify the *error* parameter, an error message is displayed on the CRT. The error code meanings are as follows:

  0: No error
  10: *drain voltage* > 200 V is not allowed
  11: Allowed *target drain current* values are ±1E−11 to ±0.9 A
  12: *drain voltage* and *target drain current* must be the same polarity
  13: *drain current compliance* > 1 A or *drain current compliance* < 1.05 × *target drain current* is not allowed
  14: *drain current compliance* and *target drain current* must be same polarity
  15: |*start gate voltage*| > 200 is not allowed
  16: |*stop gate voltage*| > 200 is not allowed
  17: (*stop gate voltage* − *start gate voltage*) and *drain voltage* must be same polarity
  19: Allowed *gate current compliance* values are ±1E−12 to ±1 A
  20: *gate input capacitance* must be 0 to 20 nF
  21: *gate-drain capacitance* must be 0 to 20 nF
  22: *output capacitance* must be 0 to 20 nF
  30: |*start gate voltage* − *stop gate voltage*| is too small
  31: |*start gate voltage* − *stop gate voltage*| > 200 is not allowed

- *hold time* (I/O: O, type: real, unit: s)

  The *hold time* for the Set_asource subprogram is returned to this parameter.

- *gm* (I/O: I, type: real, unit: siemens)

  Input the transconductance of the DUT (see DUT data sheet) as this parameter.

- *output capacitance* (I/O: I, type: real, unit: F)

  Input the sense SMU's load capacitance as this parameter.

  You can calculate the sense SMU's load capacitance by adding the output capacitance Coss of DUT (see DUT data sheet) to your measurement circuit's residual capacitance.

  The allowable values are 0 to 2E−8.

Example Statements

```
Para_vth (10, 1.E−5, 3.E−2, 0, 3, 1.E−5,
 5.E−12, 2.E−12, Integ, Rspeed, Dtime, Err)
```

Semantics

When using the AFU to perform an V_{TH} measurement, first execute the following subprogram to get the optimized parameters for the Set_asource and Measure_asearch subprograms:

```
Para_vth (Vd, Id, Id_comp, Vg_start, Vg_stop, Ig_comp, Ciss,
 Crss, Integ, Rspeed, Dtime, Err, Gm, Cd, Htime)
Set_asource (Ch1, Vg_start, Vg_stop, Rspeed, Htime, Dtime,
 Ig_comp)
Set_amonitor (Ch2, 1, Vd, Id, Id_comp)
Measure_asearch (1, 3, Integ, Vth, Id, Status)
```

Pulse_i

File: HP4142_DRV

This subprogram sets an SMU, HVU, or HCU to pulsed I source and specifies its parameters for a pulsed measurement.

HP-IB Command:

PI, PT

Syntax

For SMUs or HVUs:

`Pulse_i` (*output ch#, I output range, base current, pulse current, pulse width, hold time* [, *pulse period*] [, *V compliance*])

For HCUs:

`Pulse_i` (*output ch#, I output range, base current, pulse current, pulse width, hold time, pulse period, V compliance*)

Parameters

- *output ch#* (I/O: I, type: integer)

Unit	*output ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
HCU	2 to 8

- *I output range* (I/O: I, type: real)

0: Auto ranging
1E−8: 10 nA Limited Auto ranging
1E−7: 100 nA Limited Auto ranging
1E−6: 1 μA Limited Auto ranging
1E−5: 10 μA Limited Auto ranging
1E−4: 100 μA Limited Auto ranging
1E−3: 1 mA Limited Auto ranging
1E−2: 10 mA Limited Auto ranging
1E−1: 100 mA Limited Auto ranging
1: 1 A Limited Auto ranging
10: 10 A Limited Auto ranging

Default = 0

- *base current* (I/O: I, type: real, unit: A)
  pulse current (I/O: I, type: real, unit: A)

Unit	*base current*[1]	*pulse current*[1]
HPSMU	0 to ±1	0 to ±1
MPSMU	0 to ±100E−3	0 to ±100E−3
HVU	0 to ±10E−3	0 to ±10E−3
HCU	0[2]	0 to ±10

1 The *pulse current* and *base current* polarity must be the same.

2 During base value output, the HCU output is 0 V and no current.

- *pulse width* (I/O: I , type: real, unit: s)

  0.0001 to 0.05

  resolution: 0.0001

- *hold time* (I/O: I , type: real, unit: s)

  0 to 655.35

  resolution: 0.01

- *pulse period* (I/O: I , type: real, unit: s)

  0.01 to 0.5

  resolution: 0.0001

  Default = 0

- *V compliance* (I/O: I, type: real, unit: V)

Unit	*V compliance*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000
HCU	0 to ±10

  Default:

  - If the specified SMU is set to I source mode before the trigger:

    Default = the setting before trigger

  - If the specified SMU is set to V source mode before the trigger:

    Default = none

Example Statements

```
Pulse_i (1, 0, 1E-3, 50-E-3, 1E-3, 0.1)

Pulse_i (Ch1, Range, Base, Value, Width, Hold_time, Period, Compliance)
```

Pulse_measure

File: HP4142_DRV

This subprogram triggers a 1-ch pulsed spot measurement. A pulse output is determined by the Pulse_v or Pulse_i subprogram, a measurement is performed at the specified measurement ch#, and the measurement value is returned to the specified *measurement variable*.

HP-IB Command:

MM, FL, RV, RI, XE

Syntax

For Voltage Measurements:

`Pulse_measure (` *measurement ch#*`, 1,` *measurement variable* [`,` *V measurement range*] [`,` *status*]`)`

For Current Measurements:

`Pulse_measure (` *measurement ch#*`, 2,` *measurement variable* [`,` *I measurement range*] [`,` *status*]`)`

Parameters

- *measurement ch#* (I/O: I, type: integer)

Unit	*measurement ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
HCU	2 to 8
VM	1 to 8, 11 to 18 or 21 to 28

- *measurement variable* (I/O: O, type: real, unit: V or A)

  The measured value is returned to this parameter.

- *V measurement range* (I/O: I, type: real)

  The V measurement range sets the voltage measurement range of VMs. The voltage measurement range of SMUs, HVUs, or HCUs is set to the Compliance range automatically, regardless of the specified value.

  0: 40 V range fixed
  2: 2 V range fixed
  20: 20 V range fixed
  40: 40 V range fixed

  Default = 0

- *I measurement range* (I/O: I, type: real)

0:	Compliance range
−1E−8:	10 nA range fixed
−1E−7:	100 nA range fixed
−1E−6:	1 μA range fixed
−1E−5:	10 μA range fixed
−1E−4:	100 μA range fixed
−1E−3:	1 mA range fixed
−1E−2:	10 mA range fixed
−1E−1:	100 mA range fixed
−1:	1 A range fixed
−10:	10 A range fixed

Default = 0

- *status* (I/O: O, type: integer)

If you specify *status*, you must declare it as integer type. After the measurement is performed, an integer is returned to *status*.

Refer to the status description in this chapter.

Example Statements

```
Pulse_measure (1, 1, Voltage)

Pulse_measure (2, 2, Current)

Pulse_measure (Ch1, Meas_mode, Meas_value, Range, Status)
```

Pulse_v

File: HP4142_DRV

This subprogram sets an SMU, HVU, HCU, or VS to pulsed V source and specifies its parameters for a pulsed measurement.

HP-IB Command:

PV, PT

Syntax

`Pulse_v` (*output ch#, V output range, base voltage, pulse voltage, pulse width, hold time* [, *pulse period*] [, *I compliance*])

Parameters

- *output ch#* (I/O: I, type: integer)

Unit	*output ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
HCU	2 to 8
VS	1 to 8, 11 to 18 or 21 to 28

- *V output range* (I/O: I, type: real)

0:	Auto ranging
2:	2 V Limited Auto ranging
20:	20 V Limited Auto ranging
40:	40 V Limited Auto ranging
100:	100 V Limited Auto ranging
200:	200 V Limited Auto ranging
500	500 V Limited Auto ranging
1000	1000 V Limited Auto ranging

Default = 0

- *base voltage* (I/O: I, type: real, unit: V)
  pulse voltage (I/O: I, type: real, unit: V)

Unit	*base voltage*	*pulse voltage*
HPSMU	0 to ±200	0 to ±200
MPSMU	0 to ±100	0 to ±100
HVU[1]	0 to ±1000	0 to ±1000
HCU	0	0 to ±10

1 The *base voltage*, *start pulse voltage* and *stop pulse voltage* must be the same polarity.

- *pulse width* (I/O: I, type: real, unit: s)

  0.0001 to 0.05 resolution: 0.0001

- *hold time* (I/O: I, type: real, unit: s)

  0 to 655.35 resolution: 0.01

- *pulse period* (I/O: I, type: real, unit: s)

  0.01 to 0.5 resolution: 0.0001

  Default = 0

- *I compliance* (I/O: I, type: real, unit: A)

Unit	*I compliance*
HPSMU	±2E−9 to ±1
MPSMU	±2E−9 to ±100E−3
HVU	±1E−9 to ±10E−3
HCU	±1E−6 to ±10

  Default:

  - If the specified SMU or HCU is set to V source mode before the trigger: Default = the setting before trigger
  - If the specified SMU or HCU is set to I source mode before the trigger: Default = none

Example Statements

```
Pulse_v (1, 0, 0.1, 10, 1E−3, 0)

Pulse_v (Ch1, Range, Base, Value, Width, Hold_time, Compliance)
```

Recover_output

File: HP4142_DRV

This subprogram restores the source unit settings that were cleared during the Zero_output subprogram execution.

Note



If the output polarity of the HVU was changed after executing Zero_output, this instruction is not acceptable.

HP-IB Command:

RZ

Syntax

```
Recover_output ( [ch#][, ch#][, ch#][, ch#][, ch#][, ch#][, ch#][, ch#])
```

Parameters

- *ch#* (I/O: I, type: integer)

Unit	*ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
HCU	2 to 8
VS	1 to 8, 11 to 18 or 21 to 28

Default: all units

Example Statements

```
Recover_output(1)

Recover_output(Ch1)

Recover_output(Ch1,Ch2,Ch3,Ch4)

Recover_output
```

Self_test

File: HP4142_DRV

This subprogram performs the HP 4142B Self-Test, then stores the test result code in *test results*, and a related message in *message$*. You can then display this information.

HP-IB Command:

*TST?

Syntax

`Self_test ( test type, test results [ , message$])`

Parameters

- *test type* (I/O: I, type: integer)

  If *test type* = 0, the mainframe and all units are tested.

  If *test type* = 1 to 8, the unit at the corresponding slot# is tested.

  If *test type* = 9, the mainframe is tested.

- *test results* (I/O: O, type: integer)

  The *test results* can be interpreted using the following table.

test results	Description
0	passed
1	Slot 1 unit failed
2	Slot 2 unit failed
4	Slot 3 unit failed
8	Slot 4 unit failed
16	Slot 5 unit failed
32	Slot 6 unit failed
64	Slot 7 unit failed
128	Slot 8 unit failed
256	Mainframe failed

  If more than one unit failed, *test results* are the sum of the numbers corresponding to the failed units.

- *message$* (I/O: O, type: string)

  If this parameter is used, DIM Message$[60] is required.

Example Statements

```
Self_test (1, Result)

Self_test (Type, Result, Message$)
```

Set_amonitor

File: HP4142_DRV

This subprogram specifies an SMU at *sense ch#* to be the sense SMU for an analog search measurement, and sets the sense SMU parameters.

HP-IB Command:

AIV, AVI

Syntax

For Setting the Sense SMU to V Source (Current Monitor) Mode:

`Set_amonitor ( sense ch#, 1, output voltage, target current [ , I compliance])`

For Setting the Sense SMU to I Source (Voltage Monitor) Mode:

`Set_amonitor ( sense ch#, 2, output current, target voltage [ , V compliance])`

Parameters

- *sense ch#* (I/O: I, type: integer)

Unit	*sense ch#*
HPSMU	2 to 8
MPSMU	1 to 8

- *output voltage* (I/O: I, type: real, unit: V)

Unit	*output voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

- *output current* (I/O: I, type: real, unit: A)

Unit	*output current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3

- *target current* (I/O: I, type: real, unit: A)

Unit	*target current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3

- *target voltage* (I/O: I, type: real, unit: V)

Unit	*target voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

- *I compliance* (I/O: I, type: real, unit: A)

  I compliance must be greater than *target current*.

Unit	*I compliance*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3

- *V compliance* (I/O: I, type: real, unit: V)

  V compliance must be greater than *target voltage*.

Unit	*V compliance*
HPSMU	0 to ±200
MPSMU	0 to ±100

Example Statements

```
Set_amonitor (1, 1, 2.5, 100E−3)

Set_amonitor (8, 2, 50E−3, 5)

Set_amonitor (Ch1, Mode, Output_value, Goal_value, Compliance)
```

Set_asource

File: HP4142_DRV

This subprogram specifies an SMU at search ch# to be the search SMU for an analog search measurement, and specifies the search SMU parameters.

HP-IB Command:

ASV, AT

Syntax

`Set_asource` (*search ch#, search start voltage, search stop voltage, ramp rate, hold time, delay time* [, *I compliance*])

Parameters

- *search ch#* (I/O: I, type: integer)

Unit	*search ch#*
HPSMU	2 to 8
MPSMU	1 to 8

- *search start voltage* (I/O: I, type: real, unit: V)
  search stop voltage (I/O: I, type: real, unit: V)

Unit	*search start voltage* *search stop voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100

- *ramp rate* (I/O: I, type: real, unit: V/s)

Output Range	*ramp rate*	Resolution
2 V	0.5 to 5	0.05 V/s
	5.5 to 50	0.5 V/s
	55 to 500	5 V/s
	550 to 5000	50 V/s
20 V	5.5 to 50	0.5 V/s
	55 to 500	5 V/s
	550 to 5000	50 V/s
	55500 to 50000	500 V/s
40 V	10 to 50	1 V/s
	55 to 100	5 V/s
	110 to 500	10 V/s
	550 to 1000	50 V/s
	1100 to 5000	100 V/s
	5500 to 10000	500 V/s
	11000 to 50000	1000 V/s
	55000 to 100000	5000 V/s
100 V	25 to 50	2.5 V/s
	55 to 250	5 V/s
	275 to 500	25 V/s
	550 to 2500	50 V/s
	2750 to 5000	250 V/s
	5500 to 25000	500 V/s
	27500 to 50000	2500 V/s
	55000 to 100000	5000 V/s
200 V	55 to 500	5 V/s
	550 to 5000	50 V/s
	5500 to 50000	500 V/s
	55000 to 100000	5000 V/s

- *hold time* (I/O: I, type: real, unit: s)

  0 to 65.535 resolution: 0.001

- *delay time* (I/O: I, type: real, unit: s)

  0 to 65.535 resolution: 0.001

- *I compliance* (I/O: I, type: real, unit: A)

Unit	*I compliance*
HPSMU	±(1E−12 to 1)
MPSMU	±(1E−12 to 100E−3)

Default:

- If the specified SMU is set to V source mode before the trigger:

  Default = the setting before the trigger

- If the specified SMU is set to I source mode before the trigger:

  Default = none

Example Statements

```
Set_asource (1, 0, 5, 500, 1, 1)

Set_asource (Ch1, Start, Stop, Rate, Hold_time, Delay_time, Compliance)
```

Set_bdm

File: HP4142_DRV

This subprogram specifies an HVU or SMU as the quasi-pulsed source and specifies its parameters.

HP-IB Command:

BDV, BDT

Syntax

`Set_bdm` (*output ch#, V output range, start voltage, stop voltage, hold time, delay time* [, *I compliance*])

Parameter

- *output ch#* (I/O: I, type: integer)

Unit	*output ch#*
HVU	2 to 8
HPSMU	2 to 8
MPSMU	1 to 8

- *V output range* (I/O: I, type: real)

0:	Auto ranging
2:	2 V Limited Auto ranging
20:	20 V Limited Auto ranging
40:	40 V Limited Auto ranging
100:	100 V Limited Auto ranging
200:	200 V Limited Auto ranging
500:	500 V Limited Auto ranging
1000:	1000 V Limited Auto ranging

- *start voltage* (I/O: I, type: real, unit: V)
- *stop voltage* (I/O: I, type: real, unit: V)

Unit	*start voltage* *stop voltage*
HVU	0 to ±1000
HPSMU	0 to ±200
MPSMU	0 to ±100

- *hold time* (I/O: I, type: real, unit: s)

0 to 655.35

resolution: 0.01

- *delay time* (I/O: I, type: real, unit: s)

  0 to 6.5535

  resolution: 0.0001

- *I compliance* (I/O: I, type: real, unit: A)

Unit	*I compliance*
HVU	±(1E−9 to 10E−3)
HPSMU	±(1E−12 to 1)
MPSMU	±(1E−12 to 100E−3)

Default:

- If the specified source unit is set to V source mode before the trigger:

  Default = the setting before trigger

- If the specified source unit is set to I source mode before the trigger:

  Default = none

Example Statement

```
Set_bdm(2,500,200,210,1,1)
```

Set_iv

File: HP4142_DRV

This subprogram sets the parameters for a staircase sweep source.

HP-IB Command:

WI, WV, WT

Syntax

For Voltage Sweeps:

`Set_iv` (*output ch#, voltage sweep mode, V output range, start voltage, stop voltage, number of steps* [, *hold time*] [, *delay time*] [, *I compliance*] [, *power compliance*])

For Current Sweeps:

`Set_iv` (*output ch#, current sweep mode, I output range, start current, stop current, number of steps* [, *hold time*] [, *delay time*] [, *V compliance*] [, *power compliance*])

Parameters

- *output ch#* (I/O: I, type: integer)

Unit	*output ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
VS	1 to 8, 11 to 18 or 21 to 28

- *voltage sweep mode* (I/O: I, type: integer)

  1: linear sweep (single stair)
  3: linear sweep (double stair)
  −1: log sweep (single stair)
  −3: log sweep (double stair)

- *current sweep mode* (I/O: I, type: integer)

  2: linear sweep (single stair)
  4: linear sweep (double stair)
  −2: log sweep (single stair)
  −4: log sweep (double stair)

- *V output range* (I/O: I, type: real)

  0: Auto ranging
  2: 2 V Limited Auto ranging
  20: 20 V Limited Auto ranging
  40: 40 V Limited Auto ranging

100: 100 V Limited Auto ranging
200: 200 V Limited Auto ranging
500: 500 V Limited Auto ranging
1000: 1000 V Limited Auto ranging

- *I output range* (I/O: I, type: real)

0: Auto ranging
1E−9: 1 nA Limited Auto ranging
1E−8: 10 nA Limited Auto ranging
1E−7: 100 nA Limited Auto ranging
1E−6: 1 μA Limited Auto ranging
1E−5: 10 μA Limited Auto ranging
1E−4: 100 μA Limited Auto ranging
1E−3: 1 mA Limited Auto ranging
1E−2: 10 mA Limited Auto ranging
1E−1: 100 mA Limited Auto ranging
1: 1 A Limited Auto ranging

- *start voltage* (I/O: I, type: real, unit: V)
  stop voltage (I/O: I, type: real, unit: V)

Unit	*start voltage* *stop voltage*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU[1]	0 to ±1000
VS	0 to ±40

1 The *start voltage* and *stop voltage* must be the same polarity.

- *start current* (I/O: I, type: real, unit: A)
  stop current (I/O: I, type: real, unit: A)

Unit	*start current* *stop current*
HPSMU	0 to ±1
MPSMU	0 to ±100E−3
HVU[1]	0 to ±10E−3

1 The *start current* and *stop current* must be the same polarity.

- *number of steps* (I/O: I, type: integer)

2 to 1001

- *hold time* (I/O: I, type: real, unit: s)

0 to 655.35

resolution = 0.01

Default = 0

- *delay time* (I/O: I, type: real, unit: s)

  0 to 65.535

  resolution = 0.001

  Default = 0

- *V compliance* (I/O: I, type: real, unit: V)

Unit	*V compliance*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000

  Default:

  - If the specified SMU is set to I source mode before the trigger:

    Default = the setting before the trigger

  - If the specified SMU is set to V source mode before the trigger:

    Default = none

- *I compliance* (I/O: I, type: real, unit: A)

Unit	*I compliance*
HPSMU	±(1E−12 to 1)
MPSMU	±(1E−12 to 100E−3)
HVU	±(1E−9 to 10E−3)

  Default:

  - If the specified SMU is set to V source mode before the trigger:

    Default = the setting before the trigger

  - If the specified SMU is set to I source mode before the trigger:

    Default = none

- *power compliance* (I/O: I, type: real, unit: W)

  0.001 to 14

  resolution = 0.001

  Default = Does not set the power compliance

Example Statements

```
Set_iv (1, 1, 0, 0, 10, 50, 1, 0)

Set_iv (Ch1, Sweep_mode, Range, Start_val, Stop_val, Steps,
 Hold, Delay, I_comp, P_comp)

Set_iv (1, -2, 0, 1.0E-9, 1.0E-5, 51)

Set_iv (Ch8, Sweep_mode, Range, Start_val, Stop_val, Steps,
 Hold, Delay, V_comp, P_comp)
```

Set_piv

File: HP4142_DRV

This subprogram sets the parameters of a pulsed sweep source for a pulsed sweep measurement.

HP-IB Command:

PWI, PWV, PT

Syntax

For Pulsed Voltage Sweeps:

`Set_piv` (*output ch#, V sweep mode, V output range, base voltage, start pulse voltage, stop pulse voltage, number of steps, pulse width, pulse period, hold time* [, *I compliance*])

For Pulsed Current Sweeps:

`Set_piv` (*output ch#, I sweep mode, I output range, base current, start pulse current, stop pulse current, number of steps, pulse width, pulse period, hold time* [, *V compliance*])

Parameters

- *output ch#* (I/O: I, type: integer)

Unit	*output ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
HCU	2 to 8
VS	1 to 8, 11 to 18 or 21 to 28

- *V sweep mode* (I/O: I, type: integer)

  1: linear sweep (single stair)
  3: linear sweep (double stair)

- *I sweep mode* (I/O: I, type: integer)

  2: linear sweep (single stair)
  4: linear sweep (double stair)

- *V output range* (I/O: I, type: real)

  0: Auto ranging
  2: 2 V Limited Auto ranging
  20: 20 V Limited Auto ranging
  40: 40 V Limited Auto ranging

100: 100 V Limited Auto ranging
200: 200 V Limited Auto ranging
500: 500 V Limited Auto ranging
1000 1000 V Limited Auto ranging

- *I output range* (I/O: I, type: real)

0: Auto ranging
1E−8: 10 nA Limited Auto ranging
1E−7: 100 nA Limited Auto ranging
1E−6: 1 μA Limited Auto ranging
1E−5: 10 μA Limited Auto ranging
1E−4: 100 μA Limited Auto ranging
1E−3: 1 mA Limited Auto ranging
1E−2: 10 mA Limited Auto ranging
1E−1: 100 mA Limited Auto ranging
1: 1 A Limited Auto ranging
10: 10 A Limited Auto ranging

- *base voltage* (I/O: I, type: real, unit: V)
  start pulse voltage (I/O: I, type: real, unit: V)
  stop pulse voltage (I/O: I, type: real, unit: V)

Unit	*base voltage*	*start pulse voltage* *stop pulse voltage*
HPSMU	0 to ±200	0 to ±200
MPSMU	0 to ±100	0 to ±100
HVU[1]	0 to ±1000	0 to ±1000
HCU	0	0 to ±10
VS	0 to ±40	0 to ±40

1 The *base voltage* and *pulse voltage* must be the same polarity.

- *base current* (I/O: I, type: real, unit: A)
  start pulse current (I/O: I, type: real, unit: A)
  stop pulse current (I/O: I, type: real, unit: A)

Unit	*base current*[1]	*start pulse current*[1] *stop pulse current*[1]
HPSMU	0 to ±1	0 to ±1
MPSMU	0 to ±100E−3	0 to ±100E−3
HVU	0 to ±10E−3	0 to ±10E−3
HCU	0[2]	0 to ±10

1 The *start pulse current*, *stop pulse current*, and *base current* must be the same polarity.

2 During base value output, the HCU output is 0 V and no current.

- *number of steps* (I/O: I, type: integer)

  2 to 1001

- *pulse width* (I/O: I, type: real, unit: s)

  0.0001 to 0.05

  resolution: 0.0001

- *pulse period* (I/O: I, type: real, unit: s)

  0.01 to 0.5

  resolution: 0.0001

- *hold time* (I/O: I, type: real, unit: s)

  0 to 655.35

  resolution: 0.01

- *V compliance* (I/O: I, type: real, unit: V)

Unit	*V compliance*
HPSMU	0 to ±200
MPSMU	0 to ±100
HVU	0 to ±1000
HCU	0 to ±10

  Default:

  - If the specified SMU is set to I source mode before the trigger:

    Default = the setting before the trigger

  - If the specified SMU is set to V source mode before the trigger:

    Default = none

  Specify this parameter when you use an HCU as a pulsed sweep source.

- *I compliance* (I/O: I, type: real, unit: A)

Unit	*I compliance*
HPSMU	±(1E−12 to 1)
MPSMU	±(1E−12 to 100E−3)
HVU	±(1E−9 to 10E−3)
HCU	±(1E−6 to 10)

  Default:

  - If the specified SMU or HCU is set to V source mode before the trigger:

Default = the setting before the trigger

- If the specified SMU or HCU is set to I source mode before the trigger:

  Default = none

Example Statements

```
Set_piv (11, 1, 0, 0.1, 0.1, 10, 15, 1E-3,
 10E-3, 0)

Set_piv (Ch, Mode, Range, Base, Start, Stop, Steps, Width,
 Period, Hold_time, I_comp)
```

Set_pol

This subprogram changes the polarity of the HVU output and sets the output voltage to 0 V. If the output switch of the unit is set to off, this subprogram also sets the switch to on.

Warning **Setting the output switch to on enables the unit to force dangerous voltages.**



Set the output switch to off whenever possible when the unit is not in use.

HP-IB Command:

POL

Execution Conditions

- The INTLK terminal is shorted.
- The other unit is not in HIGH VOLTAGE state (forcing more than 42 V, or *V compliance* set to more than 42 V).

Syntax

```
Set_pol ( ch#, polarity )
```

Parameters

- *ch#* (I/O: I, type: integer)

Unit	*ch#*
HVU	2 to 8

- *polarity* (I/O: I, type: integer)

  0: + polarity
  1: − polarity

Example Statement

```
Set_pol(2,0)
```

Semantics

If the output switch of the unit is set to on, this subprogram changes the output polarity as follows:

1. Sets the unit to 0 V (same conditions as the DZ command execution).
2. Waits for either of the following conditions:
   - The unit continues to measure the output voltage until the output voltage becomes less than or equal to 30 V.

- Until 500 ms elapse.

3. Sets the output switch to off.
4. Changes the output polarity.
5. Sets the output switch to on.

Set_smu

File: HP4142_DRV

This subprogram sets the number of samples that are taken (A/D conversion) and averaged for the measurement.

HP-IB Command:

AV

Syntax

```
Set_smu ( averaging number )
```

Parameters

- *averaging number* (I/O: I, type: integer)

  1 to 1023
  −1 to −1023

  If *averaging number* is a positive integer, AUTO mode averaging is performed.

  If *averaging number* is a negative integer, POWER LINE CYCLE mode averaging is performed.

Example Statements

```
Set_smu (2)

Set_smu (−5)

Set_smu (Average_times)
```

Set_vm

File: HP4142_DRV

This subprogram sets the voltage measurement operation mode for the specified VM (HP 41424A).

HP-IB Command:

VM

Syntax

```
Set_vm ( measurement ch#, VM operation mode )
```

Parameters

- *measurement ch#* (I/O: I, type: integer)

Unit	*measurement ch#*
VM	1 to 8, 11 to 18 or 21 to 28

- *VM operation mode* (I/O: I, type: integer)

  1: Grounded measurement
  2: Differential measurement

Example Statements

```
Set_vm (8, 1)

Set_vm (Channel, Vm_mode)
```

status

Five subprograms (Dpulse_measure, Measure_asearch, Measure_i, Measure_v, Measure_bdm, and Pulse_measure) have the optional parameter status. If you specify status, you must declare it as integer type. After the measurement is performed, an integer is returned to status and the meanings are as follows:

0: Normal measurement data.

1: Another channel reached V compliance, I compliance, power compliance, or the current limit of VS.

Or, if another channel is the HCU, the measurement was performed before the pulsed output settled.

Either made the *pulse width* larger to wait for the settling time, or made the *I/V compliance* larger to speed up the settling time of the pulse output.

2: This measurement channel reached V compliance, I compliance, power compliance, or current limit of VS.

Or, if this channel is the HCU, the measurement was performed before the pulsed output settled.

Either made the *pulse width* larger to wait for the settling time, or made the *I/V compliance* larger to speed up the settling time of the pulse output.

3: This or another SMU or HVU oscillated, or the *pulse* value could not be set because the specified *pulse width* was too small.

4: Measurement exceeded measurement range, or dummy data were stored because the sweep measurement was automatically aborted by automatic sweep abort function or power compliance.

5: The target value for analog feedback measurement was not reached during a search (between *search start voltage* and *search stop voltage*).

6: Measurement was made before the analog feedback search was complete.

7: Measurement was made before the HVU was settled.

8: The detection time for the quasi-pulsed measurement is over the limit (3 s for Short mode, 12 s for Long mode). Set the *detection interval* to Long.

9: The settling detection for quasi-pulsed measurement can not perform because the output slew rate is too slow.

For the Measure_asearch subprogram, two digits are returned. The tens digit corresponds to the search SMU measurement data, and the ones digit corresponds to the sense SMU measurement data.

For example, if the returned *status* is 60, then 6 is the search SMU data status and 0 is the sense SMU data status.

Sweep_iv

File: HP4142_DRV

This subprogram triggers a staircase sweep measurement. Measurements are made at the measurement ch# for each sweep step, and the measurement values and sweep source values are returned to the measurement value array(*) and the source value array(*), respectively.

HP-IB Command:

MM, WNU?, FMT, RV, RI, XE

Syntax

For Voltage Measurements:

```
Sweep_iv ( measurement ch#, 1, V measurement range, measurement value array(*)
[ , source value array(*)])
```

For Current Measurements:

```
Sweep_iv ( measurement ch#, 2, I measurement range, measurement value array(*)
[ , source value array(*)])
```

Parameters

- *measurement ch#* (I/O: I, type: integer)

Unit	*measurement ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
VM	1 to 8, 11 to 18 or 21 to 28

- *V measurement range* (I/O: I, type: real)

  The *V measurement range* sets the voltage measurement range of VMs. The voltage measurement range of SMUs or HVUs is set to the Compliance range automatically, regardless of the specified value.

  0: Auto ranging
  0.2: 0.2 V range fixed
  2: 2 V range fixed
  20: 20 V range fixed
  40: 40 V range fixed

- *I measurement range* (I/O: I, type: real)

  0: Auto ranging
  −1E−9: 1 nA range fixed
  −1E−8: 10 nA range fixed

−1E−7: 100 nA range fixed
−1E−6: 1 μA range fixed
−1E−5: 10 μA range fixed
−1E−4: 100 μA range fixed
−1E−3: 1 mA range fixed
−1E−2: 10 mA range fixed
−1E−1: 100 mA range fixed
−1: 1 A range fixed

- *measurement value array (*)* (I/O: O, type: numeric array, unit: V or I)

  The measurement value of each sweep step is returned to this array. The number of elements of the *measurement value array(*)* must be larger than the number of sweep steps.

- *source value array (*)* (I/O: O, type: numeric array, unit: V or I)

  The sweep source values of each sweep step are returned to this array. The number of elements of the *source value array(*)* must be larger than the number of sweep steps.

Example Statements

```
Sweep_iv (1, 1, 0, Meas_data(*), Sweep_value(*))

Sweep_iv (6, 2, 0, Meas_data(*), Sweep_value(*))

Sweep_iv (Ch, Meas_mode, Range, Meas_data(*), Source_value(*))
```

Note



When using this subprogram, it is recommended that you include OPTION BASE 1 at the beginning of your program. Including OPTION BASE 1 in your program causes array element numbering to start from 1 instead of 0. This makes it easier to keep track of the array elements in the *measurement value array(*)* and [*source value array(*)*] because the *nth* returned value is array element *n* instead of *n − 1*.

Sweep_miv

File: HP4142_DRV

This subprogram triggers a multichannel staircase sweep measurement. Measurements are made at the units specified in the *measurement ch# array(*)*, and the measurement values and sweep source values are returned to the *measurement value array(*)* and *source value array(*)*, respectively.

HP-IB Command:

MM, WNU?, FMT, RV, RI, XE

Syntax

Sweep_miv (*measurement ch# array(*), measurement mode array(*), measurement range array(*), measurement value array(*)* [, *source value array(*)*])

Parameters

- *measurement ch# array(*)* (I/O: I, type: integer array)

Unit	*ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
HCU	2 to 8
VM	1 to 8, 11 to 18 or 21 to 28

Declare this parameter as a one dimensional array as follows:

```
INTEGER Channel (x)
```

x = number of measurement units (1 to 8)

EX.

```
INTEGER Channel (3)
Channel (1) = 1
Channel (2) = 4
Channel (3) = 6
```

Each element of this array defines a unit that measures any value in the measurements.

- *measurement mode array(*)* (I/O: I, type: integer array)

measurement mode	description
1	voltage measurement
2	current measurement

Declare this parameter as a one dimensional array as shown in the following example:

```
INTEGER Mode (x)
```

x = number of measurement units (1 to 8)

Elements of this array correspond to elements in the *measurement ch# array(*)*.

- *measurement range array(*)* (I/O: I, type: numeric array)

  Declare this parameter as a one dimensional array as shown in the following example:

  ```
  DIM Range (x)
  ```

  x = number of measurement units (1 to 8)

  Elements of this array correspond to elements in the *measurement ch# array(*)*.

- *measurement value array(*)* (I/O: O, type: numeric array)

  Declare this parameter as a two dimensional array as shown in the following example:

  ```
  DIM Data (x,y)
  ```

  x = number of measurement units (1 to 8) y = number of measurement data for each unit

  y should be larger than the *number of steps* specified in the Set_iv subprogram. If y is larger, this subprogram sets y = *number of steps*. If y is smaller, all the measurement values cannot be stored in the array.

- *source value array(*)* (I/O: O, type: numeric array)

  Declare this parameter as a one dimensional array as shown in the following example:

  ```
  DIM S_data (y)
  ```

  y = number of measurement data for each unit

  y should be larger than the *number of steps* specified in the Set_iv subprogram. If y is larger, this subprogram sets y = *number of steps*. If y is smaller, all the measurement values cannot be stored in the array.

Example Statements

```
Sweep_miv (Channel(*), Mode(*), Range(*), Data(*), Sweep(*))
```

Note



When using this subprogram, it is recommended that you include OPTION BASE 1 at the beginning of your program. Including OPTION BASE 1 in your program causes array element numbering to start from 1 instead of 0. This makes it easier to keep track of the array elements in the *measurement value array(*)* and [*source value array(*)*] because the *nth* returned value is array element n instead of $n - 1$.

Sweep_mode

File: HP4142_DRV

This subprogram sets the *automatic sweep abort function* and *output after sweep* settings for sweep sources.

HP-IB Command:

WM

Syntax

`Sweep_mode` (*automatic sweep abort function* [, *output after sweep*])

Parameters

- *automatic sweep abort function* (I/O: I, type: integer)

  1: OFF
  2: ON

  Initial = 1

- *output after sweep* (I/O: I, type: integer)

  1: The start value is output after the sweep is completed.
  2: The stop value is output after the sweep is completed.

  Initial = 1

  Default = 1

  The *output after sweep* parameter is ignored for pulsed sweeps. Pulsed sweep sources always output the *base* value after the sweep is completed.

Example Statements

```
Sweep_mode (2)

Sweep_mode (2, 2)

Sweep_mode (Stop_mode, End_set)
```

Sweep_pbias

File: HP4142_DRV

This subprogram triggers a staircase sweep with pulsed bias measurement. The staircase sweep is output as determined by the Set_iv subprogram, and for each sweep step, a pulse is output as determined by the Pulse_i or Pulse_v subprogram. During each pulse output, a measurement is performed at the specified *measurement ch#*. Measurement values and sweep source values are returned to the *measurement value array(*)* and *source value array(*)*, respectively.

HP-IB Command:

MM, WNU?, FMT, FL, RV, RI, XE

Syntax

For Voltage Measurements:

`Sweep_pbias (` *measurement ch#*`, 1,` *V measurement range*`,` *measurement value array(*)* [`,` *source value array(*)*]`)`

For Current Measurements:

`Sweep_pbias (` *measurement ch#*`, 2,` *I measurement range*`,` *measurement value array(*)* [`,` *source value array(*)*]`)`

Parameters

- *measurement ch#* (I/O: I, type: integer)

Unit	*ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
HCU	2 to 8
VM	1 to 8, 11 to 18 or 21 to 28

- *V measurement range* (I/O: I, type: real)

  The *V measurement range* sets the voltage measurement range of VMs. The voltage measurement range of SMUs, HVUs, or HCUs is set to the Compliance range automatically, regardless of specified value.

  0: 40 V range fixed
  2: 2 V range fixed
  20: 20 V range fixed
  40: 40 V range fixed

- *I measurement range* (I/O: I, type: real)

0:	Compliance range
−1E−8:	10 nA range fixed
−1E−7:	100 nA range fixed
−1E−6:	1 μA range fixed
−1E−5:	10 μA range fixed
−1E−4:	100 μA range fixed
−1E−3:	1 mA range fixed
−1E−2:	10 mA range fixed
−1E−1:	100 mA range fixed
−1:	1 A range fixed
−10:	10 A range fixed

- *measurement value array (*)* (I/O: O, type: numeric array, unit: V or I)

  The measurement value of each sweep step is returned to this array. The number of elements of the *measurement value array(*)* must be larger than the number of sweep steps.

- *source value array (*)* (I/O: O, type: numeric array, unit: V or I)

  The sweep source values of each sweep step are returned to this array. The number of elements of the *source value array(*)* must be larger than the number of sweep steps.

Example Statements

```
Sweep_pbias (1, 1, 0, Meas_data(*), Sweep_value(*))

Sweep_pbias (8, 2, 0, Meas_data(*), Sweep_value(*))

Sweep_pbias (Ch, Meas_mode, Range, Meas_data(*), Sweep_value(*))
```

Note



When using this subprogram, it is recommended that you include OPTION BASE 1 at the beginning of your program. Including OPTION BASE 1 in your program causes array element numbering to start from 1 instead of 0. This makes it easier to keep track of the array elements in the *measurement value array(*)* and *source value array(*)* because the *nth* returned value is array element *n* instead of *n − 1*.

Sweep_piv

File: HP4142_DRV

This subprogram triggers a pulsed sweep measurement. A pulsed sweep is output as determined by the Set_piv subprogram, measurements are made at the *measurement ch#* for each sweep step, and the measurement values and sweep source values are returned to *measurement value array(*)* and *source value array(*)*, respectively.

HP-IB Command:

MM, WNU?, FMT, FL, RV, RI, XE

Syntax

For Voltage Measurements:

`Sweep_piv` (*measurement ch#*, `1`, *V measurement range*, *measurement value array(*)*, [*source value array(*)*])

For Current Measurements:

`Sweep_piv` (*measurement ch#*, `2`, *I measurement range*, *measurement value array(*)*, [*source value array(*)*])

Parameters

- *measurement ch#* (I/O: I, type: integer)

Unit	*ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
HCU	2 to 8
VM	1 to 8, 11 to 18 or 21 to 28

- *V measurement range* (I/O: I, type: real)

  The *V measurement range* sets the voltage measurement range of VMs. The voltage measurement range of SMUs or HCUs is set to the Compliance range automatically.

  0: 40 V range fixed
  2: 2 V range fixed
  20: 20 V range fixed
  40: 40 V range fixed

- *I measurement range* (I/O: I, type: real)

  0: Compliance range
  −1E−8: 10 nA range fixed
  −1E−7: 100 nA range fixed

−1E−6: 1 μA range fixed
−1E−5: 10 μA range fixed
−1E−4: 100 μA range fixed
−1E−3: 1 mA range fixed
−1E−2: 10 mA range fixed
−1E−1: 100 mA range fixed
−1: 1 A range fixed
−10: 10 A range fixed

- *measurement value array (*)* (I/O: O, type: numeric array, unit: V or I)

  The measurement value of each sweep step is returned to this array. The number of elements of the *measurement value array(*)* must be larger than the number of sweep steps.

- *source value array (*)* (I/O: O, type: numeric array, unit: V or I)

  The sweep source values of each sweep step are returned to this array. The number of elements of the *source value array(*)* must be larger than the number of sweep steps.

Example Statements

```
Sweep_piv (1, 1, 0, Meas_data(*), Sweep_value(*))

Sweep_piv (Ch, Meas_mode, Range, Meas_data(*), Sweep_value(*))

Sweep_piv (4, 2, 0, Meas_data(*), Sweep_value(*))

Sweep_piv (Ch, Meas_mode, Range, Meas_data(*), Sweep_value(*))
```

Note



When using this subprogram, it is recommended that you include OPTION BASE 1 at the beginning of your program. Including OPTION BASE 1 in your program causes array element numbering to start from 1 instead of 0. This makes it easier to keep track of the array elements in the *measurement value array(*)* and *source value array(*)* because the *nth* returned value is array element *n* instead of *n − 1*.

Wbuild_file

File: GRAPHICS

This subprogram generates a measurement data file that conforms to the Basic Statistics and Data Manipulation (BSDM) format.

This subprogram converts the *data array(*)* that you set up to a BSDM format data file and stores the data file, *file comments$*, and *variable names$* in the specified mass storage device. This subprogram can be used separately or with other subprograms to create a BSDM format data file. BSDM format data files can be evaluated by the HP 98820A Statistical Library. This software provides Histograms, Control Charts, Scattergrams, data storing, and many other statistical analysis routines.

Syntax

`Wbuild_file` (*file name, data array (*), file comments$, variable names$(*)*)

Parameters

- *file name$* (I/O: I, type: string)

  This parameter defines a file name of a file that is create by this subprogram. The input format is the same as HP BASIC format.

- *data array (*)* (I/O: I, type: numeric array)

  Data that are specified by this parameter are stored in the file.

  The *data array (*)* must be a two dimensional array with a lower boundary (1, 1). If OPTION BASE 1 is included in your program, this condition is automatically set up. If OPTION BASE 1 is not included in your program, you must set up *data array(*)* so that this condition is met.

  The first dimension of this array represents the number of variables, and the number of elements must be within 50. The second dimension of this array represents the number of observations for each variable.

  The total number of variables must be within 1500.

- *file comments$* (I/O: I, type: string)

  This parameter specifies the title or comments for the data.

  Max. 80 characters are allowed.

- *variable names$* (I/O: I, type: string)

  Variable names.

  Max. 50 variable names with max. 10 characters for each variable name.

  These variable names correspond to elements in *data array(*)*.

Example Statements

```
Wbuild_file ("DATA_1", M_data(*), "MEASUREMENT DATA", Var_name$(*))

Wbuild_file (File$, all_data(*), Title$, Name$(*))
```

Zero_output

File: HP4142_DRV

This subprogram sets the specified SMUs, HVUs, HCUs, or VSs to Zero Output.

HP-IB Command:

DZ

Syntax

```
Zero_output ( [ch#][, ch#][, ch#][, ch#][, ch#][, ch#][, ch#][, ch#])
```

Parameters

- *ch#* (I/O: I, type: integer)

Unit	*ch#*
HPSMU	2 to 8
MPSMU	1 to 8
HVU	2 to 8
HCU	2 to 8
VS	1 to 8, 11 to 18, or 21 to 28

Default = all units

Example Statements

```
Zero_output (1)

Zero_output (Ch1)

Zero_output (Ch1,Ch2,Ch3,Ch4)

Zero_output
```

A

Program Listings

This appendix contains the source code for all the control software sub-programs and user-defined functions.

HP4142_DRV File

Auto_cal

```
35    SUB Auto_cal(INTEGER Cal_mode)
40      COM @Hp4142
45      !*************************************************
50      !*           Set auto calibration mode           *
55      !*************************************************
60      OUTPUT @Hp4142;"CM";Cal_mode
65      OUTPUT @Hp4142;"*OPC?"
70      !
75      ENTER @Hp4142;A$
80      S=SPOLL(@Hp4142)
85      IF BIT(S,5) THEN CALL Detect_error(S,"Auto_cal")
90    SUBEND
```

Cal_hp4142

```
105   SUB Cal_hp4142(OPTIONAL INTEGER Channel)
110     COM @Hp4142
115     !*************************************************
120     !*          Execute  calibration                 *
125     !*************************************************
130     IF NPAR=0 THEN OUTPUT @Hp4142;"CA"
135     IF NPAR=1 THEN OUTPUT @Hp4142;"CA";Channel
140     OUTPUT @Hp4142;"*OPC?"
145     !
150     ENTER @Hp4142;A$
155     S=SPOLL(@Hp4142)
160     IF BIT(S,5) THEN CALL Detect_error(S,"Cal_hp4142")
165   SUBEND
```

Ch_sw_on

```
180   SUB Ch_sw_on(OPTIONAL INTEGER Channel1,Channel2,Channel3,Channel4,Channel5,Channel6,Channel7,Channel8)
185     COM @Hp4142
190     !************************************************
195     !*          Connect the output switch           *
200     !************************************************
205     SELECT NPAR
210     CASE 0
215       OUTPUT @Hp4142;"CN"
220     CASE 1
225       OUTPUT @Hp4142;"CN";Channel1
230     CASE 2
235       OUTPUT @Hp4142;"CN";Channel1;",";Channel2
240     CASE 3
245       OUTPUT @Hp4142;"CN";Channel1;",";Channel2;",";Channel3
250     CASE 4
255       OUTPUT @Hp4142;"CN";Channel1;",";Channel2;",";Channel3;",";Channel4
260     CASE 5
265       OUTPUT @Hp4142;"CN";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5
270     CASE 6
275       OUTPUT @Hp4142;"CN";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6
280     CASE 7
285       OUTPUT @Hp4142;"CN";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6;
",";Channel7
290     CASE 8
295       OUTPUT @Hp4142;"CN";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6;
",";Channel7;",";Channel8
300     END SELECT
305     !
310     OUTPUT @Hp4142;"*OPC?"
315     ENTER @Hp4142;A$
320     S=SPOLL(@Hp4142)
325     IF BIT(S,5) THEN CALL Detect_error(S,"Ch_sw_on")
330   SUBEND
```

Ch_sw_off

```
345   SUB Ch_sw_off(OPTIONAL INTEGER Channel1,Channel2,Channel3,Channel4,Channel5,Channel6,Channel7,
Channel8)
350     COM @Hp4142
355     !************************************************
360     !*         Disconnect the channel switch          *
365     !************************************************
370     SELECT NPAR
375     CASE 0
380       OUTPUT @Hp4142;"CL"
385     CASE 1
390       OUTPUT @Hp4142;"CL";Channel1
395     CASE 2
400       OUTPUT @Hp4142;"CL";Channel1;",";Channel2
405     CASE 3
410       OUTPUT @Hp4142;"CL";Channel1;",";Channel2;",";Channel3
415     CASE 4
420       OUTPUT @Hp4142;"CL";Channel1;",";Channel2;",";Channel3;",";Channel4
425     CASE 5
430       OUTPUT @Hp4142;"CL";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5
435     CASE 6
440       OUTPUT @Hp4142;"CL";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6
445     CASE 7
450       OUTPUT @Hp4142;"CL";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6;
",";Channel7
455     CASE 8
460       OUTPUT @Hp4142;"CL";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6;
",";Channel7;",";Channel8
465     END SELECT
470     !
475     OUTPUT @Hp4142;"*OPC?"
480     ENTER @Hp4142;A$
485     S=SPOLL(@Hp4142)
490     IF BIT(S,5) THEN CALL Detect_error(S,"Ch_sw_off")
495   SUBEND
```

Zero_output

```
510   SUB Zero_output(OPTIONAL INTEGER Channel1,Channel2,Channel3,Channel4,Channel5,Channel6,Channel7,
Channel8)
515     COM @Hp4142
520     !************************************************
525     !*     Set the SMU or VS to zero output state     *
530     !************************************************
535     SELECT NPAR
540     CASE 0
545       OUTPUT @Hp4142;"DZ"
550     CASE 1
555       OUTPUT @Hp4142;"DZ";Channel1
560     CASE 2
565       OUTPUT @Hp4142;"DZ";Channel1;",";Channel2
570     CASE 3
575       OUTPUT @Hp4142;"DZ";Channel1;",";Channel2;",";Channel3
580     CASE 4
585       OUTPUT @Hp4142;"DZ";Channel1;",";Channel2;",";Channel3;",";Channel4
590     CASE 5
595       OUTPUT @Hp4142;"DZ";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5
600     CASE 6
605       OUTPUT @Hp4142;"DZ";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6
610     CASE 7
615       OUTPUT @Hp4142;"DZ";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6;
",";Channel7
620     CASE 8
625       OUTPUT @Hp4142;"DZ";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6;
",";Channel7;",";Channel8
630     END SELECT
635     !
640     OUTPUT @Hp4142;"*OPC?"
645     ENTER @Hp4142;A$
650     S=SPOLL(@Hp4142)
655     IF BIT(S,5) THEN CALL Detect_error(S,"Zero_output")
660   SUBEND
```

Recover_output

```
675   SUB Recover_output(OPTIONAL INTEGER Channel1,Channel2,Channel3,Channel4,Channel5,Channel6,Channel7,
Channel8)
680     COM @Hp4142
685     !************************************************
690     !*  Recover the SMU or VS from zero output state  *
695     !************************************************
700     SELECT NPAR
705     CASE 0
710       OUTPUT @Hp4142;"RZ"
715     CASE 1
720       OUTPUT @Hp4142;"RZ";Channel1
725     CASE 2
730       OUTPUT @Hp4142;"RZ";Channel1;",";Channel2
735     CASE 3
740       OUTPUT @Hp4142;"RZ";Channel1;",";Channel2;",";Channel3
745     CASE 4
750       OUTPUT @Hp4142;"RZ";Channel1;",";Channel2;",";Channel3;",";Channel4
755     CASE 5
760       OUTPUT @Hp4142;"RZ";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5
765     CASE 6
770       OUTPUT @Hp4142;"RZ";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6
775     CASE 7
780       OUTPUT @Hp4142;"RZ";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6;
",";Channel7
785     CASE 8
790       OUTPUT @Hp4142;"RZ";Channel1;",";Channel2;",";Channel3;",";Channel4;",";Channel5;",";Channel6;
",";Channel7;",";Channel8
795     END SELECT
800     !
805     OUTPUT @Hp4142;"*OPC?"
810     ENTER @Hp4142;A$
815     S=SPOLL(@Hp4142)
820     IF BIT(S,5) THEN CALL Detect_error(S,"Recover_output")
825   SUBEND
```

Set_smu

```
840   SUB Set_smu(INTEGER Average_time)
845     COM @Hp4142
850     !************************************************
855     !*              Set averaging time               *
860     !************************************************
865     OUTPUT @Hp4142;"AV";Average_time
870     OUTPUT @Hp4142;"*OPC?"
875     !
880     ENTER @Hp4142;A$
885     S=SPOLL(@Hp4142)
890     IF BIT(S,5) THEN CALL Detect_error(S,"Set_smu")
895   SUBEND
```

Init_hp4142

```
910   SUB Init_hp4142
915     COM @Hp4142
920     !************************************************
925     !*             4142B initial setting             *
930     !************************************************
935     OUTPUT @Hp4142;"*RST"       ! Reset 4142B
940     OUTPUT @Hp4142;"*SRE232"    ! Set status byte: bit7,6,5,3
945     OUTPUT @Hp4142;"TM2"        ! Set IE,TV,TI trigger mode
950     OUTPUT @Hp4142;"*OPC?"
955     !
960     ENTER @Hp4142;A$
965     S=SPOLL(@Hp4142)
970     IF BIT(S,5) THEN CALL Detect_error(S,"Init_hp4142")
975   SUBEND
```

Self_test

```
990   SUB Self_test(INTEGER Test_type,Result,OPTIONAL Error$)
995     COM @Hp4142
1000    !************************************************
1005    !*            Execute the self test             *
1010    !************************************************
1015    OUTPUT @Hp4142;"*TST?";Test_type
1020    !
1025    SELECT Test_type
1030    CASE 0 TO 9
1035      ENTER @Hp4142;Result
1040    CASE ELSE
1045      S=SPOLL(@Hp4142)
1050      CALL Detect_error(S,"Self_test")
1055    END SELECT
1060    !************************************************
1065    !*                Check fail code               *
1070    !************************************************
1075    IF NPAR=3 THEN
1080      ALLOCATE E$[60]
1085      IF Result THEN
1090        BEEP
1095        SELECT Test_type
1100        CASE 1 TO 8
1105          FOR I=0 TO 7
1110            IF BIT(Result,I) THEN Error$="Channel "&VAL$(I+1)&" failed on self test"
1115          NEXT I
1120        CASE 9
1125          IF BIT(Result,8) THEN Error$="A/D or CPU failed on self test"
1130        CASE 0
1135          FOR I=0 TO 7
1140            IF BIT(Result,I) THEN E$=E$&VAL$(I+1)
1145            IF BIT(Result,I+1) THEN E$=E$&","
1150          NEXT I
1155          IF BIT(Result,8) THEN E$=E$&" A/D or CPU"
1160          SELECT BIT(Result,0)
1165          CASE 0
1170            Error$="Channel "&TRIM$(E$[2,60])&" failed on self test."
1175          CASE 1
1180            Error$="Channel "&TRIM$(E$)&" failed on self test."
1185          END SELECT
1190        END SELECT
1195        IF BIT(Result,9) OR BIT(Result,10) THEN
1200          Error$="Interlock open. "&Error$
1205        END IF
1210      ELSE
1215        Error$="No Error"
1220      END IF
1225    END IF
1230  SUBEND
```

Force_i

```
1245  SUB Force_i(INTEGER Channel,REAL Current,OPTIONAL Range,V_compliance,INTEGER Polarity)
1250    COM @Hp4142
1255    !************************************************
1260    !*              Set output current              *
1265    !************************************************
1270    Module_type((Channel),Type$)
1275    IF Type$="HP41424" THEN
1280      DISP "Force_i: HP41424 is not specified for current source"
1285      BEEP
1290      STOP
1295    ELSE
1300      IF NPAR>2 THEN
1305        Rng=Range
1310        IF Rng<>0 THEN CALL Set_i_range(Rng)
1315      END IF
1320      !
1325      SELECT NPAR
1330      CASE 2
1335        OUTPUT @Hp4142;"DI";Channel;",0,";Current
1340      CASE 3
1345        OUTPUT @Hp4142;"DI";Channel;",";Rng;",";Current
1350      CASE 4
1355        OUTPUT @Hp4142;"DI";Channel;",";Rng;",";Current;",";V_compliance
1360      CASE 5
1365        OUTPUT @Hp4142;"DI";Channel;",";Rng;",";Current;",";V_compliance;",";Polarity
1370      END SELECT
1375    END IF
1380    !
1385    OUTPUT @Hp4142;"*OPC?"
1390    ENTER @Hp4142;A$
1395    S=SPOLL(@Hp4142)
1400    IF BIT(S,5) THEN CALL Detect_error(S,"Force_i")
1405  SUBEND
```

Force_v

```
1420  SUB Force_v(INTEGER Channel,REAL Voltage,OPTIONAL Range,I_compliance,INTEGER Polarity)
1425    COM @Hp4142
1430    !************************************************
1435    !*              Set output voltage              *
1440    !************************************************
1445    IF NPAR>2 THEN
1450      Rng=Range
1455      IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
1460    END IF
1465    !
1470    SELECT NPAR
1475    CASE 2
1480      OUTPUT @Hp4142;"DV";Channel;",0,";Voltage
1485    CASE 3
1490      OUTPUT @Hp4142;"DV";Channel;",";Rng;",";Voltage
1495    CASE 4
1500      OUTPUT @Hp4142;"DV";Channel;",";Rng;",";Voltage;",";I_compliance
1505    CASE 5
1510      OUTPUT @Hp4142;"DV";Channel;",";Rng;",";Voltage;",";I_compliance;",";Polarity
1515    END SELECT
1520    !
1525    OUTPUT @Hp4142;"*OPC?"
1530    ENTER @Hp4142;A$
1535    S=SPOLL(@Hp4142)
1540    IF BIT(S,5) THEN CALL Detect_error(S,"Force_v")
1545  SUBEND
```

Measure_i

```
1560  SUB Measure_i(INTEGER Channel,REAL Current,OPTIONAL REAL Range,INTEGER Status)
1565    COM @Hp4142
1570    !************************************************
1575    !* Spot measurement will execute -current value-  *
1580    !************************************************
1585    IF NPAR>2 THEN
1590      Rng=Range
1595      IF Rng<>0 THEN CALL Set_i_range(Rng)
1600    END IF
1605    !
1610    SELECT NPAR
1615    CASE 2
1620      OUTPUT @Hp4142;"FMT2;TI";Channel;",0"
1625    CASE 3
1630      OUTPUT @Hp4142;"FMT2;TI";Channel;",";Rng
1635    CASE 4
1640      OUTPUT @Hp4142;"FMT1;TI";Channel;",";Rng
1645    END SELECT
1650    !
1655    OUTPUT @Hp4142;"*OPC?"
1660    ENTER @Hp4142;A$
1665    S=SPOLL(@Hp4142)
1670    IF BIT(S,5) THEN CALL Detect_error(S,"Measure_i")
1675    !************************************************
1680    !*              Get measured data                *
1685    !************************************************
1690    IF NPAR<4 THEN
1695      ENTER @Hp4142;Current
1700    ELSE
1705      ENTER @Hp4142;Data$
1710      Current=VAL(Data$[4;12])
1715      Status$=Data$[1;1]
1720      IF Status$="N" THEN Status=0
1725      IF Status$="T" THEN Status=1
1730      IF Status$="C" THEN Status=2
1735      IF Status$="X" THEN Status=3
1740      IF Status$="V" THEN Status=4
1745      IF Status$="F" THEN Status=7
1750    END IF
1755    OUTPUT @Hp4142;"FMT1"
1760  SUBEND
```

Measure_v

```
1775  SUB Measure_v(INTEGER Channel,REAL Voltage,OPTIONAL Range,INTEGER Status)
1780    COM @Hp4142
1785    !*************************************************
1790    !* Spot measurement will execute -voltage value-  *
1795    !*************************************************
1800    IF NPAR>2 THEN
1805      Rng=Range
1810      IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
1815    END IF
1820    !
1825    SELECT NPAR
1830    CASE 2
1835      OUTPUT @Hp4142;"FMT2;TV";Channel;",0"
1840    CASE 3
1845      OUTPUT @Hp4142;"FMT2;TV";Channel;",";Rng
1850    CASE 4
1855      OUTPUT @Hp4142;"FMT1;TV";Channel;",";Rng
1860    END SELECT
1865    !
1870    OUTPUT @Hp4142;"*OPC?"
1875    ENTER @Hp4142;A$
1880    S=SPOLL(@Hp4142)
1885    IF BIT(S,5) THEN CALL Detect_error(S,"Measure_v")
1890    !*************************************************
1895    !*              Get measured data                *
1900    !*************************************************
1905    IF NPAR<4 THEN
1910      ENTER @Hp4142;Voltage
1915    ELSE
1920      ENTER @Hp4142;Data$
1925      Voltage=VAL(Data$[4;12])
1930      Status$=Data$[1;1]
1935      IF Status$="N" THEN Status=0
1940      IF Status$="T" THEN Status=1
1945      IF Status$="C" THEN Status=2
1950      IF Status$="X" THEN Status=3
1955      IF Status$="V" THEN Status=4
1960      IF Status$="F" THEN Status=7
1965    END IF
1970    OUTPUT @Hp4142;"FMT1"
1975  SUBEND
```

Set_vm

```
1990  SUB Set_vm(INTEGER Channel,INTEGER Vm_mode)
1995    COM @Hp4142
2000    !*************************************************************
2005    !*                    Set VM operation mode                  *
2010    !*************************************************************
2015    OUTPUT @Hp4142;"VM";Channel;",";Vm_mode
2020    OUTPUT @Hp4142;"*OPC?"
2025    ENTER @Hp4142;A$
2030    S=SPOLL(@Hp4142)
2035    IF BIT(S,5) THEN CALL Detect_error(S,"Set_vm")
2040  SUBEND
```

Set_iv

```
2055  SUB Set_iv(INTEGER Channel,Swp_mode,REAL Range,Start,Stop,INTEGER No_step,OPTIONAL REAL H_time,
D_time,Iv_comp,Pw_comp)
2060    COM @Hp4142
2065    !************************************************
2070    !*          Set voltage sweep parameter          *
2075    !************************************************
2080    Rng=Range
2085    IF ABS(Swp_mode)=1 OR ABS(Swp_mode)=3 THEN
2090      IF Swp_mode=1 THEN Smode=1           ! Linear sweep ( single stair )
2095      IF Swp_mode=-1 THEN Smode=2          ! Log sweep    ( single stair )
2100      IF Swp_mode=3 THEN Smode=3           ! Linear sweep ( double stairs )
2105      IF Swp_mode=-3 THEN Smode=4          ! Log sweep    ( double stairs )
2110      IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
2115      !
2120      SELECT NPAR
2125      CASE 6
2130        OUTPUT @Hp4142;"WV";Channel;",";Smode;",";Rng;",";Start;",";Stop;",";No_step
2135      CASE 7
2140        OUTPUT @Hp4142;"WV";Channel;",";Smode;",";Rng;",";Start;",";Stop;",";No_step;";WT";H_time;
",0"
2145      CASE 8
2150        OUTPUT @Hp4142;"WV";Channel;",";Smode;",";Rng;",";Start;",";Stop;",";No_step;";WT";H_time;
",";D_time
2155      CASE 9
2160        OUTPUT @Hp4142;"WV";Channel;",";Smode;",";Rng;",";Start;",";Stop;",";No_step;",";Iv_comp;
";WT";H_time;",";D_time
2165      CASE 10
2170        OUTPUT @Hp4142;"WV";Channel;",";Smode;",";Rng;",";Start;",";Stop;",";No_step;",";Iv_comp;
",";Pw_comp;";WT";H_time;",";D_time
2175      END SELECT
2180    END IF
2185    !************************************************
2190    !*          Set current sweep parameter          *
2195    !************************************************
2200    IF ABS(Swp_mode)=2 OR ABS(Swp_mode)=4 THEN
2205      IF Swp_mode=2 THEN Smode=1           ! Linear sweep ( single stair )
2210      IF Swp_mode=-2 THEN Smode=2          ! Log sweep    ( single stair )
2215      IF Swp_mode=4 THEN Smode=3           ! Linear swep  ( double stairs )
2220      IF Swp_mode=-4 THEN Smode=4          ! Log sweep    ( double stairs )
2225      Module_type((Channel),Type$)
2230      !
2235      IF Type$="HP41424" THEN
2240        DISP "Set_iv: HP41424 is not specified for current source"
2245        BEEP
2250        STOP
2255      ELSE
2260        IF Rng<>0 THEN CALL Set_i_range(Rng)
2265        SELECT NPAR
2270        CASE 6
2275          OUTPUT @Hp4142;"WI";Channel;",";Smode;",";Rng;",";Start;",";Stop;",";No_step
2280        CASE 7
2285          OUTPUT @Hp4142;"WI";Channel;",";Smode;",";Rng;",";Start;",";Stop;",";No_step;";WT";H_time;
",0"
2290        CASE 8
2295          OUTPUT @Hp4142;"WI";Channel;",";Smode;",";Rng;",";Start;",";Stop;",";No_step;";WT";H_time;
",";D_time
2300        CASE 9
2305          OUTPUT @Hp4142;"WI";Channel;",";Smode;",";Rng;",";Start;",";Stop;",";No_step;",";Iv_comp;
";WT";H_time;",";D_time
2310        CASE 10
2315          OUTPUT @Hp4142;"WI";Channel;",";Smode;",";Rng;",";Start;",";Stop;",";No_step;",";Iv_comp;
",";Pw_comp;";WT";H_time;",";D_time
```

```
2320        END SELECT
2325      END IF
2330    END IF
2335    !
2340    OUTPUT @Hp4142;"*OPC?"
2345    ENTER @Hp4142;A$
2350    S=SPOLL(@Hp4142)
2355    IF BIT(S,5) THEN CALL Detect_error(S,"Set_iv")
2360  SUBEND
```

Sweep_iv

```
2375  SUB Sweep_iv(INTEGER Channel,Meas_mode,REAL Range,Meas_data(*),OPTIONAL REAL Sweep_value(*))
2380    OPTION BASE 1
2385    COM @Hp4142
2390    !*******************************************************
2395    !* Sweep measrurement will execute -cuurent & voltage- *
2400    !*******************************************************
2405    Data_num=SIZE(Meas_data,1)                ! check Meas_data(*) size
2410    OUTPUT @Hp4142;"MM2,";Channel
2415    OUTPUT @Hp4142;"WNU?"                     ! check number of sweep step
2420    ENTER @Hp4142;No_step
2425    IF No_step<=Data_num THEN Data_num=No_step
2430    !
2435    IF NPAR=4 THEN OUTPUT @Hp4142;"FMT1,0"    ! get only measured data
2440    IF NPAR=5 THEN OUTPUT @Hp4142;"FMT1,1"    ! get measured and sweep data
2445    IF NPAR=4 THEN ALLOCATE Data$[No_step*16]
2450    IF NPAR=5 THEN ALLOCATE Data$[(No_step*16)*2]
2455    !*******************************************************
2460    !*          Set the measurement parameters             *
2465    !*******************************************************
2470    Rng=Range
2475    Module_type((Channel),Type$)
2480    SELECT Meas_mode
2485    CASE 1
2490      IF Type$="HP41424" THEN
2495        IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
2500        OUTPUT @Hp4142;"RV";Channel;",";Rng
2505      END IF
2510    CASE 2
2515      IF Type$="HP41424" THEN
2520        DISP "Sweep_iv: HP41424 is not specified for current measure"
2525        BEEP
2530        STOP
2535      ELSE
2540        IF Rng<>0 THEN CALL Set_i_range(Rng)
2545        OUTPUT @Hp4142;"RI";Channel;",";Rng
2550      END IF
2555    CASE ELSE
2560      DISP "Sweep_iv: Illegal measurement mode value"
2565      BEEP
2570      STOP
2575    END SELECT
2580    !*******************************************************
2585    !*       Start sweep and get the measured value        *
2590    !*******************************************************
2595    OUTPUT @Hp4142;"XE"
2600    OUTPUT @Hp4142;"*OPC?"
2605    ENTER @Hp4142;A$
2610    S=SPOLL(@Hp4142)
2615    IF BIT(S,5) THEN CALL Detect_error(S,"Sweep_iv")
2620    ENTER @Hp4142;Data$
2625    !*******************************************************
2630    !*            Return only measured value               *
2635    !*******************************************************
2640    IF NPAR=4 THEN
2645      Pointer=1
2650      FOR I=1 TO Data_num*16 STEP 16
2655        Meas$=Data$[I;15]
2660        IF Meas$[1;1]<>"N" THEN GOSUB Error_disp
2665        Meas_data(Pointer)=VAL(Meas$[4;12])
2670        Pointer=Pointer+1
2675      NEXT I
2680      SUBEXIT
```

```
2685    END IF
2690    !*********************************************************
2695    !*       Return both measured and source value           *
2700    !*********************************************************
2705    IF NPAR=5 THEN
2710      Pointer=1
2715      FOR I=1 TO (Data_num*16)*2 STEP 32
2720        Meas$=Data$[I;15]
2725        Sweep$=Data$[I+16;15]
2730        IF Meas$[1;1]<>"N" THEN GOSUB Error_disp
2735        Meas_data(Pointer)=VAL(Meas$[4;12])
2740        Sweep_value(Pointer)=VAL(Sweep$[4;12])
2745        Pointer=Pointer+1
2750      NEXT I
2755    END IF
2760    SUBEXIT
2765    !
2770 Error_disp:  !
2775    DISP "Sweep_iv: ";
2780    SELECT Meas$[1;1]
2785    CASE "T"
2790      DISP CHR$(129);" Another channel has reached compliance ";CHR$(128)
2795    CASE "C"
2800      DISP CHR$(129);" This channel has reached compliance ";CHR$(128)
2805    CASE "X"
2810      DISP CHR$(129);" This channel is oscillating ";CHR$(128)
2815    CASE "V"
2820      DISP CHR$(129);" Measurement data overflow ";CHR$(128)
2825    CASE "F"
2830      DISP CHR$(129);" HVU is not settled ";CHR$(128)
2835    END SELECT
2840    RETURN
2845    !
2850  SUBEND
```

Sweep_miv

```
2865  SUB Sweep_miv(INTEGER Channel(*),Meas_mode(*),REAL Range(*),Meas_data(*),OPTIONAL Sweep_value(*))
2870    OPTION BASE 1
2875    COM @Hp4142
2880    !*********************************************************
2885    !*            Set the measurement channel                *
2890    !*********************************************************
2895    Meas_channel=SIZE(Channel,1)              ! check meas channel number
2900    !
2905    SELECT Meas_channel
2910    CASE 1
2915      OUTPUT @Hp4142;"MM2,";Channel(1)
2920    CASE 2
2925      OUTPUT @Hp4142;"MM2,";Channel(1);",";Channel(2)
2930    CASE 3
2935      OUTPUT @Hp4142;"MM2,";Channel(1);",";Channel(2);",";Channel_(3)
2940    CASE 4
2945      OUTPUT @Hp4142;"MM2,";Channel(1);",";Channel(2);",";Channel(3);",";Channel(4)
2950    CASE 5
2955      OUTPUT @Hp4142;"MM2,";Channel(1);",";Channel(2);",";Channel(3);",";Channel(4);",";Channel(5)
2960    CASE 6
2965      OUTPUT @Hp4142;"MM2,";Channel(1);",";Channel(2);",";Channel(3);",";Channel(4);",";Channel(5);
",";Channel(6)
2970    CASE 7
2975      OUTPUT @Hp4142;"MM2,";Channel(1);",";Channel(2);",";Channel(3);",";Channel(4);",";Channel(5);
",";Channel(6);",";Channel(7)
2980    CASE 8
2985      OUTPUT @Hp4142;"MM2,";Channel(1);",";Channel(2);",";Channel(3);",";Channel(4);",";Channel(5);
",";Channel(6);",";Channel(7);",";Channel(8)
2990    END SELECT
2995    !
3000    OUTPUT @Hp4142;"*OPC?"
3005    ENTER @Hp4142;A$
3010    S=SPOLL(@Hp4142)
3015    IF BIT(S,5) THEN CALL Detect_error(S,"Sweep_miv")
3020    !*********************************************************
3025    !*                    Initial setting                    *
3030    !*********************************************************
3035    Data_num=SIZE(Meas_data,2)                ! check Meas_data(*) size
3040    OUTPUT @Hp4142;"WNU?"                     ! check number of sweep step
3045    ENTER @Hp4142;No_step
3050    IF No_step<=Data_num THEN Data_num=No_step
3055    ALLOCATE Status$(Meas_channel,Data_num)[1]
3060    !
3065    FOR I=1 TO Meas_channel
3070      FOR J=1 TO Data_num
3075        Status$(I,J)="N"
3080      NEXT J
3085    NEXT I
3090    IF NPAR=4 THEN ALLOCATE Data_buffer$[(Meas_channel*16)*No_step]
3095    IF NPAR=5 THEN ALLOCATE Data_buffer$[((Meas_channel+1)*16)*No_step]
3100    IF NPAR=4 THEN OUTPUT @Hp4142;"FMT1,0"    ! get only measured data
3105    IF NPAR=5 THEN OUTPUT @Hp4142;"FMT1,1"    ! get measured and sweep data
3110    !*********************************************************
3115    !*        Set the ranging parameters for SMU             *
3120    !*********************************************************
3125    FOR I=1 TO Meas_channel
3130      Module_type((Channel(I)),Type$)
3135      Rng=Range(I)
3140      !
3145      SELECT Meas_mode(I)
3150      CASE 1
3155        IF Rng<>0 THEN CALL Set_v_range((Channel(I)),Rng)
```

```
3160        IF Type$="HP41424" THEN OUTPUT @Hp4142;"RV";Channel(I);",";Rng
3165      CASE 2
3170        IF Type$="HP41424" THEN
3175          DISP "Sweep_miv: HP41424 is not specified for current measure"
3180          BEEP
3185          STOP
3190        ELSE
3195          IF Rng<>0 THEN CALL Set_i_range(Rng)
3200          OUTPUT @Hp4142;"RI";Channel(I);",";Rng
3205        END IF
3210      CASE ELSE
3215        DISP "Sweep_miv:  Illegal Measurement mode value"
3220        BEEP
3225        STOP
3230      END SELECT
3235      !
3240      OUTPUT @Hp4142;"*OPC?"
3245      ENTER @Hp4142;A$
3250      S=SPOLL(@Hp4142)
3255      IF BIT(S,5) THEN CALL Detect_error(S,"Sweep_miv")
3260    NEXT I
3265    !*********************************************************
3270    !*       Start sweep and get the measured value          *
3275    !*********************************************************
3280    OUTPUT @Hp4142;"XE"
3285    OUTPUT @Hp4142;"*OPC?"
3290    ENTER @Hp4142;A$
3295    S=SPOLL(@Hp4142)
3300    IF BIT(S,5) THEN CALL Detect_error(S,"Sweep_miv")
3305    ENTER @Hp4142;Data_buffer$
3310    !*********************************************************
3315    !*             Return only measured value                *
3320    !*********************************************************
3325    Pointer=1
3330    Chan=1
3335    IF NPAR=4 THEN
3340      FOR I=1 TO (Meas_channel*16)*Data_num STEP Meas_channel*16
3345        Chan=1
3350        FOR J=1 TO Meas_channel*16 STEP 16
3355          Meas$=Data_buffer$[I+(J-1);15]
3360          IF Meas$[1;1]<>"N" THEN Status$(Chan,Pointer)=Meas$[1;1]
3365          Meas_data(Chan,Pointer)=VAL(Meas$[4;12])
3370          Chan=Chan+1
3375        NEXT J
3380        Pointer=Pointer+1
3385      NEXT I
3390    END IF
3395    !*********************************************************
3400    !*       Return both measured and source value           *
3405    !*********************************************************
3410    IF NPAR=5 THEN
3415      FOR I=1 TO ((Meas_channel+1)*16)*Data_num STEP (Meas_channel+1)*16
3420        Chan=1
3425        FOR J=1 TO Meas_channel*16 STEP 16
3430          Meas$=Data_buffer$[I+(J-1);15]
3435          IF Meas$[1;1]<>"N" THEN Status$(Chan,Pointer)=Meas$[1;1]
3440          Meas_data(Chan,Pointer)=VAL(Meas$[4;12])
3445          Chan=Chan+1
3450        NEXT J
3455        Sweep$=Data_buffer$[I+(J-1);15]
3460        Sweep_value(Pointer)=VAL(Sweep$[4;12])
3465        Pointer=Pointer+1
3470      NEXT I
3475    END IF
3480    !*****************************************************************
3485    !*        Error channel detect ... Display error message         *
```

```
3490    !*********************************************************************
3495    FOR I=1 TO Meas_channel
3500      FOR J=1 TO Data_num
3505        IF Status$(I,J)<>"N" THEN
3510          GOSUB Error_disp
3515        END IF
3520      NEXT J
3525    NEXT I
3530    SUBEXIT
3535  !
3540 Error_disp:   !
3545    DISP "Sweep_mix: ";CHR$(129);" Channel";Channel(I);":";
3550    SELECT Status$(I,J)
3555    CASE "T"
3560      DISP " Another channel has reached compliance ";CHR$(128)
3565    CASE "C"
3570      DISP " This channel has reached compliance ";CHR$(128)
3575    CASE "X"
3580      DISP " This channel is oscillating ";CHR$(128)
3585    CASE "V"
3590      DISP " Measurement data overflow ";CHR$(128)
3595    CASE "F"
3600      DISP " HVU is not settled ";CHR$(128)
3605    END SELECT
3610    RETURN
3615  !
3620  SUBEND
```

Sweep_mode

```
3635  SUB Sweep_mode(INTEGER Return_mode,OPTIONAL INTEGER Stop_mode)
3640    COM @Hp4142
3645    !************************************************
3650    !*           Set sweep operation mode           *
3655    !************************************************
3660    SELECT NPAR
3665    CASE 1
3670      OUTPUT @Hp4142;"WM";Return_mode
3675    CASE 2
3680      OUTPUT @Hp4142;"WM";Return_mode;",";Stop_mode
3685    END SELECT
3690    !
3695    OUTPUT @Hp4142;"*OPC?"
3700    ENTER @Hp4142;A$
3705    S=SPOLL(@Hp4142)
3710    IF BIT(S,5) THEN CALL Detect_error(S,"Sweep_mode")
3715  SUBEND
```

Dpluse_v

```
3730  SUB Dpulse_v(INTEGER Channel,REAL Range,Pbase,Pvalue,OPTIONAL Compliance)
3735    COM @Hp4142
3740    !******************************************************
3745    !*    Setup the pulse voltage measurement parameter   *
3750    !******************************************************
3755    Rng=Range
3760    Module_type((Channel),Type$)
3765    IF Type$="HP41424" THEN
3770      DISP "Dpulse_v: HP41424 is not specified for 2ch pulse channel"
3775      BEEP
3780      STOP
3785    ELSE
3790      IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
3795      SELECT NPAR
3800      CASE 4
3805        OUTPUT @Hp4142;"PDV";Channel;",";Rng;",";Pbase;",";Pvalue
3810      CASE 5
3815        OUTPUT @Hp4142;"PDV";Channel;",";Rng;",";Pbase;",";Pvalue;",";Compliance
3820      END SELECT
3825    END IF
3830    !
3835    OUTPUT @Hp4142;"*OPC?"
3840    ENTER @Hp4142;A$
3845    S=SPOLL(@Hp4142)
3850    IF BIT(S,5) THEN CALL Detect_error(S,"Dpulse_v")
3855  SUBEND
```

Pulse_v

```
3870  SUB Pulse_v(INTEGER Channel,REAL Range,Pbase,Pvalue,Pwidth,Htime,OPTIONAL Period,Compliance)
3875    COM @Hp4142
3880    !******************************************************
3885    !*    Setup the pulse voltage measurement parameter   *
3890    !******************************************************
3895    Rng=Range
3900    IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
3905    SELECT NPAR
3910    CASE 6
3915      OUTPUT @Hp4142;"PV";Channel;",";Rng;",";Pbase;",";Pvalue;";PT";Htime;",";Pwidth
3920    CASE 7
3925      OUTPUT @Hp4142;"PV";Channel;",";Rng;",";Pbase;",";Pvalue;";PT";Htime;",";Pwidth;",";Period
3930    CASE 8
3935      OUTPUT @Hp4142;"PV";Channel;",";Rng;",";Pbase;",";Pvalue;",";Compliance;";PT";Htime;",";Pwidth;
",";Period
3940    END SELECT
3945    !
3950    OUTPUT @Hp4142;"*OPC?"
3955    ENTER @Hp4142;A$
3960    S=SPOLL(@Hp4142)
3965    IF BIT(S,5) THEN CALL Detect_error(S,"Pulse_v")
3970  SUBEND
```

Dpulse_i

```
3985  SUB Dpulse_i(INTEGER Channel,REAL Range,Pbase,Pvalue,OPTIONAL Compliance)
3990    COM @Hp4142
3995    !******************************************************
4000    !*   Setup the pulse current measurement parameter   *
4005    !******************************************************
4010    Rng=Range
4015    Module_type((Channel),Type$)
4020    IF Type$="HP41424" THEN
4025      DISP "Dpulse_i: HP41424 is not specified for 2ch pulse channel"
4030      BEEP
4035      STOP
4040    ELSE
4045      IF Rng<>0 THEN CALL Set_i_range(Rng)
4050      SELECT NPAR
4055      CASE 4
4060        OUTPUT @Hp4142;"PDI";Channel;",";Rng;",";Pbase;",";Pvalue
4065      CASE 5
4070        OUTPUT @Hp4142;"PDI";Channel;",";Rng;",";Pbase;",";Pvalue;",";Compliance
4075      END SELECT
4080    END IF
4085    !
4090    OUTPUT @Hp4142;"*OPC?"
4095    ENTER @Hp4142;A$
4100    S=SPOLL(@Hp4142)
4105    IF BIT(S,5) THEN CALL Detect_error(S,"Dpulse_i")
4110  SUBEND
```

Pulse_i

```
4125  SUB Pulse_i(INTEGER Channel,REAL Range,Pbase,Pvalue,Pwidth,Htime,OPTIONAL Period,Compliance)
4130    COM @Hp4142
4135    !*****************************************************
4140    !*   Setup the pulse current measurement parameter   *
4145    !*****************************************************
4150    Rng=Range
4155    Module_type((Channel),Type$)
4160    IF Type$="HP41424" THEN
4165      DISP "Pulse_i: HP41424 is not specified for current source"
4170      BEEP
4175      STOP
4180    ELSE
4185      IF Rng<>0 THEN CALL Set_i_range(Rng)
4190      SELECT NPAR
4195      CASE 6
4200        OUTPUT @Hp4142;"PI";Channel;",";Rng;",";Pbase;",";Pvalue;";PT";Htime;",";Pwidth
4205      CASE 7
4210        OUTPUT @Hp4142;"PI";Channel;",";Rng;",";Pbase;",";Pvalue;";PT";Htime;",";Pwidth;",";Period
4215      CASE 8
4220        OUTPUT @Hp4142;"PI";Channel;",";Rng;",";Pbase;",";Pvalue;",";Compliance;";PT";Htime;",";Pwidth;
",";Period
4225      END SELECT
4230    END IF
4235    !
4240    OUTPUT @Hp4142;"*OPC?"
4245    ENTER @Hp4142;A$
4250    S=SPOLL(@Hp4142)
4255    IF BIT(S,5) THEN CALL Detect_error(S,"Pulse_i")
4260  SUBEND
```

Dpulse_measure

```
4275  SUB Dpulse_measure(INTEGER Channel,Meas_mode,REAL Meas_data,OPTIONAL INTEGER Primary,REAL Range,
INTEGER Status)
4280    COM @Hp4142
4285    !*********************************************************************
4290    !*  Performs the 2CH pulsed spot measurement  -current & voltage -  *
4295    !*********************************************************************
4300    Rng=0
4305    IF NPAR>4 THEN Rng=Range
4310    Module_type((Channel),Type$)
4315    OUTPUT @Hp4142;"MM7,";Channel
4320    OUTPUT @Hp4142;"FLO"                          ! SMU filter off
4325    !
4330    SELECT Meas_mode
4335    CASE 1
4340      IF Type$="HP41424" THEN
4345        IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
4350        OUTPUT @Hp4142;"RV";Channel;",";Rng
4355      END IF
4360    CASE 2
4365      IF Type$="HP41424" THEN
4370        DISP "Dpulse_measure: HP41424 is not specified for current measure"
4375        BEEP
4380        STOP
4385      ELSE
4390        IF Rng<>0 THEN CALL Set_i_range(Rng)
4395        OUTPUT @Hp4142;"RI";Channel;",";Rng
4400      END IF
4405    CASE ELSE
4410      DISP "Dpulse_measure: Illegal measurement mode value"
4415      BEEP
4420      STOP
4425    END SELECT
4430    !
4435    IF NPAR>3 THEN
4440      IF Primary=0 THEN
4445        OUTPUT @Hp4142;"PDM"
4450      ELSE
4455        OUTPUT @Hp4142;"PDM";Primary
4460      END IF
4465    ELSE
4470      OUTPUT @Hp4142;"PDM"
4475    END IF
4480    OUTPUT @Hp4142;"XE"
4485    OUTPUT @Hp4142;"*OPC?"
4490    ENTER @Hp4142;A$
4495    S=SPOLL(@Hp4142)
4500    IF BIT(S,5) THEN CALL Detect_error(S,"Dpulse_measure")
4505    !*************************************************************
4510    !*          Execute trigger and get measured data          *
4515    !*************************************************************
4520    IF NPAR<6 THEN
4525      ENTER @Hp4142;Meas_data
4530      OUTPUT @Hp4142;"FL1"                        ! SMU filter on
4535      SUBEXIT
4540    ELSE
4545      ENTER @Hp4142;Data$
4550      OUTPUT @Hp4142;"FL1"                        ! SMU filter on
4555      Meas_data=VAL(Data$[4;12])
4560      Status$=Data$[1;1]
4565      IF Status$="N" THEN Status=0
4570      IF Status$="T" THEN Status=1
4575      IF Status$="C" THEN Status=2
```

```
4580       IF Status$="X" THEN Status=3
4585       IF Status$="V" THEN Status=4
4590       IF Status$="F" THEN Status=7
4595     END IF
4600     !
4605   SUBEND
```

Pulse_measure

```
4620  SUB Pulse_measure(INTEGER Channel,Meas_mode,REAL Meas_data,OPTIONAL Range,INTEGER Status)
4625    COM @Hp4142
4630    !*****************************************************************
4635    !*  Performs the pulsed spot measurement  -current & voltage -  *
4640    !*****************************************************************
4645    Rng=0
4650    IF NPAR>3 THEN Rng=Range
4655    Module_type((Channel),Type$)
4660    OUTPUT @Hp4142;"MM3,";Channel
4665    OUTPUT @Hp4142;"FL0"                          ! SMU filter off
4670    !
4675    SELECT Meas_mode
4680    CASE 1
4685      IF Type$="HP41424" THEN
4690        IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
4695        OUTPUT @Hp4142;"RV";Channel;",";Rng
4700      END IF
4705    CASE 2
4710      IF Type$="HP41424" THEN
4715        DISP "Pulse_measure: HP41424 is not specified for current measure"
4720        BEEP
4725        STOP
4730      ELSE
4735        IF Rng<>0 THEN CALL Set_i_range(Rng)
4740        OUTPUT @Hp4142;"RI";Channel;",";Rng
4745      END IF
4750    CASE ELSE
4755      DISP "Pulse_measure: Illegal measurement mode value"
4760      BEEP
4765      STOP
4770    END SELECT
4775    !
4780    OUTPUT @Hp4142;"XE"
4785    OUTPUT @Hp4142;"*OPC?"
4790    ENTER @Hp4142;A$
4795    S=SPOLL(@Hp4142)
4800    IF BIT(S,5) THEN CALL Detect_error(S,"Pulse_measure")
4805    !*************************************************************
4810    !*          Execute trigger and get measured data          *
4815    !*************************************************************
4820    IF NPAR<5 THEN
4825      ENTER @Hp4142;Meas_data
4830      OUTPUT @Hp4142;"FL1"                        ! SMU filter on
4835      SUBEXIT
4840    ELSE
4845      ENTER @Hp4142;Data$
4850      OUTPUT @Hp4142;"FL1"                        ! SMU filter on
4855      Meas_data=VAL(Data$[4;12])
4860      Status$=Data$[1;1]
4865      IF Status$="N" THEN Status=0
4870      IF Status$="T" THEN Status=1
4875      IF Status$="C" THEN Status=2
4880      IF Status$="I" THEN Status=3
4885      IF Status$="V" THEN Status=4
4890      IF Status$="F" THEN Status=7
4895    END IF
4900    !
4905  SUBEND
```

Set_piv

```
4920  SUB Set_piv(INTEGER Channel,Swp_mode,REAL Range,Pbase,Start,Stop,No_step,Pwidth,Period,Htime,
OPTIONAL Compliance)
4925    COM @Hp4142
4930    !*****************************************************
4935    !*         Setup the pluse sweep parameters          *
4940    !*****************************************************
4945    Rng=Range
4950    IF Swp_mode<1 OR Swp_mode>4 THEN
4955      DISP "Set_piv: Illegal sweep mode value"
4960      BEEP
4965      STOP
4970    END IF
4975    !
4980    IF Swp_mode=1 OR Swp_mode=3 THEN
4985      IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
4990      SELECT NPAR
4995      CASE 10
5000        OUTPUT @Hp4142;"PWV";Channel;",";Swp_mode;",";Rng;",";Pbase;",";Start;",";Stop;",";No_step;
";PT";Htime;",";Pwidth;",";Period
5005      CASE 11
5010        OUTPUT @Hp4142;"PWV";Channel;",";Swp_mode;",";Rng;",";Pbase;",";Start;",";Stop;",";No_step;
",";Compliance;";PT";Htime;",";Pwidth;",";Period
5015      END SELECT
5020    END IF
5025    !
5030    IF Swp_mode=2 OR Swp_mode=4 THEN
5035      Module_type((Channel),Type$)
5040      IF Type$="HP41424" THEN
5045        DISP "Set_piv: HP41424 is not specified for current source"
5050        BEEP
5055        STOP
5060      ELSE
5065        Swp_mode=Swp_mode-1
5070        IF Rng<>0 THEN CALL Set_i_range(Rng)
5075        SELECT NPAR
5080        CASE 10
5085          OUTPUT @Hp4142;"PWI";Channel;",";Swp_mode;",";Rng;",";Pbase;",";Start;",";Stop;",";No_step;
";PT";Htime;",";Pwidth;",";Period
5090        CASE 11
5095          OUTPUT @Hp4142;"PWI";Channel;",";Swp_mode;",";Rng;",";Pbase;",";Start;",";Stop;",";No_step;
",";Compliance;";PT";Htime;",";Pwidth;",";Period
5100        END SELECT
5105      END IF
5110    END IF
5115    !
5120    OUTPUT @Hp4142;"*OPC?"
5125    ENTER @Hp4142;A$
5130    S=SPOLL(@Hp4142)
5135    IF BIT(S,5) THEN CALL Detect_error(S,"Set_piv")
5140  SUBEND
```

Dsweep_piv

```
5155  SUB Dsweep_piv(INTEGER Channel,Mmode,REAL Range,Meas_data(*),OPTIONAL INTEGER Primary,
REAL Sweep_value(*))
5160    OPTION BASE 1
5165    COM @Hp4142
5170    !************************************************************
5175    !*        Performs the 2CH pulsed sweep mesurement          *
5180    !************************************************************
5185    Data_num=SIZE(Meas_data,1)                ! check Meas_data(*) size
5190    OUTPUT @Hp4142;"MM8,";Channel
5195    OUTPUT @Hp4142;"WNU?"                     ! check number of sweep step
5200    ENTER @Hp4142;No_step
5205    IF No_step<=Data_num THEN Data_num=No_step
5210    !
5215    IF NPAR<6 THEN OUTPUT @Hp4142;"FMT1,0"    ! get only measured data
5220    IF NPAR=6 THEN OUTPUT @Hp4142;"FMT1,1"    ! get measured and sweep data
5225    IF NPAR<6 THEN ALLOCATE Data$[No_step*16]
5230    IF NPAR=6 THEN ALLOCATE Data$[(No_step*16)*2]
5235    !*********************************************************
5240    !*          Setup the measurement parameters             *
5245    !*********************************************************
5250    Rng=Range
5255    Module_type((Channel),Type$)
5260    OUTPUT @Hp4142;"FLO"                      ! SMU filter off
5265    SELECT Mmode
5270    CASE 1
5275      IF Type$="HP41424" THEN
5280        IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
5285        OUTPUT @Hp4142;"RV";Channel;",";Rng
5290      END IF
5295    CASE 2
5300      IF Type$="HP41424" THEN
5305        DISP "Dsweep_piv: HP41424 is not specified for current measure"
5310        BEEP
5315        STOP
5320      ELSE
5325        IF Rng<>0 THEN CALL Set_i_range(Rng)
5330        OUTPUT @Hp4142;"RI";Channel;",";Rng
5335      END IF
5340    CASE ELSE
5345      DISP "Dsweep_piv: Illegal measurement mode value"
5350      BEEP
5355      STOP
5360    END SELECT
5365    IF NPAR>4 THEN
5370      IF Primary=0 THEN
5375        OUTPUT @Hp4142;"PDM"
5380      ELSE
5385        OUTPUT @Hp4142;"PDM";Primary
5390      END IF
5395    ELSE
5400      OUTPUT @Hp4142;"PDM"
5405    END IF
5410    OUTPUT @Hp4142;"*OPC?"
5415    ENTER @Hp4142;A$
5420    S=SPOLL(@Hp4142)
5425    IF BIT(S,5) THEN CALL Detect_error(S,"Dsweep_piv")
5430    !*********************************************************
5435    !*        Start sweep and get the measured value         *
5440    !*********************************************************
5445    OUTPUT @Hp4142;"XE"
5450    OUTPUT @Hp4142;"*OPC?"
5455    ENTER @Hp4142;A$
```

```
5460    S=SPOLL(@Hp4142)
5465    IF BIT(S,5) THEN CALL Detect_error(S,"Dsweep_piv")
5470    ENTER @Hp4142;Data$
5475    OUTPUT @Hp4142;"FL1"                        ! SMU filter on
5480    !*********************************************************
5485    !*              Return only measured value               *
5490    !*********************************************************
5495    IF NPAR<6 THEN
5500      Pointer=1
5505      FOR I=1 TO Data_num*16 STEP 16
5510        Meas$=Data$[I;15]
5515        IF Meas$[1;1]<>"N" THEN GOSUB Error_disp
5520        Meas_data(Pointer)=VAL(Meas$[4;12])
5525        Pointer=Pointer+1
5530      NEXT I
5535      SUBEXIT
5540    END IF
5545    !*********************************************************
5550    !*        Return both measured and source value          *
5555    !*********************************************************
5560    IF NPAR=6 THEN
5565      Pointer=1
5570      FOR I=1 TO (Data_num*16)*2 STEP 32
5575        Meas$=Data$[I;15]
5580        Sweep$=Data$[I+16;15]
5585        IF Meas$[1;1]<>"N" THEN GOSUB Error_disp
5590        Meas_data(Pointer)=VAL(Meas$[4;12])
5595        Sweep_value(Pointer)=VAL(Sweep$[4;12])
5600        Pointer=Pointer+1
5605      NEXT I
5610    END IF
5615    SUBEXIT
5620    !
5625 Error_disp:  !
5630    DISP "Dsweep_piv: ";
5635    SELECT Meas$[1;1]
5640    CASE "T"
5645      DISP CHR$(129);" Another channel has reached compliance ";CHR$(128)
5650    CASE "C"
5655      DISP CHR$(129);" This channel has reached compliance ";CHR$(128)
5660    CASE "X"
5665      DISP CHR$(129);" This channel is oscillating ";CHR$(128)
5670    CASE "V"
5675      DISP CHR$(129);" Measurement data overflow ";CHR$(128)
5680    END SELECT
5685    RETURN
5690    !
5695  SUBEND
```

Sweep_piv

```
5710  SUB Sweep_piv(INTEGER Channel,Mmode,REAL Range,Meas_data(*),OPTIONAL Sweep_value(*))
5715    OPTION BASE 1
5720    COM @Hp4142
5725    !*********************************************************
5730    !*        Performs the pulsed sweep mesurement           *
5735    !*********************************************************
5740    Data_num=SIZE(Meas_data,1)                ! check Meas_data(*) size
5745    OUTPUT @Hp4142;"MM4,";Channel
5750    OUTPUT @Hp4142;"WNU?"                     ! check number of sweep step
5755    ENTER @Hp4142;No_step
5760    IF No_step<=Data_num THEN Data_num=No_step
5765    !
5770    IF NPAR=4 THEN OUTPUT @Hp4142;"FMT1,0"    ! get only measured data
5775    IF NPAR=5 THEN OUTPUT @Hp4142;"FMT1,1"    ! get measured and sweep data
5780    IF NPAR=4 THEN ALLOCATE Data$[No_step*16]
5785    IF NPAR=5 THEN ALLOCATE Data$[(No_step*16)*2]
5790    !*********************************************************
5795    !*          Setup the measurement parameters             *
5800    !*********************************************************
5805    Rng=Range
5810    Module_type((Channel),Type$)
5815    OUTPUT @Hp4142;"FLO"                      ! SMU filter off
5820    SELECT Mmode
5825    CASE 1
5830      IF Type$="HP41424" THEN
5835        IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
5840        OUTPUT @Hp4142;"RV";Channel;",";Rng
5845      END IF
5850    CASE 2
5855      IF Type$="HP41424" THEN
5860        DISP "Sweep_piv: HP41424 is not specified for current measure"
5865        BEEP
5870        STOP
5875      ELSE
5880        IF Rng<>0 THEN CALL Set_i_range(Rng)
5885        OUTPUT @Hp4142;"RI";Channel;",";Rng
5890      END IF
5895    CASE ELSE
5900      DISP "Sweep_piv: Illegal measurement mode value"
5905      BEEP
5910      STOP
5915    END SELECT
5920    !*********************************************************
5925    !*        Start sweep and get the measured value         *
5930    !*********************************************************
5935    OUTPUT @Hp4142;"XE"
5940    OUTPUT @Hp4142;"*OPC?"
5945    ENTER @Hp4142;A$
5950    S=SPOLL(@Hp4142)
5955    IF BIT(S,5) THEN CALL Detect_error(S,"Sweep_piv")
5960    ENTER @Hp4142;Data$
5965    OUTPUT @Hp4142;"FL1"                      ! SMU filter on
5970    !*********************************************************
5975    !*             Return only measured value                *
5980    !*********************************************************
5985    IF NPAR=4 THEN
5990      Pointer=1
5995      FOR I=1 TO Data_num*16 STEP 16
6000        Meas$=Data$[I;15]
6005        IF Meas$[1;1]<>"N" THEN GOSUB Error_disp
6010        Meas_data(Pointer)=VAL(Meas$[4;12])
6015        Pointer=Pointer+1
```

```
6020      NEXT I
6025      SUBEXIT
6030    END IF
6035    !*********************************************************
6040    !*        Return both measured and source value          *
6045    !*********************************************************
6050    IF NPAR=5 THEN
6055      Pointer=1
6060      FOR I=1 TO (Data_num*16)*2 STEP 32
6065        Meas$=Data$[I;15]
6070        Sweep$=Data$[I+16;15]
6075        IF Meas$[1;1]<>"N" THEN GOSUB Error_disp
6080        Meas_data(Pointer)=VAL(Meas$[4;12])
6085        Sweep_value(Pointer)=VAL(Sweep$[4;12])
6090        Pointer=Pointer+1
6095      NEXT I
6100    END IF
6105    SUBEXIT
6110    !
6115 Error_disp:  !
6120    DISP "Sweep_piv: ";
6125    SELECT Meas$[1;1]
6130    CASE "T"
6135      DISP CHR$(129);" Another channel has reached compliance ";CHR$(128)
6140    CASE "C"
6145      DISP CHR$(129);" This channel has reached compliance ";CHR$(128)
6150    CASE "X"
6155      DISP CHR$(129);" This channel is oscillating ";CHR$(128)
6160    CASE "V"
6165      DISP CHR$(129);" Measurement data overflow ";CHR$(128)
6170    CASE "F"
6175      DISP CHR$(129);" HVU is not settled ";CHR$(128)
6180    END SELECT
6185    RETURN
6190    !
6195  SUBEND
```

Sweep_pbias

```
6210  SUB Sweep_pbias(INTEGER Channel,Mmode,REAL Range,Meas_data(*),OPTIONAL Sweep_value(*))
6215    OPTION BASE 1
6220    COM @Hp4142
6225    !*********************************************************
6230    !*        Performs the pulsed sweep mesurement           *
6235    !*********************************************************
6240    Data_num=SIZE(Meas_data,1)                ! check Meas_data(*) size
6245    OUTPUT @Hp4142;"MM5,";Channel
6250    OUTPUT @Hp4142;"WNU?"                     ! check number of sweep step
6255    ENTER @Hp4142;No_step
6260    IF No_step<=Data_num THEN Data_num=No_step
6265    !
6270    IF NPAR=4 THEN OUTPUT @Hp4142;"FMT1,0"    ! get only measured data
6275    IF NPAR=5 THEN OUTPUT @Hp4142;"FMT1,1"    ! get measured and sweep data
6280    IF NPAR=4 THEN ALLOCATE Data$[No_step*16]
6285    IF NPAR=5 THEN ALLOCATE Data$[(No_step*16)*2]
6290    !*********************************************************
6295    !*          Setup the measurement parameters             *
6300    !*********************************************************
6305    Rng=Range
6310    Module_type((Channel),Type$)
6315    OUTPUT @Hp4142;"FLO"                      ! SMU filter off
6320    SELECT Mmode
6325    CASE 1
6330      IF Type$="HP41424" THEN
6335        IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
6340        OUTPUT @Hp4142;"RV";Channel;",";Rng
6345      END IF
6350    CASE 2
6355      IF Type$="HP41424" THEN
6360        DISP "Sweep_pbias: HP41424 is not specified for current measure"
6365        BEEP
6370        STOP
6375      ELSE
6380        IF Rng<>0 THEN CALL Set_i_range(Rng)
6385        OUTPUT @Hp4142;"RI";Channel;",";Rng
6390      END IF
6395    CASE ELSE
6400      DISP "Sweep_pbias: Illegal measurement value"
6405      BEEP
6410      STOP
6415    END SELECT
6420    !*********************************************************
6425    !*        Start sweep and get the measured value         *
6430    !*********************************************************
6435    OUTPUT @Hp4142;"XE"
6440    OUTPUT @Hp4142;"*OPC?"
6445    ENTER @Hp4142;A$
6450    S=SPOLL(@Hp4142)
6455    IF BIT(S,5) THEN CALL Detect_error(S,"Sweep_pbias")
6460    ENTER @Hp4142;Data$
6465    OUTPUT @Hp4142;"FL1"                      ! SMU filter on
6470    !*********************************************************
6475    !*             Return only measured value                *
6480    !*********************************************************
6485    IF NPAR=4 THEN
6490      Pointer=1
6495      FOR I=1 TO Data_num*16 STEP 16
6500        Meas$=Data$[I;15]
6505        IF Meas$[1;1]<>"N" THEN GOSUB Error_disp
6510        Meas_data(Pointer)=VAL(Meas$[4;12])
6515        Pointer=Pointer+1
```

```
6520      NEXT I
6525      SUBEXIT
6530    END IF
6535    !*********************************************************
6540    !*        Return both measured and source value          *
6545    !*********************************************************
6550    IF NPAR=5 THEN
6555      Pointer=1
6560      FOR I=1 TO (Data_num*16)*2 STEP 32
6565        Meas$=Data$[I;15]
6570        Sweep$=Data$[I+16;15]
6575        IF Meas$[1;1]<>"N" THEN GOSUB Error_disp
6580        Meas_data(Pointer)=VAL(Meas$[4;12])
6585        Sweep_value(Pointer)=VAL(Sweep$[4;12])
6590        Pointer=Pointer+1
6595      NEXT I
6600    END IF
6605    SUBEXIT
6610  !
6615 Error_disp:  !
6620    DISP "Sweep_pbias: ";
6625    SELECT Meas$[1;1]
6630    CASE "T"
6635      DISP CHR$(129);" Another channel has reached compliance ";CHR$(128)
6640    CASE "C"
6645      DISP CHR$(129);" This channel has reached compliance ";CHR$(128)
6650    CASE "X"
6655      DISP CHR$(129);" This channel is oscillating ";CHR$(128)
6660    CASE "V"
6665      DISP CHR$(129);" Measurement data overflow ";CHR$(128)
6670    CASE "F"
6675      DISP CHR$(129);" HVU is not settled ";CHR$(128)
6680    END SELECT
6685    RETURN
6690    !
6695  SUBEND
```

Set_asource

```
6710  SUB Set_asource(INTEGER Channel,REAL Rstart,Rstop,Rspeed,Htime,Dtime,OPTIONAL Compliance)
6715    COM @Hp4142
6720    !*********************************************************
6725    !*    Setup the analog feedback measurement parameters   *
6730    !*********************************************************
6735    SELECT NPAR
6740    CASE 6
6745      OUTPUT @Hp4142;"ASV";Channel;",";Rstart;",";Rstop;",";Rspeed;";AT";Htime;",";Dtime
6750    CASE 7
6755      OUTPUT @Hp4142;"ASV";Channel;",";Rstart;",";Rstop;",";Rspeed;",";Compliance;";AT";Htime;",";Dtime
6760    END SELECT
6765    !
6770    OUTPUT @Hp4142;"*OPC?"
6775    ENTER @Hp4142;A$
6780    S=SPOLL(@Hp4142)
6785    IF BIT(S,5) THEN CALL Detect_error(S,"Set_asource")
6790  SUBEND
```

Set_amonitor

```
6805  SUB Set_amonitor(INTEGER Channel,Mmode,REAL Source,Goal,OPTIONAL Compliance)
6810    COM @Hp4142
6815    !*********************************************************
6820    !*    Setup the analog feedback measurement parameters   *
6825    !*********************************************************
6830    SELECT Mmode
6835    CASE 1
6840      IF NPAR=4 THEN
6845        OUTPUT @Hp4142;"AVI";Channel;",";Source;",";Goal
6850      ELSE
6855        OUTPUT @Hp4142;"AVI";Channel;",";Source;",";Goal;",";Compliance
6860      END IF
6865    CASE 2
6870      IF NPAR=4 THEN
6875        OUTPUT @Hp4142;"AIV";Channel;",";Source;",";Goal
6880      ELSE
6885        OUTPUT @Hp4142;"AIV";Channel;",";Source;",";Goal;",";Compliance
6890      END IF
6895    CASE ELSE
6900      DISP "Set_amonitor: Illegal measurement mode value"
6905      BEEP
6910      STOP
6915    END SELECT
6920    !
6925    OUTPUT @Hp4142;"*OPC?"
6930    ENTER @Hp4142;A$
6935    S=SPOLL(@Hp4142)
6940    IF BIT(S,5) THEN CALL Detect_error(S,"Set_amonitor")
6945  SUBEND
```

Measure_asearch

```
6960  SUB Measure_asearch(INTEGER Smode,Mmode,REAL Integtime,Sdata,OPTIONAL Mdata,INTEGER Status)
6965    COM @Hp4142
6970    INTEGER Sst,Mst
6975    !*********************************************************
6980    !*       Performs the analog feedback measurement        *
6985    !*********************************************************
6990    ALLOCATE Data$[32]
6995    OUTPUT @Hp4142;"FMT1;MM6;ASM";Smode;",";Mmode;",";Integtime
7000    OUTPUT @Hp4142;"XE"
7005    OUTPUT @Hp4142;"*OPC?"
7010    ENTER @Hp4142;A$
7015    S=SPOLL(@Hp4142)
7020    IF BIT(S,5) THEN CALL Detect_error(S,"Measure_asearch")
7025    ENTER @Hp4142;Data$
7030    !*********************************************************
7035    !*           Return search data or sense data            *
7040    !*********************************************************
7045    IF Mmode<3 THEN
7050      IF NPAR>4 THEN
7055        DISP "Measure_asearch: This meas mode returns only ";CHR$(129);"Source";CHR$(128);" value."
7060        BEEP
7065        STOP
7070      END IF
7075      Sdata=VAL(Data$[4;12])              ! Setup source data
7080    ELSE
7085      IF NPAR<5 THEN
7090        BEEP
7095        DISP "Measure_asearch: This meas mode must be specified ";CHR$(129);"Source";CHR$(128);" and "
;CHR$(129);"Goal";CHR$(128);" value."
7100        STOP
7105      END IF
7110      Sdata=VAL(Data$[4;12])              ! Setup source data
7115      Mdata=VAL(Data$[20;12])             ! Setup monitor data
7120    END IF
7125    !*********************************************************
7130    !*             Error and status data handling            *
7135    !*********************************************************
7140    IF NPAR<6 THEN
7145      IF Data$[1;1]<>"N" THEN GOSUB Error_disp
7150    ELSE
7155      Sst$=Data$[1;1]
7160      Mst$=Data$[17;1]
7165      IF Sst$="N" THEN Sst=0
7170      IF Sst$="T" THEN Sst=10
7175      IF Sst$="C" THEN Sst=20
7180      IF Sst$="X" THEN Sst=30
7185      IF Sst$="V" THEN Sst=40
7190      IF Sst$="G" THEN Sst=50
7195      IF Sst$="S" THEN Sst=60
7200      IF Sst$="F" THEN Sst=70
7205        !
7210      IF Mst$="N" THEN Mst=0
7215      IF Mst$="T" THEN Mst=1
7220      IF Mst$="C" THEN Mst=2
7225      IF Mst$="X" THEN Mst=3
7230      IF Mst$="V" THEN Mst=4
7235      IF Mst$="F" THEN Mst=7
7240      Status=Sst+Mst
7245    END IF
7250    !
7255    SUBEXIT
7260    !
```

```
7265 Error_disp:  !
7270    DISP "Measure_asearch: ";
7275    SELECT Data$[1;1]
7280    CASE "T"
7285      DISP CHR$(129);" Monitor channel has reached compliance ";CHR$(128)
7290    CASE "C"
7295      DISP CHR$(129);" Source channel has reached compliance ";CHR$(128)
7300    CASE "X"
7305      DISP CHR$(129);" Source channel is Oscillating ";CHR$(128)
7310    CASE "G"
7315      DISP CHR$(129);" No search goal found ";CHR$(128)
7320    CASE "S"
7325      DISP CHR$(129);" Unsettled feedback operation ";CHR$(128)
7330    CASE "V"
7335      DISP CHR$(129);" Source data overflow ";CHR$(128)
7340    CASE "F"
7345      DISP CHR$(129);" HVU does not settle before the measurement";CHR$(128)
7350    END SELECT
7355    BEEP
7360    RETURN
7365    !
7370  SUBEND
```

Para_vth

```
7385  SUB Para_vth(Vd,Id,Id_max,Rstart,Rstop,Ig_max,Cin,Cgd,Integ_time,Rspeed,Dtime,OPTIONAL INTEGER Err,
REAL Hold_time,Gm,Cd)
7390    !*********************************************************
7395    !*        Parameter Extraction of Vth measurement        *
7400    !*********************************************************
7405    !*                   Initialize routine                  *
7410    !*********************************************************
7415    Id_a=ABS(Id)
7420    Id_max_a=ABS(Id_max)
7425    GOSUB Err_check
7430    CALL V_range(Rstart,Rstop,Vrange,Error)
7435    IF Error THEN GOSUB Err_disp
7440    !
7445    !  SENSE I-RANGE SELECTION
7450    Ir_d=1+INT(LGT(Id_max_a/1.150005))
7455    IF Ir_d<-9.5 THEN Ir_d=-9
7460    Rr_d=1/10^Ir_d
7465    !
7470    !  SEARCH I-RANGE SELECTION
7475    Ir_g=1+INT(LGT(ABS(Ig_max)/1.150005))
7480    IF Ir_g<-9.5 THEN Ir_g=-9
7485    Rr_g=1/10^Ir_g
7490    IF NPAR<13.5 THEN
7495      Gm_=20*SQR(Id_a*Id_max_a)
7500    ELSE
7505      Gm_=Gm*SQR(Id_a*Id_max_a)/Id_a
7510    END IF
7515    IF NPAR<14.5 THEN
7520      Cd0=3.E-11
7525    ELSE
7530      Cd0=Cd
7535      IF Cd<0 THEN Error=22
7540      IF Cd>2.E-8 THEN Error=22
7545      IF Error THEN GOSUB Err_disp
7550    END IF
7555    !*********************************************************
7560    !*                  Calculate Integ_time                 *
7565    !*********************************************************
7570    CALL Tau_read(Ir_g,Ir_d,Tau30,Tau31,Tau50,Tau51,Tau_m,V_slew_m,Cod_m,Tau_s,V_slew_s,Cod_s)
7575    !   Tau3 : V-loop F-response : affected with load capacitance
7580    Tau3=Tau30
7585    IF Cin>1.E-10 THEN Tau3=Tau3+Tau31*(Cin-1.00E-10)/9.00E-10
7590    !   Tau4 : Current through cap. between Sense-SMU and Search-SMU
7595    Tau4=2*Rr_d*Cgd                              ! 2 IS 6dB GAIN MARGIN
7600    !   Tau5 : F-response of current to AFU error-amp output ; determined
7605    !  with I-range and influenced by load cap. of Sense-SMU
7610    Tau5=Tau50
7615    IF Cd0>1.00E-10 THEN Tau5=Tau5+Tau51*(Cd0-1.E-10)/9.E-10
7620    Tau=Tau2*Tau2+Tau3*Tau3+Tau5*Tau5
7625    Adut=Gm_*Rr_d
7630    Integ_time=1.5*SQR(Adut*Adut*Tau+Tau4*Tau4)        ! 1.5 IS MARGIN
7635    It_min=1.0E-4/Vrange                     ! min Integ_time
7640    IF Integ_time<It_min THEN Integ_time=It_min
7645    !*********************************************************
7650    !*                 Calculate Ramp_speed                  *
7655    !*********************************************************
7660    IF Vrange>25 THEN                            ! max Ramp_speed
7665      Sr1=1.E+5
7670    ELSE
7675      Sr1=2.5E+3*Vrange
7680    END IF
7685    Dt=Tau3+Tau5+2.0E-5
```

```
7690    Adut2=Gm_/Id_a
7695    Sr2=ABS(Id_max-Id)/(Cgd+Adut2*Dt/Rr_d)*.8    ! .8 IS MARGIN
7700    Dt_all=Dt+Cgd/Gm_
7705    IF Ir_d<-5 THEN                              ! For low current range
7710      Sr_fb0=.1/Integ_time
7715      Sr_n=Sr2*2
7720      IF Cgd=0 THEN Cgd=1.E-15
7725      LOOP
7730        Sr_fb=MIN(Sr_fb0,Sr_n*Gm_*Dt_all*Rr_d/Integ_time)
7735        I_0=Id_a+Sr_n*Gm_*(Tau5+2.0E-5-Tau_m)
7740        IF I_0<0 THEN I_0=0
7745        D_i=Id_a+Sr_n*(Gm_*Dt+Cgd)-I_0
7750        I_fb=Sr_fb*Cgd
7755        I_d_fb=Sr_n*Gm_*Dt+Cgd*(Sr_n+Sr_fb)
7760        T_0=(Dt*Sr_n*Gm_+Cgd*(Sr_n+Sr_fb))/Sr_fb/Gm_+Tau3
7765          !   Im_last=I_0+(D_i+I_fb)-I_d_fb
7770        IF Tau_m<>T_0 THEN
7775          A=(D_i+I_fb)/Tau_m-I_d_fb/(Tau_m-T_0)
7780          B=I_d_fb/(T_0-Tau_m)
7785          IF A/B>0 THEN
7790            T_max=LOG(A/B)/(1/Tau_m-1/T_0)
7795            IF T_max<0 THEN T_max=0
7800            M1=EXP(-T_max/Tau_m)
7805            M2=EXP(-T_max/T_0)
7810            I_max_2=I_0+(D_i+I_fb)*(1-M1)-I_d_fb*(1-T_0/(T_0-Tau_m)*M2-Tau_m/(Tau_m-T_0)*M1)
7815          ELSE
7820            I_max_2=MAX(I_0,Id_a)
7825          END IF
7830        ELSE
7835          I_max_2=MAX(I_0,Id_a)
7840        END IF
7845      EXIT IF I_max_2>Id_max_a
7850        Sr_n=Sr_n*2
7855        I_mm=I_max_2
7860      END LOOP
7865      Sr20=Sr_n/2*(1+(Id_max_a-I_mm)/(I_max_2-I_mm))*.8
7870      Sr21=MAX(Sr2,Sr20)
7875      Sr22=.8*ABS(Id_max-Id)/Cgd                 ! .8 IS MARGIN
7880      Sr2=MIN(Sr21,Sr22)
7885    END IF
7890    Sr3=.8*ABS(Ig_max)/(Cin+Cod_s+1/Rr_g/580000) ! .8 IS MARGIN
7895    Sr_rec=SQR(ABS(Rstart-Rstop)/8/Integ_time/Dt_all)
7900    Rspeed=MIN(Sr1,Sr2,Sr3,Sr_rec)
7905    !*********************************************************
7910    !*                  Calculate Delay_time                 *
7915    !*********************************************************
7920    Conv_time=1.2*(Rspeed*D1/8*Integ_time+5*Integ_time/Adut)
7925    Dt_defaults=MAX(1.00E-4,Integ_time)
7930    IF Conv_time>Dt_defaults+1.E-4 THEN
7935      Dtime=(INT((Conv_time-Dt_defaults-1.E-4)*1.E+3)+1)*1.E-3
7940    ELSE
7945      Dtime=0
7950    END IF
7955    !        Hold_t1 : Vd setting time
7960    CALL Cal_hold_time(Id_max,Ir_d,Vd,Cd0,Cod_m,Tau_m,V_slew_m,Hold_t1,Wait_d1)
7965    !        Hold_t2 : Vg ( start voltage ) setting time
7970    CALL Cal_hold_time(Ig_max,Ir_g,Rstart,Cin,Cod_s,Tau_s,V_slew_s,Hold_t2,Wait_d2)
7975    !        Ig_comp_time : Period of current through Cgd drive Search SMU
7980    Ig_comp_time=ABS(Vd)*Cgd/Ig_max
7985    IF Ig_comp_time>Wait_d1 THEN
7990      Hold_t3=Ig_comp_time-Wait_d1
7995    ELSE
8000      Hold_t3=0
8005    END IF
8010    IF Hold_t2>0 THEN
8015      T_hold=Hold_t2+Ig_comp_time-Wait_d1
```

```
8020    END IF
8025    IF NPAR>12.5 THEN
8030      Hold_time=1.E-3*(INT((MAX(Hold_t1,Hold_t3,T_hold)*1.E+3)+.95))
8035    END IF
8040    SUBEXIT
8045    !
8050 Err_check:   !
8055      !*************************************************************
8060      !*                Parameter  error check                     *
8065      !*************************************************************
8070    Error=0
8075    IF NPAR>11.5 THEN Err=0
8080    IF ABS(Vd)>200 THEN Error=10
8085    IF Error THEN GOSUB Err_disp
8090    IF Id_a<1.E-11 THEN Error=11
8095    IF Id_a>.9 THEN Error=11
8100    IF Error THEN GOSUB Err_disp
8105    IF SGN(Vd)<>SGN(Id) THEN Error=12
8110    IF Error THEN GOSUB Err_disp
8115    IF Id_max_a<1.05*Id_a THEN Error=13
8120    IF Id_max_a>1 THEN Error=13
8125    IF Error THEN GOSUB Err_disp
8130    IF SGN(Id_max)<>SGN(Id) THEN Error=14
8135    IF Error THEN GOSUB Err_disp
8140    IF ABS(Rstart)>200 THEN Error=15
8145    IF Error THEN GOSUB Err_disp
8150    IF ABS(Rstop)>200 THEN Error=16
8155    IF Error THEN GOSUB Err_disp
8160    IF (Rstop-Rstart)*Vd<0 THEN Error=17
8165    IF Error THEN GOSUB Err_disp
8170    IF ABS(Ig_max)>1 THEN Error=19
8175    IF ABS(Ig_max)<1.E-12 THEN Error=19
8180    IF Error THEN GOSUB Err_disp
8185    IF Cin<0 THEN Error=20
8190    IF Cin>2.E-8 THEN Error=20
8195    IF Error THEN GOSUB Err_disp
8200    IF Cgd<0 THEN Error=21
8205    IF Cgd>2.E-8 THEN Error=21
8210    IF Error THEN GOSUB Err_disp
8215    RETURN
8220    !
8225 Err_disp:     !
8230    IF NPAR<12 THEN
8235      IF Error=10 THEN DISP "Para_vth: |Vd| > 200 is not allowed."
8240      IF Error=11 THEN DISP "Para_vth: Unsuitable Id. (too small or too large)"
8245      IF Error=12 THEN DISP "Para_vth: Vd and Id must be same polarity."
8250      IF Error=13 THEN DISP "Para_vth: |Id_max| > 1  or |Id_max| < 1.05 * |Id| is not allowed."
8255      IF Error=14 THEN DISP "Para_vth: Id_max and Id must be same polarity."
8260      IF Error=15 THEN DISP "Para_vth: |Start| > 200 is not allowed."
8265      IF Error=16 THEN DISP "Para_vth: |Stop| > 200 is not allowed."
8270      IF Error=17 THEN DISP "Para_vth: (Stop - Start) and Vd must be same  polarity."
8275      IF Error=19 THEN DISP "Para_vth: Unsuitable Ig_max. (too small or too large)"
8280      IF Error=20 THEN DISP "Para_vth: Cin must be 0 to 20nF."
8285      IF Error=21 THEN DISP "Para_vth: Cgd must be 0 to 20nF."
8290       !    IF Error=22 THEN DISP "Para_vth: Cd must be 0 to 20nF."
8295      IF Error=30 THEN DISP "Para_vth: |Stop - Start | is too small."
8300      IF Error=31 THEN DISP "Para_vth: |Stop - Start | > 200 is not allowed."
8305       !
8310      BEEP
8315      STOP
8320    ELSE
8325      Err=Error
8330      SUBEXIT
8335    END IF
8340    RETURN
8345    !
```

```
8350  SUBEND
```

Para_hfe

```
8365  SUB Para_hfe(Vc,Ic,Ic_max,Rstart,Rstop,Hfe_min,Hfe_max,Ft,Cin,Cbc,Ib,Ib_max,Integ_time,Rspeed,Dtime,
OPTIONAL INTEGER Err,REAL Hold_time,Cc)
8370    !*********************************************************
8375    !*        Parameter Extraction of Hfe measurement        *
8380    !*********************************************************
8385    Ic_a=ABS(Ic)
8390    Ic_max_a=ABS(Ic_max)
8395    GOSUB Err_check
8400    CALL V_range(Rstart,Rstop,Vrange,Error)
8405    IF Error THEN GOSUB Err_disp
8410    IF HPAR<17.5 THEN
8415      Cc0=3.E-11
8420    ELSE
8425      Cc0=Cc
8430      IF Cc<0 THEN Error=24
8435      IF Cc>2.0E-8 THEN Error=24
8440      IF Error THEN GOSUB Err_disp
8445    END IF
8450   !
8455    Ir_c=1+INT(LGT(ABS(Ic_max)/1.150005))
8460    IF Ir_c<-9.5 THEN Ir_c=-9
8465    Rr_c=1/10^Ir_c
8470    !*********************************************************
8475    !*              Calculate Ib and Ib_max                  *
8480    !*********************************************************
8485    Ib=Ic/Hfe_min
8490    Ir_b=1+INT(LGT(ABS(Ib)/1.000005))
8495    IF Ir_b<-9.5 THEN Ir_b=-9
8500    Rr_b=1/10^Ir_b
8505    Ib_max=SGN(Ib)*1.15/Rr_b
8510    IF Ib_max>1 THEN Ib_max=1
8515    CALL Tau_read(Ir_b,Ir_c,Tau30,Tau31,Tau50,Tau51,Tau_m,V_slew_m,Cod_m,Tau_s,V_slew_s,Cod_s)
8520    !*********************************************************
8525    !*                 Calculate Integ_time                  *
8530    !*********************************************************
8535    Tau1=Hfe_max/(2*PI*Ft)
8540    Tau2=8.E-7*(1+Rr_b*ABS(Ib)/2.5E-2)
8545    IF ABS(Ib)<1.00E-7 THEN Tau2=3.E-6
8550    Tau3=Tau30
8555    C_be=1/.026*ABS(Ic)/2/PI/Ft
8560    IF Cin+C_be>1.E-10 THEN Tau3=Tau3+Tau31*(Cin+C_be-1.E-10)/9.E-10
8565    Tau4=2*Rr_c*Cbc                              ! 2 IS 6dB GAIN MARGIN
8570    Tau5=Tau50
8575    IF Cc0>1.E-10 THEN Tau5=Tau5+Tau51*(Cc0-1.E-10)/9.E-10
8580    Tau=(Tau1*Tau1+Tau2*Tau2+Tau3*Tau3+Tau5*Tau5)
8585    Adut=40*ABS(Ic*Rr_c)
8590    Gm_=Adut/Rr_c*SQR(Ic_a*Ic_max_a)/Ic_a
8595    Integ_time=1.5*SQR(Adut*Adut*Tau+Tau4*Tau4)            ! 1.5 IS MARGIN
8600    It_min=1.E-4/Vrange                      ! min Integ_time @2V range
8605    IF Integ_time<It_min THEN Integ_time=It_min
8610    !*********************************************************
8615    !*           Calculate Ramp_speed (=Slew rate)           *
8620    !*********************************************************
8625    IF Vrange>25 THEN
8630      Sr1=1.E+5
8635    ELSE
8640      Sr1=2.5E+3*Vrange
8645    END IF
8650    Dt=Tau3+Tau5+2.0E-5+Tau1+Tau2
8655    Adut2=Gm_*Rr_c
8660    Sr2=ABS(Ic_max-Ic)/(Cbc+Adut2*Dt/Rr_c)*.8     ! .8 IS MARGIN
8665    Sr_fb=.1/Integ_time
```

```
8670    Dt_all=Dt+Cbc/Gm_
8675    IF Ir_c<-4 THEN
8680      Sr_n=Sr2*2
8685      Sr_fb0=Sr_fb
8690      IF Cbc=0 THEN Cbc=1.E-15
8695      LOOP
8700        Sr_fb=MIN(Sr_fb0,Sr_n*(Gm_*Dt_all+Cbc)*Rr_c/Integ_time)
8705        I_0=Ic_a+Sr_n*Gm_*(Tau5+2.0E-5-Tau_m)
8710        IF I_0<0 THEN I_0=0
8715        D_i=Ic_a+Sr_n*(Gm_*Dt+Cbc)-I_0
8720        I_fb=Sr_fb*Cbc
8725        I_c_fb=Sr_n*Gm_*Dt+Cbc*(Sr_n+Sr_fb)
8730        T_0=(Dt*Sr_n*Gm_+Cbc*(Sr_n+Sr_fb))/Sr_fb/Gm_+Tau3+Tau1+Tau2
8735        IF Tau_m<>T_0 THEN
8740          A=(D_i+I_fb)/Tau_m-I_c_fb/(Tau_m-T_0)
8745          B=I_c_fb/(T_0-Tau_m)
8750          IF A/B>0 THEN
8755            T_max=LOG(A/B)/(1/Tau_m-1/T_0)
8760            IF T_max<0 THEN T_max=0
8765            M1=EXP(-T_max/Tau_m)
8770            M2=EXP(-T_max/T_0)
8775            I_max_2=I_0+(D_i+I_fb)*(1-M1)-I_c_fb*(1-T_0/(T_0-Tau_m)*M2-Tau_m/(Tau_m-T_0)*M1)
8780          ELSE
8785            I_max_2=MAX(I_0,Ic_a)
8790          END IF
8795        ELSE
8800          I_max_2=MAX(I_0,Ic_a)
8805        END IF
8810      EXIT IF I_max_2>ABS(Ic_max)
8815        Sr_n=Sr_n*2
8820        I_mm=I_max_2
8825      END LOOP
8830      Sr20=Sr_n/2*(1+(ABS(Ic_max)-I_mm)/(I_max_2-I_mm))*.8
8835      Sr21=MAX(Sr2,Sr20)
8840      Sr22=.8*ABS(Ic_max-Ic)/Cbc
8845      Sr2=MIN(Sr21,Sr22)
8850    END IF
8855    C_be=1/.026*ABS(Ic)/2/PI/Ft
8860    Sr3=.8*ABS(Ib_max-Ib)/(Cin+Cod_s+1/Rr_b/580000+C_be)          ! .8 IS MARGIN
8865    Sr_rec=SQR(ABS(Rstart-Rstop)/8/Integ_time/Dt_all)
8870    Rspeed=MIN(Sr1,Sr2,Sr3,Sr_rec)
8875    !*********************************************************
8880    !*                Calculate Delay_time  Hold_time        *
8885    !*********************************************************
8890    Conv_time=(Rspeed*Dt_all/8*Integ_time+5*Integ_time/Adut)*1.2
8895    Max_di=Rspeed*(Dt_all*40*ABS(Ib)+Cod_s+Cin+Cbc+1/Rr_b/580000+C_be)
8900    Ib_min=Ic/Hfe_max
8905    M_tau=MAX(ABS(LOG(ABS(Ib_min/10/Max_di))),3)
8910    Dtt=Conv_time+M_tau*Tau_s
8915    Dt_defaults=MAX(Integ_time,1.00E-4)
8920    IF Dtt>Dt_defaults+1.E-4 THEN
8925      Dtime=(INT((Dtt-Dt_defaults-1.E-4)*1.E+3)+1)*1.E-3
8930    ELSE
8935      Dtime=0
8940    END IF
8945    CALL Cal_hold_time(Ic_max,Ir_c,Vc,Cc0,Cod_m,Tau_m,V_slew_m,H_time,Wait_def)
8950    IF H_time>0 THEN
8955      H_time=1.E-3*INT(H_time*1.E+3)+1.E-3
8960    END IF
8965    Wait_base=ABS(Vc*Cbc/Ib_max)
8970    IF Wait_base>H_time+Wait_def THEN
8975      H_time=(INT((Wait_base-Wait_def)*1.E+3+1))*1.E-3
8980    END IF
8985    IF NPAR>16.5 THEN Hold_time=H_time
8990    SUBEXIT
8995    !
```

```
9000 Err_check:   !
9005      !*********************************************************
9010      !*                Parameter error check                  *
9015      !*********************************************************
9020    Error=0
9025    IF NPAR>15.5 THEN Err=0
9030    IF ABS(Vc)>200 THEN Error=10
9035    IF Error THEN GOSUB Err_disp
9040    IF ABS(Ic)<1.E-11 THEN Error=11
9045    IF ABS(Ic)>.9 THEN Error=11
9050    IF Error THEN GOSUB Err_disp
9055    IF SGN(Vc)<>SGN(Ic) THEN Error=12
9060    IF Error THEN GOSUB Err_disp
9065    IF ABS(Ic_max)<1.05*ABS(Ic) THEN Error=13
9070    IF ABS(Ic_max)>1 THEN Error=13
9075    IF Error THEN GOSUB Err_disp
9080    IF SGN(Ic_max)<>SGN(Ic) THEN Error=14
9085    IF Error THEN GOSUB Err_disp
9090    IF ABS(Rstart)>200 THEN Error=15
9095    IF Error THEN GOSUB Err_disp
9100    IF ABS(Rstop)>200 THEN Error=16
9105    IF Error THEN GOSUB Err_disp
9110    IF (Rstop-Rstart)*Vc<0 THEN Error=17
9115    IF Error THEN GOSUB Err_disp
9120    IF Hfe_min<1 THEN Error=19
9125    IF Hfe_max<1 THEN Error=19
9130    IF Error THEN GOSUB Err_disp
9135    IF Hfe_max<=Hfe_min THEN Error=20
9140    IF Error THEN GOSUB Err_disp
9145    IF Ft<=0 THEN Error=21
9150    IF Error THEN GOSUB Err_disp
9155    IF Cin<0 THEN Error=22
9160    IF Cin>2.0E-8 THEN Error=22
9165    IF Error THEN GOSUB Err_disp
9170    IF Cbc<0 THEN Error=23
9175    IF Cbc>2.0E-8 THEN Error=23
9180    IF Error THEN GOSUB Err_disp
9185    RETURN
9190    !
9195 Err_disp:!
9200    IF NPAR<16 THEN
9205      IF Error=10 THEN DISP "Para_hfe: |Vc| > 200 is not allowed."
9210      IF Error=11 THEN DISP "Para_hfe: Unsuitable Ic. (too small or too large)"
9215      IF Error=12 THEN DISP "Para_hfe: Vc and Ic must be same polarity."
9220      IF Error=13 THEN DISP "Para_hfe: |Ic_max| > 1  or |Ic_max| < 1.05 * |Ic| is not allowed."
9225      IF Error=14 THEN DISP "Para_hfe: Ic_max and Ic must be same polarity."
9230      IF Error=15 THEN DISP "Para_hfe: |Start| > 200 is not allowed."
9235      IF Error=16 THEN DISP "Para_hfe: |Stop| > 200 is not allowed."
9240      IF Error=17 THEN DISP "Para_hfe: (Stop - Start) and Vc must be same  polarity."
9245      IF Error=19 THEN DISP "Para_hfe: Hfe_min < 1 or Hfe_max < 1 is not allowed."
9250      IF Error=20 THEN DISP "Para_hfe: Hfe_max <= Hfe_min is not allowed."
9255      IF Error=21 THEN DISP "Para_hfe: Ft <= 0 is not allowed."
9260      IF Error=22 THEN DISP "Para_hfe: Cin must be 0 to 20nF."
9265      IF Error=23 THEN DISP "Para_hfe: Cbc must be 0 to 20nF."
9270      IF Error=30 THEN DISP "Para_hfe: |Stop - Start | is too small."
9275      IF Error=31 THEN DISP "Para_hfe: |Stop - Start | > 200 is not allowed."
9280        !
9285      BEEP
9290      STOP
9295    ELSE
9300      Err=Error
9305      SUBEXIT
9310    END IF
9315    RETURN
9320    !
```

```
9325  SUBEND
```

Set_v_range

```
9340  SUB Set_v_range(INTEGER Channel,REAL Range)
9345    !*******************************************************
9350    !*            Setup voltage range paramater            *
9355    !*******************************************************
9360    Module_type((Channel),Type$)   ! check installed module type
9365    !
9370    SELECT Type$
9375    CASE "HP41420"
9380      IF Range<2 THEN Range=-999
9385      IF Range>200 THEN Range=999
9390    CASE "HP41421"
9395      IF Range<2 THEN Range=-999
9400      IF Range>100 THEN Range=999
9405    CASE "HP41424"
9410      IF Range<.2 THEN Range=-999
9415      IF Range>40 THEN Range=999
9420    CASE "HP41422"
9425      IF Range<2 THEN Range=-999
9430      IF Range>20 THEN Range=999
9435    CASE "HP41423"
9440      IF Range<100 THEN Range=-999
9445      IF Range>1000 THEN Range=999
9450    END SELECT
9455    !
9460    IF Range<>999 AND Range<>-999 THEN
9465      SELECT ABS(Range)
9470      CASE .2,2,20,40,100,200,500,1000
9475        IF ABS(Range)=.2 THEN Rng=10
9480        IF ABS(Range)=2 THEN Rng=11
9485        IF ABS(Range)=20 THEN Rng=12
9490        IF ABS(Range)=40 THEN Rng=13
9495        IF ABS(Range)=100 THEN Rng=14
9500        IF ABS(Range)=200 THEN Rng=15
9505        IF ABS(Range)=500 THEN Rng=16
9510        IF ABS(Range)=1000 THEN Rng=17
9515      CASE ELSE
9520        Rng=0
9525      END SELECT
9530      Range=Rng
9535    END IF
9540  SUBEND
```

Set_i_range

```
9555  SUB Set_i_range(REAL Range)
9560    !*******************************************************
9565    !*          Setup the current range parameater          *
9570    !*******************************************************
9575    IF Range>0 THEN
9580      SELECT Range
9585      CASE 1.E-9 TO 10
9590        Rselect=((20+LGT(Range))-INT((20+LGT(Range))))
9595        IF Rselect=0 THEN Range=20+LGT(Range)
9600        IF Rselect<>0 THEN Range=0
9605      CASE ELSE
9610        IF Range>10 THEN Range=999
9615        IF Range<1.E-9 THEN Range=-999
9620      END SELECT
9625    END IF
9630    !
9635    IF Range<0 THEN
9640      SELECT Range
9645      CASE -10 TO -1.E-9
9650        Rselect=((-20-LGT(ABS(Range)))-INT((-20-LGT(ABS(Range)))))
9655        IF Rselect=0 THEN Range=-20-LGT(ABS(Range))
9660        IF Rselect<>0 THEN Range=0
9665      CASE ELSE
9670        IF Range>-1.E-9 THEN Range=999
9675        IF Range<-10 THEN Range=-999
9680      END SELECT
9685    END IF
9690  SUBEND
```

Module_type

```
9705  SUB Module_type(INTEGER Chan,Type$)
9710    COM @Hp4142
9715    !************************************************************
9720    !*               Check installed module type                *
9725    !************************************************************
9730    IF Chan>=11 AND Chan<=18 THEN Chan=Chan-10
9735    IF Chan>=21 AND Chan<=28 THEN Chan=Chan-20
9740    ALLOCATE A$[100],Unt$(8)[8]
9745    !
9750    OUTPUT @Hp4142;"UNT?"
9755    ENTER @Hp4142;A$
9760    K=1
9765    FOR I=1 TO 8
9770      IF A$[K;1]="0" THEN
9775        Unt$(I)=A$[K;1]
9780        K=K+4
9785      ELSE
9790        Unt$(I)=A$[K;7]
9795        K=K+11
9800      END IF
9805    NEXT I
9810    !************************************************************
9815    !*                    Return module type                    *
9820    !************************************************************
9825    Type$=Unt$(Chan)
9830    !
9835  SUBEND
```

Detect_error

```
9850  SUB Detect_error(Spoll_value,Module_name$)
9855    COM @Hp4142
9860    !************************************************************
9865    !*               Emergency error process                    *
9870    !************************************************************
9875    IF BIT(Spoll_value,7) OR BIT(Spoll_value,3) THEN
9880      IF BIT(Spoll_value,7) THEN
9885        DISP CHR$(129);" 4142B SHUT DOWN  !! ";CHR$(128)
9890      ELSE
9895        DISP CHR$(129);" 4142B NOT INTERLOCKED !! ";CHR$(128)
9900      END IF
9905      BEEP
9910      STOP
9915    END IF
9920    !************************************************************
9925    !*                  Normal error process                    *
9930    !************************************************************
9935    OUTPUT @Hp4142;"ERR?"
9940    ENTER @Hp4142;E(1)
9945    DISP "4142B ERROR";E(1);" In ";Module_name$
9950    BEEP
9955    STOP
9960  SUBEND
```

Tau_read

```
9975  SUB Tau_read(S_range,M_range,Tau30,Tau31,Tau50,Tau51,Tau_m,V_slew_m,Cod_m,Tau_s,V_slew_s,Cod_s)
9980    SELECT S_range
9985    CASE 0,-1,-2,-3
9990      Tau30=1.2E-6+1/10^S_range*1.E-9
9995      Tau31=2.E-7
10000     Cod_s=3.500E-9
10005     Tau_s=3.E-6
10010     V_slew_s=2.E-5
10015   CASE -4,-5
10020     Tau30=6.1E-6-1.4E-5*(S_range+4)
10025     Tau31=1.E-6-2.E-6*(S_range+4)
10030     Cod_s=3.500E-9
10035     Tau_s=1.E-5
10040     V_slew_s=1.65E-3
10045     IF S_range=-4 THEN V_slew_s=1.5E-4
10050   CASE -6
10055     Tau30=1.2E-5
10060     Tau31=2.0E-5
10065     Cod_s=2.20E-10
10070     Tau_s=5.E-5
10075     V_slew_s=1.11E-3
10080   CASE -7
10085     Tau30=1.3E-5
10090     Tau31=3.2E-5
10095     Cod_s=7.0E-11
10100     Tau_s=2.E-4
10105     V_slew_s=3.68E-3
10110   CASE -8
10115     Tau30=1.8E-5
10120     Tau31=8.2E-5
10125     Cod_s=4.E-12
10130     Tau_s=9.E-4
10135     V_slew_s=.004
10140   CASE -9
10145     Tau30=4.8E-5
10150     Tau31=3.70E-4
10155     Cod_s=2.E-12
10160     Tau_s=3.E-3
10165     V_slew_s=.024
10170   END SELECT
10175   !
10180   SELECT M_range
10185   CASE 0,-1,-2,-3,-4
10190     Tau50=3.E-6
10195     Tau51=1.E-7
10200     Tau_m=3.E-6
10205     V_slew_m=2.0E-5
10210     IF M_range=-4 THEN V_slew_m=1.5E-4
10215     Cod_m=3.500E-9
10220   CASE -5
10225     Tau50=2.0E-5
10230     Tau51=1.E-6
10235     Tau_m=1.E-5
10240     V_slew_m=1.650E-3
10245     Cod_m=3.500E-9
10250   CASE -6
10255     Tau50=1.0E-5
10260     Tau51=8.E-6
10265     Tau_m=5.E-5
10270     V_slew_m=1.11E-3
10275     Cod_m=2.20E-10
10280   CASE -7
```

```
10285      Tau50=1.5E-5
10290      Tau51=2.0E-5
10295      Tau_m=2.E-4
10300      V_slew_m=3.68E-3
10305      Cod_m=7.0E-11
10310    CASE -8
10315      Tau50=2.2E-5
10320      Tau51=8.0E-5
10325      Tau_m=9.0E-4
10330      V_slew_m=4.E-3
10335      Cod_m=4.E-12
10340    CASE -9
10345      Tau50=8.0E-5
10350      Tau51=2.70E-4
10355      Tau_m=2.0E-3
10360      V_slew_m=2.4E-2
10365      Cod_m=2.E-12
10370    END SELECT
10375 SUBEND
```

Cal_hold_time

```
10390 SUB Cal_hold_time(I_s_max,I_range,V_set,Cap_s,Cod,Tau_m,V_slew,Hold_time,Wait_def)
10395   V_set_a=ABS(V_set)
10400   V_range=2
10405   IF V_set_a>2 THEN V_range=20
10410   IF V_set_a>20 THEN V_range=40
10415   IF V_set_a>40 THEN V_range=100
10420   IF V_set_a>100 THEN V_range=200
10425   Wait_def=3*Tau_m+(INT(V_set_a/V_range/2*13)+1)/16*V_slew*V_range/2
10430   Cap_dummy=10^I_range/580000
10435   Hold_time=(Cap_s+Cod+Cap_dummy)*V_set_a/I_s_max+4*Tau_m-Wait_def
10440   IF Hold_time<0 THEN Hold_time=0
10445 SUBEND
10450!
10455!
```

V_range

```
10460 SUB V_range(Rstart,Rstop,Vrange,Error_n)
10465   V_diff=ABS(Rstop-Rstart)
10470   Max_v=MAX(V_diff,ABS(Rstart),ABS(Rstop))
10475   Vrange=0
10480   SELECT Max_v
10485   CASE <=2
10490     IF V_diff>=.1 THEN Vrange=2
10495   CASE <2,<=20
10500     IF V_diff>=1 THEN Vrange=20
10505   CASE <20,<=40
10510     IF V_diff>=2 THEN Vrange=40
10515   CASE <40,<=100
10520     IF V_diff>=5 THEN Vrange=100
10525   CASE ELSE
10530     IF V_diff>=10 THEN Vrange=200
10535   END SELECT
10540   Error_n=0
10545   IF Vrange<1 THEN Error_n=30
10550   IF V_diff>200 THEN Error_n=31
10555 SUBEND
```

Set_bdm

```
10585 SUB Set_bdm(INTEGER Channel,REAL Vrange,Vstart,Vstop,Thold,Tsettle,OPTIONAL I_compliance)
10590   !
10595   COM @Hp4142
10600   !************************************************
10605   !*              Setup parameters                *
10610   !************************************************
10615   Rng=Vrange
10620   IF Rng<>0 THEN CALL Set_v_range((Channel),Rng)
10625   !
10630   SELECT NPAR
10635   CASE 6
10640     OUTPUT @Hp4142;"BDV";Channel,Rng,Vstart,Vstop
10645   CASE 7
10650     OUTPUT @Hp4142;"BDV";Channel,Rng,Vstart,Vstop,I_compliance
10655   END SELECT
10660   !
10665   OUTPUT @Hp4142;"BDT";Thold,Tsettle
10670   !
10675   OUTPUT @Hp4142;"*OPC?"
10680   ENTER @Hp4142;A$
10685   S=SPOLL(@Hp4142)
10690   IF BIT(S,5) THEN CALL Detect_error(S,"Set_bdm")
10695   !
10700 SUBEND
```

Measure_bdm

```
10720 SUB Measure_bdm(INTEGER Channel,Judge_mode,Measure_mode,REAL Measure_value,OPTIONAL INTEGER Status)
10725   !
10730   COM @Hp4142
10735   !*****************************************************
10740   !*           Setup measurement parameters            *
10745   !*****************************************************
10750   OUTPUT @Hp4142;"BDM";Judge_mode,Measure_mode
10755   OUTPUT @Hp4142;"MM";9,Channel
10760   OUTPUT @Hp4142;"XE"
10765   !
10770   OUTPUT @Hp4142;"*OPC?"
10775   ENTER @Hp4142;A$
10780   S=SPOLL(@Hp4142)
10785   IF BIT(S,5) THEN CALL Detect_error(S,"Measure_bdm")
10790   !*****************************************************
10795   !*          Get measure data and status data         *
10800   !*****************************************************
10805   IF NPAR<5 THEN
10810     ENTER @Hp4142;Measure_value
10815   ELSE
10820     ENTER @Hp4142;Data$
10825     Measure_value=VAL(Data$[4;12])
10830     Status$=Data$[1;1]
10835     IF Status$="N" THEN Status=0
10840     IF Status$="T" THEN Status=1
10845     IF Status$="C" THEN Status=2
10850     IF Status$="X" THEN Status=3
10855     IF Status$="V" THEN Status=4
10860     IF Status$="F" THEN Status=7
10865     IF Status$="G" THEN Status=8
10870     IF Status$="S" THEN Status=9
10875   END IF
10880   !
10885 SUBEND
```

Set_pol

```
10905 SUB Set_pol(INTEGER Channel,Mode)
10910   !
10915   COM @Hp4142
10920   !*************************************************
10925   !*            Setup polaraty parameter           *
10930   !*************************************************
10935   OUTPUT @Hp4142;"POL";Channel,Mode
10940   !
10945   OUTPUT @Hp4142;"*OPC?"
10950   ENTER @Hp4142;A$
10955   S=SPOLL(@Hp4142)
10960   IF BIT(S,5) THEN CALL Detect_error(S,"Set_pol")
10965   !
10970 SUBEND
```

Connect_relay1

```
10990 SUB Connect_relay1(OPTIONAL INTEGER Channel)
10995   !
11000   COM @Hp4142
11005   !*******************************************************
11010   !*        OUTPUT RELAY CHANNEL                         *
11015   !*******************************************************
11020   SELECT NPAR
11025   CASE 0
11030     OUTPUT @Hp4142;"ERC";1,0,0
11035   CASE 1
11040     OUTPUT @Hp4142;"ERC";1,Channel,0
11045   END SELECT
11050   !
11055   OUTPUT @Hp4142;"*OPC?"
11060   ENTER @Hp4142;A$
11065   S=SPOLL(@Hp4142)
11070   IF BIT(S,5) THEN CALL Detect_error(S,"Connect_relay1")
11075   !
11080 SUBEND
```

Connect_relay2

```
11100 SUB Connect_relay2(INTEGER Mode,OPTIONAL INTEGER Port1,Port2,Port3,Port4,Port5,Port6,Port7,Port8,
Port9,Port10,Port11,Port12,Port13,Port14,Port15,Port16)
11105   !
11110   COM @Hp4142
11115   INTEGER Bit_val
11120   Bit_val=0
11125   Value=0
11130   !************************************************
11135   !*          ERROR CHECK AND SET BIT              *
11140   !************************************************
11145   IF NPAR>1 THEN
11150     IF Port1<1 OR 16<Port1 THEN GOSUB Connect_erc_err
11155     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port1-1)))
11160   END IF
11165   !
11170   IF NPAR>2 THEN
11175     IF Port2<1 OR 16<Port2 THEN GOSUB Connect_erc_err
11180     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port2-1)))
11185   END IF
11190   !
11195   IF NPAR>3 THEN
11200     IF Port3<1 OR 16<Port3 THEN GOSUB Connect_erc_err
11205     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port3-1)))
11210   END IF
11215   !
11220   IF NPAR>4 THEN
11225     IF Port4<1 OR 16<Port4 THEN GOSUB Connect_erc_err
11230     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port4-1)))
11235   END IF
11240   !
11245   IF NPAR>5 THEN
11250     IF Port5<1 OR 16<Port5 THEN GOSUB Connect_erc_err
11255     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port5-1)))
11260   END IF
11265   !
11270   IF NPAR>6 THEN
11275     IF Port6<1 OR 16<Port6 THEN GOSUB Connect_erc_err
11280     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port6-1)))
11285   END IF
11290   !
11295   IF NPAR>7 THEN
11300     IF Port7<1 OR 16<Port7 THEN GOSUB Connect_erc_err
11305     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port7-1)))
11310   END IF
11315   !
11320   IF NPAR>8 THEN
11325     IF Port8<1 OR 16<Port8 THEN GOSUB Connect_erc_err
11330     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port8-1)))
11335   END IF
11340   !
11345   IF NPAR>9 THEN
11350     IF Port9<1 OR 16<Port9 THEN GOSUB Connect_erc_err
11355     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port9-1)))
11360   END IF
11365   !
11370   IF NPAR>10 THEN
11375     IF Port10<1 OR 16<Port10 THEN GOSUB Connect_erc_err
11380     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port10-1)))
11385   END IF
11390   !
11395   IF NPAR>11 THEN
11400     IF Port11<1 OR 16<Port11 THEN GOSUB Connect_erc_err
```

```
11405     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port11-1)))
11410   END IF
11415   !
11420   IF NPAR>12 THEN
11425     IF Port12<1 OR 16<Port12 THEN GOSUB Connect_erc_err
11430     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port12-1)))
11435   END IF
11440   !
11445   IF NPAR>13 THEN
11450     IF Port13<1 OR 16<Port13 THEN GOSUB Connect_erc_err
11455     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port13-1)))
11460   END IF
11465   !
11470   IF NPAR>14 THEN
11475     IF Port14<1 OR 16<Port14 THEN GOSUB Connect_erc_err
11480     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port14-1)))
11485   END IF
11490   !
11495   IF NPAR>15 THEN
11500     IF Port15<1 OR 16<Port15 THEN GOSUB Connect_erc_err
11505     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port15-1)))
11510   END IF
11515   !
11520   IF NPAR>16 THEN
11525     IF Port16<1 OR 16<Port16 THEN GOSUB Connect_erc_err
11530     Bit_val=BINIOR(Bit_val,SHIFT(1,-(Port16-1)))
11535   END IF
11540   !************************************************
11545   !*          OUTPUT RELAY BIT                    *
11550   !************************************************
11555   IF Bit_val<0 THEN
11560     Value=65535-BINCMP(Bit_val)
11565   ELSE
11570     Value=Bit_val
11575   END IF
11580   !
11585   OUTPUT @Hp4142;"ERC";2,Value,Mode
11590   !
11595   OUTPUT @Hp4142;"*OPC?"
11600   ENTER @Hp4142;A$
11605   S=SPOLL(@Hp4142)
11610   IF BIT(S,5) THEN CALL Detect_error(S,"Connect_relay2")
11615   !
11620   SUBEXIT
11625   !************************************************
11630   !*           SELECT BIT ERROR                   *
11635   !************************************************
11640 Connect_erc_err:!
11645   DISP "CONNECT_RELAY2: PORT SELECT IS 1 TO 16  "
11650   BEEP
11655   STOP
11660   RETURN
11665   !
11670   !
11675 SUBEND
```

GRAPHICS File

Dump_screen

```
30    SUB Dump_screen(OPTIONAL INTEGER Expand_output)
35      !*************************************************************
40      !*           Dumps the graphic screen to a printer           *
45      !*************************************************************
50      INTEGER Dump_device
55      INTEGER Key_labels
60      Dump_device=701                       ! HP-IB address of printer
65      !*************************************************************
70      !*                     Setup the printer                     *
75      !*************************************************************
80      ASSIGN @Printer TO Dump_device        ! Assign I/O path to printer
85      ON TIMEOUT SC(@Printer),20 GOTO No_printer
90      IF NPAR=1 THEN
95        SELECT Expand_output
100       CASE 1
105         DUMP DEVICE IS Dump_device,EXPANDED
110       CASE 0
115         DUMP DEVICE IS Dump_device
120       CASE ELSE
125         Disp_error("Dump_screen: Illegal parameter has been passed")
130         STOP
135       END SELECT
140     END IF
145     !
150     IF NPAR=0 THEN
155       DUMP DEVICE IS Dump_device
160     END IF
165     !*************************************************************
170     !*                     Dump the screen                       *
175     !*************************************************************
180     DUMP GRAPHICS                         ! Dump the graphics page
185     OFF TIMEOUT                           ! Disable timeout
190     SUBEXIT
195     !
200 No_printer: !
205     Disp_error("Dump_screen:  Printer is not responding")
210     ASSIGN @Printer TO *                  ! Deassign I/O path
215     OFF TIMEOUT                           ! Disable timeout
220   SUBEND
```

Init_computer

```
SUB Init_computer(OPTIONAL INTEGER Separate_pages)
  !*************************************************************
  !*          Initializes the computer and its display         *
  !*************************************************************
  INTEGER Alpha_planes
  INTEGER Graphics_planes(1:1)
  !*************************************************************
  !*                    Clear the display                      *
  !*************************************************************
  OUTPUT KBD;CHR$(255);"K";             ! Clear the screen
  GINIT                                 ! Initialize graphics page
  GCLEAR                                ! Clear the graphics page
  ALPHA ON                              ! Enable alpha page
  GRAPHICS ON                           ! Enable graphics page
  CONTROL CRT,12;1                      ! Turn off softkey labels
  !*************************************************************
  !*            Set keyboard auto-repeat parameters            *
  !*************************************************************
  CONTROL KBD,3;2.5                     ! Auto-repeat interval = 25 ms
  CONTROL KBD,4;20                      ! Auto-repeat delay = 200 ms
  !*************************************************************
  !*         Check the display color or monochrome             *
  !*************************************************************
  Crt_type$=TRIM$(SYSTEM$("CRT ID"))    ! Get the CRT ID
  !*************************************************************
  !*    Intialize the monochrome display both bit-mapped and   *
  !*    non-bit-mapped display                                 *
  !*                                                           *
  !*     @ non-bit-mapped CRT ... HP9000 200 series 9836/9816  *
  !*     @ bit-mapped CRT     ... HP9000 300 series 310/320    *
  !*************************************************************
  IF (Crt_type$[7,9]=" GB") OR (Crt_type$[7,9]=" G") THEN
    IF NPAR THEN
      Disp_error("Init_computer:  Argument is not specified for the monochrome display")
      STOP
    ELSE
      SUBEXIT
    END IF
  END IF
  !*************************************************************
  !*         Intialize the non-bit-mapped color display        *
  !*               - for HP9000 200 series 9836C -             *
  !*************************************************************
  IF Crt_type$[7,9]="CG" THEN
    IF NPAR THEN
      Disp_error("Init_computer: Argument is not specified for the non-bit-mapped color display")
      STOP
    ELSE
      PLOTTER IS CRT,"INTERNAL";COLOR MAP   ! Define the colors and pens
      CONTROL 1,5;138                       ! Set yellow alpha characters
      SET PEN 0 INTENSITY 0,2/15,7/15       ! Blue background
    END IF
  END IF
  !*************************************************************
  !*           Intialize the bit-mapped color display          *
  !*             - for HP9000 300 series color CRT -           *
  !*************************************************************
  IF Crt_type$[7,9]="CGB" THEN
    PLOTTER IS CRT,"INTERNAL";COLOR MAP
    IF NPAR THEN
      IF Separate_pages=1 THEN
        SET PEN 8 INTENSITY 1,1,0           ! Yellow
```

```
545           CONTROL CRT,5;0                    ! Turn off the cursor (temp.)
550           CONTROL CRT,18;IVAL("1000",2)      ! Select plane 4 for alpha
555           CONTROL CRT,5;8                    ! Yellow alpha
560           Graphics_planes(1)=IVAL("0111",2)  ! Select planes 1 - 3 for
565           GESCAPE CRT,7,Graphics_planes(*)   !  graphics.
570         END IF
575         !*************************************************************
580         !*             Alpha and graphics will overlap               *
585         !*************************************************************
590         IF Separate_pages=0 THEN
595           STATUS 1,18;Alpha_planes          ! Read alpha write-enable mask
600           IF Alpha_planes<>IVAL("1111",2) THEN
605             CONTROL CRT,18;IVAL("1111",2)
610             Graphics_planes(1)=IVAL("1111",2)
615             GESCAPE CRT,7,Graphics_planes(*)
620             CONTROL CRT,5;3                 ! Yellow alpha
625           END IF
630         END IF
635         !
640         IF (Separate_pages<0) OR (Separate_pages>1) THEN
645           Disp_error("Init_computer:  Illegal argument has been passed")
650           STOP
655         END IF
660       END IF
665       SET PEN 0 INTENSITY 0,2/15,5/15       ! Blue background
670     END IF
675   SUBEND
```

```
690   SUB Wbuild_file(Filename$,Meas_data(*),File_comment$,Variable_names$(*))
695   !************************************************************************
700   !*  Stores data in a file that conforms to the Basic Statistics and     *
705   !*  Data Manipulation (BSDM) format.  The HP4062B uses a similar method.*
710   !*  The data can be evaluated by the HP98820A Statistical Library.      *
715   !************************************************************************
720     ALLOCATE Subfile_names$(1:20)[10]
725     ALLOCATE Var_names$(1:50)[10]
730     INTEGER I
735     INTEGER Meas_data_base                ! Measurement data base
740     INTEGER Var_names_base                ! Variable name base
745     REAL Number_obs                       ! Number of observations
750     REAL Number_subfiles                  ! Number of subfiles
755     REAL Number_var                       ! Number of variables
760     REAL Subfile_char(1:20)
765   !
770     Meas_data_base=BASE(Meas_data,1)
775     Var_names_base=BASE(Variable_names$,1)
780   !*************************************************************
785   !*             Check the length of the title                 *
790   !*************************************************************
795     IF LEN(File_comment$)>80 THEN
800       Disp_error(" Wbuild_file: File comment is longer than 80 characters")
805       STOP
810     END IF
815   !*************************************************************
820   !*             Check the size of the data array              *
825   !*************************************************************
830     Number_var=SIZE(Meas_data,1)
835     IF Number_var>50 THEN
840       Disp_error("Wbuild_file: Too Many Variables (over 50)")
845       STOP
850     END IF
855   !
860     Number_obs=SIZE(Meas_data,2)
865     IF Number_var*Number_obs>1500 THEN
870       Disp_error("Wbuild_file: More than 1500 data points were provided")
875       STOP
880     END IF
885   !*************************************************************
890   !*           Check the number of variable names              *
895   !*************************************************************
900     SELECT SIZE(Variable_names$,1)
905     CASE <Number_var
910       Disp_error("Wbuild_file: Not Enough Variable Names")
915       STOP
920     CASE >Number_var
925       Disp_error("Wbuild_file: Too many variable names")
930       STOP
935     END SELECT
940   !*************************************************************
945   !*         Check the length of the variable names            *
950   !*************************************************************
955     IF LEN(Variable_names$(Var_names_base))>10 THEN
960       Disp_error("Wbuild_file: The variable names are longer than 10 characters")
965       STOP
970     END IF
975   !*************************************************************
980   !*                Process the variable names                 *
985   !*************************************************************
990     FOR I=1 TO Number_var
995       Var_names$(I)=Variable_names$(Var_names_base-1+I)[1;MIN(10,LEN(Variable_names$(Var_names_base)))]
```

```
1000    NEXT I
1005  !
1010    FOR I=Number_var+1 TO 50
1015      Var_names$(I)=""
1020    NEXT I
1025  !*************************************************************************
1030  !*  Initialize the subfile variables. Although the statistical library  *
1035  !*  allows subfiles, they are not used in this subprogram.              *
1040  !*************************************************************************
1045    Number_subfiles=0
1050    MAT Subfile_names$= ("")
1055    MAT Subfile_char= (0)
1060  !*************************************************************
1065  !*       Create the data file and assign an I/O path          *
1070  !*************************************************************
1075    ON ERROR GOTO Duplicate_file        ! Prevent duplicate filenames
1080    CREATE BDAT Filename$,2+(8*Number_var*Number_obs DIV 1280),1280
1085    OFF ERROR
1090    ASSIGN @File TO Filename$           ! Assign I/O path
1095  !*************************************************************
1100  !*                Store the data in the file                 *
1105  !*************************************************************
1110    OUTPUT @File,1;File_comment$[1;MIN(80,LEN(File_comment$))],Number_obs,Number_var,Var_names$(*),
Number_subfiles,Subfile_names$(*),Subfile_char(*)
1115    OUTPUT @File,2                      ! Point to record 2
1120    OUTPUT @File;Meas_data(*)           ! Store data
1125    ASSIGN @File TO *                   ! Close the file
1130    SUBEXIT
1135  !
1140 Duplicate_file:!
1145    OFF ERROR
1150    ALLOCATE E$[80]
1155    E$=ERRM$
1160    Disp_error("Wbuild_file:  "&E$[19;37]&" ")
1165    STOP
1170  SUBEND
```

Lingraph

```
1185  SUB Lingraph(X_min,X_max,Y_min,Y_max,X_axes_name$,Y_axes_name$,Graph_name$,OPTIONAL INTEGER Grid,
Quadrant_mode,Right_subtitle$,Left_subtitle$)
1190    !*************************************************************
1195    !*         Set the parameters of linear scale graph          *
1200    !*************************************************************
1205    ALLOCATE Titles$(1:5)[40]
1210    INTEGER Grid_pattern
1215    INTEGER Quadrant
1220    !*************************************************************
1225    !*                       Error check                         *
1230    !*************************************************************
1235    IF (Y_min=Y_max) OR (X_min=X_max) THEN
1240      Disp_error("Lingraph: Minimum and maximun values are duplicate   ( check the X or Y value )")
1245      STOP
1250    END IF
1255    IF LEN(X_axes_name$)>30 OR LEN(Y_axes_name$)>30 OR LEN(Graph_name$)>35 THEN
1260      Disp_error("Lingraph: Graph name or axes name is too long")
1265      STOP
1270    END IF
1275    IF NPAR>=8 THEN
1280      IF Grid<0 OR Grid>2 THEN
1285        Disp_error("Lingraph: Illegal Grid control parameter")
1290        STOP
1295      END IF
1300    END IF
1305    IF NPAR>=9 THEN
1310      IF Quadrant_mode<0 OR Quadrant_mode>4 THEN
1315        Disp_error("Lingraph: Illegal Quadrant mode parameter")
1320        STOP
1325      END IF
1330    END IF
1335    IF NPAR>=10 THEN
1340      IF LEN(Right_subtitle$)>20 THEN
1345        Disp_error("Lingraph: Right_subtitle is too long")
1350        STOP
1355      END IF
1360    END IF
1365    IF NPAR=11 THEN
1370      IF LEN(Left_subtitle$)>20 THEN
1375        Disp_error("Lingraph: Left_subtitle is too long")
1380        STOP
1385      END IF
1390    END IF
1395    !
1400    Xmin=X_min
1405    Xmax=X_max
1410    Ymin=Y_min
1415    Ymax=Y_max
1420    Titles$(1)=Graph_name$
1425    Titles$(2)=""
1430    Titles$(3)=""
1435    Titles$(4)=X_axes_name$
1440    Titles$(5)=Y_axes_name$
1445    Grid_pattern=0
1450    Quadrant=0
1455    !
1460    IF NPAR>=8 THEN Grid_pattern=Grid
1465    IF NPAR>=9 THEN Quadrant=Quadrant_mode
1470    IF NPAR>=10 THEN Titles$(3)=Right_subtitle$
1475    IF NPAR=11 THEN Titles$(2)=Left_subtitle$
1480    !*************************************************************
1485    !*                  Darw linear scale graph                  *
```

```
1490    !*************************************************************
1495    Draw_lin(Xmin,Xmax,Ymin,Ymax,Titles$(*),Grid_pattern,Quadrant)
1500  SUBEND
```

Loggraph

```
1515  SUB Loggraph(X_min,X_max,Y_min,Y_max,X_axes_name$,Y_axes_name$,Graph_name$,OPTIONAL INTEGER
 Graph_mode,Grid,Quadrant_mode,Right_subtitle$,Left_subtitle$)
1520    !*************************************************************
1525    !*           Set the parameters of log scale graph           *
1530    !*************************************************************
1535    ALLOCATE Titles$(1:5)[50]
1540    INTEGER Graph_pattern
1545    INTEGER Grid_pattern
1550    INTEGER Quadrant
1555    INTEGER Y_polarity            !  Polarity flag of y-axis
1560    INTEGER Y_val_exchange        !  Exchange flag of Y_min and Y_max
1565    INTEGER X_polarity            !  Polarity flag of x-axis
1570    INTEGER X_val_exchange        !  Exchange flag of X_min and X_max
1575    !*************************************************************
1580    !*                         Error check                       *
1585    !*************************************************************
1590    Graph_pattern=1
1595    IF NPAR>=8 THEN Graph_pattern=Graph_mode
1600    !
1605    IF Graph_pattern=1 OR Graph_pattern=3 THEN
1610      IF Y_min=0 OR Y_max=0 THEN
1615        Disp_error("Loggraph: 0 is not available for Y_min or Y_max value")
1620        STOP
1625      END IF
1630      IF Y_max<0 AND Y_min>0 OR Y_max>0 AND Y_min<0 THEN
1635        Disp_error("Loggraph: Y_min and Y_max must be same polarity")
1640        STOP
1645      END IF
1650    END IF
1655    !
1660    IF Graph_pattern=2 OR Graph_pattern=3 THEN
1665      IF X_min=0 OR X_max=0 THEN
1670        Disp_error("Loggraph: 0 is not available for X_min or X_max value")
1675        STOP
1680      END IF
1685      IF X_max<0 AND X_min>0 OR X_max>0 AND X_min<0 THEN
1690        Disp_error("Loggraph: X_min and X_max must be same polarity")
1695        STOP
1700      END IF
1705    END IF
1710    !
1715    IF Y_min=Y_max OR X_min=X_max THEN
1720      Disp_error("Loggraph: Minimum and maximum values are duplicate   ( check the X or Y value )")
1725      STOP
1730    END IF
1735    IF LEN(X_axes_name$)>30 OR LEN(Y_axes_name$)>30 OR LEN(Graph_name$)>35 THEN
1740      Disp_error("Loggraph: Graph name or axes name is too long")
1745      STOP
1750    END IF
1755    IF NPAR>=8 THEN
1760      IF Graph_mode>3 OR Graph_mode<1 THEN
1765        Disp_error("Loggraph: Illegal Graph mode parameter")
1770        STOP
1775      END IF
1780    END IF
1785    IF NPAR>=9 THEN
1790      IF Grid<0 OR Grid>2 THEN
1795        Disp_error("Loggraph: Illegal Grid control parameter")
1800        STOP
1805      END IF
1810    END IF
1815    IF NPAR>=10 THEN
```

```
1820      IF Quadrant_mode<0 OR Quadrant_mode>4 THEN
1825        Disp_error("Loggraph: Illegal Quadrant mode parameter")
1830        STOP
1835      END IF
1840    END IF
1845    IF NPAR>=11 THEN
1850      IF LEN(Right_subtitle$)>20 THEN
1855        Disp_error("Loggraph: Right_subtitle is too long")
1860        STOP
1865      END IF
1870    END IF
1875    IF NPAR=12 THEN
1880      IF LEN(Left_subtitle$)>20 THEN
1885        Disp_error("Loggraph: Left_subtitle is too long")
1890        STOP
1895      END IF
1900    END IF
1905    !
1910    Xmin=X_min
1915    Xmax=X_max
1920    Ymin=Y_min
1925    Ymax=Y_max
1930    Titles$(1)=Graph_name$
1935    Titles$(2)=""
1940    Titles$(3)=""
1945    Titles$(4)=X_axes_name$
1950    Titles$(5)=Y_axes_name$
1955    Grid_pattern=0
1960    Y_polarity=0
1965    Y_val_exchange=0
1970    X_polarity=0
1975    X_val_exchange=0
1980    !
1985    IF Graph_pattern=1 THEN
1990      IF Ymax<Ymin THEN Y_val_exchange=1
1995      IF Ymax<0 AND Ymin<0 THEN Y_polarity=1
2000      IF NPAR>=9 THEN Grid_pattern=Grid
2005      IF NPAR>=10 THEN Quadrant=Quadrant_mode
2010      IF NPAR>=11 THEN Titles$(3)=Right_subtitle$
2015      IF NPAR=12 THEN Titles$(2)=Left_subtitle$
2020    END IF
2025    !
2030    IF Graph_pattern=2 THEN
2035      IF Xmax<Xmin THEN X_val_exchange=1
2040      IF Xmax<0 AND Xmin<0 THEN X_polarity=1
2045      IF NPAR>=9 THEN Grid_pattern=Grid
2050      IF NPAR>=10 THEN Quadrant=Quadrant_mode
2055      IF NPAR>=11 THEN Titles$(3)=Right_subtitle$
2060      IF NPAR=12 THEN Titles$(2)=Left_subtitle$
2065    END IF
2070    !
2075    IF Graph_pattern=3 THEN
2080      IF Ymax<Ymin THEN Y_val_exchange=1
2085      IF Ymax<0 AND Ymin<0 THEN Y_polarity=1
2090      IF Xmax<Xmin THEN X_val_exchange=1
2095      IF Xmax<0 AND Xmin<0 THEN X_polarity=1
2100      IF NPAR>=9 THEN Grid_pattern=Grid
2105      IF NPAR>=10 THEN Quadrant=Quadrant_mode
2110      IF NPAR>=11 THEN Titles$(3)=Right_subtitle$
2115      IF NPAR=12 THEN Titles$(2)=Left_subtitle$
2120    END IF
2125    !*****************************************************************
2130    !*                    Darw log scale graph                       *
2135    !*****************************************************************
2140    IF Graph_pattern=1 THEN
2145      Draw_log1(Xmin,Xmax,Ymin,Ymax,Titles$(*),Grid_pattern,Quadrant,Y_polarity,Y_val_exchange)
```

```
2150    END IF
2155    !
2160    IF Graph_pattern=2 THEN
2165      Draw_log2(Xmin,Xmax,Ymin,Ymax,Titles$(*),Grid_pattern,Quadrant,X_polarity,X_val_exchange)
2170    END IF
2175    !
2180    IF Graph_pattern=3 THEN
2185      Draw_log3(Xmin,Xmax,Ymin,Ymax,Titles$(*),Grid_pattern,Quadrant,X_polarity,X_val_exchange,
Y_polarity,Y_val_exchange)
2190    END IF
2195  SUBEND
```

Draw_lin

```
2210  SUB Draw_lin(Xmin,Xmax,Ymin,Ymax,Titles$(*),INTEGER Grid_pattern,Quadrant)
2215    !*********************************************************************
2220    !*     Draws horizontal and vertical axes with linear scales         *
2225    !*********************************************************************
2230    INTEGER I
2235    INTEGER Minor_ticks
2240    INTEGER Quarter_screen
2245    INTEGER Title_base
2250    !*********************************************************************
2255    !*  Determine the plot area and the number of minor tick marks per   *
2260    !*  major division.                                                  *
2265    !*********************************************************************
2270    Quarter_screen=Quadrant
2275    SELECT Quadrant
2280    CASE 0
2285      Minor_ticks=5
2290    CASE 1,2,3,4
2295      Minor_ticks=4
2300    END SELECT
2305    GRAPHICS ON                          ! Enable graphics page
2310    WINDOW 0,100,0,100                   ! Fixes a BASIC 3.01 bug
2315    !*************************************************************
2320    !*      Zoom to the plotting area and write the titles       *
2325    !*************************************************************
2330    Zoom_plot_area(Quarter_screen)       ! Zoom to the plotting area.
2335    Title_base=BASE(Titles$,1)
2340    Write_title(Titles$(Title_base),Titles$(Title_base+1),Titles$(Title_base+2),Quarter_screen)
2345    !*************************************************************
2350    !*      Zoom to the graph area and write the axes names      *
2355    !*************************************************************
2360    Zoom_graph_area(Quarter_screen)      ! Zoom to the graph area.
2365    Write_axes_name(Titles$(Title_base+3),Titles$(Title_base+4),Quarter_screen)
2370    !*************************************************************
2375    !*                    Scale the axes                           *
2380    !*************************************************************
2385    Calc_lin_axis(Xmin,Xmax,Xaxis_min,Xaxis_max,Xmajor_div,Quarter_screen)
2390    Calc_lin_axis(Ymin,Ymax,Yaxis_min,Yaxis_max,Ymajor_div,Quarter_screen)
2395    !*************************************************************
2400    !*                    Draw the axes                            *
2405    !*************************************************************
2410    WINDOW Xaxis_min,Xaxis_max,Yaxis_min,Yaxis_max
2415    LINE TYPE 1                          ! Solid line
2420    PEN 1                                ! White
2425    IF Quarter_screen THEN
2430      AXES 0,0,Xaxis_max,Yaxis_max
2435      AXES 0,0,Xaxis_min,Yaxis_min
2440    ELSE
2445      AXES 0,0,Xaxis_max,Yaxis_max
2450      AXES 0,0,Xaxis_min,Yaxis_min
2455    END IF
2460    !*************************************************************
2465    !*                 Label the tick marks                      *
2470    !*************************************************************
2475    Label_lin_xaxis(Xaxis_min,Xaxis_max,Xmajor_div,Yaxis_min,Yaxis_max,Minor_ticks,Quarter_screen)
2480    Label_lin_yaxis(Xaxis_min,Xaxis_max,Yaxis_min,Yaxis_max,Ymajor_div,Minor_ticks,Quarter_screen)
2485    !*************************************************************
2490    !*               Draw the grid if necessary                  *
2495    !*************************************************************
2500    IF Grid_pattern THEN
2505      LINE TYPE 4
2510      IF Grid_pattern=2 THEN LINE TYPE 1
2515      !*********************************************************
```

```
2520      !*                  draw vertical grid                      *
2525      !************************************************************
2530      IF Yaxis_min*Yaxis_max<0 THEN
2535        FOR Y1=0 TO Yaxis_max STEP Ymajor_div
2540          IF Y1<>Yaxis_max THEN
2545            MOVE Xaxis_min,Y1
2550            DRAW Xaxis_max,Y1
2555          END IF
2560        NEXT Y1
2565        FOR Y1=0-Ymajor_div TO Yaxis_min STEP -Ymajor_div
2570          IF Y1<>Yaxis_min THEN
2575            MOVE Xaxis_min,Y1
2580            DRAW Xaxis_max,Y1
2585          END IF
2590        NEXT Y1
2595      ELSE
2600        FOR Y1=Yaxis_min TO Yaxis_max STEP Ymajor_div
2605          IF Y1<>Yaxis_min AND Y1<>Yaxis_max THEN
2610            MOVE Xaxis_min,Y1
2615            DRAW Xaxis_max,Y1
2620          END IF
2625        NEXT Y1
2630      END IF
2635      !************************************************************
2640      !*                   draw horizontal grid                   *
2645      !************************************************************
2650      IF Xaxis_min*Xaxis_max<0 THEN
2655        FOR X1=0 TO Xaxis_max STEP Xmajor_div
2660          IF X1<>Xaxis_max THEN
2665            MOVE X1,Yaxis_min
2670            DRAW X1,Yaxis_max
2675          END IF
2680        NEXT X1
2685        FOR X1=0-Xmajor_div TO Xaxis_min STEP -Xmajor_div
2690          IF X1<>Xaxis_min THEN
2695            MOVE X1,Yaxis_min
2700            DRAW X1,Yaxis_max
2705          END IF
2710        NEXT X1
2715      ELSE
2720        FOR X1=Xaxis_min TO Xaxis_max STEP Xmajor_div
2725          IF X1<>Xaxis_min AND X1<>Xaxis_max THEN
2730            MOVE X1,Yaxis_min
2735            DRAW X1,Yaxis_max
2740          END IF
2745        NEXT X1
2750      END IF
2755    END IF
2760    !************************************************************
2765    !*           Move the pen to the bottom left corner         *
2770    !************************************************************
2775    LINE TYPE 1
2780    MOVE Xaxis_min,Yaxis_min
2785  SUBEND
```

Draw_log1

```
2800  SUB Draw_log1(Xmin,Xmax,Ymin,Ymax,Titles$(*),INTEGER Grid_pattern,Quadrant,Y_polarity,Y_val_exchange)
2805  !*********************************************************************
2810  !*   The vertical axis will have a logarithmic (base 10) scale,      *
2815  !*   while the horizontal axis will have a linear scale.             *
2820  !*********************************************************************
2825    INTEGER I,Mantissa
2830    INTEGER Title_base,Quarter_screen
2835    INTEGER Xminor_tick
2840    INTEGER Yaxis_min,Yaxis_max
2845    INTEGER Yminor_tick,Ymajor_tick
2850    INTEGER Y1,Y2
2855  !*********************************************************************
2860  !*   Determine the plot area and number of x-axis minor tick marks   *
2865  !*   per major division.                                             *
2870  !*********************************************************************
2875    Quarter_screen=Quadrant
2880    SELECT Quadrant
2885    CASE 0
2890      Xminor_tick=5
2895    CASE 1,2,3,4
2900      Xminor_tick=4
2905    END SELECT
2910    GRAPHICS ON                          ! Enable graphics page
2915    WINDOW 0,100,0,100                   ! Fixes a BASIC 3.01 bug
2920  !*************************************************************
2925  !*      Zoom to the plotting area and write the titles       *
2930  !*************************************************************
2935    Zoom_plot_area(Quarter_screen)       ! Zoom to the plotting area.
2940    Title_base=BASE(Titles$,1)
2945    Write_title(Titles$(Title_base),Titles$(Title_base+1),Titles$(Title_base+2),Quarter_screen)
2950  !*************************************************************
2955  !*       Zoom to the graph area and write the axes name      *
2960  !*************************************************************
2965    Zoom_graph_area(Quarter_screen)      ! Zoom to the graph area.
2970    Write_axes_name(Titles$(Title_base+3),Titles$(Title_base+4),Quarter_screen)
2975  !*************************************************************
2980  !*                    Scale the axes                           *
2985  !*************************************************************
2990    Calc_lin_axis(Xmin,Xmax,Xaxis_min,Xaxis_max,Xmajor_div,Quarter_screen)
2995    Calc_log_axis(Ymin,Ymax,Yaxis_min,Yaxis_max,Ymajor_tick,Yminor_tick,Quarter_screen)
3000  !*************************************************************
3005  !*                    Draw the axes                            *
3010  !*************************************************************
3015    WINDOW Xaxis_min,Xaxis_max,Yaxis_min,Yaxis_max
3020    LINE TYPE 1
3025    PEN 1                                ! White
3030    AXES 0,0,Xaxis_max,Yaxis_max
3035    AXES 0,0,Xaxis_min,Yaxis_min
3040  !*************************************************************
3045  !*                   Label the tick marks                      *
3050  !*************************************************************
3055    Label_lin_xaxis((Xaxis_min),(Xaxis_max),(Xmajor_div),(Yaxis_min),(Yaxis_max),Xminor_tick,
Quarter_screen)
3060    Label_log_yaxis((Xaxis_min),(Xaxis_max),(Yaxis_min),(Yaxis_max),(Ymajor_tick),(Yminor_tick),
Quarter_screen,Y_polarity,Y_val_exchange,Grid_pattern)
3065  !*************************************************************
3070  !*     Draw the grid if necessary   -- draw vertical grid --  *
3075  !*************************************************************
3080    IF Grid_pattern THEN
3085      GOSUB Line_type
3090      IF Xaxis_min*Xaxis_max<0 THEN
3095        FOR X1=0 TO Xaxis_max STEP Xmajor_div
```

```
3100          IF X1<>Xaxis_max THEN
3105            MOVE X1,Yaxis_min
3110            DRAW X1,Yaxis_max
3115          END IF
3120        NEXT X1
3125        FOR X1=0-Xmajor_div TO Xaxis_min STEP -Xmajor_div
3130          IF X1<>Xaxis_min THEN
3135            MOVE X1,Yaxis_min
3140            DRAW X1,Yaxis_max
3145          END IF
3150        NEXT X1
3155      ELSE
3160        FOR X1=Xaxis_min TO Xaxis_max STEP Xmajor_div
3165          IF X1<>Xaxis_min AND X1<>Xaxis_max THEN
3170            MOVE X1,Yaxis_min
3175            DRAW X1,Yaxis_max
3180          END IF
3185        NEXT X1
3190      END IF
3195  !*****************************************************************
3200  !*    Draw the grid if necessary   -- draw horizontal grid -- *
3205  !*****************************************************************
3210      LINE TYPE 1
3215      MOVE Xaxis_min,Yaxis_min
3220      IF Yminor_tick=0 THEN GOSUB Line_type
3225      IF Ymin>Ymax THEN Ymajor_tick=-Ymajor_tick
3230      FOR Y1=Yaxis_min TO Yaxis_max STEP Ymajor_tick
3235        IF Y1<>Yaxis_min AND Y1<>Yaxis_max THEN
3240          MOVE Xaxis_min,Y1
3245          DRAW Xaxis_max,Y1
3250        END IF
3255      NEXT Y1
3260    !*****************************************************************
3265    !*         Draw the grid line(s) between each decade          *
3270    !*****************************************************************
3275      GOSUB Line_type
3280      IF Yminor_tick<>0 THEN
3285        MOVE Xaxis_min,Yaxis_min
3290        Y_start=MIN(Yaxis_min,Yaxis_max)
3295        Y_stop=MAX(Yaxis_min,Yaxis_max)
3300        IF Y_polarity=0 THEN Y_stop=Y_stop-1
3305        IF Y_polarity=1 THEN Y_start=Y_start+1
3310      !
3315        FOR Exponent=Y_start TO Y_stop
3320          FOR Mantissa=2 TO 9
3325            IF Y_polarity=0 THEN Y_coordinate=LGT(Mantissa*(10^Exponent))
3330            IF Y_polarity=1 THEN Y_coordinate=-LGT(Mantissa*(10^(-Exponent)))
3335            MOVE Xaxis_min,Y_coordinate
3340            DRAW Xaxis_max,Y_coordinate
3345          NEXT Mantissa
3350        NEXT Exponent
3355      END IF
3360    END IF
3365    LINE TYPE 1
3370  !*****************************************************************
3375  !*           Move the pen to the bottom left corner           *
3380  !*****************************************************************
3385    MOVE Xaxis_min,Yaxis_min
3390    SUBEXIT
3395  !
3400 Line_type: !
3405    LINE TYPE 4
3410    IF Grid_pattern=2 THEN LINE TYPE 1
3415    RETURN
```

```
3420  SUBEND
```

Draw_log2

```
3435  SUB Draw_log2(Xmin,Xmax,Ymin,Ymax,Titles$(*),INTEGER Grid_pattern,Quadrant,X_polarity,X_val_exchange)
3440  !*********************************************************************
3445  !*   The horizontal axis will have a logarithmic (base 10) scale,    *
3450  !*   while the vertical axis will have a linear scale.               *
3455  !*********************************************************************
3460    INTEGER I,Mantissa
3465    INTEGER Title_base,Quarter_screen
3470    INTEGER Yminor_tick
3475    INTEGER Xaxis_min,Xaxis_max
3480    INTEGER Xminor_tick,Xmajor_tick
3485    INTEGER X1,X2
3490  !*********************************************************************
3495  !*   Determine the plot area and number of x-axis minor tick marks   *
3500  !*   per major division.                                             *
3505  !*********************************************************************
3510    Quarter_screen=Quadrant
3515    SELECT Quadrant
3520    CASE 0
3525      Yminor_tick=5
3530    CASE 1,2,3,4
3535      Yminor_tick=4
3540    END SELECT
3545    GRAPHICS ON                         ! Enable graphics page
3550    WINDOW 0,100,0,100                  ! Fixes a BASIC 3.01 bug
3555  !*************************************************************
3560  !*      Zoom to the plotting area and write the titles       *
3565  !*************************************************************
3570    Zoom_plot_area(Quarter_screen)      ! Zoom to the plotting area.
3575    Title_base=BASE(Titles$,1)
3580    Write_title(Titles$(Title_base),Titles$(Title_base+1),Titles$(Title_base+2),Quarter_screen)
3585  !*************************************************************
3590  !*       Zoom to the graph area and write the axes name      *
3595  !*************************************************************
3600    Zoom_graph_area(Quarter_screen)     ! Zoom to the graph area.
3605    Write_axes_name(Titles$(Title_base+3),Titles$(Title_base+4),Quarter_screen)
3610  !*************************************************************
3615  !*                    Scale the axes                           *
3620  !*************************************************************
3625    Calc_lin_axis(Ymin,Ymax,Yaxis_min,Yaxis_max,Ymajor_div,Quarter_screen)
3630    Calc_log_axis(Xmin,Xmax,Xaxis_min,Xaxis_max,Xmajor_tick,Xminor_tick,Quarter_screen)
3635  !*************************************************************
3640  !*                    Draw the axes                            *
3645  !*************************************************************
3650    WINDOW Xaxis_min,Xaxis_max,Yaxis_min,Yaxis_max
3655    LINE TYPE 1
3660    PEN 1                               ! White
3665    AXES 0,0,Xaxis_max,Yaxis_max
3670    AXES 0,0,Xaxis_min,Yaxis_min
3675  !*************************************************************
3680  !*                   Label the tick marks                      *
3685  !*************************************************************
3690    Label_lin_yaxis((Xaxis_min),(Xaxis_max),(Yaxis_min),(Yaxis_max),(Ymajor_div),Yminor_tick,
Quarter_screen)
3695    Label_log_xaxis((Xaxis_min),(Xaxis_max),(Yaxis_min),(Yaxis_max),(Xmajor_tick),(Xminor_tick),
Quarter_screen,X_polarity,X_val_exchange,Grid_pattern)
3700  !*************************************************************
3705  !*     Draw the grid if necessary   -- draw vertical grid --  *
3710  !*************************************************************
3715    IF Grid_pattern THEN
3720      GOSUB Line_type
3725      IF Yaxis_min*Yaxis_max<0 THEN
3730        FOR Y1=0 TO Yaxis_max STEP Ymajor_div
```

```
3735          IF Y1<>Yaxis_max THEN
3740            MOVE Xaxis_min,Y1
3745            DRAW Xaxis_max,Y1
3750          END IF
3755        NEXT Y1
3760        FOR Y1=0-Ymajor_div TO Yaxis_min STEP -Ymajor_div
3765          IF Y1<>Yaxis_min THEN
3770            MOVE Xaxis_min,Y1
3775            DRAW Xaxis_max,Y1
3780          END IF
3785        NEXT Y1
3790      ELSE
3795        FOR Y1=Yaxis_min TO Yaxis_max STEP Ymajor_div
3800          IF Y1<>Yaxis_min AND Y1<>Yaxis_max THEN
3805            MOVE Xaxis_min,Y1
3810            DRAW Xaxis_max,Y1
3815          END IF
3820        NEXT Y1
3825      END IF
3830    !*************************************************************
3835    !*    Draw the grid if necessary   -- draw horizontal grid -- *
3840    !*************************************************************
3845      LINE TYPE 1
3850      MOVE Xaxis_min,Yaxis_min
3855      IF Xminor_tick=0 THEN GOSUB Line_type
3860      IF Xmin>Xmax THEN Xmajor_tick=-Xmajor_tick
3865      FOR X1=Xaxis_min TO Xaxis_max STEP Xmajor_tick
3870        IF X1<>Xaxis_min AND X1<>Xaxis_max THEN
3875          MOVE X1,Yaxis_min
3880          DRAW X1,Yaxis_max
3885        END IF
3890      NEXT X1
3895    !*************************************************************
3900    !*         Draw the grid line(s) between each decade          *
3905    !*************************************************************
3910      GOSUB Line_type
3915      IF Xminor_tick<>0 THEN
3920        MOVE Xaxis_min,Yaxis_min
3925        X_start=MIN(Xaxis_min,Xaxis_max)
3930        X_stop=MAX(Xaxis_min,Xaxis_max)
3935        IF X_polarity=0 THEN X_stop=X_stop-1
3940        IF X_polarity=1 THEN X_start=X_start+1
3945      !
3950        FOR Exponent=X_start TO X_stop
3955          FOR Mantissa=2 TO 9
3960            IF X_polarity=0 THEN X_coordinate=LGT(Mantissa*(10^Exponent))
3965            IF X_polarity=1 THEN X_coordinate=-LGT(Mantissa*(10^(-Exponent)))
3970            MOVE X_coordinate,Yaxis_min
3975            DRAW X_coordinate,Yaxis_max
3980          NEXT Mantissa
3985        NEXT Exponent
3990      END IF
3995    END IF
4000    LINE TYPE 1
4005  !*************************************************************
4010  !*           Move the pen to the bottom left corner           *
4015  !*************************************************************
4020    MOVE Xaxis_min,Yaxis_min
4025    SUBEXIT
4030  !
4035 Line_type: !
4040    LINE TYPE 4
4045    IF Grid_pattern=2 THEN LINE TYPE 1
4050    RETURN
```

```
4055  SUBEND
```

Draw_log3

```
4070  SUB Draw_log3(Xmin,Xmax,Ymin,Ymax,Titles$(*),INTEGER Grid_pattern,Quadrant,X_polarity,X_val_exchange,
Y_polarity,Y_val_exchange)
4075  !*********************************************************************
4080  !*    The vertical axis and horizontal axis will have logarithmic    *
4085  !*    (base 10) scale.                                               *
4090  !*********************************************************************
4095    INTEGER I
4100    INTEGER Mantissa
4105    INTEGER Quarter_screen
4110    INTEGER Title_base
4115    INTEGER Xaxis_min,Xaxis_max
4120    INTEGER Xminor_tick,Xmajor_tick
4125    INTEGER X1,X2
4130    INTEGER Yaxis_min,Yaxis_max
4135    INTEGER Yminor_tick,Ymajor_tick
4140    INTEGER Y1,Y2
4145  !*********************************************************************
4150  !*   Determine the plot area and number of x-axis minor tick marks   *
4155  !*   per major division.                                             *
4160  !*********************************************************************
4165    Quarter_screen=Quadrant
4170    SELECT Quadrant
4175    CASE 0
4180      Xminor_tick=5
4185      Yminor_tick=5
4190    CASE 1,2,3,4
4195      Xminor_tick=4
4200      Yminor_tick=4
4205    END SELECT
4210    GRAPHICS ON                          ! Enable graphics page
4215    WINDOW 0,100,0,100                   ! Fixes a BASIC 3.01 bug
4220  !*****************************************************************
4225  !*      Zoom to the plotting area and write the titles           *
4230  !*****************************************************************
4235    Zoom_plot_area(Quarter_screen)       ! Zoom to the plotting area.
4240    Title_base=BASE(Titles$,1)
4245    Write_title(Titles$(Title_base),Titles$(Title_base+1),Titles$(Title_base+2),Quarter_screen)
4250  !*****************************************************************
4255  !*       Zoom to the graph area and write the axes name          *
4260  !*****************************************************************
4265    Zoom_graph_area(Quarter_screen)      ! Zoom to the graph area.
4270    Write_axes_name(Titles$(Title_base+3),Titles$(Title_base+4),Quarter_screen)
4275  !*****************************************************************
4280  !*                    Scale the axes                             *
4285  !*****************************************************************
4290    Calc_log_axis(Xmin,Xmax,Xaxis_min,Xaxis_max,Xmajor_tick,Xminor_tick,Quarter_screen)
4295    Calc_log_axis(Ymin,Ymax,Yaxis_min,Yaxis_max,Ymajor_tick,Yminor_tick,Quarter_screen)
4300  !*****************************************************************
4305  !*                    Draw the axes                              *
4310  !*****************************************************************
4315    WINDOW Xaxis_min,Xaxis_max,Yaxis_min,Yaxis_max
4320    LINE TYPE 1
4325    PEN 1                                ! White
4330    AXES 0,0,Xaxis_max,Yaxis_max
4335    AXES 0,0,Xaxis_min,Yaxis_min
4340  !*****************************************************************
4345  !*                   Label the tick marks                        *
4350  !*****************************************************************
4355    Label_log_xaxis((Xaxis_min),(Xaxis_max),(Yaxis_min),(Yaxis_max),(Xmajor_tick),(Xminor_tick),
Quarter_screen,X_polarity,X_val_exchange,Grid_pattern)
4360    Label_log_yaxis((Xaxis_min),(Xaxis_max),(Yaxis_min),(Yaxis_max),(Ymajor_tick),(Yminor_tick),
Quarter_screen,Y_polarity,Y_val_exchange,Grid_pattern)
```

```
!*************************************************************
!*     Draw the grid if necessary   -- draw vertical grid --  *
!*************************************************************
  IF Grid_pattern THEN
    LINE TYPE 1
    IF Xminor_tick=0 THEN GOSUB Line_type
    MOVE Xaxis_min,Yaxis_min
    IF Xmin>Xmax THEN Xmajor_tick=-Xmajor_tick
    FOR X1=Xaxis_min TO Xaxis_max STEP Xmajor_tick
      IF X1<>Xaxis_min AND X1<>Xaxis_max THEN
        MOVE X1,Yaxis_min
        DRAW X1,Yaxis_max
      END IF
    NEXT X1
  !*************************************************************
  !*         Draw the grid line(s) between each decade         *
  !*************************************************************
    IF Xminor_tick<>0 THEN
      GOSUB Line_type
      IF Yminor_tick=0 THEN GOSUB Line_type
      MOVE Xaxis_min,Yaxis_min
      X_start=MIN(Xaxis_min,Xaxis_max)
      X_stop=MAX(Xaxis_min,Xaxis_max)
    !
      FOR Exponent=X_start TO X_stop
        FOR Mantissa=2 TO 9
          IF X_polarity=0 THEN X_coordinate=LGT(Mantissa*(10^Exponent))
          IF X_polarity=1 THEN X_coordinate=-LGT(Mantissa*(10^(-Exponent)))
          MOVE X_coordinate,Yaxis_min
          DRAW X_coordinate,Yaxis_max
        NEXT Mantissa
      NEXT Exponent
    END IF
  !*************************************************************
  !*    Draw the grid if necessary   -- draw horizontal grid -- *
  !*************************************************************
    LINE TYPE 1
    IF Yminor_tick=0 THEN GOSUB Line_type
    MOVE Xaxis_min,Yaxis_min
    IF Ymin>Ymax THEN Ymajor_tick=-Ymajor_tick
    FOR Y1=Yaxis_min TO Yaxis_max STEP Ymajor_tick
      IF Y1<>Yaxis_min AND Y1<>Yaxis_max THEN
        MOVE Xaxis_min,Y1
        DRAW Xaxis_max,Y1
      END IF
    NEXT Y1
  !*************************************************************
  !*         Draw the grid line(s) between each decade         *
  !*************************************************************
    IF Yminor_tick<>0 THEN
      GOSUB Line_type
      IF Xminor_tick=0 THEN GOSUB Line_type
      MOVE Xaxis_min,Yaxis_min
      Y_start=MIN(Yaxis_min,Yaxis_max)
      Y_stop=MAX(Yaxis_min,Yaxis_max)
    !
      FOR Exponent=Y_start TO Y_stop
        FOR Mantissa=2 TO 9
          IF Y_polarity=0 THEN Y_coordinate=LGT(Mantissa*(10^Exponent))
          IF Y_polarity=1 THEN Y_coordinate=-LGT(Mantissa*(10^(-Exponent)))
          MOVE Xaxis_min,Y_coordinate
          DRAW Xaxis_max,Y_coordinate
        NEXT Mantissa
      NEXT Exponent
    END IF
  END IF
```

```
4695    LINE TYPE 1
4700  !*****************************************************************
4705  !*           Move the pen to the bottom left corner              *
4710  !*****************************************************************
4715    MOVE Xaxis_min,Yaxis_min
4720    SUBEXIT
4725  !
4730 Line_type: !
4735    LINE TYPE 4
4740    IF Grid_pattern=2 THEN LINE TYPE 1
4745    RETURN
4750  SUBEND
```

Disp_error

```
4765  SUB Disp_error(Error_message$)
4770    BEEP
4775    !*************************************************************
4780    !*        Displays the given error message on the CRT        *
4785    !*************************************************************
4790    INTEGER Alpha_color
4795    INTEGER Alpha_planes
4800    !*************************************************************
4805    !*            For bit-mapped color display                   *
4810    !*************************************************************
4815    Crt_type$=TRIM$(SYSTEM$("CRT ID"))
4820    IF Crt_type$[7;9]="CGB" THEN
4825      STATUS 1,5;Alpha_color               ! Determine current alpha color
4830      STATUS 1,18;Alpha_planes             ! Read alpha write-enable mask
4835      IF Alpha_planes<>IVAL("1111",2) THEN
4840        DISP Error_message$
4845      ELSE
4850        DISP CHR$(137);Error_message$
4855        CONTROL 1,5;Alpha_color            ! Restore previous alpha color
4860      END IF
4865    ELSE
4870    !*****************************************************************
4875    !*    For non-bit-mapped color display and monochrome display    *
4880    !*****************************************************************
4885      DISP Error_message$
4890    END IF
4895  SUBEND
```

Zoom_plot_area

```
4910  SUB Zoom_plot_area(INTEGER Quadrant)
4915    !*************************************************************
4920    !*                Zooms to the plotting area                 *
4925    !*************************************************************
4930    X_left=0
4935    X_center=50*RATIO
4940    X_right=100*RATIO
4945    !*************************************************************
4950    !*  If desired, leave space for main titles at the top of     *
4955    !*  the screen.                                               *
4960    !*************************************************************
4965    Title_offset=0
4970    Y_bottom=0
4975    Y_center=(100-Title_offset)/2
4980    Y_top=100-Title_offset
4985    !*************************************************************
4990    !*                 Zoom to the plotting area                 *
4995    !*************************************************************
5000    SELECT Quadrant
5005    CASE 1
5010      VIEWPORT X_center,X_right,Y_center,Y_top
5015    CASE 2
5020      VIEWPORT X_left,X_center,Y_center,Y_top
5025    CASE 3
5030      VIEWPORT X_left,X_center,Y_bottom,Y_center
5035    CASE 4
5040      VIEWPORT X_center,X_right,Y_bottom,Y_center
5045    CASE ELSE
5050      VIEWPORT X_left,X_right,Y_bottom,Y_top
5055    END SELECT
5060    !
5065    PEN 7                                 ! Magenta
5070    FRAME                                 ! Frame the quadrant
5075    PEN 1                                 ! White
5080  SUBEND
```

Write_title

```
5095  SUB Write_title(Main_title$,Left_title$,Right_title$,INTEGER Quadrant)
5100    !************************************************************************
5105    !* Writes a title and two subtitles at the top of the current viewport *
5110    !************************************************************************
5115    INTEGER X_coordinate
5120    INTEGER Y_coordinate
5125    LINE TYPE 1                           ! Solid line
5130    DEG                                   ! All angles in degrees
5135    LDIR 0                                ! 0 degrees rotation
5140    !*****************************************************************
5145    !*       Determine the character size of the main title          *
5150    !*****************************************************************
5155    IF Quadrant THEN
5160      Character_size=3.25
5165    ELSE
5170      Character_size=5.1
5175    END IF
5180    !*****************************************************************
5185    !*                   Write the main title                        *
5190    !*****************************************************************
5195    CSIZE Character_size
5200    PEN 3                                 ! Yellow
5205    LORG 6
5210    WINDOW 0,100,0,100
5215    MOVE 50,100
5220    LABEL Main_title$
5225    !*****************************************************************
5230    !*      Calculate the vertical position of the subtitles         *
5235    !*****************************************************************
5240    WHERE X_coordinate,Y_coordinate
5245    Y_coordinate=.90*Y_coordinate+10
5250    CSIZE .7*Character_size               ! Reduce character size
5255    !*****************************************************************
5260    !*                   Write the subtitles                         *
5265    !*****************************************************************
5270    LORG 1
5275    MOVE 1,Y_coordinate-5
5280    LABEL Left_title$
5285    LORG 7
5290    MOVE 99,Y_coordinate-5
5295    LABEL Right_title$
5300  SUBEND
```

Zoom_graph_area

```
5315  SUB Zoom_graph_area(INTEGER Quadrant)
5320    !*************************************************************
5325    !*                   Zooms to the graph area                 *
5330    !*************************************************************
5335    X_lef=0
5340    X_cen=50*RATIO
5345    X_rig=100*RATIO
5350    !*************************************************************************
5355    !* If desired, leave space for main titles at the top of the screen *
5360    !*************************************************************************
5365    Title_offset=0
5370    Y_bot=0
5375    Y_cen=(100-Title_offset)/2
5380    Y_top=100-Title_offset
5385    !*************************************************************************
5390    !*  Determine the offsets of the graph area from the plotting area  *
5395    !*************************************************************************
5400    IF Quadrant THEN
5405      Lef_off=11.3*RATIO                ! Space for y-axis labels
5410      Rig_off=4.5*RATIO                 ! Space for x-axis labels
5415      Bot_off=8.5                       ! Space for x-axis labels
5420      Top_off=8.25                      ! Space for graph's title
5425    ELSE
5430      Lef_off=16*RATIO
5435      Rig_off=7*RATIO
5440      Bot_off=12
5445      Top_off=14
5450    END IF
5455    !*************************************************************
5460    !*                    Zoom to the graph area                 *
5465    !*************************************************************
5470    SELECT Quadrant
5475    CASE 1
5480      VIEWPORT X_cen+Lef_off,X_rig-Rig_off,Y_cen+Bot_off,Y_top-Top_off
5485    CASE 2
5490      VIEWPORT X_lef+Lef_off,X_cen-Rig_off,Y_cen+Bot_off,Y_top-Top_off
5495    CASE 3
5500      VIEWPORT X_lef+Lef_off,X_cen-Rig_off,Y_bot+Bot_off,Y_cen-Top_off
5505    CASE 4
5510      VIEWPORT X_cen+Lef_off,X_rig-Rig_off,Y_bot+Bot_off,Y_cen-Top_off
5515    CASE ELSE
5520      VIEWPORT X_lef+Lef_off,X_rig-Rig_off,Y_bot+Bot_off,Y_top-Top_off
5525    END SELECT
5530  SUBEND
```

Write_axes_name

```
5545  SUB Write_axes_name(Xaxis_name$,Yaxis_name$,INTEGER Quadrant)
5550    !*************************************************************
5555    !*              Writes the names of the axes                 *
5560    !*************************************************************
5565    LINE TYPE 1                          ! Solid line
5570    DEG                                  ! All angles in degrees
5575    LORG 6
5580    PEN 4                                ! Green
5585    !*************************************************************
5590    !*     Determine the size and location of the axes labels     *
5595    !*************************************************************
5600    IF Quadrant THEN
5605      Character_size=3                  ! Character size of axes labels
5610      Left_offset=-32.5                 ! Horiz. offset of y-axis label
5615      Bottom_offset=-13.5               ! Vert. offset of x-axis label
5620    ELSE
5625      Character_size=3.8
5630      Left_offset=-19.5
5635      Bottom_offset=-8.5
5640    END IF
5645    !
5650    CLIP OFF                             ! Turn off soft clipping
5655    WINDOW 0,100,0,100
5660    CSIZE Character_size
5665    !
5670    LDIR 0
5675    MOVE 50,Bottom_offset
5680    LABEL Xaxis_name$                    ! Label x-axis
5685    LDIR 90
5690    MOVE Left_offset,50
5695    LABEL Yaxis_name$                    ! Label y-axis
5700    CLIP ON                              ! Turn on soft clipping
5705  SUBEND
```

Calc_lin_axis

```
5720  SUB Calc_lin_axis(Min_val,Max_val,Axis_min,Axis_max,Major_div,INTEGER Quadrant)
5725    !*********************************************************************
5730    !*  Calculate the minimum and maximum values of a linear scale axis *
5735    !*********************************************************************
5740    INTEGER Exponent
5745    !*************************************************************
5750    !*                 Calculate the major division              *
5755    !*************************************************************
5760    Data_min=MIN(Min_val,Max_val)
5765    Data_max=MAX(Min_val,Max_val)
5770    !
5775    IF Quadrant THEN
5780      Approx_division=(Data_max-Data_min)/(4/1.2)
5785    ELSE
5790      Approx_division=(Data_max-Data_min)/5
5795    END IF
5800    !
5805    Exponent=INT(LGT(Approx_division))
5810    Mantissa=Approx_division/(10.0^Exponent)
5815    !
5820    SELECT Mantissa
5825    CASE <=1.35
5830      Major_div=1
5835    CASE <=2.4
5840      Major_div=2
5845    CASE <=3.6
5850      Major_div=3
5855    CASE <=7.2
5860      Major_div=5
5865    CASE ELSE
5870      Major_div=10
5875    END SELECT
5880    !
5885    Major_div=DROUND(Major_div*10^Exponent,1)
5890    IF Min_val>Max_val THEN Major_div=-Major_div
5895    !*************************************************************
5900    !*    Calculate the minimum and maximum values of the axis    *
5905    !*************************************************************
5910    IF Min_val<0 THEN
5915      IF ABS(Max_val)>=1 THEN Axis_min=PROUND(Min_val,Exponent)
5920      IF ABS(Max_val)<1 THEN Axis_min=PROUND(Min_val,Exponent)
5925    ELSE
5930      IF ABS(Max_val)>=1 THEN Axis_min=PROUND(Min_val,Exponent)
5935      IF ABS(Max_val)<1 THEN Axis_min=PROUND(Min_val,Exponent)
5940    END IF
5945    !
5950    IF Max_val<0 THEN
5955      IF ABS(Max_val)>=1 THEN Axis_max=PROUND(Max_val,Exponent)
5960      IF ABS(Max_val)<1 THEN Axis_max=PROUND(Max_val,Exponent)
5965    ELSE
5970      IF ABS(Max_val)>=1 THEN Axis_max=PROUND(Max_val,Exponent)
5975      IF ABS(Max_val)<1 THEN Axis_max=PROUND(Max_val,Exponent)
5980    END IF
5985  SUBEND
```

Label_lin_xaxis

```
5995  SUB Label_lin_xaxis(X_min,X_max,Xmajor_div,Y_min,Y_max,INTEGER Xminor_tick,Quadrant)
6000    !*************************************************************
6005    !*              Labels the linear scaled x-axis              *
6010    !*************************************************************
6015    LINE TYPE 1                              ! Solid line
6020    LDIR 0                                   ! 0 degrees rotation
6025    LORG 6
6030    CLIP OFF                                 ! Soft clip off
6035    !*********************************************************************
6040    !*  Determine the vertical position and size of the axis labels *
6045    !*********************************************************************
6050    IF Quadrant THEN
6055      Y_coordinate=Y_min-.028*(Y_max-Y_min)
6060      Y_coord_1=Y_min-.1*(Y_max-Y_min)
6065      CSIZE 2.6                              !  use small characters.
6070    ELSE
6075      Y_coordinate=Y_min-.02*(Y_max-Y_min)
6080      Y_coord_1=Y_min-.07*(Y_max-Y_min)
6085      CSIZE 3.0
6090    END IF
6095    Tick_length=.018*(Y_max-Y_min)
6100    !*********************************************************************
6105    !*                       Draw minor ticks                            *
6110    !*********************************************************************
6115    IF X_min*X_max<0 THEN
6120      FOR X_coordinate=0 TO X_max STEP Xmajor_div/Xminor_tick
6125        MOVE X_coordinate,Y_min
6130        IDRAW 0,Tick_length*.5
6135      NEXT X_coordinate
6140      !
6145      FOR X_coordinate=0-Xmajor_div/Xminor_tick TO X_min STEP -Xmajor_div/Xminor_tick
6150        MOVE X_coordinate,Y_min
6155        IDRAW 0,Tick_length*.5
6160      NEXT X_coordinate
6165    ELSE
6170      FOR X_coordinate=X_min+Xmajor_div/Xminor_tick TO X_max STEP Xmajor_div/Xminor_tick
6175        MOVE X_coordinate,Y_min
6180        IDRAW 0,Tick_length*.5
6185      NEXT X_coordinate
6190    END IF
6195    !*********************************************************************
6200    !*            Write the labels and draw major ticks              *
6205    !*********************************************************************
6210    Max_val=MAX(ABS(X_min),ABS(X_max))
6215    Digit=INT(LGT(ABS(Max_val)))-INT(LGT(ABS(Xmajor_div)))
6220    IF Digit<4 THEN
6225      IF Quadrant=0 THEN
6230        B=ABS(X_max/(Xmajor_div/Xminor_tick) MOD Xminor_tick)
6235        IF B>1 OR B=0 THEN
6240          GOSUB Calc_axis
6245          X_coordinate=X_max
6250          MOVE X_coordinate,Y_coordinate
6255          GOSUB Write_label
6260        END IF
6265         !
6270        B=ABS(X_min/(Xmajor_div/Xminor_tick) MOD Xminor_tick)
6275        IF B>1 OR B=0 THEN
6280          GOSUB Calc_axis
6285          X_coordinate=X_min
6290          MOVE X_coordinate,Y_coordinate
6295          GOSUB Write_label
6300        END IF
```

```
6305      END IF
6310       !
6315      IF X_min*X_max<0 THEN
6320        GOSUB Calc_axis
6325        X_position=0
6330        FOR I=0 TO INT(ABS(X_max/Xmajor_div))
6335          X_coordinate=PROUND(X_position,INT(LGT(ABS(Xmajor_div))))
6340          MOVE X_coordinate,Y_coordinate
6345          GOSUB Write_label
6350          GOSUB Draw_x_tick
6355          X_position=X_position+Xmajor_div
6360        NEXT I
6365         !
6370        GOSUB Calc_axis
6375        X_position=0-Xmajor_div
6380        FOR I=0 TO INT(ABS(X_min/Xmajor_div))-1
6385          X_coordinate=PROUND(X_position,INT(LGT(ABS(Xmajor_div))))
6390          MOVE X_coordinate,Y_coordinate
6395          GOSUB Write_label
6400          GOSUB Draw_x_tick
6405          X_position=X_position-Xmajor_div
6410        NEXT I
6415      ELSE
6420        GOSUB Calc_axis
6425        IF X_min<>0 THEN
6430          IF ABS(X_max/X_min)=2 OR ABS(X_max/X_min)=.5 THEN
6435            X_stop=X_max+Xmajor_div
6440          ELSE
6445            X_stop=X_max
6450          END IF
6455        ELSE
6460          X_stop=X_max
6465        END IF
6470         !
6475        FOR X_coordinate=X_min TO X_stop STEP Xmajor_div
6480          MOVE X_coordinate,Y_coordinate
6485          GOSUB Write_label
6490          GOSUB Draw_x_tick
6495        NEXT X_coordinate
6500      END IF
6505    ELSE
6510      GOSUB Calc_axis
6515      FOR X_coordinate=X_min TO X_max STEP Xmajor_div
6520        MOVE X_coordinate,Y_coordinate
6525        IF X_coordinate<>X_min AND X_coordinate<>X_max THEN GOSUB Draw_x_tick
6530      NEXT X_coordinate
6535       !
6540      FOR X_coordinate=X_min TO X_max STEP (X_max-X_min)
6545        GOSUB Calc_axis
6550        MOVE X_coordinate,Y_coordinate
6555        GOSUB Write_label
6560      NEXT X_coordinate
6565      GOSUB Write_sublabel
6570    END IF
6575    !*********************************************************************
6580    !*                      Write exponent value                         *
6585    !*********************************************************************
6590    MOVE X_max,Y_coord_1
6595    LORG 6
6600    A$=VAL$(Exponent)
6605    LABEL "(xE"&A$&")"
6610    CLIP ON
6615    SUBEXIT
6620    !
6625 Write_label:!
6630    X_coordinate=PROUND(X_coordinate,INT(LGT(ABS(Xmajor_div)))-2)
```

```
6635    IF Quadrant THEN
6640      IF Digit<4 THEN
6645        LABEL USING "K";DROUND((X_coordinate/(10^Exponent)),5)
6650      ELSE
6655        LABEL USING "K";DROUND((X_coordinate/(10^Exponent)),15)
6660      END IF
6665    ELSE
6670      IF Digit<4 THEN
6675        LABEL USING "K";DROUND((X_coordinate/(10^Exponent)),6)
6680      ELSE
6685        LABEL USING "K";DROUND((X_coordinate/(10^Exponent)),15)
6690      END IF
6695    END IF
6700    RETURN
6705    !
6710 Write_sublabel:   !
6715    MOVE X_min+(X_max-X_min)/2,Y_coordinate
6720    LABEL USING "K";Xmajor_div/Xminor_tick;"/div"
6725    RETURN
6730    !
6735 Draw_x_tick:   !
6740    MOVE X_coordinate,Y_min
6745    IDRAW 0,Tick_length
6750      !
6755    MOVE X_coordinate,Y_max
6760    IDRAW 0,-Tick_length
6765    RETURN
6770    !
6775 Calc_axis:     !
6780    A1=MAX(ABS(X_min),ABS(X_max))
6785      !
6790    IF A1<-1 OR A1>1 THEN
6795      FOR I=1 TO 102
6800        IF (A1/(10^(3*(I-1))))<1000 THEN
6805          Exponent=3*(I-1)
6810          I=103
6815        END IF
6820      NEXT I
6825    END IF
6830      !
6835    IF A1>=-1 AND A1<=1 THEN
6840      FOR I=1 TO 102
6845        IF (A1/((10^(-3*(I-1)))))>=1 THEN
6850          Exponent=-3*(I-1)
6855          I=103
6860        END IF
6865      NEXT I
6870    END IF
6875    RETURN
6880  SUBEND
```

Label_lin_yaxis

```
6895  SUB Label_lin_yaxis(X_min,X_max,Y_min,Y_max,Ymajor_div,INTEGER Minor_ticks,Quadrant)
6900    !*****************************************************************
6905    !*               Labels the linear scaled y-axis                 *
6910    !*****************************************************************
6915    IF Quadrant THEN                  ! If a quadrant is specified,
6920      CSIZE 2.6                       !  use small characters.
6925    ELSE
6930      CSIZE 3
6935    END IF
6940    !
6945    LINE TYPE 1                       ! Solid line
6950    LDIR 0                            ! 0 degrees rotation
6955    LORG 8
6960    CLIP OFF                          ! Soft clip off
6965    !*****************************************************************
6970    !*     Calculate the horizontal position of the axis labels      *
6975    !*****************************************************************
6980    X_coordinate=X_min-.015*(X_max-X_min)
6985    X_coord_1=X_min+.005*(X_max-X_min)
6990    Tick_length=.01*(X_max-X_min)
6995    !*****************************************************************
7000    !*                       Draw minor ticks                        *
7005    !*****************************************************************
7010    IF Y_min*Y_max<0 THEN
7015      FOR Y_coordinate=0 TO Y_max STEP Ymajor_div/Minor_ticks
7020        MOVE X_min,Y_coordinate
7025        IDRAW Tick_length*.5,0
7030      NEXT Y_coordinate
7035      !
7040      FOR Y_coordinate=0-Ymajor_div/Minor_ticks TO Y_min STEP -Ymajor_div/Minor_ticks
7045        MOVE X_min,Y_coordinate
7050        IDRAW Tick_length*.5,0
7055      NEXT Y_coordinate
7060    ELSE
7065      FOR Y_coordinate=Y_min+Ymajor_div/Minor_ticks TO Y_max STEP Ymajor_div/Minor_ticks
7070        MOVE X_min,Y_coordinate
7075        IDRAW Tick_length*.5,0
7080      NEXT Y_coordinate
7085    END IF
7090    !*****************************************************************
7095    !*             Write the labels and draw major ticks             *
7100    !*****************************************************************
7105    Max_val=MAX(ABS(Y_min),ABS(Y_max))
7110    Digit=INT(LGT(ABS(Max_val)))-INT(LGT(ABS(Ymajor_div)))
7115    IF Digit<4 THEN
7120      IF Quadrant=0 THEN
7125        B=ABS(Y_max/(Ymajor_div/Minor_ticks) MOD Minor_ticks)
7130        IF B>1 THEN
7135          GOSUB Calc_axis
7140          Y_coordinate=Y_max
7145          MOVE X_coordinate,Y_coordinate
7150          GOSUB Write_label
7155        END IF
7160        !
7165        B=ABS(Y_min/(Ymajor_div/Minor_ticks) MOD Minor_ticks)
7170        IF B>1 THEN
7175          GOSUB Calc_axis
7180          Y_coordinate=Y_min
7185          MOVE X_coordinate,Y_coordinate
7190          GOSUB Write_label
7195        END IF
7200      END IF
```

```
7205      !
7210      IF Y_min*Y_max<0 THEN
7215        GOSUB Calc_axis
7220        Y_position=0
7225        FOR I=0 TO INT(ABS(Y_max/Ymajor_div))
7230          Y_coordinate=PROUND(Y_position,INT(LGT(ABS(Ymajor_div))))
7235          MOVE X_coordinate,Y_coordinate
7240          GOSUB Write_label
7245          GOSUB Draw_y_tick
7250          Y_position=Y_position+Ymajor_div
7255        NEXT I
7260        !
7265        GOSUB Calc_axis
7270        Y_position=0-Ymajor_div
7275        FOR I=0 TO INT(ABS(Y_min/Ymajor_div))-1
7280          Y_coordinate=PROUND(Y_position,INT(LGT(ABS(Ymajor_div))))
7285          MOVE X_coordinate,Y_coordinate
7290          GOSUB Write_label
7295          GOSUB Draw_y_tick
7300          Y_position=Y_position-Ymajor_div
7305        NEXT I
7310      ELSE
7315        GOSUB Calc_axis
7320        IF Y_min<>0 THEN
7325          IF ABS(Y_max/Y_min)=2 OR ABS(Y_max/Y_min)=.5 THEN
7330            Y_stop=Y_max+Y_major_div
7335          ELSE
7340            Y_stop=Y_max
7345          END IF
7350        ELSE
7355          Y_stop=Y_max
7360        END IF
7365        !
7370        FOR Y_coordinate=Y_min TO Y_stop STEP Ymajor_div
7375          MOVE X_coordinate,Y_coordinate
7380          GOSUB Write_label
7385          GOSUB Draw_y_tick
7390        NEXT Y_coordinate
7395      END IF
7400    ELSE
7405      GOSUB Calc_axis
7410      FOR Y_coordinate=Y_min TO Y_max STEP Ymajor_div
7415        MOVE X_coordinate,Y_coordinate
7420        IF Y_coordinate<>Y_min AND Y_coordinate<>Y_max THEN GOSUB Draw_y_tick
7425      NEXT Y_coordinate
7430       !
7435      FOR Y_coordinate=Y_min TO Y_max STEP (Y_max-Y_min)
7440        GOSUB Calc_axis
7445        MOVE X_coordinate,Y_coordinate
7450        GOSUB Write_label
7455      NEXT Y_coordinate
7460      GOSUB Write_sublabel
7465    END IF
7470    !*********************************************************************
7475    !*                      Write exponent value                         *
7480    !*********************************************************************
7485    MOVE X_coord_1,Y_max+.025*(Y_max-Y_min)
7490    LORG 7
7495    A$=VAL$(Exponent)
7500    LABEL "(xE"&A$&")"
7505    CLIP ON
7510    SUBEXIT
7515    !
7520 Write_label:   !
7525    Y_coordinate=PROUND(Y_coordinate,INT(LGT(ABS(Ymajor_div)))-2)
7530    IF Quadrant THEN
```

```
7535      IF Digit<4 THEN
7540        LABEL USING "K";DROUND(Y_coordinate/(10^Exponent),5)
7545      ELSE
7550        LABEL USING "K";DROUND(Y_coordinate/(10^Exponent),15)
7555      END IF
7560    ELSE
7565      IF Digit<4 THEN
7570        LABEL USING "K";DROUND(Y_coordinate/(10^Exponent),6)
7575      ELSE
7580        LABEL USING "K";DROUND(Y_coordinate/(10^Exponent),15)
7585      END IF
7590    END IF
7595    RETURN
7600    !
7605 Write_sublabel:   !
7610    MOVE X_coordinate,Y_min+(Y_max-Y_min)/2
7615    LDIR 3.1415926/2
7620    LORG 4
7625    LABEL USING "K";Ymajor_div/Minor_ticks;"/div"
7630    LDIR 0
7635    LORG 8
7640    RETURN
7645    !
7650 Draw_y_tick:   !
7655    MOVE X_min,Y_coordinate
7660    IDRAW Tick_length,0
7665      !
7670    MOVE X_max,Y_coordinate
7675    IDRAW -Tick_length,0
7680    RETURN
7685    !
7690 Calc_axis:   !
7695    A1=MAX(ABS(Y_min),ABS(Y_max))
7700      !
7705    IF A1<-1 OR A1>1 THEN
7710      FOR I=1 TO 102
7715        IF (A1/(10^(3*(I-1))))<1000 THEN
7720          Exponent=3*(I-1)
7725          I=103
7730        END IF
7735      NEXT I
7740    END IF
7745      !
7750    IF A1>=-1 AND A1<=1 THEN
7755      FOR I=1 TO 102
7760        IF (A1/((10^(-3*(I-1)))))>=1 THEN
7765          Exponent=-3*(I-1)
7770          I=102
7775        END IF
7780      NEXT I
7785    END IF
7790    RETURN
7795  SUBEND
```

Calc_log_axis

```
7810  SUB Calc_log_axis(Min_val,Max_val,INTEGER Axis_min,Axis_max,Major_tick,Minor_tick,Quadrant)
7815    !*************************************************************************
7820    !*  Calculate the minimum number of decades that will span the data,  *
7825    !*  and determine the tick mark spacing.                               *
7830    !*************************************************************************
7835    IF Min_val>0 OR Max_val>0 THEN
7840      Data_min=Min_val
7845      Data_max=Max_val
7850      Axis_min=LGT(Data_min)
7855      Axis_max=LGT(Data_max)
7860      !
7865      IF Min_val<Max_val THEN
7870        IF LGT(Data_min)<Axis_min THEN Axis_min=Axis_min-1
7875        IF LGT(Data_max)>Axis_max THEN Axis_max=Axis_max+1
7880      END IF
7885      !
7890      IF Min_val>Max_val THEN
7895        IF LGT(Data_min)>Axis_min THEN Axis_min=Axis_min+1
7900        IF LGT(Data_max)<Axis_max THEN Axis_max=Axis_max-1
7905      END IF
7910    END IF
7915    !
7920    IF Min_val<0 OR Max_val<0 THEN
7925      Data_min=ABS(Min_val)
7930      Data_max=ABS(Max_val)
7935      Axis_min=-LGT(Data_min)
7940      Axis_max=-LGT(Data_max)
7945      !
7950      IF Min_val<Max_val THEN
7955        IF -LGT(Data_min)<Axis_min THEN Axis_min=Axis_min-1
7960        IF -LGT(Data_max)>Axis_max THEN Axis_max=Axis_max+1
7965      END IF
7970      !
7975      IF Min_val>Max_val THEN
7980        IF -LGT(Data_min)>Axis_min THEN Axis_min=Axis_min+1
7985        IF -LGT(Data_max)<Axis_max THEN Axis_max=Axis_max-1
7990      END IF
7995    END IF
8000    !*********************************************************************
8005    !*      Determine the number of major and minor tick marks      *
8010    !*********************************************************************
8015    IF Axis_min*Axis_max>0 THEN
8020      Draw_type=MAX(ABS(Axis_min),ABS(Axis_max))-MIN(ABS(Axis_min),ABS(Axis_max))
8025    ELSE
8030      Draw_type=MAX(Axis_min,Axis_max)-MIN(Axis_min,Axis_max)
8035    END IF
8040    !
8045    SELECT Draw_type
8050    CASE 1
8055      Major_tick=1
8060      IF Quadrant THEN
8065        Minor_tick=3
8070      ELSE
8075        Minor_tick=10
8080      END IF
8085    CASE 2
8090      Major_tick=1
8095      IF Quadrant THEN
8100        Minor_tick=1
8105      ELSE
8110        Minor_tick=3
8115      END IF
```

```
8120    CASE 3
8125      Major_tick=1
8130      IF Quadrant THEN
8135        Minor_tick=1
8140      ELSE
8145        Minor_tick=2
8150      END IF
8155    CASE 4 TO 5
8160      Major_tick=1
8165      IF Quadrant THEN
8170        Minor_tick=0
8175        IF Draw_type=4 THEN Major_tick=1
8180        IF Draw_type=5 THEN Major_tick=2
8185      ELSE
8190        Minor_tick=1
8195      END IF
8200    CASE 6 TO 9
8205      IF Quadrant THEN
8210        IF Draw_type=6 OR Draw_type=7 THEN Major_tick=3
8215        IF Draw_type=8 OR Draw_type=9 THEN Major_tick=3
8220      ELSE
8225        Major_tick=1
8230      END IF
8235      Minor_tick=0
8240    CASE 10 TO 16
8245      IF Quadrant THEN
8250        Major_tick=5
8255      ELSE
8260        Major_tick=2
8265      END IF
8270      Minor_tick=0
8275    CASE 17 TO 30
8280      IF Quadrant THEN
8285        IF Draw_tppe<21 THEN Major_tick=5
8290        IF Draw_type>=21 THEN Major_tick=10
8295      ELSE
8300        Major_tick=5
8305      END IF
8310      Minor_tick=0
8315    CASE 31 TO 40
8320      Major_tick=10
8325      Minor_tick=0
8330    CASE 41 TO 100
8335      IF Quadrant THEN
8340        IF Draw_type<50 THEN Major_tick=15
8345        IF Draw_type>=50 THEN Major_tick=25
8350      ELSE
8355        Major_tick=20
8360      END IF
8365      Minor_tick=0
8370    CASE 101 TO 200
8375      IF Quadrant THEN
8380        IF Draw_type<=150 THEN Major_tick=50
8385        IF Draw_type>150 THEN Major_tick=100
8390      ELSE
8395        Major_tick=50
8400      END IF
8405      Minor_tick=0
8410    CASE ELSE
8415      Major_tick=100
8420      Minor_tick=0
8425    END SELECT
8430  SUBEND
```

Label_log_yaxis

```
8445  SUB Label_log_yaxis(REAL X_min,X_max,INTEGER Y_min,Y_max,Major_tick,Minor_tick,Quadrant,Y_polarity,
Y_val_exchange,Grid_pattern)
8450    !*****************************************************************
8455    !*                Labels the log scaled y-axis                   *
8460    !*****************************************************************
8465    INTEGER Exponent
8470    INTEGER Mantissa
8475    !*****************************************************************
8480    !*    Determine the character size and minor tick mark length    *
8485    !*****************************************************************
8490    IF Quadrant THEN
8495      CSIZE 2.6
8500      Tick_length=.0155*(X_max-X_min)
8505    ELSE
8510      CSIZE 3
8515      Tick_length=.0062*(X_max-X_min)
8520    END IF
8525    LINE TYPE 1                           ! Solid line
8530    LDIR 0                                ! 0 degrees rotation
8535    LORG 8
8540    CLIP OFF                              ! Soft clip off
8545    !*****************************************************************
8550    !*     Calculate the horizontal position of the axis labels      *
8555    !*****************************************************************
8560    X_coordinate=X_min-.01*(X_max-X_min)
8565    !*****************************************************************
8570    !*                  Label the major tick marks                   *
8575    !*****************************************************************
8580    IF ABS(ABS(Y_min)-ABS(Y_max))<=40 THEN
8585      IF Y_min<Y_max THEN Y_step=1
8590      IF Y_min>Y_max THEN Y_step=-1
8595    END IF
8600    !
8605    IF Y_val_exchange=1 THEN Major_tick=-Major_tick
8610    FOR Exponent=Y_min TO Y_max STEP Y_step
8615      IF Exponent<>Y_min AND Exponent<>Y_max THEN GOSUB Draw_y_tick
8620      GOSUB Draw_y_tick
8625    NEXT Exponent
8630    !
8635    FOR Exponent=Y_min TO Y_max STEP Major_tick
8640      IF ABS(Exponent)>=0 AND ABS(Exponent)<=9 THEN Using$="MDESZ"
8645      IF ABS(Exponent)>=10 AND ABS(Exponent)<=99 THEN Using$="MDESZZ"
8650      IF ABS(Exponent)>=100 AND ABS(Exponent)<=999 THEN Using$="MDESZZZ"
8655      !
8660      IF Exponent<>Y_min AND Exponent<>Y_max THEN GOSUB Draw_y_tick
8665      MOVE X_coordinate,Exponent
8670      IF Y_polarity=0 THEN
8675        LABEL USING Using$;PROUND(10^Exponent,Exponent)
8680      ELSE
8685        LABEL USING Using$;-(1/PROUND(10^Exponent,Exponent))
8690      END IF
8695    NEXT Exponent
8700    !*****************************************************************
8705    !*                  Label the minor tick marks                   *
8710    !*****************************************************************
8715    Y_start=MIN(Y_min,Y_max)
8720    Y_stop=MAX(Y_min,Y_max)
8725    IF Y_polarity=0 THEN Y_stop=Y_stop-1
8730    IF Y_polarity=1 THEN Y_start=Y_start+1
8735    !
8740    IF Minor_tick<>0 THEN
8745      FOR Exponent=Y_start TO Y_stop
```

```
8750        FOR Mantissa=1 TO 10
8755          IF Y_polarity=0 THEN Y_coordinate=PROUND(Mantissa*(10^Exponent),Exponent)
8760          IF Y_polarity=1 THEN Y_coordinate=PROUND(Mantissa*(10^(-Exponent)),-Exponent)
8765          IF Grid_pattern=0 THEN GOSUB Write_label
8770        NEXT Mantissa
8775      NEXT Exponent
8780    END IF
8785    !
8790    CLIP ON
8795    SUBEXIT
8800  !
8805 Write_label:!
8810    IF Y_polarity=0 THEN
8815      MOVE X_min,LGT(Y_coordinate)
8820      IDRAW Tick_length*.8,0
8825       !
8830      MOVE X_max,LGT(Y_coordinate)
8835      IDRAW -Tick_length*.8,0
8840    END IF
8845     !
8850    IF Y_polarity=1 THEN
8855      MOVE X_min,-LGT(Y_coordinate)
8860      IDRAW Tick_length*.8,0
8865       !
8870      MOVE X_max,-LGT(Y_coordinate)
8875      IDRAW -Tick_length*.8,0
8880    END IF
8885    RETURN
8890    !
8895 Draw_y_tick: !
8900    MOVE X_min,Exponent
8905    IDRAW Tick_length*1.5,0
8910    MOVE X_max,Exponent
8915    IDRAW -Tick_length*1.5,0
8920    RETURN
8925  SUBEND
```

Label_log_xaxis

```
8940  SUB Label_log_xaxis(INTEGER X_min,X_max,REAL Y_min,Y_max,INTEGER Major_tick,Minor_tick,Quadrant,
X_polarity,X_val_exchange,Grid_pattern)
8945    !*****************************************************************
8950    !*                Labels the log scaled x-axis                   *
8955    !*****************************************************************
8960    INTEGER Exponent
8965    INTEGER Mantissa
8970    !*****************************************************************
8975    !*    Determine the character size and minor tick mark length    *
8980    !*****************************************************************
8985    IF Quadrant THEN
8990      CSIZE 2.6
8995      Tick_length=.0155*(Y_max-Y_min)
9000    ELSE
9005      CSIZE 3
9010      Tick_length=.0085*(Y_max-Y_min)
9015    END IF
9020    LINE TYPE 1                          ! Solid line
9025    LDIR 0                               ! 0 degrees rotation
9030    LORG 6
9035    CLIP OFF                             ! Soft clip off
9040    !*****************************************************************
9045    !*     Calculate the horizontal position of the axis labels      *
9050    !*****************************************************************
9055    Y_coordinate=Y_min-.015*(Y_max-Y_min)
9060    !*****************************************************************
9065    !*                  Label the major tick marks                   *
9070    !*****************************************************************
9075    IF ABS(ABS(X_min)-ABS(X_max))<=40 THEN
9080      IF X_min<X_max THEN X_step=1
9085      IF X_min>X_max THEN X_step=-1
9090    END IF
9095    !
9100    IF X_val_exchange=1 THEN Major_tick=-Major_tick
9105    FOR Exponent=X_min TO X_max STEP X_step
9110      IF Exponent<>X_min AND Exponent<>X_max THEN GOSUB Draw_x_tick
9115    NEXT Exponent
9120    !
9125    FOR Exponent=X_min TO X_max STEP Major_tick
9130      IF ABS(Exponent)>=0 AND ABS(Exponent)<=9 THEN Using$="MDESZ"
9135      IF ABS(Exponent)>=10 AND ABS(Exponent)<=99 THEN Using$="MDESZZ"
9140      IF ABS(Exponent)>=100 AND ABS(Exponent)<=999 THEN Using$="MDESZZZ"
9145      !
9150      IF Exponent<>X_min AND Exponent<>X_max THEN GOSUB Draw_x_tick
9155      MOVE Exponent,Y_coordinate
9160      IF X_polarity=0 THEN
9165        LABEL USING Using$;PROUND(10^Exponent,Exponent)
9170      ELSE
9175        LABEL USING Using$;-(1/PROUND(10^Exponent,Exponent))
9180      END IF
9185    NEXT Exponent
9190    !*****************************************************************
9195    !*                  Label the minor tick marks                   *
9200    !*****************************************************************
9205    X_start=MIN(X_min,X_max)
9210    X_stop=MAX(X_min,X_max)
9215    IF X_polarity=0 THEN X_stop=X_stop-1
9220    IF X_polarity=1 THEN X_start=X_start+1
9225    !
9230    IF Minor_tick<>0 THEN
9235      FOR Exponent=X_start TO X_stop
9240        FOR Mantissa=2 TO 9
```

```
9245          IF X_polarity=0 THEN X_coordinate=PROUND(Mantissa*(10^Exponent),Exponent)
9250          IF X_polarity=1 THEN X_coordinate=PROUND(Mantissa*(10^(-Exponent)),-Exponent)
9255          IF Grid_pattern=0 THEN GOSUB Write_label
9260        NEXT Mantissa
9265      NEXT Exponent
9270    END IF
9275    !
9280    CLIP ON
9285    SUBEXIT
9290  !
9295 Write_label:!
9300    IF X_polarity=0 THEN
9305      MOVE LGT(X_coordinate),Y_min
9310      IDRAW 0,Tick_length
9315       !
9320      MOVE LGT(X_coordinate),Y_max
9325      IDRAW 0,-Tick_length
9330    END IF
9335     !
9340    IF X_polarity=1 THEN
9345      MOVE -LGT(X_coordinate),Y_min
9350      IDRAW 0,Tick_length
9355       !
9360      MOVE -LGT(X_coordinate),Y_max
9365      IDRAW 0,-Tick_length
9370    END IF
9375    RETURN
9380    !
9385 Draw_x_tick: !
9390    MOVE Exponent,Y_min
9395    IDRAW 0,Tick_length*1.7
9400    MOVE Exponent,Y_max
9405    IDRAW 0,-Tick_length*1.7
9410    RETURN
9415  SUBEND
```

FNHfe

```
30    DEF FNHfe(INTEGER Channel(*),REAL Vc,Ic,Vbstart,Vbstop,OPTIONAL Vbspeed,Integtime,Hfe_val)
35      OPTION BASE 1
40      INTEGER Ch1,Ch2,Ch3,St
45      !-------------------------------------------------------------------------
50      Ch_num=SIZE(Channel,1)
55      Init_hp4142
60      Ch_sw_off
65      Vbrate=500                              ! RAMP SPEED DEFAULT
70      Integ=5.0E-2                            ! INTEG TIME DEFAULT
75      Hfe=50                                  ! Hfe DFAULT
80      Htime=1                                 ! HOLD TIME DEFAULT
85      Dtime=1.5                               ! DELAY TIME DEFAULT
90      !
95      IF NPAR>5 THEN
100       Vbrate=Vbspeed
105       IF NPAR=7 THEN Integ=Integtime
110       IF NPAR=8 THEN Hfe=Hfe_val
115     END IF
120     !
125     IF Ch_num>2 THEN
130       Ch3=Channel(3)
135       SELECT Channel(3)
140       CASE 1 TO 8
145         Ch_sw_on(Ch3)                       ! SET SMU 0(V)
150         Force_v(Ch3,0,0,1.E-1)              ! HPSMU allows 1(A) compliance
155       CASE ELSE
160         IF Channel(3)<>99 THEN
165           DISP "FNHfe: Illegal channel number"
170           BEEP
175           STOP
180         END IF
185       END SELECT
190     END IF
195     !-------------------------------------------------------------------------
200     Ch1=Channel(1)
205     Ch2=Channel(2)
210     Ch_sw_on(Ch1,Ch2)
215     Set_amonitor(Ch1,1,Vc,Ic,Ic*1.1)
220     Set_asource(Ch2,Vbstart,Vbstop,Vbrate,Htime,Dtime,(Ic*1.1)/Hfe)
225     Measure_asearch(1,4,Integ,Ibmeas,Icmeas,St)
230     Ch_sw_off
235     !-------------------------------------------------------------------------
240     IF St=0 THEN
245       Hfe_meas=Icmeas/Ibmeas
250     ELSE
255       Hfe_meas=-9999999.99999               ! OUT OF MEASUREMENT
260     END IF
265     !-------------------------------------------------------------------------
270     RETURN Hfe_meas
275   FNEND
<\figure>

<s2>FNBvcbo

<figure text nonumber smaller>
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290   DEF FNBvcbo(INTEGER Channel(*),REAL Ic,OPTIONAL Vlim,Time)
295     OPTION BASE 1
300     INTEGER N,Ch1,Ch2,Ch3,St
```

```
305     N=NPAR
310     !-------------------------------------------------------------------------
315     Init_hp4142
320     Ch_num=SIZE(Channel,1)
325     Vlimit=20                                ! VOLTAGE LIMIT DEFAULT
330     Twait=.4                                 ! WAIT TIME DEFAULT
335     IF N>2 THEN
340       IF Vlim<>0 THEN Vlimit=ABS(Vlim)
345       IF N>3 THEN Twait=Time                 ! SET WAIT TIME
350     END IF
355     !-------------------------------------------------------------------------
360     IF Ch_num>1 THEN
365       Ch2=Channel(2)
370       SELECT Channel(2)
375       CASE 1 TO 8
380         Comp=1.E-1                           ! SET HPSMU COMPLIANCE
385         Module_type((Ch2),Type$)
390         IF Type$="HP41423" THEN Comp=1.E-2    ! SET HVU COMPLIANCE
395         IF Type$="HP41423" AND Ic>=0 THEN
400           Set_pol(Ch2,1)
405         ELSE
410           Ch_sw_on(Ch2)
415         END IF
420         Force_v(Ch2,0,0,Comp)
425       CASE ELSE
430         IF Channel(2)<>99 THEN
435           DISP "FNBvcbo: Illegal channel number"
440           BEEP
445           STOP
450         END IF
455       END SELECT
460       !
465       IF Ch_num=3 THEN
470         Ch3=Channel(3)
475         Ch_sw_off(Ch3)
480       END IF
485     END IF
490     !-------------------------------------------------------------------------
495     WAIT .01
500     Ch1=Channel(1)
505     Module_type((Ch1),Type$)
510     IF Type$="HP41423" AND Ic<0 THEN
515       Set_pol(Ch1,1)
520     ELSE
525       Ch_sw_on(Ch1)
530     END IF
535     Force_i(Ch1,Ic,0,Vlimit)                 ! SET CURRENT
540     WAIT Twait
545     Measure_v(Ch1,Vmeas,0,St)                ! MEASURE Bvcbo
550     Ch_sw_off
555     WAIT .01
560     RETURN Vmeas
565   FNEND
```

FNBvces

```
580   DEF FNBvces(INTEGER Channel(*),REAL Ic,OPTIONAL Vlim,Time)
585     OPTION BASE 1
590     INTEGER N,Ch1,Ch2
595     !-------------------------------------------------------------------------
600     Init_hp4142
605     Ch_num=SIZE(Channel,1)
610     N=NPAR
615     Vlimit=20                                 ! VLIM DEFAULT
620     Twait=.4                                  ! WAIT TIME DEFAULT
625     IF N>2 THEN
630       IF Vlim<>0 THEN Vlimit=ABS(Vlim)
635       IF N>3 THEN Twait=Time
640     END IF
645     !-------------------------------------------------------------------------
650     IF Ch_num>1 THEN
655       Ch2=Channel(2)
660       SELECT Channel(2)
665       CASE 1 TO 8
670         Comp=1.E-1                            ! SET HPSMU COMPLIANCE
675         Module_type((Ch2),Type$)
680         IF Type$="HP41423" THEN Comp=1.E-2    ! SET HVU COMPLIANCE
685         IF Type$="HP41423" AND Ic>=0 THEN
690           Set_pol(Ch2,1)
695         ELSE
700           Ch_sw_on(Ch2)
705         END IF
710         Force_v(Ch2,0,0,Comp)                 ! HPSMU allows 1(A) compliance
715       CASE ELSE
720         IF Channel(2)<>99 THEN
725           DISP "FNBvces: Illegal channel number"
730           BEEP
735           STOP
740         END IF
745       END SELECT
750     END IF
755     !-------------------------------------------------------------------------
760     WAIT .01
765     Ch1=Channel(1)
770     Module_type((Ch1),Type$)
775     IF Type$="HP41423" AND Ic<0 THEN
780       Set_pol(Ch1,1)
785     ELSE
790       Ch_sw_on(Ch1)
795     END IF
800     Force_i(Ch1,Ic,0,Vlimit)                  ! SET COLLECTOR CURRENT
805     WAIT Twait
810     Measure_v(Ch1,Vmeas,0)                    ! MEASURE Bvces
815     Ch_sw_off
820     WAIT .01
825     RETURN Vmeas
830   FNEND
```

FNIds

```
DEF FNIds(INTEGER Channel(*),REAL Vds,Vgs,OPTIONAL Idslim,Vsubs)
  OPTION BASE 1
  INTEGER N,St,Ch1,Ch2,Ch3,Ch4
  !-------------------------------------------------------------------------
  Ch_num=SIZE(Channel,1)
  Init_hp4142
  N=NPAR
  Vsubs1=0                                ! VSUBS DEFAULT VALUE
  Ilimit=1.E-6                            ! CURRENT LIMIT SMU DEFAULT VALUE
  IF N>3 THEN
    Ilimit=ABS(Idslim)
    IF N=5 THEN Vsubs1=Vsubs
  END IF
  Ch1=Channel(1)
  Ch2=Channel(2)
  Module_type((Ch1),Type$)
  IF Type$="HP41423" AND Vds<0 THEN
    Set_pol(Ch1,1)
  ELSE
    Ch_sw_on(Ch1)
  END IF
  Module_type((Ch2),Type$)
  IF Type$="HP41423" AND Vgs<0 THEN
    Set_pol(Ch2,1)
  ELSE
    Ch_sw_on(Ch2)
  END IF
  IF Ch_num=4 AND NPAR=5 THEN
    Ch4=Channel(4)
    Module_type((Ch4),Type$)
    IF Type$="HP41423" AND Vsubs1<0 THEN
      Set_pol(Ch4,1)
    ELSE
      Ch_sw_on(Ch4)
    END IF
  END IF
  !-------------------------------------------------------------------------
  IF Ch_num>2 THEN
    Ch3=Channel(3)
    SELECT Channel(3)
    CASE 1 TO 8
      Module_type((Ch3),Type$)
      IF Type$="HP41423" THEN
        Comp=1.E-2
      ELSE
        Comp=1.E-1
      END IF
      IF Type$="HP41423" AND Vds>=0 THEN
        Set_pol(Ch3,1)
      ELSE
        Ch_sw_on(Ch3)
      END IF
      Ch_sw_on(Ch3)
      Force_v(Ch3,0,0,Comp)
    CASE ELSE
      IF Channel(3)<>99 THEN
        DISP "FNIds: Illegal channel number"
        BEEP
        STOP
      END IF
    END SELECT
    !
```

```
1155      IF Ch_num=4 AND NPAR=5 THEN
1160        Ch4=Channel(4)
1165        Module_type((Ch4),Type$)
1170        IF Type$="HP41423" THEN
1175          Comp=1.E-2
1180        ELSE
1185          Comp=1.E-1
1190        END IF
1195        Force_v(Ch4,Vsubs1,0,Comp)        ! HPSMU allows 1(A) compliance
1200      END IF
1205    END IF
1210    !-------------------------------------------------------------------
1215    Force_v(Ch1,Vds,0,Ilimit)              ! SET DRAIN-SOURCE VOLTAGE
1220    Force_v(Ch2,Vgs,0,1.0E-5)              ! SET GATE-SOURCE VOLTAGE
1225    Measure_i(Ch1,Ids,0,St)                ! MEASURE DRAIN-SOURCE CURRENT
1230    !
1235    IF St>0 THEN Ids=-9999999.99999
1240    Ch_sw_off
1245    RETURN Ids
1250  FNEND
```

FNVth1

```
1265  DEF FNVth1(INTEGER Channel(*),REAL Ids,OPTIONAL Vlim,Vsubs)
1270    OPTION BASE 1
1275    INTEGER N,St,Ch1,Ch2,Ch3
1280    !-------------------------------------------------------------------------
1285    Ch_num=SIZE(Channel,1)
1290    Init_hp4142
1295    N=NPAR
1300    Iforce=ABS(Ids)
1305    Vlimit=20                                 ! VLIM DEFAULT
1310    Vsubs1=0                                  ! VSUBS DEFAULT
1315    IF N>2 THEN
1320      IF Vlim<>0 THEN Vlimit=ABS(Vlim)
1325      IF N=4 THEN Vsubs1=Vsubs
1330    END IF
1335    !
1340    Twait=.01                                 ! WAIT TIME SELECTION
1345    IF Iforce<=2.E-5 THEN
1350      Twait=.1
1355      IF Iforce<=3.E-8 THEN
1360        Twait=1
1365        IF Iforce<=5.E-9 THEN Twait=2
1370      END IF                                  ! IF Iforce<=3E-8
1375    END IF                                    ! IF Iforce<=2E-5
1380    !-------------------------------------------------------------------------
1385    IF Ch_num>1 THEN
1390      Ch2=Channel(2)
1395      SELECT Channel(2)
1400      CASE 1 TO 8
1405        Ch_sw_on(Ch2)                         ! SET SMU 0(V)
1410        Force_v(Ch2,0,0,1.E-1)                ! HPSMU allows 1(A) compliance
1415      CASE ELSE
1420        IF Channel(2)<>99 THEN
1425          DISP "FNVth1: Illegal channel number"
1430          BEEP
1435          STOP
1440        END IF
1445      END SELECT
1450      !
1455      IF Ch_num=3 AND NPAR=4 THEN
1460        Ch3=Channel(3)
1465        Ch_sw_on(Ch3)                         ! SET SMU 0(V)
1470        Force_v(Ch3,Vsubs1,0,1.E-1)           ! HPSMU allows 1(A) compliance
1475      END IF
1480    END IF
1485    !-------------------------------------------------------------------------
1490    Ch1=Channel(1)
1495    Ch_sw_on(Ch1)
1500    Force_i(Ch1,Ids,0,Vlimit)                 ! SET DRAIN-SOURCE CURRENT
1505    WAIT Twait
1510    Measure_v(Ch1,Vgs,0,St)                   ! MEASURE GATE-SOURCE VOLTAGE
1515    Vth=Vgs
1520    IF St THEN Vth=-9999999.99999
1525    Ch_sw_off
1530    RETURN Vth
1535  FNEND
```

FNVth2

```
1550  DEF FNVth2(INTEGER Channel(*),REAL Ids1,Ids2,OPTIONAL Vlim,Vsubs)
1555    OPTION BASE 1
1560    INTEGER N,I,St1,St2,Ch1,Ch2,Ch3
1565    REAL Twait(1:2)
1570    !-------------------------------------------------------------------------
1575    Init_hp4142
1580    Ch_num=SIZE(Channel,1)
1585    N=NPAR
1590    Vlimit=20                                 ! VLIM DEFAULT
1595    Vsubs1=0                                  ! VSUBS DEFAULT
1600    IF N>3 THEN
1605      IF Vlim<>0 THEN Vlimit=ABS(Vlim)
1610      IF N=5 THEN Vsubs1=Vsubs
1615    END IF
1620    Iforce=ABS(Ids1)
1625    FOR I=1 TO 2
1630      Twait(I)=.01                            ! WAIT TIME SELECTION
1635      IF Iforce<=2.E-5 THEN
1640        Twait(I)=.1
1645        IF Iforce<=3.E-8 THEN
1650          Twait(I)=1
1655          IF Iforce<=5.E-9 THEN Twait(I)=2
1660        END IF                                ! IF Iforce<=3E-8
1665      END IF                                  ! IF Iforce<=2E-5
1670      Iforce=ABS(Ids2)
1675    NEXT I
1680    !-------------------------------------------------------------------------
1685    IF Ch_num>1 THEN
1690      Ch2=Channel(2)
1695      SELECT Channel(2)
1700      CASE 1 TO 8
1705        Ch_sw_on(Ch2)                         ! SET SMU 0(V)
1710        Force_v(Ch2,0,0,1.E-1)                ! HPSMU allows 1(A) compliance
1715      CASE ELSE
1720        IF Channel(2)<>99 THEN
1725          DISP "FNVth2: Illegal channel number"
1730          BEEP
1735          STOP
1740        END IF
1745      END SELECT
1750      !
1755      IF Ch_num=3 AND NPAR=5 THEN
1760        Ch3=Channel(3)
1765        Ch_sw_on(Ch3)                         ! SET SMU 0(V)
1770        Force_v(Ch3,Vsubs1,0,1.E-1)           ! HPSMU allows 1(A) compliance
1775      END IF
1780    END IF
1785    !-------------------------------------------------------------------------
1790    Ch1=Channel(1)
1795    Ch_sw_on(Ch1)
1800    Force_i(Ch1,Ids1,0,Vlimit)                ! SET Ids1
1805    WAIT Twait(1)
1810    Measure_v(Ch1,Vgs1,0,St1)                 ! MEASURE Vgs1
1815    Force_i(Ch1,Ids2,0,Vlimit)                ! SET Ids2
1820    WAIT Twait(2)
1825    Measure_v(Ch1,Vgs2,0,St2)                 ! MEASURE Vgs2
1830    IF Ids2-Ids1=0 THEN Ids1=Ids2*.99
1835    Vth=(Vgs1*ABS(Ids2)-Vgs2*ABS(Ids1)+(Vgs1-Vgs2)*SQR(ABS(Ids2)*ABS(Ids1)))/(ABS(Ids2)-ABS(Ids1))
                        ! CALCULATE Vth
1840    IF St1 OR St2 THEN
1845      Vth=-9999999.99999
1850    ELSE
```

```
1855      Vth=PROUND(Vth,-3)
1860    END IF
1865    Ch_sw_off
1870    RETURN Vth
1875  FNEND
```

FNVth3

```
1890  DEF FNVth3(INTEGER Channel(*),REAL Ids,Vds,Vgstart,Vgstop,Gate_i_comp,OPTIONAL Vgspeed,Integtime,
Vsubs)
1895    OPTION BASE 1
1900    INTEGER St,Ch1,Ch2,Ch3,Ch4
1905    !-------------------------------------------------------------------------
1910    Init_hp4142
1915    Ch_num=SIZE(Channel,1)
1920    Vgrate=500                              ! RAMP SPEED DEFAULT
1925    Integ=5.E-3                             ! INTEG TIME DEFAULT
1930    Htime=1                                 ! HOLD TIME DEFAULT
1935    Dtime=1.5                               ! DELAY TIME DEFAULT
1940    !
1945    IF NPAR>6 THEN
1950      Vgrate=Vgspeed
1955      IF NPAR>=8 THEN Integ=Integtime
1960      IF NPAR=9 THEN Vsubs1=Vsubs
1965    END IF
1970    !
1975    IF Ch_num>2 THEN
1980      Ch3=Channel(3)
1985      SELECT Channel(3)
1990      CASE 1 TO 8
1995        Ch_sw_on(Ch3)                       ! SET SMU 0(V)
2000        Force_v(Ch3,0,0,1.E-1)              ! HPSMU allows 1(A) compliance
2005      CASE ELSE
2010        IF Channel(3)<>99 THEN
2015          DISP "FNVth3: Illegal channel number"
2020          BEEP
2025          STOP
2030        END IF
2035      END SELECT
2040      !
2045      IF Ch_num=4 AND NPAR=9 THEN
2050        Ch4=Channel(4)
2055        Ch_sw_on(Ch4)                       ! SET SMU 0(V)
2060        Force_v(Ch4,Vsubs1,0,1.E-1)         ! HPSMU allows 1(A) compliance
2065      END IF
2070    END IF
2075    !-------------------------------------------------------------------------
2080    Ch1=Channel(1)
2085    Ch2=Channel(2)
2090    Ch_sw_on(Ch1,Ch2)
2095    Set_amonitor(Ch1,1,Vds,Ids,Ids*1.1)
2100    Set_asource(Ch2,Vgstart,Vgstop,Vgrate,Htime,Dtime,Gate_i_comp)
2105    Measure_asearch(1,3,Integ,Vth,Id,St)
2110    Ch_sw_off
2115    IF St THEN Vth=-9999999.99999           ! OUT OF MEASUREMENT
2120    RETURN Vth
2125  FNEND
```

FNR_measure

```
2140  DEF FNR_measure(INTEGER High_i,Low_i,High_v,Low_v,Meas_mode,REAL Itest,OPTIONAL Vlim)
2145    INTEGER St1,St2
2150    !*************************************************************************
2155    !*                    SMU two terminals measurement                      *
2160    !*************************************************************************
2165    Init_hp4142
2170    Ch_sw_off
2175    IF Meas_mode=1 THEN
2180      Iforce=ABS(Itest)                          ! SOURCE CURRENT
2185      Module_type((Low_i),Type$)
2190      IF (Iforce>=1.E-9 AND Type$<>"HP41423") OR (Iforce>=1.E-8 AND Type$="HP41423") THEN
2195        IF Type$="HP41423" THEN
2200          Twait=.1
2205        ELSE
2210          Twait=.01                              ! WAIT TIME SELECTION
2215        END IF
2220        IF Iforce<=2.E-5 THEN                    ! 2E-5>=|Itest|>3E-8
2225          Twait=.4
2230          IF Iforce<=3.E-8 THEN                  ! 3E-8>=|Itest|>5E-9
2235            Twait=5
2240            IF Iforce<5.E-9 THEN Twait=10        ! 5E-9>=|Itest|>=1E-9
2245          END IF
2250        END IF
2255        Vlimit=20
2260        IF NPAR=7 THEN Vlimit=Vlim               ! VOLTAGE LIMIT
2265        !
2270        Module_type((High_i),Type$)
2275        IF Type$="HP41423" AND Itest>=0 THEN
2280          Set_pol(High_i,1)
2285        ELSE
2290          Ch_sw_on(High_i)
2295        END IF
2300        IF Type$="HP41423" THEN
2305          Force_range=100
2310          Comp=1.E-2
2315        ELSE
2320          Force_range=20
2325          Comp=1.E-1
2330        END IF
2335        Force_v(High_i,0,Force_range,Comp)              ! SET SMU OV
2340        Module_type((Low_i),Type$)
2345        IF Type$="HP41423" AND Itest<0 THEN
2350          Set_pol(Low_i,1)
2355        ELSE
2360          Ch_sw_on(Low_i)
2365        END IF
2370        Force_i(Low_i,Itest,0,Vlimit)            ! SET CURRENT
2375        WAIT Twait
2380        Measure_v(Low_i,Vmeas,0)                 ! MEASURE VOLTAGE
2385        Measure_i(High_i,Imeas,0,St1)            ! MEASURE CURRENT
2390        IF ABS(Imeas)>=9.E-10 AND ABS(Vmeas)>=1.E-2 AND St1<>2 THEN
2395          R=DROUND(-Vmeas/Imeas,5)               ! CALCULATE R
2400        ELSE
2405          R=-9999999.99999
2410        END IF
2415        Ch_sw_off
2420      ELSE
2425        R=-9999999.99999                         ! OUT OF MEASUREMENT
2430      END IF                                     ! IF ABS(Iforce)>=1.E-9
2435      RETURN R
2440    END IF
2445    !*************************************************************************
```

```
2450    !*                  SMU four terminals measurement                  *
2455    !*******************************************************************
2460    IF Meas_mode=2 THEN
2465      Iforce=ABS(Itest)                          ! SOURCE CURRENT
2470      IF Iforce>=1.E-6 THEN
2475        Vlimit=20                                ! VLIM DEFAULT
2480        IF NPAR=7 THEN Vlimit=Vlim               ! VOLTAGE LIMIT
2485        !
2490        Module_type((High_i),Type$)
2495        IF Type$="HP41423" THEN
2500          Twait=.1
2505        ELSE
2510          Twait=.01
2515        END IF
2520        IF Iforce<=2.E-5 THEN Twait=.4           ! WAIT TIME SELECTION
2525        Module_type((Low_i),Type$)
2530        IF Type$="HP41423" AND Itest>=0 THEN
2535          Set_pol(Low_i,1)
2540        ELSE
2545          Ch_sw_on(Low_i)
2550        END IF
2555        IF Type$="HP41423" THEN
2560          Force_range=100
2565          Comp=1.E-2
2570        ELSE
2575          Force_range=20
2580          Comp=1.E-1
2585        END IF
2590        Force_v(Low_i,0,Force_range,Comp)        ! SET I MEASUREMENT MODE
2595        Ch_sw_on(Low_v,High_v)
2600        Module_type((High_i),Type$)
2605        IF Type$="HP41423" AND Itest<0 THEN
2610          Set_pol(High_i,1)
2615        ELSE
2620          Ch_sw_on(High_i)
2625        END IF
2630        Force_i(Low_v,1.E-10,0,20)               ! SET V MEASUREMENT MODE
2635        Force_i(High_v,1.E-10,0,Vlimit)          ! SET V MEASUREMENT MODE
2640        Force_i(High_i,Itest,0,Vlimit)           ! SET CURRENT
2645        WAIT Twait
2650        Measure_i(Low_i,Imeas,0,St1)             ! MEASURE CURRENT
2655        Measure_v(Low_v,Vm2,0)                   ! MEASURE V2
2660        Measure_v(High_v,Vm1,0)                  ! MEASURE V1
2665        IF ABS(Imeas)>=9.E-7 AND ABS(Vm1)>=1.E-2 AND St1<>2 THEN
2670          R=DROUND(-(Vm1-Vm2)/Imeas,5)           ! CALCULATE R
2675        ELSE
2680          R=-9999999.99999
2685        END IF
2690        Ch_sw_off
2695      ELSE
2700        R=-9999999.99999                         ! OUT OF MEASUREMENT
2705      END IF                                     ! IF Iforce>=1.E-6
2710      RETURN R
2715    END IF
2720    !*******************************************************************
2725    !*                    VM differential measurement                  *
2730    !*******************************************************************
2735    IF Meas_mode=3 THEN
2740      Iforce=ABS(Itest)                          ! SOURCE CURRENT
2745      Module_type((High_i),Type$)
2750      IF (Iforce>=1.E-9 AND Type$<>"HP41423") OR (Iforce>=1.E-8 AND Type$="HP41423") THEN
2755        IF Type$="HP41423" THEN
2760          Twait=.1
2765        ELSE
2770          Twait=.01
2775        END IF
```

```
2780        IF Iforce<=2.E-5 THEN
2785          Twait=.4
2790          IF Iforce<=3.E-8 THEN
2795            Twait=5
2800            IF Iforce<5.E-9 THEN Twait=10
2805          END IF
2810        END IF
2815        Vlimit=20                              ! VLIM DEFAULT
2820        !
2825        IF NPAR=7 THEN Vlimit=Vlim             ! VOLTAGE LIMIT
2830        Module_type((Low_i),Type$)
2835        IF Type$="HP41423" AND Itest>=0 THEN
2840          Set_pol(Low_i,1)
2845        ELSE
2850          Ch_sw_on(Low_i)
2855        END IF
2860        IF Type$="HP41423" THEN
2865          Force_range=100
2870          Comp=1.E-2
2875        ELSE
2880          Force_range=20
2885          Comp=1.E-1
2890        END IF
2895        Force_v(Low_i,0,Force_range,Comp)      ! SET I MEASUREMENT MODE
2900        Module_type((High_i),Type$)
2905        IF Type$="HP41423" AND Itest<0 THEN
2910          Set_pol(High_i,1)
2915        ELSE
2920          Ch_sw_on(High_i)
2925        END IF
2930        Force_i(High_i,Itest,0,Vlimit)         ! SET CURRENT
2935        WAIT Twait
2940        Measure_i(Low_i,Imeas,0,St1)           ! MEASURE CURRENT
2945        Set_vm(High_v,2)                       ! SET VM DIFF MODE
2950        Measure_v(High_v,Vmeas,0,St2)          ! MEASURE VOLTAGE
2955        Set_vm(High_v,1)                       ! SET VM NORMAL MODE
2960        IF ABS(Imeas)>=9.E-7 AND ABS(Vmeas)>=1.E-2 AND St1<>2 THEN
2965          R=DROUND(Vmeas/Imeas,5)              ! CALCULATE R
2970        ELSE
2975          R=-9999999.99999
2980        END IF
2985        Ch_sw_off
2990      ELSE
2995        R=-9999999.99999                       ! OUT OF MEASUREMENT
3000      END IF
3005      RETURN R
3010    END IF
3015  FNEND
```